

31 Discontinuous Galerkin methods 4

Now let us discuss implementation aspects of DG schemes

The theoretical idea is similar to finite element methods

We use a map from a reference cell into the physical cell

$$X_j: \underbrace{[-1, 1]}_{\substack{\text{reference cell} \\ \text{in 1D}}} \longrightarrow \underbrace{[x_{j-\frac{1}{2}}, x_{j+\frac{1}{2}}]}_{\text{j-th cell}}$$

$$r \longmapsto x_{j-\frac{1}{2}} + \frac{1+r}{2} h_j$$

where $h_j = x_{j+\frac{1}{2}} - x_{j-\frac{1}{2}}$. With that we have on the j-th cell

$$\underbrace{\phi_j^i(x(r))}_{\substack{\text{i-th basis function} \\ \text{on the j-th cell}}} = \underbrace{\phi^i(r)}_{\substack{\text{i-th basis function} \\ \text{on the reference cell}}}$$

$$\left[\phi_j^i(x) = \phi^i(X_j^{-1}(x)) \right]$$

and

$$\begin{aligned} U_h^j(x, t) &:= U_h^j(x(r), t) \\ &= \sum_{i=0}^m U_j^i(t) \phi_j^i(x(r)) \\ &= \sum_{i=0}^m U_j^i(t) \phi^i(r) \end{aligned}$$

One can show that

$$\underbrace{M^j}_{\substack{\text{j-th physical} \\ \text{mass matrix}}} = \frac{h_j}{2} \underbrace{M}_{\substack{\text{ref mass matrix}}}, \quad \underbrace{S^j}_{\substack{\text{j-th physical stiffness matrix}}} = \underbrace{S}_{\substack{\text{ref stiffness matrix}}}$$

Thus we can transform the computations to the ref. cell.

Consider the approximation

$$U_h(r) := \sum_{i=0}^m \hat{U}^i \phi^i(r)$$

↑
module coefficients

This is the module representation. What is a good choice of the basis on the reference cell?

(A) $\phi^i(r) := r^i$ (monomials)

The L^2 projection U_h of U onto the approximation space is calculated via a LSE with the local mass matrix.

$$\int_{-1}^1 U_h(r) \phi^l(r) dr \equiv \sum_{i=0}^m \hat{U}^i \int_{-1}^1 \phi^i(r) \phi^l(r) dr = \int_{-1}^1 U(r) \phi^l(r) dr$$

Solving a system with the mass matrix is "difficult" if we choose the monomial basis. Then the mass matrix has entries resembling a Hilbert matrix:

$$M_{kl} = \frac{1 + (-1)^{k+l}}{k+l+1}$$

But such matrices are ill-conditioned for larger m .

(B) Alternatively we can choose an orthonormal basis, constructed via Gram-Schmidt. Then the mass matrix is the identity matrix.

Applying Gram-Schmidt to the monomials produces the Legendre polynomials:

$$\phi^0(r) = \frac{1}{\sqrt{2}}, \quad \phi^1(r) = \sqrt{\frac{3}{2}} r,$$

$$r \phi^i = \alpha_i \phi^{i-1} + \alpha_{i+1} \phi^{i+1} \quad (\text{recurrence relation})$$

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We still want to calculate the integrals

$$\int_{-1}^1 U(r) \phi^l(r) dr$$

We can use Gauss-Legendre quadrature:

$$\int_{-1}^1 U(r) \phi^l(r) dr := \sum_{k=0}^m U(r_k) \phi^l(r_k) \omega_k$$

quadrature nodes quadrature weights

Exact for polynomials up to degree $2m+1$.

Alternatively, we use classical interpolation to construct U_h .

Find U_h s.t. $U(r_\ell) = U_h(r_\ell)$

at distinct nodal points $r_0, r_1, \dots, r_m \in [-1, 1]$

$$U(r_\ell) = \sum_{i=0}^m \hat{U}^i \phi^i(r_\ell) \quad \ell = 0, \dots, m$$

Another linear system of equations. The corresponding matrix is the Vandermonde matrix

$$V_{\ell k} = \phi^k(r_\ell)$$

The nodal representation is the representation

$$U_h(r) = \sum_{i=0}^m U(r_i) l^i(r)$$

$$U_h(r) = \sum_{i=0}^m U(r_i) l^i(r)$$

↑
nodal coefficients
↑
Lagrange polynomial

The transformation between nodal and modal coefficients is just a linear transformation.

The two representations are generally not the same.

$$U_h(r) := \sum_{i=0}^m \hat{U}^i \phi^i(r)$$

↑
 via L^2 projection
 requires integrals of U

$$U_h(r) := \sum_{i=0}^m \tilde{U}^i \phi^i(r)$$

↑
 via interpolation
 requires point values of U

Major application of the L^2 projection and nodal interpolation:

Polynomial approximation of non-polynomial terms

for the computation of the matrices in the discrete formulation
(or RHS)