

Exercise sheet 11: Displacement current, magnetic energy

27/11/2024

We indicate the challenges of the problems by categories I ("warming-up"), II ("exam-level"), III ("advanced"). For your orientation: problems attributed to category II have been or could have been considered for an exam (assuming a specific duration for finding the solution; see comments in the solutions). The exact problem setting cannot be repeated in an exam however.

Exercise 1.

(Magnetic field from displacement current/Category I)

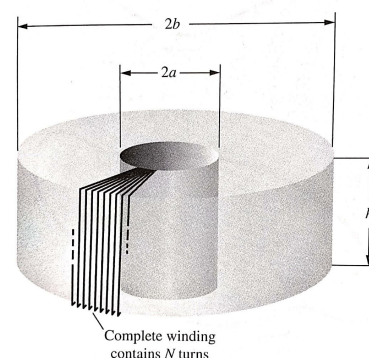
Suppose that a circular parallel-plate capacitor has a radius of $R_0 = 3.0$ cm and a plate separation of $d = 5.0$ mm. A sinusoidal potential difference $V = V_0 \sin(2\pi ft)$ is applied across the plates, where $V_0 = 150$ V and $f = 60$ Hz. Ignore fringing fields of E . Hint: This exercise is meant to show that fields from the term dE/dt in a capacitor are small at 60 Hz, i.e., when AC currents/electric fields vary slowly.

- In the region between the plates, show that the magnitude of the induced magnetic field is given by $B = B_0(R) \cos(2\pi ft)$, where R is the radial distance from the capacitor's central axis.
- Determine the expression for the amplitude $B_0(R)$ of this time-dependent (sinusoidal) field when $R \leq R_0$ and when $R > R_0$.
- Plot $B_0(R)$ in tesla for the range $0 \leq R \leq 10$ cm.
- Now assume that a wire connected to the capacitor carries exactly the amount of absolute charge current I as given by the maximum displacement current I_D flowing through the whole cross-section of the capacitor in its gap. The wire is assumed to be infinitely long and has a diameter of 2 mm. Calculate the magnetic field generated by I just at its surface in the limit of an infinitely long wire. Compare this value with the field B in the gap of the capacitor at $R = 1$ mm. How much weaker is this field generated by the displacement current in the capacitor compared to the field of the charge-based current?

Exercise 2.

[Self-inductance and magnetic energy in toroidal solenoid /Category II (After training for solution: 25 min)]

Consider a toroidal solenoid (coil) with the geometrical parameters presented in the figure. Complete winding contains N turns all around the core.



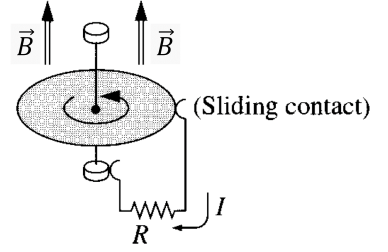
Toroidal coil of rectangular cross section. Only a few turns are shown.

- Calculate the self-inductance, L , of the system.
- Obtain the magnetic energy density, u , stored in the system.
- Calculate the total energy, U , stored in the system.
- Evaluate L for a toroidal solenoid with dimensions of $2a = 10$ mm, $2b = 15$ mm and $h = 5$ mm with $N = 100$ turns of wire. How much magnetic energy is stored in the system if one applies a current of $I = 3$ A to the solenoid. Suppose that we store the same amount of energy on a circular plate capacitor with plate diameter of $R = 2b = 15$ mm and distance between plates $d = h = 5$ mm filled with a dielectric with dielectric constant of 5. How much voltage, V , needs to be applied?

Exercise 3.

(Faraday's disk / Category II (After training time needed: 20-25 min))

Faraday's disc was the first electromagnetic generator. The working principle is as follows: A conductor disc (metal) of radius a rotates with a constant angular velocity ω about a vertical axis, through a uniform field \vec{B} , pointing up. A circuit is made by connecting one end of a resistor to the axle and the other end to a sliding contact, which touches the edge of the disk (see sketch).



