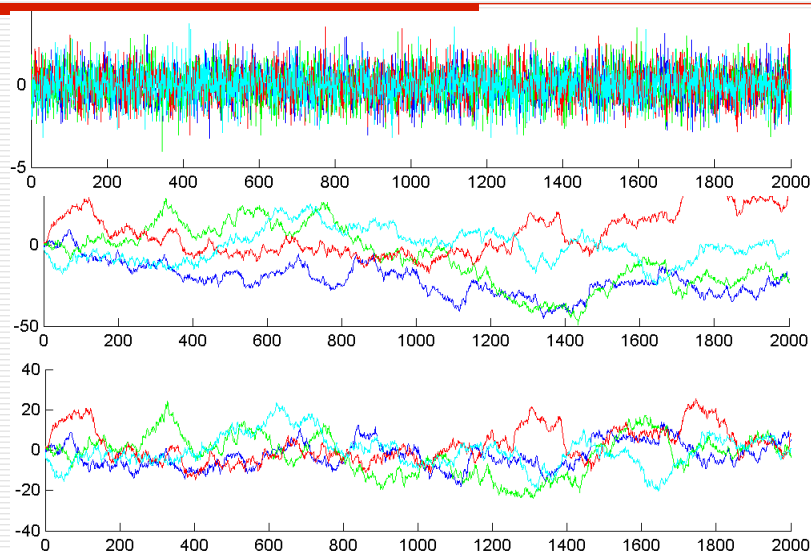


Topics

- Random **process**
 - General concept
 - Classification of random processes
 - Empirical **model identification**
- Random process **examples**
 - White Noise
 - Random bias
 - Shaped white noise
- Characteristic functions
 - AC
 - PSD

Random process – an example



Random processes – general concept

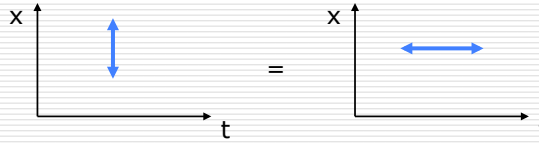
- ☐ Random process:
 - **Association** of random variable(s) with a deterministic parameter (e.g. time)
 - Stochastic **collection** – values depend on the outcome of an experiment
 - Time is a **parameter** but the process is ONLY LOOSELY/stochastic “function” of time
 - Discrete or continuous

Random variable vs. random process

- ☐ Probability
 - Distribution
 - Density
 - ☐ Characteristics
 - Variable
 - ☐ Moments
 - ☐ Characteristic function
 - Process
 - ☐ Autocorrelation function (AC)
 - ☐ Power spectral density (PSD)
- TABLE – black board

Classification of random processes

□ By ergodicity



$$E(x) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t) dt$$

$$E(x^2) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x^2(t) dt$$

$$\varphi_{xx}(\tau) = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t_1)x(t_2) dt$$

Classification of random processes

□ By stationarity

- Characteristics = const.(t)
- Can be computed from 'sample' interval

$$\varphi_{xx}(\tau) = E(x(t)x(t+\tau))$$

$$\varphi_{xx}(0) = E(x^2)$$

$$\varphi_{xx}(-\tau) = \varphi_{xx}(\tau)$$

Empirical model identification

- Autocorrelation techniques:
 - Assumption **1**: Underlying process is **stationary** Gaussian random process
 - Assumption **2**: Data (z) sampled at **constant Δt**

$$m = \frac{1}{N} \sum_{i=1}^N z_i$$

$$\varphi_{zz}(l\Delta t) = \frac{1}{N-l-1} \sum_{i=1}^{N-l} (z_i - m)(z_{i+l} - m)^T; l = 0, 1, \dots, N-2$$

- Time series analysis:
 - AR, MA, ARMA, ARIMA, ...
 - AV, GMWM, ...



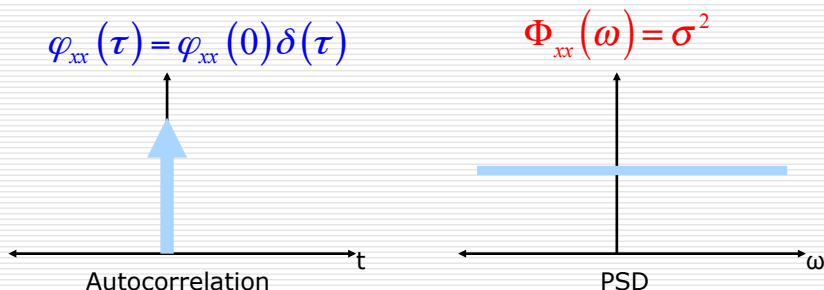
9/27/13

Sensor Orientation

10/L2

White noise process

- State propagation: $x_{k+1} = w_k$
- Differential equation: theoretically not differentiable

