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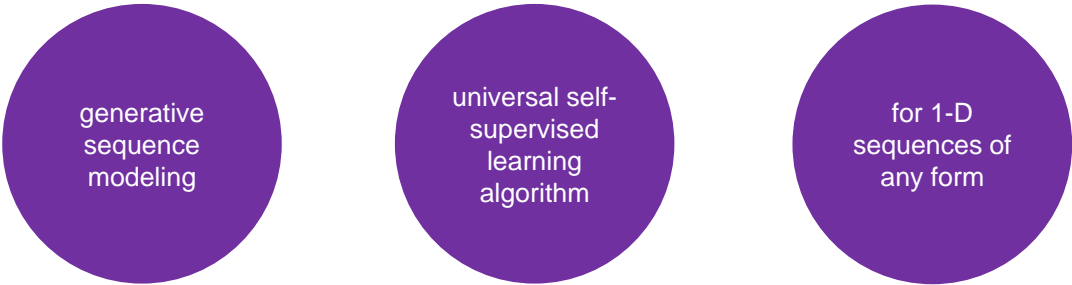
# EE-559

# Deep Learning

## What's on today?

- **Vision transformer**: from coherent text to coherent images
- **Audio transformer**: adapting transformers for sound understanding
- **Audio-visual transformer**: analyzing jointly audio & video data
- **Vision and language models**: fusing vision & language understanding
- **Exercises**: multimodal transformer

# Transformer



generative  
sequence  
modeling

universal self-  
supervised  
learning  
algorithm

for 1-D  
sequences of  
any form

**Concepts:** Transformer as self-supervised learning algorithm,  
sequences of bytes, trained to maximize the likelihood (mode covering)

# Vision transformer

## Transformers for visual tasks



image  
generation

image  
completion

image  
classification

## From language to vision

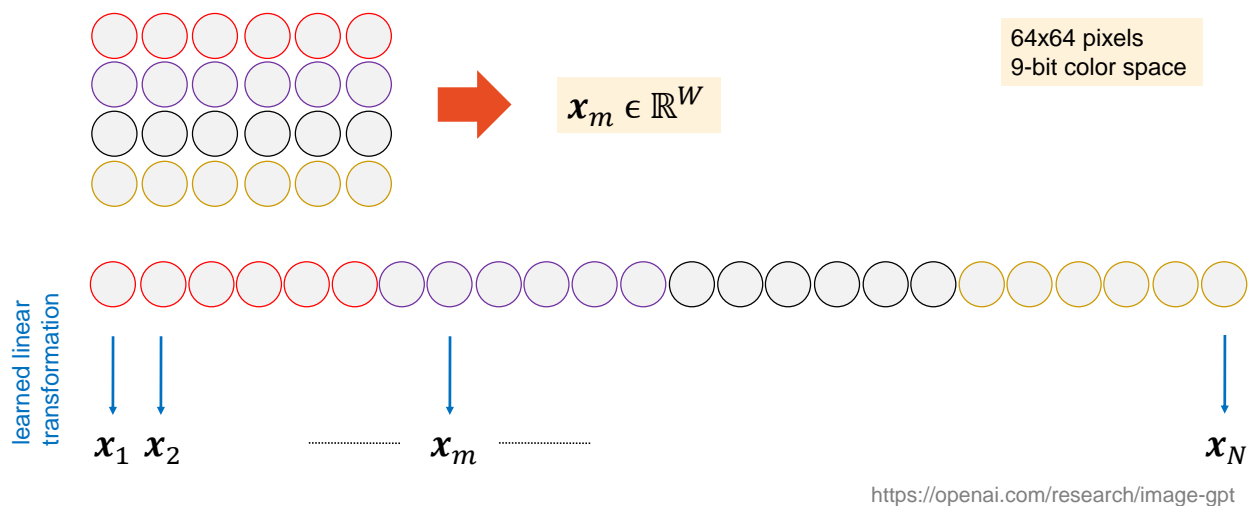


domain  
differences

visual entities:  
large scale  
variations

high resolution  
of pixels  
(compared  
to words)

