

# Numerical Approximation of PDEs

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**Exercise 1.** [The MINI Element for the steady Stokes problem]

- Consider the Stokes problem:

$$\begin{cases} -\Delta \underline{u} + \nabla p = \underline{f} & \text{in } \Omega, \\ \nabla \cdot \underline{u} = 0 & \text{in } \Omega, \\ \underline{u} = 0 & \text{on } \partial\Omega. \end{cases}$$

Write the variational formulation.

- If you replace the Hilbert spaces with finite dimensional spaces  $V_h$  for  $\underline{u}$  and  $Q_h$  for  $p$ ; then the discrete problem takes the form of the following linear system:

$$\begin{pmatrix} A & B^T \\ B & 0 \end{pmatrix} \begin{pmatrix} U \\ P \end{pmatrix} = \begin{pmatrix} F \\ 0 \end{pmatrix},$$

To what corresponds the matrices  $A$  and  $B$ ?

- Let  $\mathcal{T}_h$  be a conforming triangulation of  $\Omega \subset \mathbb{R}^2$ . For each triangle  $T \in \mathcal{T}_h$ , define the bubble function:

$$b_T(x) = \lambda_1(x)\lambda_2(x)\lambda_3(x),$$

where  $\lambda_i(x)$  are the barycentric coordinates on  $T$ .

Define the velocity and pressure spaces as:

$$\begin{aligned} V_h &= \left\{ \underline{u}_h \in [H_0^1(\Omega)]^2 : \underline{u}_h|_T \in [\mathbb{P}^1(T) \oplus \text{span}(b_T)]^2, \forall T \in \mathcal{T}_h \right\}, \\ Q_h &= \left\{ q_h \in L_0^2(\Omega) \cap C^0(\Omega) : q_h|_T \in \mathbb{P}^1(T), \forall T \in \mathcal{T}_h \right\}. \end{aligned}$$

Prove that with this choice of  $V_h$  and  $Q_h$  (known as the MINI Element), the matrix  $B \in \mathbb{R}^{M \times N}$  has full rank.

Note that:  $\dim(V_h) = \#V_0 + \#T = N > \dim(Q_h) = \#V - 1 = M$ , where

- $\#V$  is the total number of vertices in  $\mathcal{T}_h$ .
- $\#V_0$  is the number of interior vertices.
- $\#T$  is the number of triangles in  $\mathcal{T}_h$ .

**NB.** For further details, see the book by Boffi, Brezzi and Fortin.

**Solution:**

- We seek  $\underline{u} \in V := [H_0^1(\Omega)]^2$  and  $p \in Q := L_0^2(\Omega)$  such that:

$$\begin{aligned} \int_{\Omega} \nabla \underline{u} : \nabla \underline{v} \, dx - \int_{\Omega} p \nabla \cdot \underline{v} \, dx &= \int_{\Omega} \underline{f} \cdot \underline{v} \, dx \quad \forall \underline{v} \in V, \\ \int_{\Omega} q \nabla \cdot \underline{u} \, dx &= 0 \quad \forall q \in Q. \end{aligned}$$

- Let  $V_h \subset V$  and  $Q_h \subset Q$  be finite-dimensional subspaces. The discrete problem takes the form:

$$\begin{pmatrix} A & B^T \\ B & 0 \end{pmatrix} \begin{pmatrix} U \\ P \end{pmatrix} = \begin{pmatrix} F \\ 0 \end{pmatrix},$$

where:

- $A_{ij} = \int_{\Omega} \nabla \phi_j : \nabla \phi_i \, dx$  corresponds to the stiffness matrix for the velocity space  $V_h$ ,
- $B_{ij} = - \int_{\Omega} \psi_i \nabla \cdot \phi_j \, dx$  represents the discretization of the divergence operator,
- $F_i = \int_{\Omega} \underline{f} \cdot \phi_i \, dx$  is the load vector.

Here,  $\{\phi_j\}$  is a basis for  $V_h$  and  $\{\psi_i\}$  is a basis for  $Q_h$ .

- We want to prove that the matrix  $B$  has full rank. This is needed to show that the discrete inf-sup (Ladyzhenskaya–Babuška–Brezzi) condition holds for the pair  $(V_h, Q_h)$ . That is, there exists a constant  $\beta > 0$ , independent of  $h$ , such that:

$$\inf_{q_h \in Q_h \setminus \{0\}} \sup_{\underline{v}_h \in V_h \setminus \{0\}} \frac{\int_{\Omega} q_h \nabla \cdot \underline{v}_h \, dx}{\|\underline{v}_h\|_{H^1} \|q_h\|_{L^2}} \geq \beta.$$

A sufficient condition for  $B$  to have full rank is to show that  $\forall q_h \in Q_h$ ,  $\exists \underline{v}_h \in V_h$  such that:

$$\int_{\Omega} q_h \nabla \cdot \underline{v}_h \, dx \neq 0.$$

Integration by parts gives:

$$-\int_{\Omega} q_h \nabla \cdot \underline{v}_h \, dx = \int_{\Omega} \underline{v}_h \cdot \nabla q_h \, dx - \int_{\partial\Omega} \underbrace{\underline{v}_h \cdot n}_{=0} q_h \, dx.$$

Since  $q_h$  is continuous and piecewise linear on  $\mathcal{T}_h$ , we have  $\nabla q_h|_T \in [\mathbb{P}_0(T)]^2$ .

Now, let us construct a test function  $\underline{v}_h \in V_h$  supported in each triangle  $T$  using the bubble function  $b_T(x) = \lambda_1(x)\lambda_2(x)\lambda_3(x)$ .

Define, for a fixed triangle  $T$ , the local function:

$$\underline{v}_h^T = b_T \nabla q_h|_T.$$

Note that  $\underline{v}_h^T \in [b^T]^2$  and vanishes on  $\partial T$ , so  $\underline{v}_h^T \in V_h$ .

Then:

$$\int_T \underline{v}_h^T \cdot \nabla q_h \, dx = |\nabla q_h|^2 \int_T b_T \, dx \geq 0 \quad \text{since } \nabla q_h \text{ is constant on } T.$$

To construct a global function, define:

$$\underline{v}_h(x) = \sum_{T \in \mathcal{T}_h} \underline{v}_h^T(x).$$

This function is in  $V_h$  because each  $\underline{v}_h^T$  is supported on  $T$  and belongs to  $[P^1(T) \oplus \text{span}(b_T)]^2$ .

Now :

$$\int_{\Omega} \underline{v}_h \cdot \nabla q_h \, dx = \sum_{T \in \mathcal{T}_h} \int_T \underline{v}_h^T \cdot \nabla q_h \, dx = \sum_{T \in \mathcal{T}_h} |\nabla q_h|^2 \int_T b_T(x) \, dx.$$

Since each term in the sum is non-negative and at least one term is strictly positive whenever  $q_h \neq 0$ , we conclude:

$$\int_{\Omega} \underline{v}_h \cdot \nabla q_h \, dx \neq 0.$$

This proves that  $B$  has full rank for the MINI Element.