

### Couplings

A flexible coupling (bellows) makes it possible to

- ☐ Correct the alignment between the axes to be coupled
- ☐ To improve the guidance of the axes to be coupled
- ☐ To reduce the play between the two axes to be coupled
- ☐ To reduce the inertia of the transmission
- ☐ None of the other proposals

### Choice transmission

For the realization of a machine tool axis of 400mm, you recommend a transmission:

- ☐ with a rigid belt TCH-XX
- ☐ screw
- ☐ with rack
- ☐ None of the other proposals

### Choice of transmission

For the implementation of the axes of a machine of laser cutting of 2mX3m, it is preferable to use:

- ☐ A belt
- ☐ Screw transmission
- ☐ Rack-pinion transmission
- ☐ Connecting rod transmission
- ☐ Cable transmission

### Direct drive

A direct drive axis (direct actuation) is a motorized axis without reducer. Check the correct answer(s)

- ☐ A DD is more sensitive to external disturbances
- ☐ A solution with DD axes induces more mechanical noise and requires lubrication
- ☐ The absence of a reduction gear induces better mechanical reliability.
- ☐ The absence of a reducer makes the system more fragile.
- ☐ A DD solution has a better natural frequency

### Ball guideways

The balls of a recirculating ball guide

- ☐ reduce friction
- ☐ improve rigidity
- ☐ reduce manufacturing costs
- ☐ make the implementation more compact

### Guideways

For the implementation of a linear guide with a small stroke ( $<10$  mm) and without backlash, it is preferable to use:

- ☐ A guide with flexible blades
- ☐ A guide with ball bearings
- ☐ An Igus smooth guide
- ☐ A Hydrostatic guide
- ☐ None of the other proposals

### Backlash

Consider a planetary gearbox with 1 degree of mechanical backlash, controlling a 300 mm long arm-  
The backlash at the tip of the arm is approximately:

- ☐ 5 mm
- ☐ 1.67 mm
- ☐ 300 microns
- ☐ 10 mm

### Materials

To improve the eigen frequency of an arm, it is preferable to choose

- ☐ An aluminum alloy
- ☐ A steel alloy
- ☐ A Magnesium alloy
- ☐ A Titanium alloy
- ☐ The choice is not decisive

### Reducers

For the implementation of a rotary axis without backlash, it is recommended to use:

- ☐ a Harmonic Drive reducer, if the reduction ratio is low
- ☐ a Harmonic Drive reducer, if the reduction ratio is high
- ☐ a belt reducer, if the reduction ratio is low
- ☐ a belt reducer, if the reduction ratio is high

### Spring

A spring mechanism is recommended in a screw transmission to

- ☐ reduce the mechanical play in the transmission
- ☐ reduce the friction in the transmission
- ☐ increase the natural frequency of the mechanism
- ☐ make the system oscillatory

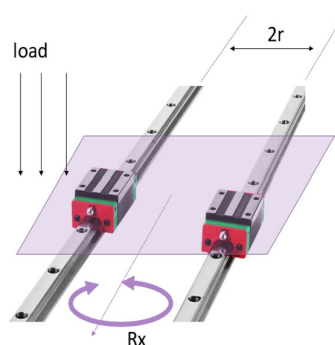
### Spring

The use of a preload spring induces the following behavior(s)

- ☐ It increases the friction in the mechanism
- ☐ It reduces the friction in the mechanism
- ☐ It reduces the mechanical backlash in the mechanism
- ☐ It makes the mechanism simpler

### Rigidity - guideways

Given the construction of a guide with double linear rails, distant by  $(2r)$

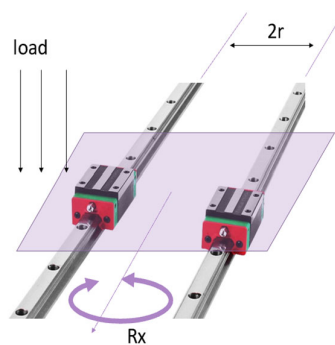


The torsional stiffness (in the Rx direction) is then:

- ☐ Proportional to  $r^2$
- ☐ Proportional to  $r$
- ☐ inversely proportional to  $r^2$
- ☐ inversely proportional to  $r$

### Rigidity - guideways

Given the construction of a guide with double linear rails, distant by  $(2r)$



This construction has the following characteristics:

- ☐ Allows better torsional rigidity in the Rx axis
- ☐ Allows better rigidity in the vertical direction
- ☐ Allows better torsional rigidity in the axis Rx but weakens the stiffness in the direction of the load.
- ☐ Allows better rigidity in the direction of the load but weakens the torsional rigidity in the Rx axis
- ☐ Is hyperguided

### Cable transmission

A cable transmission is recommended in the implementation of haptic devices because of

- ☐ its very good mechanical performance
- ☐ its very good reversibility
- ☐ its very low friction
- ☐ its very compact implementation
- ☐ The stiffness of the cable

### Belt transmission

A belt transmission is recommended in the case of:

- ☐ rapid
- ☐ movements precise
- ☐ movements movements requiring great forces

### rack-and-pinion

A rack-pinion transmission is recommended for:

- ☐ rapid movements
- ☐ precise movements
- ☐ movements requiring great forces

### screw

A Screw transmission is recommended for:

- ☐ rapid movements
- ☐ precise movements
- ☐ movements requiring great forces

### Ball screws

Ball screw transmissions allow to:

- ☐ Reduce the manufacturing cost
- ☐ Improve the compactness of the screw
- ☐ Reduce the s friction
- ☐ Improves mechanical reversibility
- ☐ None of the other proposals.

### Biocompatible materials

Stainless steel is biocompatible

- ☐ True
- ☐ False

### Quality factor

Quality factor introduced by Dr. Marc Olivier Demaurex makes it possible to compare the performance of robots regardless of their size.

- ☐ True
- ☐ False

### Ball guideways

The balls of a recirculating ball guide reduce friction.

- ☐ True
- ☐ False

### Materials

For the construction of a rigid arm, a steel alloy is preferable to an aluminum alloy

- ☐ True
- ☐ False

### Precision

The higher the natural frequency, the better the positioning precision of a robot arm .

- ☐ True
- ☐ False

### Precision

For reducing the positioning error of a robot arm, a bang-bang acceleration profile is better than a sinusoidal acceleration profile

- ☐ True
- ☐ False

### Reducers

A planetary gearhead can achieve higher reduction ratios than a Harmonic Drive

- ☐ True
- ☐ False

### Reducers

A Harmonic Drive reducer is more rigid than a planetary reducer

- ☐ True
- ☐ False

### Springs

A spring is recommended to dampen oscillatory behavior,

- ☐ True
- ☐ False

### Trajectories

The profile acceleration has no effect on the position accuracy of a robot arm.

- ☐ True
- ☐ False

### Cable transmissions

A cable transmission is recommended in the implementation of haptic devices

- ☐ True
- ☐ False

### Cable transmissions

Cable and belt transmissions have comparable efficiencies

- ☐ True
- ☐ False

### Ball screws

Ball screw transmissions are chosen because of their lower manufacturing cost

- ☐ True
- ☐ False