

VECTOR IDENTITIES⁴

Notation: f, g , are scalars; $\mathbf{A}, \mathbf{B}$, etc., are vectors; $\mathbf{T}$ is a tensor; $\mathbf{I}$ is the unit dyad.

$$(1) \mathbf{A} \cdot \mathbf{B} \times \mathbf{C} = \mathbf{A} \times \mathbf{B} \cdot \mathbf{C} = \mathbf{B} \cdot \mathbf{C} \times \mathbf{A} = \mathbf{B} \times \mathbf{C} \cdot \mathbf{A} = \mathbf{C} \cdot \mathbf{A} \times \mathbf{B} = \mathbf{C} \times \mathbf{A} \cdot \mathbf{B}$$

$$(2) \mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = (\mathbf{C} \times \mathbf{B}) \times \mathbf{A} = (\mathbf{A} \cdot \mathbf{C})\mathbf{B} - (\mathbf{A} \cdot \mathbf{B})\mathbf{C}$$

$$(3) \mathbf{A} \times (\mathbf{B} \times \mathbf{C}) + \mathbf{B} \times (\mathbf{C} \times \mathbf{A}) + \mathbf{C} \times (\mathbf{A} \times \mathbf{B}) = 0$$

$$(4) (\mathbf{A} \times \mathbf{B}) \cdot (\mathbf{C} \times \mathbf{D}) = (\mathbf{A} \cdot \mathbf{C})(\mathbf{B} \cdot \mathbf{D}) - (\mathbf{A} \cdot \mathbf{D})(\mathbf{B} \cdot \mathbf{C})$$

$$(5) (\mathbf{A} \times \mathbf{B}) \times (\mathbf{C} \times \mathbf{D}) = (\mathbf{A} \times \mathbf{B} \cdot \mathbf{D})\mathbf{C} - (\mathbf{A} \times \mathbf{B} \cdot \mathbf{C})\mathbf{D}$$

$$(6) \nabla(fg) = \nabla(gf) = f\nabla g + g\nabla f$$

$$(7) \nabla \cdot (f\mathbf{A}) = f\nabla \cdot \mathbf{A} + \mathbf{A} \cdot \nabla f$$

$$(8) \nabla \times (f\mathbf{A}) = f\nabla \times \mathbf{A} + \nabla f \times \mathbf{A}$$

$$(9) \nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot \nabla \times \mathbf{A} - \mathbf{A} \cdot \nabla \times \mathbf{B}$$

$$(10) \nabla \times (\mathbf{A} \times \mathbf{B}) = \mathbf{A}(\nabla \cdot \mathbf{B}) - \mathbf{B}(\nabla \cdot \mathbf{A}) + (\mathbf{B} \cdot \nabla)\mathbf{A} - (\mathbf{A} \cdot \nabla)\mathbf{B}$$

$$(11) \mathbf{A} \times (\nabla \times \mathbf{B}) = (\nabla \mathbf{B}) \cdot \mathbf{A} - (\mathbf{A} \cdot \nabla)\mathbf{B}$$

$$(12) \nabla(\mathbf{A} \cdot \mathbf{B}) = \mathbf{A} \times (\nabla \times \mathbf{B}) + \mathbf{B} \times (\nabla \times \mathbf{A}) + (\mathbf{A} \cdot \nabla)\mathbf{B} + (\mathbf{B} \cdot \nabla)\mathbf{A}$$

$$(13) \nabla^2 f = \nabla \cdot \nabla f$$

$$(14) \nabla^2 \mathbf{A} = \nabla(\nabla \cdot \mathbf{A}) - \nabla \times \nabla \times \mathbf{A}$$

$$(15) \nabla \times \nabla f = 0$$

$$(16) \nabla \cdot \nabla \times \mathbf{A} = 0$$

If $\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3$ are orthonormal unit vectors, a second-order tensor $\mathbf{T}$ can be written in the dyadic form

$$(17) \mathbf{T} = \sum_{i,j} T_{ij} \mathbf{e}_i \mathbf{e}_j$$

In cartesian coordinates the divergence of a tensor is a vector with components

$$(18) (\nabla \cdot \mathbf{T})_i = \sum_j (\partial T_{ji} / \partial x_j)$$

[This definition is required for consistency with Eq. (29)]. In general

$$(19) \nabla \cdot (\mathbf{A}\mathbf{B}) = (\nabla \cdot \mathbf{A})\mathbf{B} + (\mathbf{A} \cdot \nabla)\mathbf{B}$$

$$(20) \nabla \cdot (f\mathbf{T}) = \nabla f \cdot \mathbf{T} + f\nabla \cdot \mathbf{T}$$