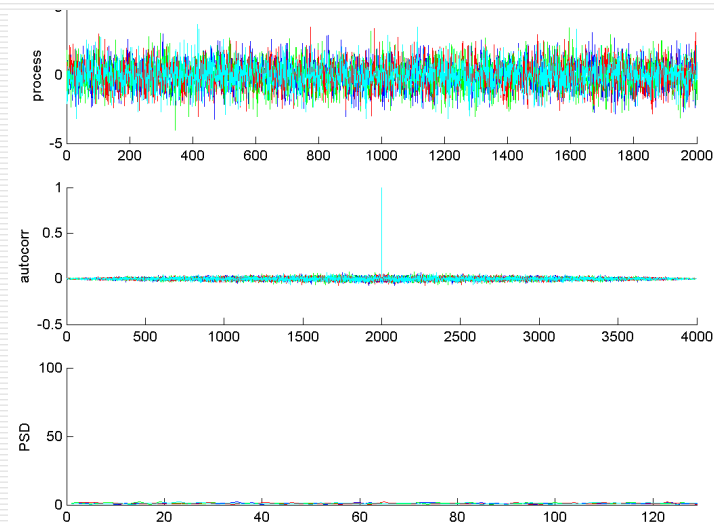


9/27/13

Sensor Orientation

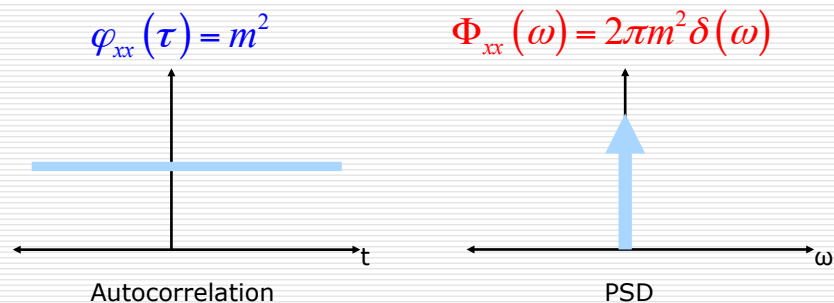
11/L2

White noise - example



Random bias/constant

- State propagation: $x_{k+1} = x_k = m$
- Differential equation: $\dot{x}(t) = 0$



Shaped white noise

- Amplitude:
 - Gaussian probability density -> results of number of independent random variables.
- Correlation in time (frequency)
 - **White noise**: not correlated in time
 - **Colored noise**: white noise put through a small linear system can duplicate virtually any form of time-correlated noise.
- Linear transformation of white noise = **Shaping Filter**



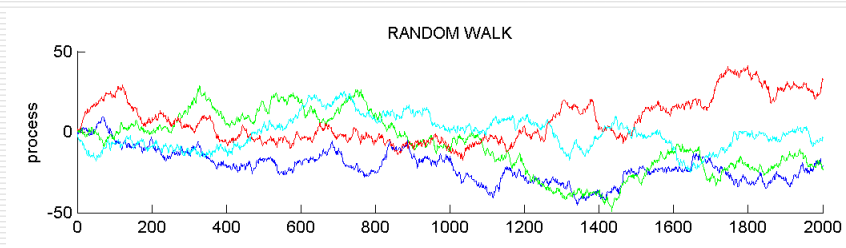
9/27/13

Sensor Orientation

14/L2

Random walk

- State propagation: $x_{k+1} = x_k + w_k$
- Differential equation: $\dot{x}(t) = w(t)$
- Not a stationary process!



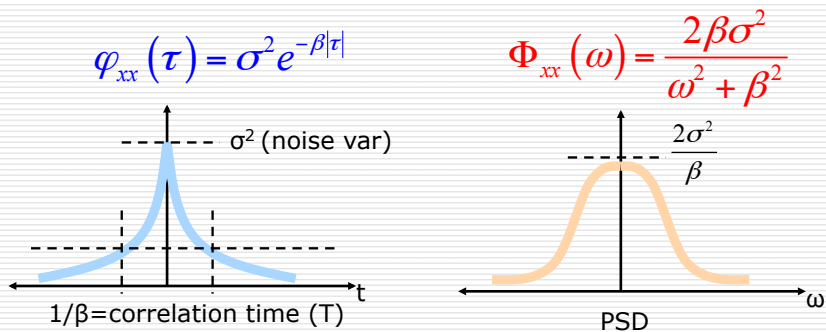
9/27/13

Sensor Orientation

15/L2

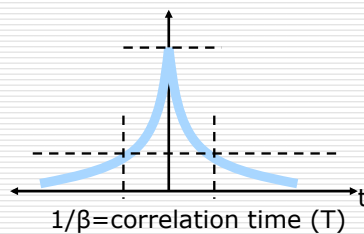
1st order Gauss-Markov process

- State propagation: $x_{k+1} = e^{-\beta\Delta t} x_k + w_k$
- Differential equation: $\dot{x}(t) = -\beta x(t) + w(t)$

