

Week 5

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By this week

- Slide 1: clear statement of the scenario i) need ii) novelty of your design in comparison to the state of the art iii) impact of the produce

By this week

- Slide 2: Define at least three R categories and create engineering specifications with numbers (with a specific range that fits your application) – create a table.

| R category | Engineering specification | values | Solution A | Solution B | Solution C |
|---|---------------------------|--|------------|------------|------------|
| Reuse for 3 applications require large range of motion ie Watering & cat feed | Range of motion | end effector hinge range Vertical displacement Personalization etc | | | |
| Reduce – more payload to reduce the size of the links | Overall payload | Vertical / dynamic /continuous load etc | | | |
| Refuse – bandwidth is higher to be effective in ... | Bandwidth | motor bandwidth Control bandwidth Feedback speed etc | | | |

By this week

Slide 3: three solution directions (some sketches with the chosen actuator and sensor)

- → show how they are all satisfying the motivation and functionality of the proposed product

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|---|---------------------------|--|------------|------------|------------|
| Reuse for 3 applications require large range of motion ie Watering & cat feed | Range of motion | end effector hinge range Vertical displacement Personalization etc | | | |
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By next week

- Slide 1: Clean scenario – clear need for the **function**
 - Schematics for the working principles
 - Hardware Design
 - Control strategy
- Slide 2: what will the proposed **sustainable functionality** be measured?
 - How is it improving the world without the product? – before and after (quantify)
 - What is the prediction of the measurement? (compare)

By this week

- **Slide 3: “Improvement column”** of the motor + sensor solution based on the design:
 - pick a parameter in the engineering specification
 - Iterate design parameters (size of the pouch / spring constant / link dimensions) to improve the functionality/ engineering specification

| Engineering specification | values | Solution A | Solution B | Solution C |
|---------------------------|---------------------------------|-----------------|----------------|---------------|
| Range of motion | $90 < \text{hinge range} < 300$ | $200 < r < 300$ | $90 < r < 100$ | $40 < r < 41$ |
| Overall payload | $10\text{N} < \text{load}$ | 20N | 13N | 50N |
| Bandwidth rpm | $100 < \text{rpm}$ | 200 | 101 | 100 |

By next week

- **Slide 3: “Improvement column”** of the motor + sensor solution based on the design :
 - pick a parameter in the engineering specification
 - Iterate design parameters (size of the pouch / spring constant / link dimensions) to improve the functionality/ engineering specification

| Engineering specification | values | Solution A | Solution A - improved |
|---------------------------|---------------------------------|-----------------|-----------------------|
| Range of motion | $90 < \text{hinge range} < 300$ | $200 < r < 300$ | $200 < r < 400$ |
| Overall payload | $10\text{N} < \text{load}$ | 20N | 30N |
| Bandwidth rpm | $100 < \text{rpm}$ | 200 | 200 |