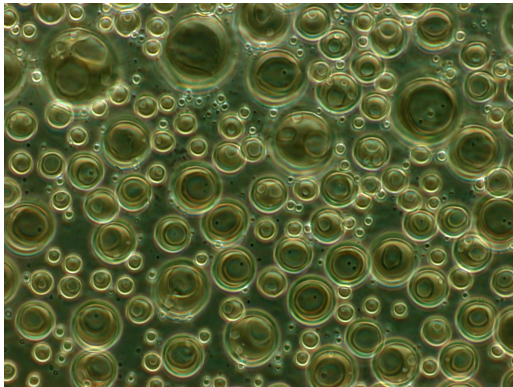
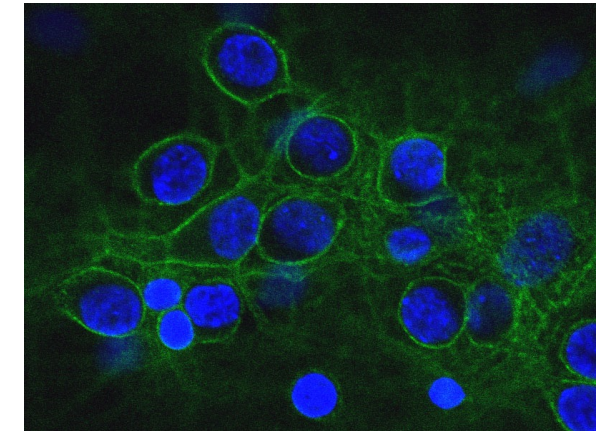
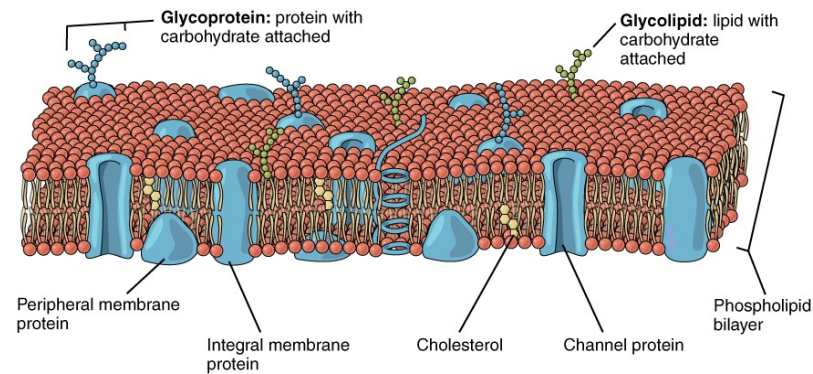
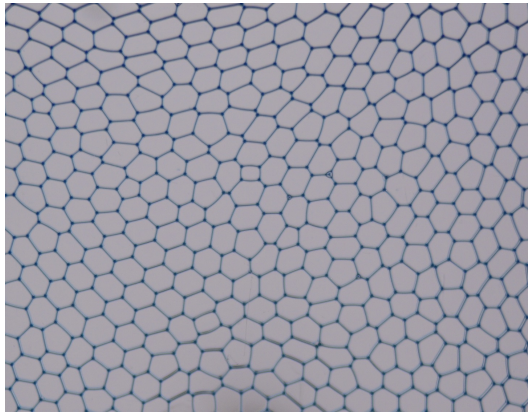