- Find the expression for the current in the resistor. Hint: When the disk rotates the charges in the conductor inherit a velocity vector.
- Now let's consider to construct a bicycle dynamo using Faraday's disk. Instead of the resistor, we power a lightbulb with an electrical power consumption $P_{\text{el.}} = 4 \text{ W}$ and resistance $R = 1 \Omega$. Due to size restrictions, we choose a disk radius of $a = 2 \text{ cm}$. Using permanent magnets, we provide $B = 0.2 \text{ T}$. Calculate the frequency of rotation f (turns per second, $f = \omega/2\pi$) needed to supply 4 W to the bulb. Is the required frequency realistic for the application as a bicycle dynamo?

Exercise 4.

(Bicycle dynamo / Category II (After training time needed: 15-20 min))

Consider a commercial bicycle dynamo as sketched below. Instead of spinning a coil in a magnetic field (compare with Exercise 3), a permanent magnet is spinning with respect to a fixed coil (solenoid). The part labeled "Soft iron core" allows one to guide the magnetic field lines of the rotating magnet through the "fixed coil". As a consequence one can assume a magnetic field inside the coil which amounts to $B(t) = B_0 \sin(\omega t)$ with $B_0 = 0.2 \text{ T}$. The coil has $N = 1000$ turns and all the turns have a radius $a = 2 \text{ cm}$.

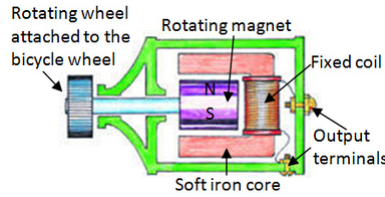


Figure 1: Bicycle Dynamo.

- Calculate the frequency of rotation f (turns per second, $f = \omega/2\pi$) needed to apply a time-averaged electric power $P_{\text{avg}} = 4 \text{ W}$ to the bulb with $R = 1 \Omega$. (Here we neglect any self-inductance of the coil. Time-averaged electric power means that one averages the time-dependent dissipated power $P(t)$ over one period T . The time-averaged power P_{avg} is found to be $emf_0^2/2R$ where emf_0 is the amplitude of the time-dependent electromotive force.)
- Plausibility check (optional): A cyclist drives with a velocity $v = 20 \text{ km/h}$. The bicycle wheel's radius is $r_W = 31 \text{ cm}$. The radius of the dynamo wheel is $r_D = 0.5 \text{ cm}$. Calculate the frequency f that is relevant for induction and compare to the value of a).

Solution 1.

- From Ampere's law including the displacement current, we find in the gap of a capacitor (see Fig. 2) $\oint_{\Gamma} \vec{B} \cdot d\vec{l} = \mu_0 \epsilon_0 \frac{d\Phi_E}{dt}$. The electric flux Φ_E is given by $E\pi R_{\text{path}}^2$ if the radius of the Amperian loop R_{path} is smaller than the capacitor radius R_0 , and $E\pi R_0^2$ if the radius of the Amperian loop is larger than R_0 . For $R_{\text{path}} < R_0$ we obtain:

$$B(2\pi R_{\text{path}}) = \mu_0 \epsilon_0 \pi R_{\text{path}}^2 \left(\frac{dE}{dt} \right) = \mu_0 \epsilon_0 \pi R_{\text{path}}^2 \left(\frac{1}{d} \frac{dV}{dt} \right)$$

$$\Rightarrow B = \mu_0 \epsilon_0 \pi R_{\text{path}}^2 \left(\frac{1}{d} \frac{2\pi f V_0}{2\pi R_{\text{path}}} \cos(2\pi f t) \right) = \mu_0 \epsilon_0 \pi R_{\text{path}}^2 \left(\frac{f V_0}{R_{\text{path}} d} \cos(2\pi f t) \right).$$

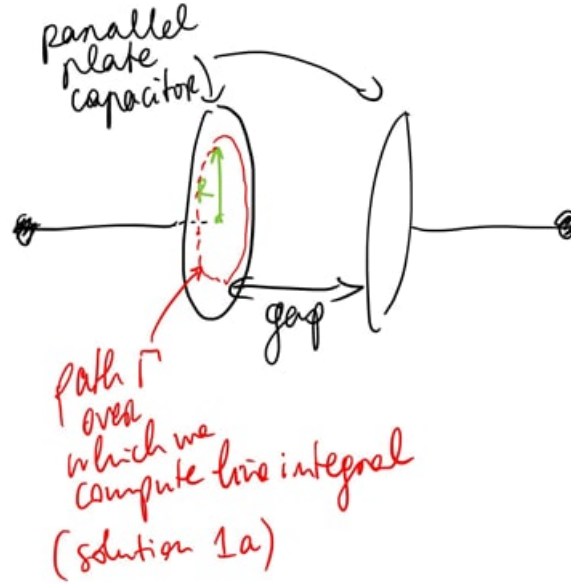


Figure 2: Sketch showing parallel plate capacitor and chosen line path for Ampere's law.