# imageGPT – transformer decoder



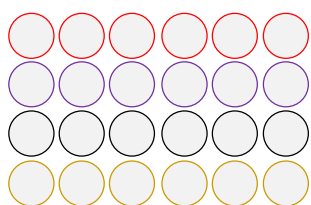
Sample generated images



Sample completed images



## Vision transformer

 $x_1$  $x_2$  $x_m$  $x_N$ learned linear  
transformation

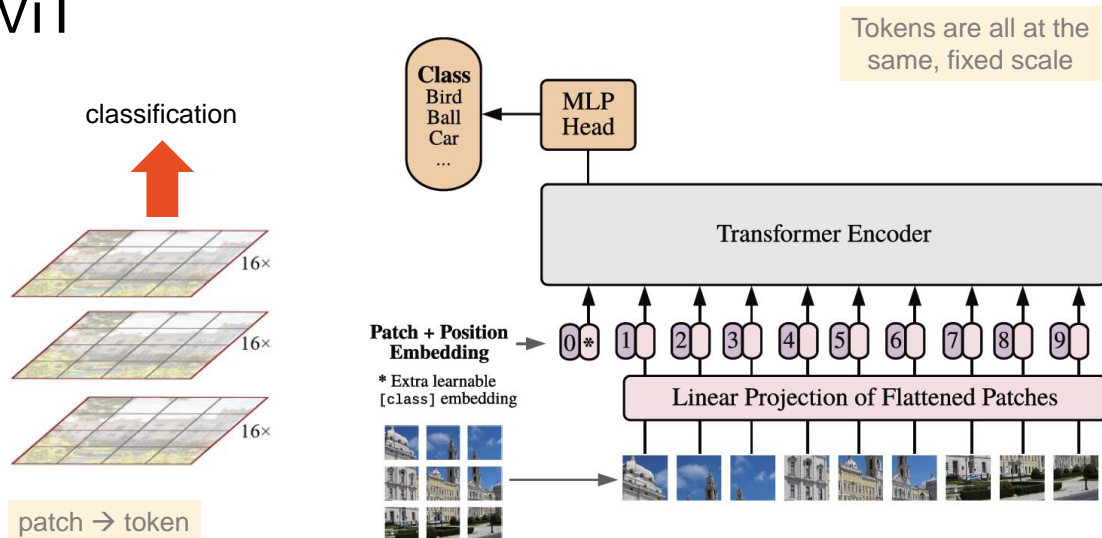
$$p_m \in \mathbb{R}^{P \times P}$$

$$P = 16$$

$$x_m \in \mathbb{R}^W$$

**Concepts:** Learned 1D positional encoding, single scale,  
supervised training on 303,000,000 labelled images of 18,000 classes

## ViT

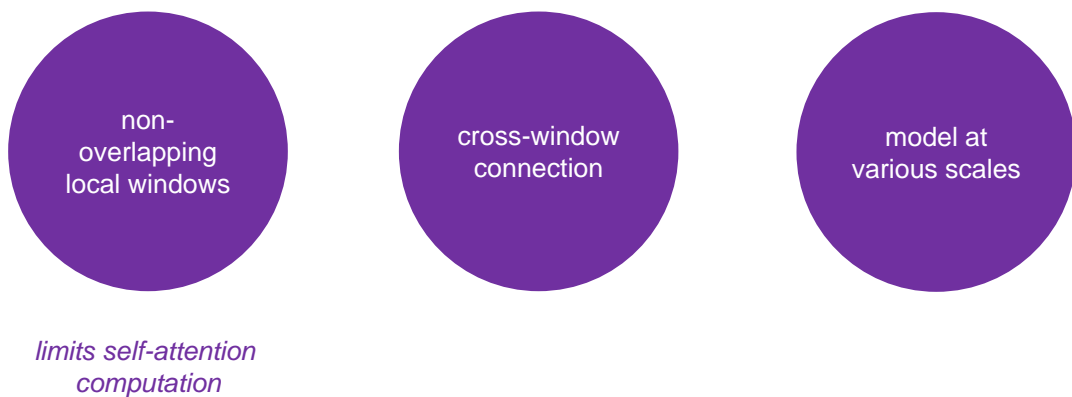


[arXiv:2010.11929](https://arxiv.org/abs/2010.11929)

