

EXERCISE SET 7 – MATH-250 Advanced Numerical Analysis I

There is quiz on this exercise sheet. The exercises marked with (\star) are graded homework. The exercises marked with **(Python)** are implementation based and can be solved in the Jupyter notebooks which are available on Moodle/Noto. **The deadline for submitting your solutions to the homework is Friday, April 11 at 10h15.**

Exercises

Problem 1. (Python)

The degree n best approximation in the L^2 norm is the polynomial $p_n^* \in \mathbb{P}_n$ that minimizes the L^2 approximation error

$$\|p_n - f\|_2 = \sqrt{\int_{-1}^1 (p_n(t) - f(t))^2 dt} \quad (1)$$

among all degree n polynomials $p_n \in \mathbb{P}_n$. It can explicitly be expressed as

$$p_n^* = \sum_{k=0}^n (\tilde{q}_k, f)_2 \tilde{q}_k, \quad (2)$$

where \tilde{q}_k are the rescaled Legendre polynomials $\tilde{q}_k = q_k \sqrt{(2k+1)/2}$, $k = 0, 1, \dots, n$, and $(u, v)_2 = \int_{-1}^1 u(t)v(t) dt$ denotes the L^2 inner product.

- (a) Define a function `rescaled_legendre_polynomial(k)` which returns the k -th rescaled Legendre polynomial. You can use `np.polynomial.legendre.Legendre.basis` which takes as input a natural number k and returns the k -th Legendre polynomial q_k .
- (b) Define a function `l_2_inner_product` which takes as input two functions u and v and approximates their L^2 inner product $(u, v)_2$ with a sufficiently accurate quadrature rule of your choice.
- (c) Using the two previously defined functions and the expression (2), write a function `l_2_optimal_approximation` which takes as input a function f and a natural number n and returns the L^2 best approximation p_n^* .
- (d) For the function $f(x) = 1/(1 + 25x^2)$ and the degrees $n = 1, 2, \dots, 20$, compare the L^2 -error (1) of the best approximation in the L^2 norm with the one for the Chebyshev interpolant of the same degree. Use an appropriate quadrature rule of your choice to approximate the integral.

Hint: Use `np.polynomial.chebyshev.Chebyshev.interpolate` to compute the Chebyshev interpolant.

Solution. Available in the Jupyter notebook `serie07-sol.ipynb` on Moodle.

Problem 2.

- (a) For each of the following matrices, determine if an LU factorisation exists. If an LU factorisation exists, compute it.

$$(i) \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} \quad (ii) \begin{pmatrix} 4 & 2 \\ 3 & 4 \end{pmatrix} \quad (iii) \begin{pmatrix} 3 & 3 \\ 1 & 1.5 \end{pmatrix} \quad (iv) \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}$$

(b) Compute the LU factorisation with pivoting for the matrix

$$A = \begin{pmatrix} 5 & 1 & 2 \\ 2 & \frac{2}{5} & 1 \\ -4 & 0 & 6 \end{pmatrix}$$

Compare it with the Python function `sp.linalg.lu`. (If you are not working in the notebooks we provided you will need to use `scipy.linalg.lu`.)

- (c) Suppose that $PA = LU$ is the LU factorisation with pivoting of A . Find a simple formula for $\det(A)$ and $|\det(A)|$ in terms of L , U , and the permutation determining P .
- (d) In your linear algebra course you have seen the following definition of the determinant of a matrix $A \in \mathbb{R}^{n \times n}$:

$$\det(A) = \sum_{\sigma \in S_n} \text{sgn}(\sigma) \prod_{i=1}^n a_{i, \sigma(i)} \quad (3)$$

where S_n is the set of all permutations of length n .

Compare the computational complexity of computing the determinant with Equation (3) and computing the determinant via the LU factorisation.

Solution.

(a) (i) The LU factorization exists and equals $\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 0 & -3 \end{pmatrix}$.

(ii) The LU factorization exists and equals $\begin{pmatrix} 4 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ \frac{3}{4} & 1 \end{pmatrix} \begin{pmatrix} 4 & 2 \\ 0 & \frac{5}{2} \end{pmatrix}$

(iii) The LU factorization exists and equals $\begin{pmatrix} 3 & 3 \\ 1 & 1.5 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ \frac{1}{3} & 1 \end{pmatrix} \begin{pmatrix} 3 & 3 \\ 0 & \frac{1}{2} \end{pmatrix}$

(iv) No LU factorization exists. One can see that if such factorization would exist then

$$\begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ \ell & 1 \end{pmatrix} \begin{pmatrix} u_1 & u_2 \\ 0 & u_3 \end{pmatrix}$$

which implies $u_1 = 0, u_2 = 1$. This is a contradiction because it would mean

$$1 = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}_{2,1} = \ell \cdot 0 + 1 \cdot 0 = 0$$

which is clearly a contradiction. The reason why the LU factorization does not exist is because the first leading principal supmatrix is not invertible.