# ME470: Mechanics of Soft and Biological Matter

## Lecture5-1: Worm-like Chain, Bulk Entropic Materials

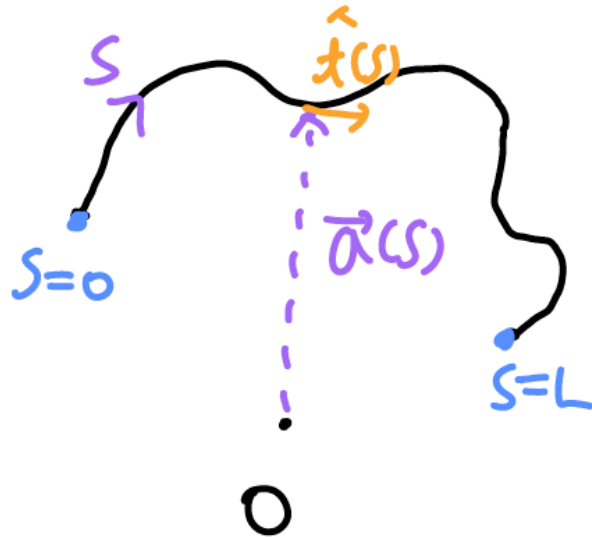


Sangwoo Kim

MESOBIO – IGM – STI – EPFL

Red Blood Cells

Replace n links by a continuous, elastic curve in 3D



Enforce a fixed contour length

$$\left(\frac{\partial \vec{a}}{\partial s}\right)^2 = 1 \quad \forall s \quad \Rightarrow \quad \int_0^L \sqrt{\left(\frac{\partial \vec{a}}{\partial s}\right)^2} ds = L$$

Unit tangent vector from differential geometry

$$\hat{t}(s) = \frac{\partial \vec{a}}{\partial s}$$

$$U_b = \frac{EI}{2} \int_0^L \kappa^2 ds = \frac{1}{2} k_B T l_p \int_0^L \left(\frac{\partial^2 \vec{a}}{\partial s^2}\right)^2 ds$$

$$(\text{curvature}, \kappa(s) = \frac{\partial^2 \vec{a}(s)}{\partial s^2} )$$

⇒ Canonical ensemble with

$$U = U_b - F_z R_z(\vec{a})$$

$$(\text{Note: } R_z(\vec{a}) = \int_0^L \frac{\partial \vec{a}(s)}{\partial s} \cdot \hat{e}_z ds)$$



$$U = \int_0^L \left[ \frac{k_B T l_p}{2} \left( \frac{\partial^2 \vec{a}}{\partial s^2} \right)^2 - F_z \left( \frac{\partial \vec{a}(s)}{\partial s} \cdot \hat{e}_z \right) \right] ds$$

$$\text{Probability: } P(\vec{a}) = \frac{1}{Z} \exp \left( -\frac{U(\vec{a})}{k_B T} \right)$$

$$\text{Partition function: } Z = \int_{All} \exp \left( -\frac{U(\vec{a})}{k_B T} \right)$$

Z: not analytically computable, but approximation by combining asymptotes exist



$$F_z = \frac{k_B T}{l_p} \left[ \frac{1}{4} \left( 1 - \frac{\langle R_z \rangle}{L} \right)^{-2} - \frac{1}{4} + \frac{\langle R_z \rangle}{L} \right]$$

