

Couplings

A flexible coupling (bellows) makes it possible to

- Correct the alignment between the axes to be coupled
- To improve the guidance of the axes to be coupled
- To reduce the play between the two axes to be coupled
- To reduce the inertia of the transmission
- None of the other proposals

Choice transmission

For the realization of a machine tool axis of 400mm, you recommend a transmission:

- with a rigid belt TCH-XX
- screw
- with rack
- None of the other proposals

Choice of transmission

For the implementation of the axes of a machine of laser cutting of 2mX3m, it is preferable to use:

- A belt
- Screw transmission
- Rack-pinion transmission
- Connecting rod transmission
- Cable transmission

Direct drive

A direct drive axis (direct actuation) is a motorized axis without reducer. Check the correct answer(s)

- A DD is more sensitive to external disturbances
- A solution with DD axes induces more mechanical noise and requires lubrication
- The absence of a reduction gear induces better mechanical reliability.
- The absence of a reducer makes the system more fragile.
- A DD solution has a better natural frequency

Ball guideways

The balls of a recirculating ball guide

- reduce friction
- improve rigidity
- reduce manufacturing costs
- make the implementation more compact

Guideways

For the implementation of a linear guide with a small stroke (<10 mm) and without backlash, it is preferable to use:

- A guide with flexible blades
- A guide with ball bearings
- An Igus smooth guide
- A Hydrostatic guide
- None of the other proposals

Backlash

Consider a planetary gearbox with 1 degree of mechanical backlash, controlling a 300 mm long arm- The backlash at the tip of the arm is approximately:

- 5 mm
- 1.67 mm
- 300 microns
- 10 mm

Materials

To improve the eigen frequency of an arm, it is preferable to choose

- An aluminum alloy
- A steel alloy
- A Magnesium alloy
- A Titanium alloy
- The choice is not decisive

Reducers

For the implementation of a rotary axis without backlash, it is recommended to use:

- a Harmonic Drive reducer, if the reduction ratio is low
- a Harmonic Drive reducer, if the reduction ratio is high
- a belt reducer, if the reduction ratio is low
- a belt reducer, if the reduction ratio is high

Spring

A spring mechanism is recommended in a screw transmission to

- reduce the mechanical play in the transmission
- reduce the friction in the transmission
- increase the natural frequency of the mechanism
- make the system oscillatory

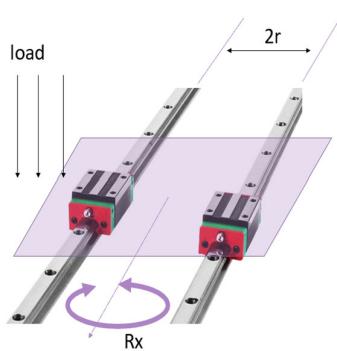
Spring

The use of a preload spring induces the following behavior(s)

- It increases the friction in the mechanism
- It reduces the friction in the mechanism
- It reduces the mechanical backlash in the mechanism
- It makes the mechanism simpler

Rigidity - guideways

Given the construction of a guide with double linear rails, distant by $(2r)$

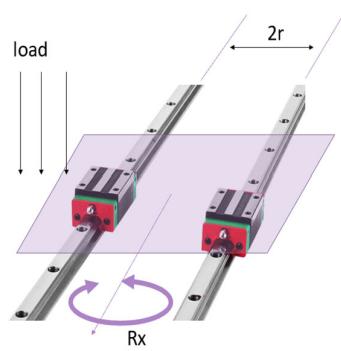


The torsional stiffness (in the Rx direction) is then:

- Proportional to r^2
- Proportional to r
- inversely proportional to r^2
- inversely proportional to r

Rigidity - guideways

Given the construction of a guide with double linear rails, distant by $(2r)$



This construction has the following characteristics:

- Allows better torsional rigidity in the Rx axis
- Allows better rigidity in the vertical direction
- Allows better torsional rigidity in the axis Rx but weakens the stiffness in the direction of the load.
- Allows better rigidity in the direction of the load but weakens the torsional rigidity in the Rx axis
- Is hyperguided

Cable transmission

A cable transmission is recommended in the implementation of haptic devices because of

- its very good mechanical performance
- its very good reversibility
- its very low friction
- its very compact implementation
- The stiffness of the cable

Belt transmission

A belt transmission is recommended in the case of:

- rapid
- movements precise
- movements movements requiring great forces

rack-and-pinion

A rack-pinion transmissionAis recommended for:

- rapid movements
- precise movements
- movements requiring great forces

screw

A Screw transmission is recommended for:

- rapid movements
- precise movements
- movements requiring great forces

Ball screws

Ball screw transmissions allow to:

- Reduce the manufacturing cost
- Improve the compactness of the screw
- Reduce the s friction
- Improves mechanical reversibility
- None of the other proposals.

Biocompatible materials

Stainless steel is biocompatible

- True
- False

Quality factor

Quality factor introduced by Dr. Marc Olivier Demaurex makes it possible to compare the performance of robots regardless of their size.

- True
- False

Ball guideways

The balls of a recirculating ball guide reduce friction.

- True
- False

Materials

For the construction of a rigid arm, a steel alloy is preferable to an aluminum alloy

- True
- False

Precision

The higher the natural frequency, the better the positioning precision of a robot arm .

- True
- False

Precision

For reducing the positioning error of a robot arm, a bang-bang acceleration profile is better than a sinusoidal acceleration profile

- True
- False

Reducers

A planetary gearhead can achieve higher reduction ratios than a Harmonic Drive

- True
- False

Exam- questions- English

Reducers

A Harmonic Drive reducer is more rigid than a planetary reducer

- True
- False

Springs

A spring is recommended to dampen oscillatory behavior,

- True
- False

Trajectories

The profile acceleration has no effect on the position accuracy of a robot arm.

- True
- False

Cable transmissions

A cable transmission is recommended in the implementation of haptic devices

- True
- False

Cable transmissions

Cable and belt transmissions have comparable efficiencies

- True
- False

Ball screws

Ball screw transmissions are chosen because of their lower manufacturing cost

- True
- False