$\Rightarrow B_0(R) = \mu_0 \epsilon_0 \pi R_{path} \left(\frac{fV_0}{d} \right)$. Inside the capacitor, the field increases with the distance from the axis. For a distance R_{path} larger than R_0 from the central axis we have $B_0(R) = \mu_0 \epsilon_0 \pi R_0^2 \left(\frac{fV_0}{R_{path} d} \right)$

- b) For $R = R_{path} \leq R_0$ we have $B_0(R \leq R_0) = \mu_0 \epsilon_0 \pi R \left(\frac{fV_0}{d} \right)$ (See Fig. 3). Inserting the known numerical values one finds $B_0(R \leq R_0) = cR$ with $c = \mu_0 \epsilon_0 \pi \left(\frac{fV_0}{d} \right) \approx 6.29 \cdot 10^{-11} \text{ T/m}$.

For $R \geq R_0$ we have $B_0(R \geq R_0) = \mu_0 \epsilon_0 \pi R_0^2 \left(\frac{fV_0}{R d} \right) \rightarrow B_0(R \geq R_0) = c' \frac{1}{R}$ with $c' \approx 5.66 \cdot 10^{-14} \text{ Tm}$.

- c) See Fig. 4.

- d) We start from the definition of the displacement current density in vacuum $\vec{J}_D = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$. The flux of \vec{J}_D over the surface $\Sigma = \pi R^2$ is the displacement current and it is equal to:

$\int_{\Sigma} \vec{J}_D \cdot d\vec{a} = I_D = \epsilon_0 \int_{\Sigma} \frac{\partial \vec{E}}{\partial t} \cdot d\vec{a} = \frac{\partial}{\partial t} \epsilon_0 \int_{\Sigma} \vec{E} \cdot d\vec{a} = \frac{\partial}{\partial t} \epsilon_0 \Phi_E = \epsilon_0 \frac{\partial \Phi_E}{\partial t} = \epsilon_0 \frac{\pi R^2}{d} \frac{dV(t)}{dt} = \frac{2\pi^2 \epsilon_0 V_0 f R^2}{d} \cos(2\pi f t)$. To summarize:

$$I_D(R, t) = \frac{2\pi^2 \epsilon_0 V_0 f R^2}{d} \cos(2\pi f t)$$

The space-dependent component of I_D is maximum at $R = R_0$: $I_{D, max} = \frac{2\pi^2 \epsilon_0 V_0 f R_0^2}{d}$.

Now we assume that the same amount of current flows through an infinitely long wire with diameter β . The generated magnetic field \vec{B}_W is circumferential. Biot-Savart's law is used to compute the magnetic field generated by the current carrying wire at a distance $r = \beta/2$ with $\beta = 2 \text{ mm}$:

$$\vec{B}_W(\beta/2) = \hat{e}_{\phi} \frac{\mu_0 I_{D, max}}{2\pi(\beta/2)}$$

Therefore $B_W = \frac{2\pi \cdot (4\pi 10^{-7}) \cdot (8.85 \cdot 10^{-12}) 150 \cdot 60 \cdot 0.03^2}{0.005 \cdot 0.002} T = 5.66 \cdot 10^{-11} \text{ T} = 56.6 \text{ pT}$.

