

Linear System Theory

Lecture 4

Ph. Nüllhaupt

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Outline

1. Recap:
2. Algorithm:
3. 3.1 decoupling zeros
3.2 " "
3.3 decoupling zeros
3.4
3.5

4. Examples.

1. Recap system description
Polynomial

$$P(s) = \begin{bmatrix} & \\ & \end{bmatrix} \quad P \begin{bmatrix} \\ \end{bmatrix} = \begin{bmatrix} \\ \end{bmatrix}$$

in state-space description $T(s) =$ with $s = \lambda$

and considering only $T(s)$ we can
"compute" the invariant polynomials of
 $T(s)$.

Strict system equivalence

Equivalence through

whose inverse

are square matrices nonsingular

$$\begin{bmatrix} | & | \end{bmatrix} \in \left(\text{polynomial} \right)$$
$$\begin{bmatrix} \\ \end{bmatrix} = \begin{bmatrix} \\ \end{bmatrix} \begin{bmatrix} \\ \end{bmatrix} \begin{bmatrix} \\ \end{bmatrix}$$

$\nwarrow \quad \nearrow$

2. Smith Form

By (resp.)
an $n \times n$ polynomial matrix $A(s)$
can be brought $\left(\right)$

Definition: Elementary unimodular matrices

$$T_1 = \begin{bmatrix} & & \\ & & \\ & & \end{bmatrix} \in \mathbb{Z}$$

$$T_2 = \begin{bmatrix} 1 & & & & \\ & 1 & & & \\ & & \ddots & & \\ & & & 1 & \\ & & & & 1 \end{bmatrix} =$$

$$T_3 = \begin{bmatrix} 1 & & & \\ & \diagdown & & \\ & 0 & & \\ & & \diagup & \\ 0 & & & 1 \end{bmatrix}$$

single entry where
appears
otherwise identity matrix

$$S_1 =$$

$$S_2 =$$

$$S_3 =$$

()

Smith decomposition:

$$P(s) = \begin{bmatrix} p_{11}(s) & \dots \\ \vdots & \end{bmatrix} \xrightarrow{\text{Smith Form}} \begin{bmatrix} & \\ & \end{bmatrix}$$

$p_{mn}(s)$

Algorithm:

STEP 1: Find the polynomial in s in the 1st column

$\leq$

STEP 2: Bring the $(\quad) (\quad)$

STEP 3: Use $\quad$ on the elements of the 1st column then with

$$= \bigcirc +$$

$\leq$

Use $T_3 = \begin{bmatrix} 1 & & \\ & \diagdown & 0 \\ & 0 & \diagdown & 1 \end{bmatrix}$

Repeat STEPS 1-2-3 until the first column looks like

$$\begin{bmatrix} c_{11} \\ \\ \\ \end{bmatrix}$$

STEP 4 do STEPS 1-2-3

using matrices

until

$$\begin{bmatrix} \\ \\ \\ \end{bmatrix}$$

STEP 5 do steps 1 to 4 with

→ until $\begin{bmatrix} \\ \\ \\ \end{bmatrix}$ is obtained.

Definition the resulting $(\quad)$ is called the $\quad$ of the original polynomial matrix.

$$P = \begin{bmatrix} T & U \\ -V & W \end{bmatrix}$$

3. decoupling zeros, zeros, poles, i-d. z., o-d. z., i-o-d. z.

3.1 consider the matrix $(\quad)$ 3.1. i-d. zeros
input decoupling $\equiv$ i-d.

and compute its Smith Form using the algorithm.

collect all the zeros of the diagonal entries in the Smith Form.

$$[\quad] \rightarrow \{ \}$$

β_s are the

3.2 output-decoupling zeros (o-d. z.)

Consider $\begin{pmatrix} & \end{pmatrix}$ in form

Perform on $\begin{pmatrix} & \end{pmatrix}$ a Smith decomposition
using the algorithm to achieve

$$\begin{pmatrix} & \end{pmatrix}$$

and compute the zeros of every $\begin{pmatrix} & \end{pmatrix}$ to get the
set of output-decoupling zeros :

3.3 input-output decoupling zeros (i-o-d. z.)

Remove the $\{ \}$ from
to get

i.e. apply the unimodular matrices obtained
to bring the $\begin{pmatrix} & \end{pmatrix}$ to Smith form
by inverting them

extend

$\begin{pmatrix} & \end{pmatrix}$ is therefore obtained

$\Rightarrow$ compute the Smith Form of $\begin{pmatrix} & \end{pmatrix}$
and compute the zeros of the diagonal entries
of the resulting Smith-Form.

$$\longrightarrow \begin{Bmatrix} \\ \end{Bmatrix}$$

Remove the $\begin{Bmatrix} \\ \end{Bmatrix}$ from the $\begin{Bmatrix} \\ \end{Bmatrix}$
to find the input-output decoupling
zeros. (i-o-d z.).

$$\begin{Bmatrix} \\ \end{Bmatrix} = \begin{Bmatrix} \\ \end{Bmatrix} - \begin{Bmatrix} \\ \end{Bmatrix}$$

3.4 Zeros

Simply compute the Smith-Form of
let the zeros of the diagonal entries of
the Smith form be $\begin{Bmatrix} \\ \end{Bmatrix}$

3.5Poles

$$d = \{ \dots \} - \{ \dots \} - \{ \dots \}$$

$$\{ \dots \} \quad \text{i.d.}$$

$$\{ \dots \} \quad \text{o.d.}$$

$$\{ \dots \} \quad \text{i.o.d.}$$

$$\{ \dots \} \quad \text{zeros}$$

$$\{ \dots \} \quad \text{poles of } G(s)$$

$$P(s) = \left[\begin{array}{c} \vdots \\ \hline \vdots \end{array} \right]$$

$$\{\eta_i\} = \{ \dots \}$$

$$\{\beta_i\} = \{ \dots \}$$

$$\{\gamma_i\} = \{ \dots \}$$

$$\{\alpha_i\} = \{ \dots \}$$

$$\{\delta_i\} = \{ \dots \}$$

$$\{\alpha_i\} = \{ \dots \}$$