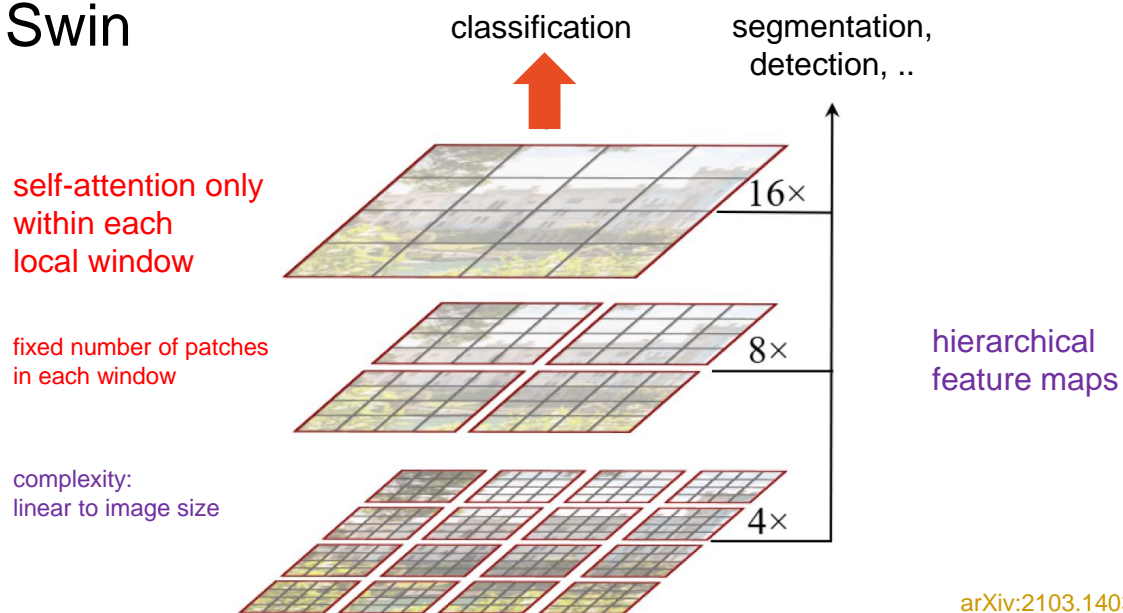
## Scale



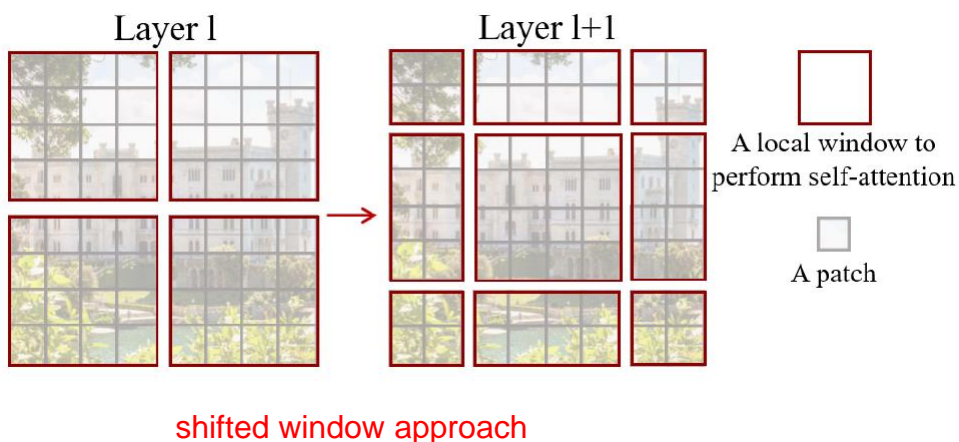
# Scale: hierarchical architecture



## Swin

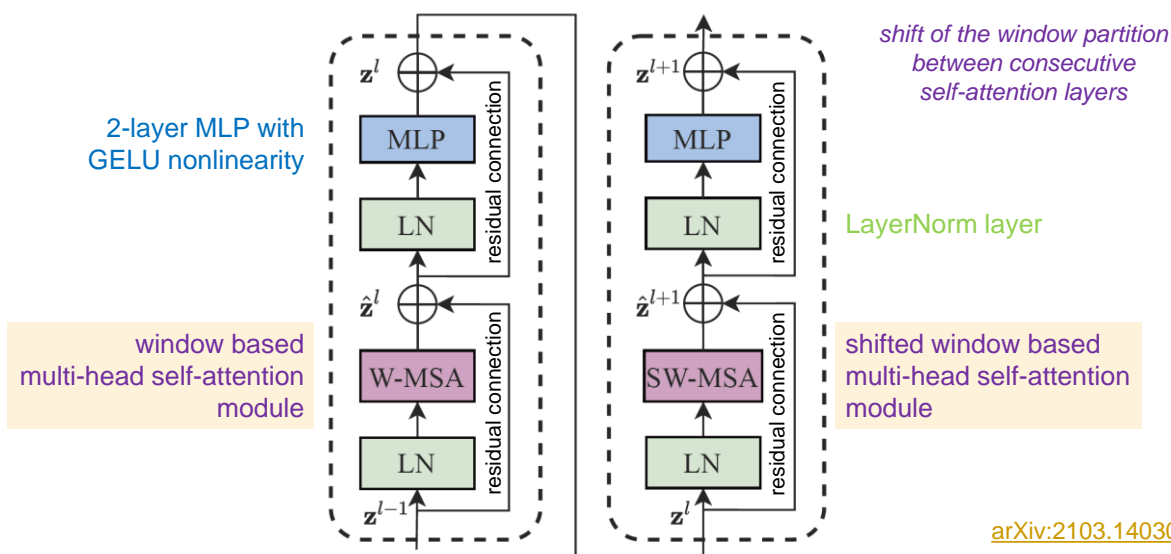