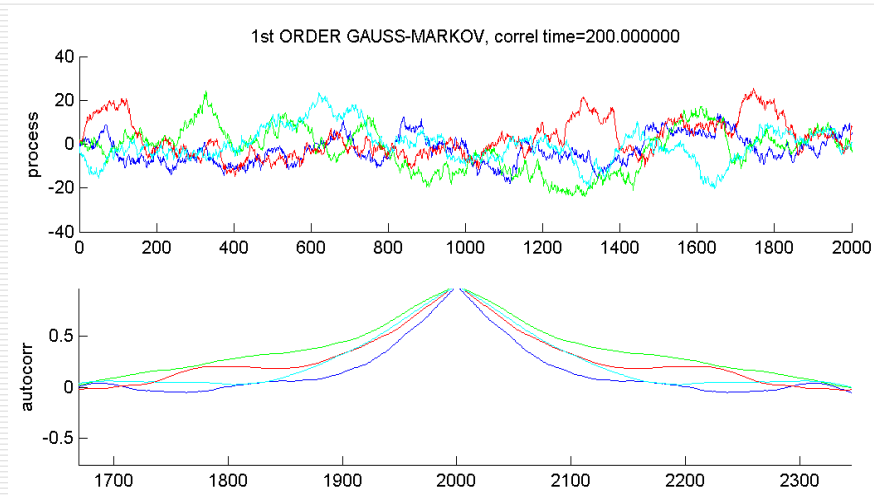


Question:

$$\varphi_{xx}(T) = \varphi_{xx}(1/\beta) = ?$$



1st o. Gauss-Markov process - example



Other random processes

- ☐ Random ramp
- ☐ Auto-Regressive (AR) process
- ☐ Moving-Average (MA) process
- ☐ Auto-Regressive Moving Average (ARMA)
- ☐ :

Power spectrum (or PSD)

- PSD is the discrete Fourier transform (DFT) of AC:

$$\Phi_{xx}(\omega) = \sum_{\tau=-\infty}^{\infty} \phi_{xx}(\tau) e^{-j\omega\tau}$$

- If we have a signal of length N:

- Sample AC (AC estimate):

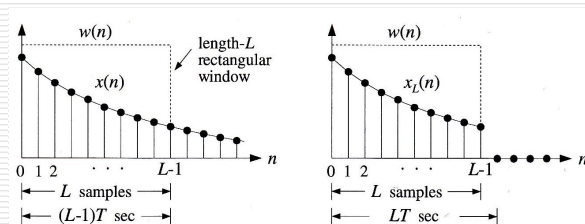
$$\hat{\phi}_{xx}(\tau) = \frac{1}{N} \sum_{n=0}^{N-1-\tau} x_{n+\tau} x_n; \tau = 0, 1, \dots, N-1$$

- Periodogram spectrum (PSD estimate)

$$\hat{\Phi}_{xx}(\omega) = \sum_{\tau=-\infty}^{\infty} \hat{\phi}_{xx}(\tau) e^{-j\omega\tau}$$

Note about windowing in DFT

- Time windowing (e.g. rectangular window)



- Original and time-windowed spectrum:

$$\hat{\Phi}(\omega) = \sum_{n=-\infty}^{\infty} x(nT) e^{-2\pi j\omega nT}$$

$$\hat{\Phi}_L(\omega) = \sum_{n=0}^{L-1} x_L(nT) e^{-2\pi j\omega nT} = \sum_{n=-\infty}^{\infty} x_L(n) e^{-j\omega n}$$

Note about windowing in DFT

- Windowing has two (side) effects:
 - Reduction of the frequency resolution of the computed spectrum