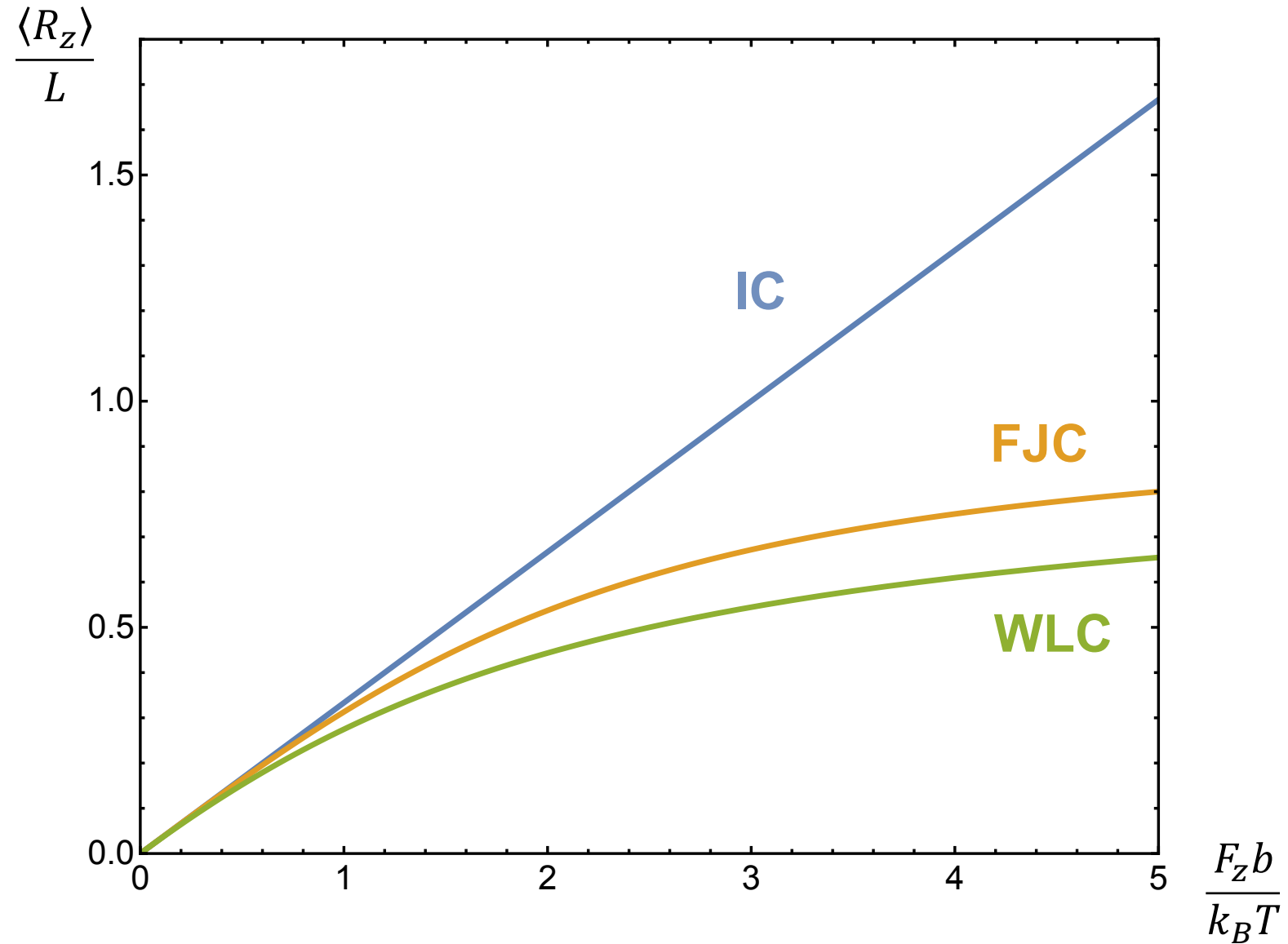
Check:  $\frac{\langle R_z \rangle}{L} \ll 1 \quad \Rightarrow \quad F_z = \frac{k_B T}{l_p} \left[ \frac{1}{4} \left( 1 + 2 \frac{\langle R_z \rangle}{L} \right) - \frac{1}{4} + \frac{\langle R_z \rangle}{L} \right] = \frac{3k_B T}{2l_p L} \langle R_z \rangle$

Need to show that  $b = 2l_p$ , to apply chain models with freely rotating Kuhn links

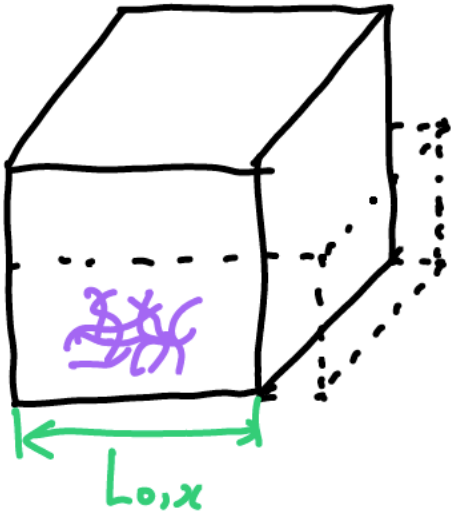
Q: Show  $b = 2l_p$  (Exercise)