(b) Following Algorithm 4.13 we get

$$\begin{aligned}\tilde{A}^{(0)} &= A, P_1 = I_3 \\ A^{(1)} &= \begin{pmatrix} 5 & 1 & 2 \\ -\frac{2}{5} & 0 & \frac{1}{5} \\ -\frac{4}{5} & \frac{4}{5} & \frac{38}{5} \end{pmatrix} \\ \tilde{A}^{(1)} &= \begin{pmatrix} 5 & 1 & 2 \\ -\frac{4}{5} & \frac{4}{5} & \frac{38}{5} \\ \frac{2}{5} & 0 & \frac{1}{5} \end{pmatrix}, P_2 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \\ A^{(2)} &= \tilde{A}^{(2)}\end{aligned}$$

Hence,

$$L = \begin{pmatrix} 1 & 0 & 0 \\ -\frac{4}{5} & 1 & 0 \\ \frac{2}{5} & 0 & 1 \end{pmatrix}, U = \begin{pmatrix} 5 & 1 & 2 \\ 0 & \frac{4}{5} & \frac{38}{5} \\ 0 & 0 & \frac{1}{5} \end{pmatrix}, P = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

and if we use `P, L, U = sp.linalg.lu(A)` we can see that it returns the same matrices.

- (c) We have $\det(PA) = \det(P)\det(A) = \det(LU) = \det(L)\det(U) \Rightarrow \det(A) = \frac{\det(L)\det(U)}{\det(P)}$. Since P is a permutation matrix, $\det(P)$ equals the sign of the associated permutation, call it σ . Since L and U are triangular their determinants are equal to the product of their diagonal elements. Since, $\text{sgn}(\sigma) = \pm 1$ we have

$$\det(A) = \frac{\prod_{i=1}^n \ell_{ii} u_{ii}}{\text{sgn}(\sigma)} = \text{sgn}(\sigma) \prod_{i=1}^n u_{ii}$$

and

$$|\det(A)| = \prod_{i=1}^n |u_{ii}|$$

- (d) Computing the $\det(A)$ via the LU factorization requires $O(n^3)$ operations to get the factorization and $O(n)$ operations to carry out the multiplications. Hence, the total work done is $O(n^3)$.

Computing the determinant from its definition requires $O(n \cdot n!)$ operations, since we need to perform n multiplications $n!$ times and sum the resulting values.

Problem 3.

Let the linear system $Ax = b$ be given by defining

$$A = \begin{pmatrix} 10^{-4} & 1 \\ 1 & 1 \end{pmatrix}, \quad b = \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

Solve the system of linear equations $Ax = b$ via the LU factorisation

- (a) in exact arithmetic,

- (b) without pivoting in floating point arithmetic $\mathbb{F}(10, 3, -10, 10)$ (i.e. with 3 significant digits), and
- (c) with partial pivoting in floating point arithmetic $\mathbb{F}(10, 3, -10, 10)$.
- and compare the results.

Solution.

- (a) Exact arithmetic:

$$\begin{aligned} & \frac{1}{1 \cdot 10^{-4}} \left(\begin{array}{cc|c} 1 \cdot 10^{-4} & 1 & 1 \\ & 1 & 2 \end{array} \right) \\ & \left(\begin{array}{cc|c} 1 \cdot 10^{-4} & 1 & 1 \\ 0 & -9999 & -9998 \end{array} \right) \\ & \Rightarrow x_2 = \frac{9998}{9999} = 1 - \frac{1}{9999} \\ & x_1 = \frac{1}{1 \cdot 10^{-4}} \left(1 - \left(1 - \frac{1}{9999} \right) \right) = \frac{10000}{9999} = 1 + \frac{1}{9999}. \end{aligned}$$

- (b) Solution in floating point arithmetic without pivoting:

$$\frac{1}{1 \cdot 10^{-4}} \left(\begin{array}{cc|c} 1 \cdot 10^{-4} & 1 & 1 \\ & 1 & 2 \end{array} \right)$$

Performing the operations in floating point arithmetic gives us

$$\begin{aligned} a_{22} &= 1 - 1.00 \cdot 10^4 \cdot 1 = -9.999 \cdot 10^3 \approx -1.00 \cdot 10^4 \\ b_2 &= 2 - 1.00 \cdot 10^4 \cdot 1 = -9.998 \cdot 10^3 \approx -1.00 \cdot 10^4 \end{aligned}$$

This gives us the system in the next step

$$\begin{aligned} & \left(\begin{array}{cc|c} 1 \cdot 10^{-4} & 1 & 1 \\ 0 & -1 \cdot 10^4 & -1 \cdot 10^4 \end{array} \right) \\ & \Rightarrow x_2 = 1 \\ & x_1 = 1 \cdot 10^4 (1 - 1) = 0, \end{aligned}$$

whereby the result for x_1 deviates significantly from the exact result.

- (c) Solution in floating point arithmetic, with pivoting. We swap lines 1 and 2 because $|a_{21}| > |a_{11}|$:

$$1 \cdot 10^{-4} \left(\begin{array}{cc|c} 1 & 1 & 2 \\ 1 \cdot 10^{-4} & 1 & 1 \end{array} \right)$$

Performing the operations in floating point arithmetic gives us

$$\begin{aligned} a_{22} &= 1 - 1.00 \cdot 10^{-4} \cdot 1 = 9.999 \cdot 10^{-1} \approx 1.00 \cdot 10^0 \\ b_2 &= 1 - 1.00 \cdot 10^{-4} \cdot 2 = 9.998 \cdot 10^{-1} \approx 1.00 \cdot 10^0. \end{aligned}$$

This gives us the system in the next step

$$\begin{pmatrix} 1 & 1 & | & 2 \\ 0 & 1 & | & 1 \end{pmatrix}$$
$$\Rightarrow x_2 = 1$$
$$x_1 = 2 - 1 = 1,$$

which corresponds to the exact result rounded to 3 significant digits. Different algorithms can therefore lead to different results numerically, even if the results would have to be the same in theory.