The magnetic field generated from the displacement current in the capacitor for the numerical values specified from the text amount to:

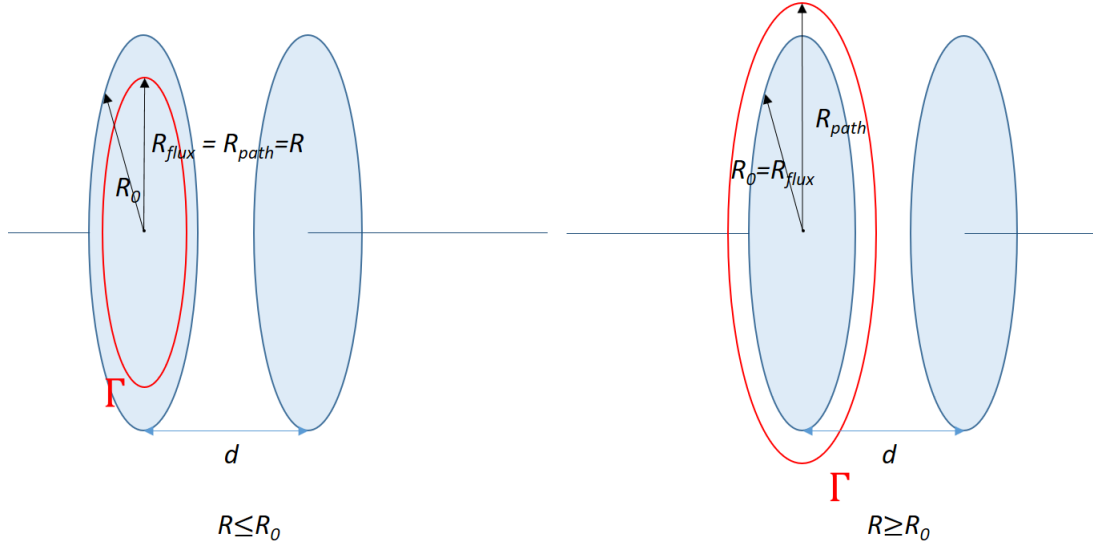


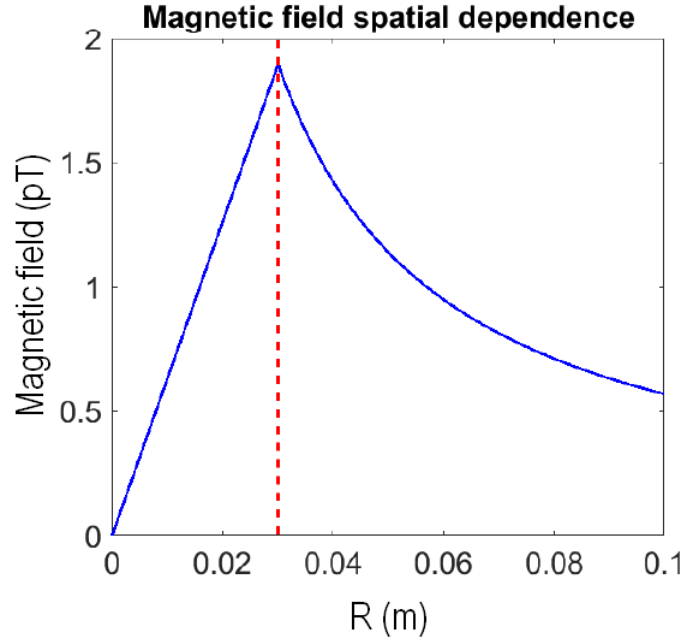
Figure 3: Sketch showing parallel plate capacitor and chosen line path for Ampere's law in the two cases: (a) $R \leq R_0$, and (b) $R \geq R_0$.

$$B_C(R = 1 \text{ mm}) = \frac{\pi \epsilon_0 \mu_0 V_0 f R}{d} = \frac{\pi \cdot (4\pi 10^{-7}) \cdot (8.85 \cdot 10^{-12}) 150 \cdot 60 \cdot 0.001}{0.005} T = 6.29 \cdot 10^{-14} \text{ T} = 0.0629 \text{ pT}$$

We conclude that B_C is smaller than B_W by a factor $B_C/B_W \approx 0.0011$. The magnetic field contributions due to $\frac{\partial E}{\partial t}$ are both absolutely and relatively very small. This justifies that such effects were neglected in the discussion of low frequency AC circuits in Chapter 6.

Solution 2.