## Cross-window connection



[arXiv:2103.14030](https://arxiv.org/abs/2103.14030)

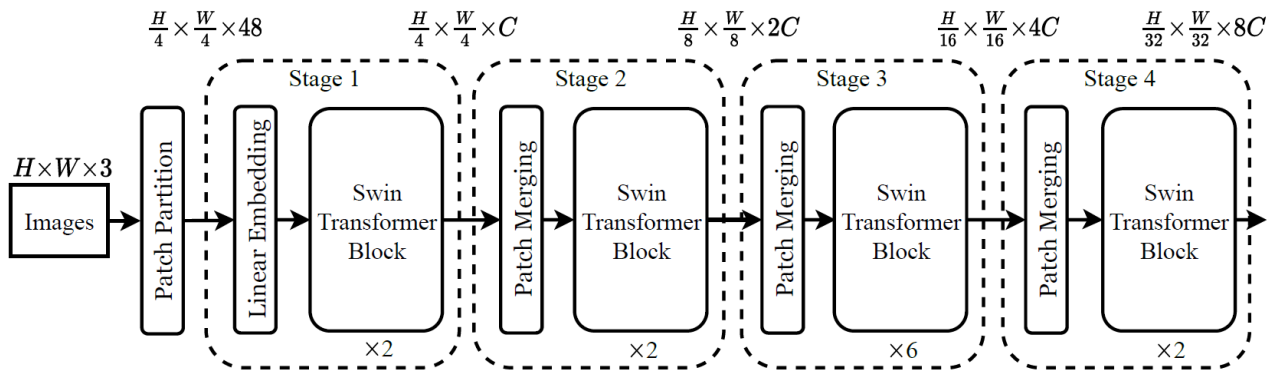
## Consecutive Swin transformer blocks



[arXiv:2103.14030](https://arxiv.org/abs/2103.14030)