Let $\mathbf{r} = ix + jy + kz$ be the radius vector of magnitude r , from the origin to the point x, y, z . Then

$$(21) \quad \nabla \cdot \mathbf{r} = 3$$

$$(22) \quad \nabla \times \mathbf{r} = 0$$

$$(23) \quad \nabla r = \mathbf{r}/r$$

$$(24) \quad \nabla(1/r) = -\mathbf{r}/r^3$$

$$(25) \quad \nabla \cdot (\mathbf{r}/r^3) = 4\pi\delta(\mathbf{r})$$

$$(26) \quad \nabla \mathbf{r} = I$$

If V is a volume enclosed by a surface S and $d\mathbf{S} = \mathbf{n}dS$, where $\mathbf{n}$ is the unit normal outward from V ,

$$(27) \quad \int_V dV \nabla f = \int_S d\mathbf{S} f$$

$$(28) \quad \int_V dV \nabla \cdot \mathbf{A} = \int_S d\mathbf{S} \cdot \mathbf{A}$$

$$(29) \quad \int_V dV \nabla \cdot T = \int_S d\mathbf{S} \cdot T$$

$$(30) \quad \int_V dV \nabla \times \mathbf{A} = \int_S d\mathbf{S} \times \mathbf{A}$$

$$(31) \quad \int_V dV (f \nabla^2 g - g \nabla^2 f) = \int_S d\mathbf{S} \cdot (f \nabla g - g \nabla f)$$

$$(32) \quad \int_V dV (\mathbf{A} \cdot \nabla \times \nabla \times \mathbf{B} - \mathbf{B} \cdot \nabla \times \nabla \times \mathbf{A}) \\ = \int_S d\mathbf{S} \cdot (\mathbf{B} \times \nabla \times \mathbf{A} - \mathbf{A} \times \nabla \times \mathbf{B})$$

If S is an open surface bounded by the contour C , of which the line element is $d\mathbf{l}$,

$$(33) \quad \int_S d\mathbf{S} \times \nabla f = \oint_C d\mathbf{l} f$$

$$(34) \quad \int_S d\mathbf{S} \cdot \nabla \times \mathbf{A} = \oint_C d\mathbf{l} \cdot \mathbf{A}$$

$$(35) \quad \int_S (d\mathbf{S} \times \nabla) \times \mathbf{A} = \oint_C d\mathbf{l} \times \mathbf{A}$$

$$(36) \quad \int_S d\mathbf{S} \cdot (\nabla f \times \nabla g) = \oint_C f dg = - \oint_C g df$$

DIFFERENTIAL OPERATORS IN CURVILINEAR COORDINATES⁵

Cylindrical Coordinates

Divergence

$$\nabla \cdot \mathbf{A} = \frac{1}{r} \frac{\partial}{\partial r} (r A_r) + \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z}$$

Gradient

$$(\nabla f)_r = \frac{\partial f}{\partial r}; \quad (\nabla f)_\phi = \frac{1}{r} \frac{\partial f}{\partial \phi}; \quad (\nabla f)_z = \frac{\partial f}{\partial z}$$

Curl

$$(\nabla \times \mathbf{A})_r = \frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z}$$

$$(\nabla \times \mathbf{A})_\phi = \frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r}$$

$$(\nabla \times \mathbf{A})_z = \frac{1}{r} \frac{\partial}{\partial r} (r A_\phi) - \frac{1}{r} \frac{\partial A_r}{\partial \phi}$$

Laplacian

$$\nabla^2 f = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \phi^2} + \frac{\partial^2 f}{\partial z^2}$$

Laplacian of a vector

$$(\nabla^2 \mathbf{A})_r = \nabla^2 A_r - \frac{2}{r^2} \frac{\partial A_\phi}{\partial \phi} - \frac{A_r}{r^2}$$

$$(\nabla^2 \mathbf{A})_\phi = \nabla^2 A_\phi + \frac{2}{r^2} \frac{\partial A_r}{\partial \phi} - \frac{A_\phi}{r^2}$$

$$(\nabla^2 \mathbf{A})_z = \nabla^2 A_z$$

Components of $(\mathbf{A} \cdot \nabla) \mathbf{B}$

$$(\mathbf{A} \cdot \nabla \mathbf{B})_r = A_r \frac{\partial B_r}{\partial r} + \frac{A_\phi}{r} \frac{\partial B_r}{\partial \phi} + A_z \frac{\partial B_r}{\partial z} - \frac{A_\phi B_\phi}{r}$$

$$(\mathbf{A} \cdot \nabla \mathbf{B})_\phi = A_r \frac{\partial B_\phi}{\partial r} + \frac{A_\phi}{r} \frac{\partial B_\phi}{\partial \phi} + A_z \frac{\partial B_\phi}{\partial z} + \frac{A_\phi B_r}{r}$$

$$(\mathbf{A} \cdot \nabla \mathbf{B})_z = A_r \frac{\partial B_z}{\partial r} + \frac{A_\phi}{r} \frac{\partial B_z}{\partial \phi} + A_z \frac{\partial B_z}{\partial z}$$