- a) We evaluate Ampere's law in a central $x-y$ plane. The magnetic field inside the coil at $a < r < b$ in the central $x-y$ plane can be calculated as $\oint \vec{B} \cdot d\vec{l} = 2\pi r B = \mu_0 N I \rightarrow \vec{B} = \frac{\mu_0 N I}{2\pi r} \hat{e}_\phi$. This solution is valid in different planes along z . The flux passing through one turn of the coil is the integral of this field over a cross-section of the coil in the $y-z$ plane i.e. $\Phi_1 = \int \vec{B} \cdot \hat{n} da = \int_a^b (B \hat{e}_\phi) \cdot (h dr \hat{e}_\phi) = \int_a^b \frac{\mu_0 N I}{2\pi r} h dr = \frac{\mu_0 N I h}{2\pi} \ln\left(\frac{b}{a}\right)$. The total flux passing through the circuit of N turns is, $\Phi_{tot} = N \Phi_1 = \frac{\mu_0 N^2 I h}{2\pi} \ln\left(\frac{b}{a}\right) \equiv L I$. The self-inductance of this coil is $L = \frac{\mu_0 N^2 h}{2\pi} \ln\left(\frac{b}{a}\right)$.
- b) Since there is no magnetic core, the magnetic energy density is given by $u = \frac{1}{2} \frac{B^2}{\mu_0} = \frac{\mu_0 N^2 I^2}{8\pi^2 r^2}$.
- c) The total energy U is the integration of energy density u over the volume of the coil i.e. $U = \int_V dV u = \int_a^b 2\pi r h dr \left(\frac{\mu_0 N^2 I^2}{8\pi^2 r^2} \right) = \frac{\mu_0 N^2 I^2 h}{4\pi} \ln\left(\frac{b}{a}\right)$. To check the result we calculate U/L with L calculated in part (a) which reads $\frac{U}{L} = \frac{1}{2} I^2$. Hence, we find $U = \frac{1}{2} L I^2$ by rearranging the terms. This is the general formula for energy stored in an inductance. The result of (c) is consistent with (a).
- d) $L = \frac{4\pi \times 10^{-7} \times 10^4 \times 5 \times 10^{-3}}{2\pi} \ln\left(\frac{7.5}{5}\right) \text{ H} = 4.05 \mu\text{H}$. For energy stored in the coil we have $U = \frac{1}{2} L I^2 = 0.5 \times 4.1 \times 10^{-6} \times 9 \text{ J} \simeq 18.25 \mu\text{J}$. The capacitance is $C = \frac{\epsilon_r \epsilon_0 (\pi b^2)}{d} = 1.56 \text{ pF}$. Therefore, the required potential difference amounts to $V = \sqrt{\frac{2U}{C}} = 4830.5 \text{ V}$.

Figure 4: Magnetic field is continuous at the transition $R = R_0$ **Solution 3.**

We exploit the disk symmetry and apply cylindrical coordinate (r, z, φ) .

- a) The velocity of a generic point P within disk's radius is $\vec{v}_r = \omega r \hat{\varphi}$, with r being the distance from the disk's axis. Assuming a charged particle with charge q at point P the magnetic Force \vec{F}_M acting on the particle is:

$$\vec{F}_M(r) = q\vec{v}_r \times \vec{B} = q(\omega r \hat{\varphi}) \times (B\hat{z}) = q\omega Br \hat{r}$$

The force has radial direction.

For the following calculation it is important to realize that in equilibrium without a connected circuit one finds for the Lorentz force $\vec{F}_L = q\vec{E}(r) + q\vec{v}_r \times (B\hat{z}) = 0$. This equation indicates that $\vec{v}_r \times (B\hat{z})$ corresponds to an electric field.

From here we find the expression of $\vec{E}(r) = \frac{q\vec{v}_r \times (B\hat{z})}{q} = \frac{\vec{F}_M(r)}{q}$ for the electric field originating from the magnetic force \vec{F}_M . Hence $\vec{F}_M(r)$ divided by the charge q is *equivalent* to the local electric field $\vec{E}(r)$ acting on the charge. This electric field gives rise to the electromotive force ΔV between the center with $r = 0$ and the outer edge with $r = a$ of the disc. To compute ΔV we evaluate the electrostatic potential difference due to the assumed electric field $F_M(r)/q$ between the center of the disk and a point on the outer edge:

$$\Delta V = \int_0^a \frac{1}{q} \vec{F}_M \cdot d\vec{r} = \int_0^a \omega Br \hat{r} \cdot d\vec{r} = \int_0^a \omega Br \cdot dr = \frac{\omega Ba^2}{2}.$$