# Swin architecture

$H$ : image height  
 $W$ : image width  
 $C$ : size of the embedding

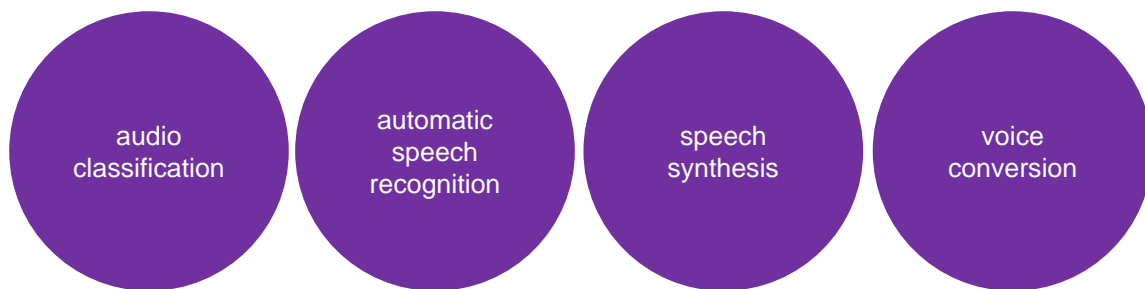


*gradually merging neighboring patches in deeper transformer layers*

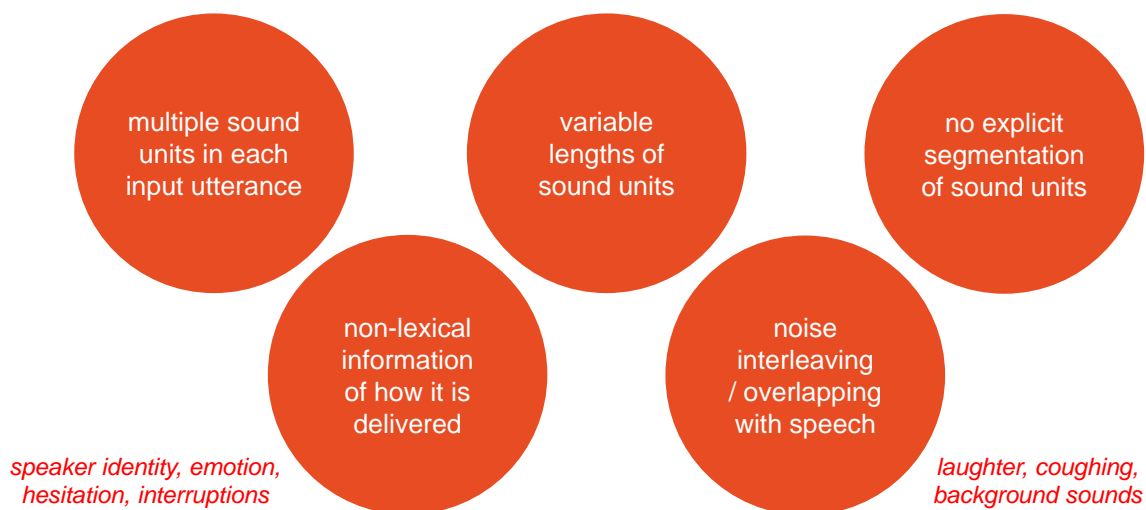
[arXiv:2103.14030](https://arxiv.org/abs/2103.14030)

# Audio transformer

## Transformers for audio tasks



## Speech representation learning



# Hidden-Unit BERT (HuBERT)

predict  
predetermined  
cluster  
assignments

learn  
representation  
of unmasked  
inputs

capture  
long-range  
temporal  
relations

*self-supervised representation learning with access to speech-only data*

[arXiv:2106.07447](https://arxiv.org/abs/2106.07447)

# Hidden-Unit BERT (HuBERT)

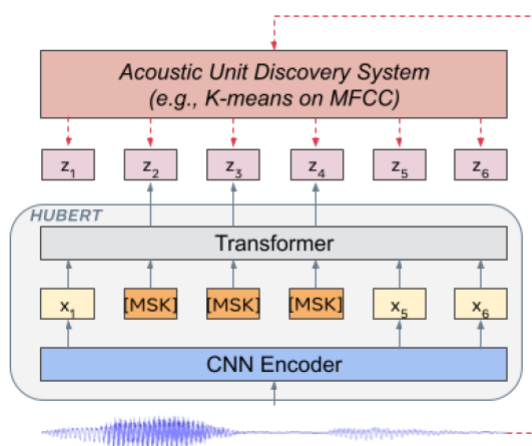
learn a **combined  
acoustic & language  
model** over the  
continuous inputs