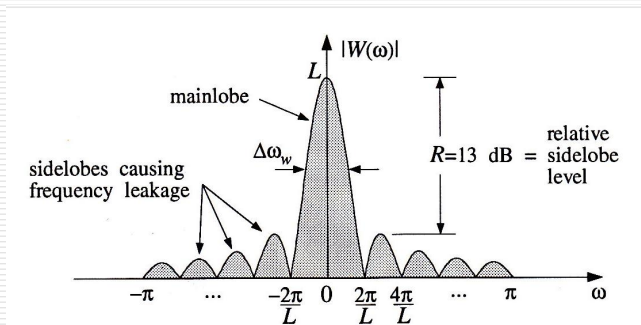
$$\Delta\omega = \frac{1}{T_L}$$

- Frequency leakage
 - Introduction of high-frequency components into the spectrum
 - Caused by the sharp clipping of the signal at the left & right sides of the rectangular window

$$|W(\omega)| = \left| \frac{\sin(\omega L / 2)}{\sin(\omega / 2)} \right|$$

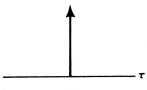
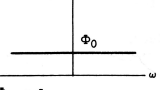
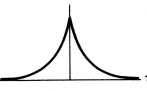
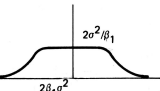
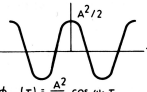
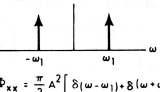
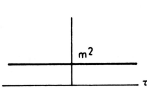
Note about windowing in DFT

- Magnitude spectrum of rectangular window:



$$|W(\omega)| = \left| \frac{\sin(\omega L / 2)}{\sin(\omega / 2)} \right|$$

Common Random Processes (distributed)

PROCESS	AUTOCORRELATION FUNCTION	POWER SPECTRAL DENSITY
WHITE NOISE	 $\phi_{xx}(\tau) = \phi_0 \delta(\tau)$	 $\Phi_{xx} = \Phi_0$
MARKOV PROCESS $m=0$	 $\phi_{xx}(\tau) = \sigma_a^2 e^{-\beta_1 \tau }$	 $\Phi_{xx} = \frac{2\sigma_a^2 \beta_1}{\omega^2 + \beta_1^2}$
SINUSOID	 $\phi_{xx}(\tau) = \frac{A^2}{2} \cos \omega_1 \tau$	 $\Phi_{xx} = \frac{\pi}{2} A^2 [\delta(\omega - \omega_1) + \delta(\omega + \omega_1)]$
RANDOM BIAS	 $\phi_{xx}(\tau) = m^2$	 $\Phi_{xx} = 2\pi m^2 \delta(\omega)$

After Gelb, A. (1974)

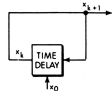
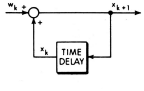
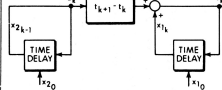
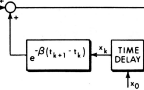


9/27/13

Sensor Orientation

25/L2

Error Models – Discrete Case (distributed)

NAME	STATE DIFFERENCE EQUATION	BLOCK DIAGRAM	RELATION of DISCRETE q_k to CONTINUOUS q
RANDOM CONSTANT	$x_{k+1} = x_k$		$q_k = 0$
RANDOM WALK	$x_{k+1} = x_k + w_k$		$q_k = q(t_{k+1} - t_k)$
RANDOM RAMP	$x_{1,k+1} = x_{1,k} + (t_{k+1} - t_k) x_{2,k}$ $x_{2,k+1} = x_{2,k}$		$q_k = 0$
EXPONENTIALLY CORRELATED RANDOM VARIABLE	$x_{k+1} = e^{-\beta(t_{k+1} - t_k)} x_k + w_k$		$q_k = \frac{q}{2\beta} [1 - e^{-2\beta(t_{k+1} - t_k)}]$

After Gelb, A. (1974)



9/27/13

Sensor Orientation

26/L2

Allan variance (AV) - D. Allan 1966

- Alternative measure of variability
- = "variations of sample averages of different length τ "

$$\bar{X}_k(\tau) = \frac{1}{\tau} \sum_{j=0}^{\tau-1} X_{k-j} \quad \sigma_{\bar{X}}^2(\tau) = \frac{1}{2} \mathbb{E} \left[\left(\bar{X}_k(\tau) - \bar{X}_{k-\tau}(\tau) \right)^2 \right]$$

- Greenhall (1991) estimator of AV

$$\hat{\sigma}_{\bar{X}}^2(\tau) = \frac{1}{2(N-2\tau+1)} \sum_{k=2\tau}^N \left(\bar{x}_k(\tau) - \bar{x}_{k-\tau}(\tau) \right)^2$$

$x_k : k = 1, \dots, N$

Process identification in AV plots