Using Ohm's law we find for the current I flowing in the circuit:

$$I = \frac{\Delta V}{R} = \frac{\omega Ba^2}{2R}.$$

- b) The dissipated power P_{diss} through the resistor R caused by the electromotive force ΔV is

$$P_{diss} = \frac{(\Delta V)^2}{R} \Rightarrow \Delta V = \sqrt{P_{diss}R} \Rightarrow \sqrt{P_{diss}R} = \frac{\omega Ba^2}{2} \Rightarrow \omega = \frac{2}{Ba^2} \sqrt{\Delta P_{diss}R}.$$

Inserting numerical values it is found that

$$\frac{1}{2\pi} \omega = \frac{1}{2\pi} 5 \cdot 10^4 \frac{\text{rad}}{\text{s}} = 7.96 \text{ kHz}.$$

The device can not be used as a bicycle dynamo.

Solution 4.

- a) We write down the formula for the magnetic flux induced in the coil $\Phi(t) = B(t)\pi a^2 N$

from which we obtain the emf $emf(t) = -\frac{d\Phi}{dt} = -B_0 \cos(\omega t) \omega \pi a^2 N$.

In the following we motivate the formula for the time-averaged power $P_{\text{avg}} = emf_0^2/2R$ given in the problem, where emf_0 is the amplitude of the time-dependent electromotive force. We start by stating the time-dependent power dissipated in the load resistor $P(t) = emf^2(t)/R$ using the known formula for power in a resistor. This value is now averaged over one period of rotation of the dynamo:

$$P_{\text{avg}} = \langle P \rangle = \frac{1}{R} \langle (\mathcal{E}_{emf})^2 \rangle = \frac{1}{R} (B_0 \omega \pi a^2 N)^2 \frac{1}{T} \int_0^T \cos^2(\omega t) dt$$

The brackets $\langle \rangle$ represent the mean value (averaged value) over a period T , that's why we consider the integral ranging from 0 to T of the time dependent term $(\cos(\omega t))^2$ and then divide the result of the integration by one period T .

The integration over time results in

$$\begin{aligned} \frac{1}{T} \int_0^T \cos^2(\omega t) dt &= \frac{1}{T} \int_0^T \left(\frac{1 + \cos(2\omega t)}{2} \right) dt \\ &= \frac{1}{2T} \int_0^T dt + \frac{1}{2T} \int_0^T \cos(2\omega t) dt \\ &= \frac{1}{2} + \frac{1}{2T} \left[\frac{\sin(2\omega t)}{2\omega} \right]_0^T \\ &= \frac{1}{2} + \frac{1}{2T} \left[\frac{\sin\left(2 \times \frac{2\pi}{T} \times T\right) - \sin(0)}{2 \times \frac{2\pi}{T}} \right] = \frac{1}{2}. \end{aligned}$$

One concludes that

$\langle P \rangle = \frac{1}{R} \langle (\mathcal{E}_{emf})^2 \rangle$ in general. This relation is now used to find the solution of the problem:

$$\langle P \rangle = \frac{1}{2} \frac{1}{R} (B_0 \omega \pi a^2 N)^2.$$

Therefore, the relation between the frequency of the rotation and the average power is obtained by inverting the previous equation and isolating and solving for ω :

$$\sqrt{2\langle P \rangle R} = B_0 N a^2 \pi \omega \Rightarrow \omega = \frac{\sqrt{2\langle P \rangle R}}{B_0 N a^2 \pi}.$$

Inserting numerical values one finds $\frac{1}{2\pi} \omega = \frac{1}{2\pi} \frac{\sqrt{2 \cdot 4.1}}{0.2 \cdot 1000 \cdot 0.02^2 \pi} \text{ Hz} = 1.79 \text{ Hz}$.

- b) One turn of the cycle wheel corresponds to $\frac{r_w}{r_D} = 62$ turns of the dynamo. At $v = 20 \text{ km/h} = 5.56 \text{ m/s}$ the wheel rotates with a frequency $f_w = \frac{\omega}{2\pi} = \frac{1}{2\pi} \frac{5.56 \text{ m/s}}{0.31 \text{ m}} = 2.85 \text{ Hz}$.

This means that the induction occurs at a frequency $f = 62 f_w = 176.7 \text{ Hz}$. This value is well larger than the value found in (a). Hence at a much smaller velocity of the bike than 20 km/h the lamp is already bright and helps one to find the way in the dark.