

# Least-square Example - Simple Harmonic Analysis

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There are many periodical ( $P$ ) phenomena in nature or electronic instruments that can be expressed as:

$$z = f(y) = f(y + P) = f(y + 2P) = \dots$$

In such a situation it is sufficient to obtain observation over one period, which duration  $y_n - y_0 = P$  we normalize by a substitution

$$t = \frac{2\pi}{P} y.$$

to the interval  $(0, 2\pi)$

## Model

Let's assume that there is only one cause (e.g. an evolution of a daily or yearly temperature) that can be modeled by a sinusoidal function

$$z = A_0 + a \sin(t + A)$$

where  $A_0$  is the mean shift on the z-axis,  $a$  is the amplitude,  $t$  is the argument over the interval  $(0, 2\pi)$  and  $(2\pi - A)$  is the shift of the sinusoidal with respect to  $t$  origin. The initial phase for  $t = 0$  corresponds to  $z_0 = A_0 + a \sin A$ .

## Problem

We aim to determine the unknown parameters from observations by the method of least-square, namely:

- unknowns:  $x' = (A_0, a, A)$
- observations:  $(t_i, z_i)$ , where  $i = 1, \dots, n$  with  $n \geq 3$

We start to form the observation equations with the help of trigonometric identity  $\sin(A + B) = \sin A \cos B + \cos A \sin B$

$$z_i = A_0 + a(\sin t_i \cos A + \cos t_i \sin A) + v_i$$

and two substitutions  $a \sin A = A_1$  and  $a \cos A = A_2$  to obtain

$$z_i = A_0 + \cos t_i \cdot A_1 + \sin t_i \cdot A_2 + v_i$$

where  $v_i$  is the correction due to random error.

## Normal equations

After substitutions there is only a linear relation between observations  $z_i$  and the 3 modified unknown parameters  $x = (A_0, A_1, A_2)$ . We rewrite the observation equations in the vector-matrix form  $z = H x$  where the design matrix  $H$  is obtained by stacking  $n$  of row-vectors  $(1 \cos t_i \sin t_i)$ .

Considering all observations equally weighted (i.e. having the same precision), the solution follows from the least-square conditions  $v^T v$  that forms the normal equations:

$$(H^T H) x = H^T z$$

## Simplification

Let's rewrite the normal equations by its individual elements through inspecting the  $(H^T H)$  matrix and the  $(H^T z)$  vector

$$nA_0 + (\sum \cos t)A_1 + (\sum \sin t)A_2 - \sum z = 0$$

$$(\sum \cos t)A_0 + (\sum \cos^2 t)A_1 + (\sum \sin t \cos t)A_2 - \sum (\cos t \cdot z) = 0$$

$$(\sum \sin t)A_0 + (\sum \sin t \cos t)A_1 + (\sum \sin^2 t)A_2 - \sum (\sin t \cdot z) = 0$$

We note that  $\sin$  and  $\cos$  are orthogonal functions with zero mean value per period. Hence, when the sampling interval is regular over the whole period the following sums are zero:

$$\sum \sin t = 0 \quad \sum \cos t = 0 \quad \sum \sin t \cos t = 0$$

Further it holds that

$$\sum \sin^2 t = \sum \cos^2 t = \frac{n}{2},$$

due to the following identities when  $a = b$

$$\sum \cos at \cdot \cos bt = \frac{n}{2} \sum \cos(a+b)t + \frac{n}{2} \sum \cos(a-b)t$$

$$\sum \sin at \cdot \sin bt = \frac{n}{2} \sum \cos(a-b)t - \frac{n}{2} \sum \cos(a+b)t$$

## Solution

With the previous reasoning, only quadratic and absolute terms remains in the previously defined normal equations. That facts leaves only one unknown per each equation:

$$nA_0 - \sum z = 0 \rightarrow A_0 = \frac{1}{n} \sum z$$

$$\frac{n}{2}A_1 - \sum \cos t \cdot z = 0 \rightarrow A_1 = \frac{2}{n} \sum \cos t \cdot z$$

$$\frac{n}{2}A_2 - \sum \sin t \cdot z = 0 \rightarrow A_2 = \frac{2}{n} \sum \sin t \cdot z$$

## Parameter confidence

The empirical variances of unknowns are found by scaling the values on the main diagonal of  $P = (H^T H)^{-1}$  by  $\sigma_0$

$$\sigma_{A_0}^2 = P_{11} \cdot \sigma_0 = \frac{1}{n} \cdot \sigma_0,$$

$$\sigma_{A_1}^2 = P_{22} \cdot \sigma_0 = \frac{2}{n} \cdot \sigma_0,$$

$$\sigma_{A_2}^2 = P_{22} \cdot \sigma_0 = \frac{2}{n} \cdot \sigma_0.$$

The empirical value of  $\sigma_0^2$  is obtained from the quadratic sum of all corrections  $v_i$  divided by the degrees of freedom, which is the number of observations minus the number of unknowns

$$\sigma_0 = \frac{v^T v}{n-3}.$$

## Remark

The original parameters  $(a, A)$  are recovered by back-substituting  $(A_1, A_2)$  into two equations  $A_1 = a \sin A$ , and  $A_2 = a \cos A$  and solving this small system.