

## Series 1

### The Kepler problem: discretization and conservation of first integrals

The motion of two bodies which attract each other by gravity is described by the Kepler problem

$$\ddot{q}_1 = -\frac{q_1}{(q_1^2 + q_2^2)^{3/2}}, \quad \ddot{q}_2 = -\frac{q_2}{(q_1^2 + q_2^2)^{3/2}}, \quad (1)$$

where  $(q_1(t), q_2(t))$  denotes the position at time  $t$  of the second body relatively to the first body.

This system is equivalent to a Hamiltonian system

$$\dot{q} = \frac{\partial H}{\partial p}(p, q), \quad \dot{p} = -\frac{\partial H}{\partial q}(p, q), \quad (2)$$

where  $p = \dot{q}$  is the velocity and the energy

$$H(p, q) = \frac{1}{2}(p_1^2 + p_2^2) - \frac{1}{\sqrt{q_1^2 + q_2^2}},$$

is a conserved quantity along time, i.e.,  $H(p(t), q(t)) = \text{const.}$

We choose the initial conditions

$$q_1(0) = 1 - e, \quad q_2(0) = 0, \quad \dot{q}_1(0) = 0, \quad \dot{q}_2(0) = \sqrt{\frac{1+e}{1-e}},$$

where  $0 \leq e < 1$  is a fixed parameter, for instance  $e = 0.6$ . Then the trajectory is elliptic with eccentricity  $e$  and the motion is periodic with period  $2\pi$ .

**Exercise 1. Numerical discretization**

Implement the following numerical methods for the Kepler problem:

1. Euler explicit method:

$$q_{n+1} = q_n + h \frac{\partial H}{\partial p}(p_n, q_n), \quad p_{n+1} = p_n - h \frac{\partial H}{\partial q}(p_n, q_n),$$

2. Euler symplectic method:

$$q_{n+1} = q_n + h \frac{\partial H}{\partial p}(p_n, q_{n+1}), \quad p_{n+1} = p_n - h \frac{\partial H}{\partial q}(p_n, q_{n+1}),$$

3. Euler implicit method:

$$q_{n+1} = q_n + h \frac{\partial H}{\partial p}(p_{n+1}, q_{n+1}), \quad p_{n+1} = p_n - h \frac{\partial H}{\partial q}(p_{n+1}, q_{n+1}),$$

4. Implicit midpoint rule:

$$\begin{aligned} q_{n+1} &= q_n + h \frac{\partial H}{\partial p} \left( \frac{1}{2}(p_n + p_{n+1}), \frac{1}{2}(q_n + q_{n+1}) \right), \\ p_{n+1} &= p_n - h \frac{\partial H}{\partial q} \left( \frac{1}{2}(p_n + p_{n+1}), \frac{1}{2}(q_n + q_{n+1}) \right). \end{aligned}$$

In each case, integrate over 20 periods with step size  $h = 2 \cdot 10^{-4}$  and plot the obtained trajectory  $\{q_n; n = 0, 1, 2, \dots\}$ .

*Hint:* in order to implement implicit methods you can employ fixed-point iterations or Newton method with tolerance  $\text{tol} = 10^{-4}$  or use the functions `fsolve` in MATLAB or `scipy.optimize.fsolve` in PYTHON.

**Exercise 2. Conservation of energy**

In each case, check whether the energy  $H(p_n, q_n)$  is conserved, by plotting  $H(p_n, q_n)$  as a function of time  $t = nh$ .

By trying different step sizes  $h$ , find numerically for each method what is the corresponding behavior where  $t = nh$ :

$$H(p_n, q_n) - H(p_0, q_0) = \mathcal{O}(ht), \quad \mathcal{O}(h^2t), \quad \mathcal{O}(h), \quad \mathcal{O}(h^2).$$

**Exercise 3. Angular momentum conservation**

The exact solution of the Kepler problem also conserves the angular momentum defined by

$$L(p, q) = q_1 p_2 - q_2 p_1.$$

Verify that  $L$  is a first integral of the system. Similarly to Exercise 2, check whether  $L$  is conserved by the considered numerical discretizations.

#### Exercise 4. Global error

We wish to study the behavior of the global error, i.e.,

$$\|q_n - q(nh)\| \text{ and } \|p_n - p(nh)\| \text{ for } n = 1, 2, 3, \dots$$

The motion is periodic with period  $2\pi$ . Then for a stepsize of the form  $h = 2\pi/r$ , where  $r$  is a positive integer, we have  $q_{kr} \approx q(k2\pi) = q_0$  and  $p_{kr} \approx p(k2\pi) = p_0$  for  $k = 1, 2, 3, \dots$ . Find numerically the behavior of  $\|q_{kr} - q_0\|$  and  $\|p_{kr} - p_0\|$ ,  $k = 1, 2, 3, \dots$  for each method, among:

$$\mathcal{O}(ht^2), \quad \mathcal{O}(h^2t^2), \quad \mathcal{O}(ht) \quad \text{or} \quad \mathcal{O}(th^2),$$

where  $t = k2\pi$  is the time.

*Hint:* to study the convergence w.r.t.  $h$  set  $t = 2\pi$  and  $h = 10^{-5}\pi \cdot 2^m$  for  $m = 0, \dots, 15$  and to study the convergence w.r.t.  $t$  set  $h = 10^{-4}\pi$  and  $t = 2\pi \cdot 2^m$  with  $m = 1, \dots, 8$ .

Collect your results of Exercise 2, 3, 4 in the table below.

method	error in $H$	error in $L$	global error
explicit Euler			
symplectic Euler			
implicit Euler			
midpoint rule			

#### Exercise 5. Linear energy drift

Consider a Hamiltonian system

$$\dot{p} = -\frac{\partial H}{\partial q}(p, q), \quad \dot{q} = \frac{\partial H}{\partial p}(p, q),$$

where  $H$  is Lipschitz. Rewrite the system in the form  $\dot{y} = J^{-1}\nabla H(y)$  where  $y = (p, q)^T$  (find the matrix  $J$ ).

Show that for a numerical method of order  $p$  integrated over  $n = 1, \dots, N$  steps of length  $h$ , one has for  $t = nh$ ,

$$H(y_n) - H(y_0) = \mathcal{O}(th^p).$$