

Least-square Example - Simple Harmonic Analysis

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There are many periodical (P) phenomena in nature or electronic instruments that can be expressed as:

$$z = f(y) = f(y + P) = f(y + 2P) = \dots$$

In such a situation it is sufficient to obtain observation over one period, which duration $y_n - y_0 = P$ we normalize by a substitution

$$t = \frac{2\pi}{P} y.$$

to the interval $(0, 2\pi)$

Model

Let's assume that there is only one cause (e.g. an evolution of a daily or yearly temperature) that can be modeled by a sinusoidal function

$$z = A_0 + a \sin(t + A)$$

where A_0 is the mean shift on the z-axis, a is the amplitude, t is the argument over the interval $(0, 2\pi)$ and $(2\pi - A)$ is the shift of the sinusoidal with respect to t origin. The initial phase for $t = 0$ corresponds to $z_0 = A_0 + a \sin A$.

Problem

We aim to determine the unknown parameters from observations by the method of least-square, namely:

- unknowns: $x' = (A_0, a, A)$
- observations: (t_i, z_i) , where $i = 1, \dots, n$ with $n \geq 3$

We start to form the observation equations with the help of trigonometric identity $\sin(A + B) = \sin A \cos B + \cos A \sin B$

$$z_i = A_0 + a(\sin t_i \cos A + \cos t_i \sin A) + v_i$$

and two substitutions $a \sin A = A_1$ and $a \cos A = A_2$ to obtain

$$z_i = A_0 + \cos t_i \cdot A_1 + \sin t_i \cdot A_2 + v_i$$

where v_i is the correction due to random error.

Normal equations

After substitutions there is only a linear relation between observations z_i and the 3 modified unknown parameters $x = (A_0, A_1, A_2)$. We rewrite the observation equations in the vector-matrix form $z = Hx$ where the design matrix H is obtained by stacking n of row-vectors $(1 \cos t_i \sin t_i)$.

Considering all observations equally weighted (i.e. having the same precision), the solution follows from the least-square conditions $v^T v$ that forms the normal equations:

$$(H^T H)x = H^T z$$

Simplification

Let's rewrite the normal equations by its individual elements through inspecting the $(H^T H)$ matrix and the $(H^T z)$ vector

$$\begin{aligned} nA_0 + (\sum \cos t)A_1 + (\sum \sin t)A_2 - \sum z &= 0 \\ (\sum \cos t)A_0 + (\sum \cos^2 t)A_1 + (\sum \sin t \cos t)A_2 - \sum (\cos t \cdot z) &= 0 \\ (\sum \sin t)A_0 + (\sum \sin t \cos t)A_1 + (\sum \sin^2 t)A_2 - \sum (\sin t \cdot z) &= 0 \end{aligned}$$

We note that \sin and \cos are orthogonal functions with zero mean value per period. Hence, when the sampling interval is regular over the whole period the following sums are zero:

$$\sum \sin t = 0 \quad \sum \cos t = 0 \quad \sum \sin t \cos t = 0$$

Further it holds that

$$\sum \sin^2 t = \sum \cos^2 t = \frac{n}{2},$$

due to the following identities when $a = b$

$$\sum \cos at \cdot \cos bt = \frac{n}{2} \sum \cos(a+b)t + \frac{n}{2} \sum \cos(a-b)t$$

$$\sum \sin at \cdot \sin bt = \frac{n}{2} \sum \cos(a-b)t - \frac{n}{2} \sum \cos(a+b)t$$

Solution

With the previous reasoning, only quadratic and absolute terms remains in the previously defined normal equations. That facts leaves only one unknown per each equation:

$$nA_0 - \sum z = 0 \rightarrow A_0 = \frac{1}{n} \sum z$$

$$\frac{n}{2}A_1 - \sum \cos t \cdot z = 0 \rightarrow A_1 = \frac{2}{n} \sum \cos t \cdot z$$

$$\frac{n}{2}A_2 - \sum \sin t \cdot z = 0 \rightarrow A_2 = \frac{2}{n} \sum \sin t \cdot z$$

Parameter confidence

The empirical variances of unknowns are found by scaling the values on the main diagonal of $P = (H^T H)^{-1}$ by σ_0

$$\sigma_{A_0}^2 = P_{11} \cdot \sigma_0 = \frac{1}{n} \cdot \sigma_0,$$

$$\sigma_{A_1}^2 = P_{22} \cdot \sigma_0 = \frac{2}{n} \cdot \sigma_0,$$

$$\sigma_{A_2}^2 = P_{33} \cdot \sigma_0 = \frac{2}{n} \cdot \sigma_0.$$

The empirical value of σ_0^2 is obtained from the quadratic sum of all corrections v_i divided by the degrees of freedom, which is the number of observations minus the number of unknowns

$$\sigma_0 = \frac{v^T v}{n-3}.$$

Remark

The original parameters (a, A) are recovered by back-substituting (A_1, A_2) into two equations $A_1 = a \sin A$, and $A_2 = a \cos A$ and solving this small system.