Divergence of a tensor

$$(\nabla \cdot \mathbf{T})_r = \frac{1}{r} \frac{\partial}{\partial r} (r T_{rr}) + \frac{1}{r} \frac{\partial T_{\phi r}}{\partial \phi} + \frac{\partial T_{zr}}{\partial z} - \frac{T_{\phi\phi}}{r}$$

$$(\nabla \cdot \mathbf{T})_\phi = \frac{1}{r} \frac{\partial}{\partial r} (r T_{r\phi}) + \frac{1}{r} \frac{\partial T_{\phi\phi}}{\partial \phi} + \frac{\partial T_{z\phi}}{\partial z} + \frac{T_{\phi r}}{r}$$

$$(\nabla \cdot \mathbf{T})_z = \frac{1}{r} \frac{\partial}{\partial r} (r T_{rz}) + \frac{1}{r} \frac{\partial T_{\phi z}}{\partial \phi} + \frac{\partial T_{zz}}{\partial z}$$

Spherical Coordinates

Divergence

$$\nabla \cdot \mathbf{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\theta) + \frac{1}{r \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

Gradient

$$(\nabla f)_r = \frac{\partial f}{\partial r}; \quad (\nabla f)_\theta = \frac{1}{r} \frac{\partial f}{\partial \theta}; \quad (\nabla f)_\phi = \frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi}$$

Curl

$$(\nabla \times \mathbf{A})_r = \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\phi) - \frac{1}{r \sin \theta} \frac{\partial A_\theta}{\partial \phi}$$

$$(\nabla \times \mathbf{A})_\theta = \frac{1}{r \sin \theta} \frac{\partial A_r}{\partial \phi} - \frac{1}{r} \frac{\partial}{\partial r} (r A_\phi)$$

$$(\nabla \times \mathbf{A})_\phi = \frac{1}{r} \frac{\partial}{\partial r} (r A_\theta) - \frac{1}{r} \frac{\partial A_r}{\partial \theta}$$

Laplacian

$$\nabla^2 f = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2}$$

Laplacian of a vector

$$(\nabla^2 \mathbf{A})_r = \nabla^2 A_r - \frac{2A_r}{r^2} - \frac{2}{r^2} \frac{\partial A_\theta}{\partial \theta} - \frac{2 \cot \theta A_\theta}{r^2} - \frac{2}{r^2 \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

$$(\nabla^2 \mathbf{A})_\theta = \nabla^2 A_\theta + \frac{2}{r^2} \frac{\partial A_r}{\partial \theta} - \frac{A_\theta}{r^2 \sin^2 \theta} - \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial A_\phi}{\partial \phi}$$

$$(\nabla^2 \mathbf{A})_\phi = \nabla^2 A_\phi - \frac{A_\phi}{r^2 \sin^2 \theta} + \frac{2}{r^2 \sin \theta} \frac{\partial A_r}{\partial \phi} + \frac{2 \cos \theta}{r^2 \sin^2 \theta} \frac{\partial A_\theta}{\partial \phi}$$

Components of $(\mathbf{A} \cdot \nabla)\mathbf{B}$

$$(\mathbf{A} \cdot \nabla\mathbf{B})_r = A_r \frac{\partial B_r}{\partial r} + \frac{A_\theta}{r} \frac{\partial B_r}{\partial \theta} + \frac{A_\phi}{r \sin \theta} \frac{\partial B_r}{\partial \phi} - \frac{A_\theta B_\theta + A_\phi B_\phi}{r}$$

$$(\mathbf{A} \cdot \nabla\mathbf{B})_\theta = A_r \frac{\partial B_\theta}{\partial r} + \frac{A_\theta}{r} \frac{\partial B_\theta}{\partial \theta} + \frac{A_\phi}{r \sin \theta} \frac{\partial B_\theta}{\partial \phi} + \frac{A_\theta B_r}{r} - \frac{\cot \theta A_\phi B_\phi}{r}$$

$$(\mathbf{A} \cdot \nabla\mathbf{B})_\phi = A_r \frac{\partial B_\phi}{\partial r} + \frac{A_\theta}{r} \frac{\partial B_\phi}{\partial \theta} + \frac{A_\phi}{r \sin \theta} \frac{\partial B_\phi}{\partial \phi} + \frac{A_\phi B_r}{r} + \frac{\cot \theta A_\phi B_\theta}{r}$$

Divergence of a tensor

$$\begin{aligned} (\nabla \cdot \mathbf{T})_r &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{rr}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta r}) \\ &\quad + \frac{1}{r \sin \theta} \frac{\partial T_{\phi r}}{\partial \phi} - \frac{T_{\theta\theta} + T_{\phi\phi}}{r} \end{aligned}$$

$$\begin{aligned} (\nabla \cdot \mathbf{T})_\theta &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{r\theta}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta\theta}) \\ &\quad + \frac{1}{r \sin \theta} \frac{\partial T_{\phi\theta}}{\partial \phi} + \frac{T_{\theta r}}{r} - \frac{\cot \theta T_{\phi\phi}}{r} \end{aligned}$$

$$\begin{aligned} (\nabla \cdot \mathbf{T})_\phi &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 T_{r\phi}) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta T_{\theta\phi}) \\ &\quad + \frac{1}{r \sin \theta} \frac{\partial T_{\phi\phi}}{\partial \phi} + \frac{T_{\phi r}}{r} + \frac{\cot \theta T_{\phi\theta}}{r} \end{aligned}$$