$$\begin{aligned} \langle R^2 \rangle &= \int_0^L \frac{\partial \vec{a}(s)}{\partial s} ds \int_0^L \frac{\partial \vec{a}(u)}{\partial u} du \\ &= \int_0^L \int_0^L \exp \left[ -\frac{|u-s|}{l_p} \right] ds du = 2l_p^2 \left[ \frac{L}{l_p} - 1 + e^{-L/l_p} \right] \end{aligned}$$

$$L \ll l_p \quad \Rightarrow \quad \langle R^2 \rangle \approx 2l_p L = nb^2 = bL \quad \Rightarrow \quad b = 2l_p$$



e.g) rubber, made of entangled entropic springs (disordered)



Assumption: affine deformation  
(microscopic deformation=macroscopic deformation)

⇒ Individual chain extent in  $x, y, z$  changes proportionally to that of the bulk

Under stretch:  $\lambda_x, \lambda_y, \lambda_z$

End to end distance:  $\vec{R}(X, Y, Z)$  ⇒  $\vec{r}(x, y, z)$

with  $\langle x^2 \rangle = \lambda_x^2 \langle X^2 \rangle$

$$\langle y^2 \rangle = \lambda_y^2 \langle Y^2 \rangle$$

$$\langle z^2 \rangle = \lambda_z^2 \langle Z^2 \rangle$$

Recall entropy of IC:

$$S(\vec{R}) = -\frac{3k_B T}{2nb^2} R^2 + S_0$$

$$\Rightarrow \langle \Delta \Psi \rangle = \left\langle -T \left( S(\vec{r}) - S(\vec{R}) \right) \right\rangle = \frac{3k_B T}{2nb^2} (\lambda_x^2 \langle X^2 \rangle + \lambda_y^2 \langle Y^2 \rangle + \lambda_z^2 \langle Z^2 \rangle - nb^2)$$

$$(\text{here, } \langle X^2 \rangle = \langle Y^2 \rangle = \langle Z^2 \rangle = \frac{nb^2}{3})$$

$$\Rightarrow \langle \Delta \Psi \rangle = \frac{k_B T}{2} (\lambda_x^2 + \lambda_y^2 + \lambda_z^2 - 3) \quad \text{For a single chain}$$

$$\text{For } N \text{ chains:} \quad \Delta \Psi_{bulk} = N \langle \Delta \Psi \rangle$$

Rubber: ideally elastic, volume conserved  $\lambda_x \lambda_y \lambda_z = 1$

e.g) uniaxial stretch,  $\lambda_x = \lambda$ ,  $\lambda_y = \lambda_z = 1/\sqrt{\lambda}$



$$\langle \Delta \Psi \rangle = \frac{k_B T}{2} \left( \lambda^2 + \frac{2}{\lambda^2} - 3 \right)$$

$$F_x = \frac{\partial \Delta \Psi_{bulk}}{\partial L_x} = \frac{1}{L_{0,x}} \frac{\partial \Delta \Psi_{bulk}}{\partial \lambda} = \frac{N k_B T}{L_{0,x}} \left( \lambda - \frac{2}{\lambda^2} \right)$$

Given a cross-section perpendicular to x is A,

$$\sigma_{xx} = \frac{F_x}{A} = \frac{N}{A L_{0,x}} k_B T \left( \lambda - \frac{2}{\lambda^2} \right) = \rho_c k_B T \left( \lambda - \frac{2}{\lambda^2} \right)$$

Chain volume density



A hyperelastic constitutive relation can be derived for small strain

$$\lambda = 1 + \varepsilon \quad \Rightarrow \quad \left( \lambda - \frac{2}{\lambda^2} \right) \approx 3\varepsilon$$



$$E = 3\rho_c k_B T$$

Notes:

- The stiffness scales linearly with the chain density
- The stiffness increase for higher temperature (different from most engineering materials)