prediction loss over  
the masked regions only

*K-means*: clustering

*MFCC*: Mel Freq. Cepstral Coefficients

*CNN*: Convolutional Neural Network

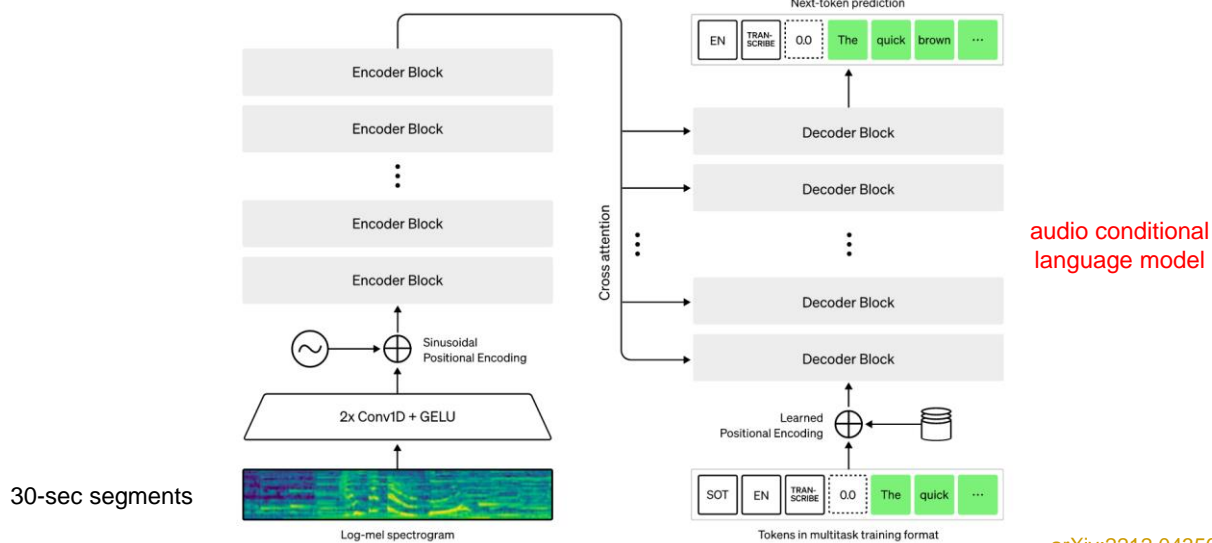


offline clustering  
( $K=100$ )  
provides aligned  
target labels

self-supervised speech  
representation learning

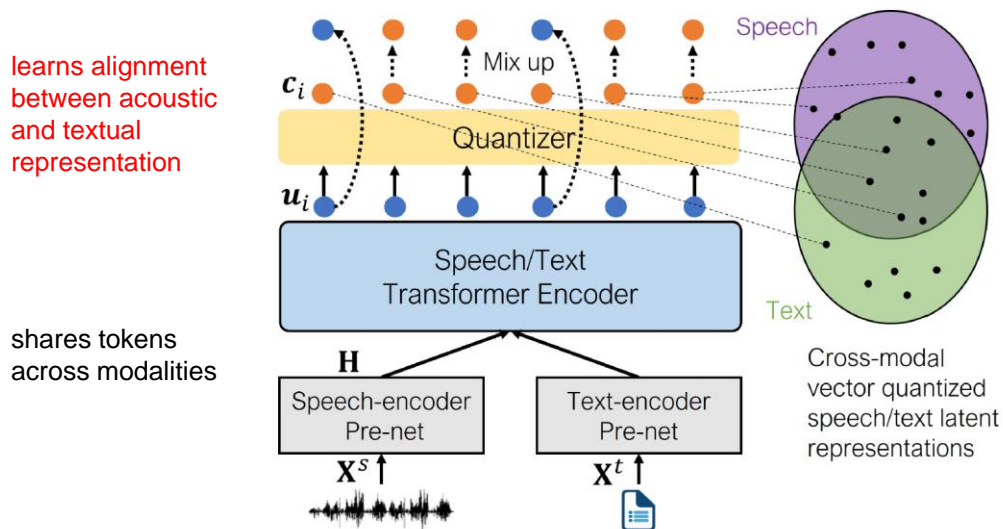
[arXiv:2106.07447](https://arxiv.org/abs/2106.07447)

# Whisper



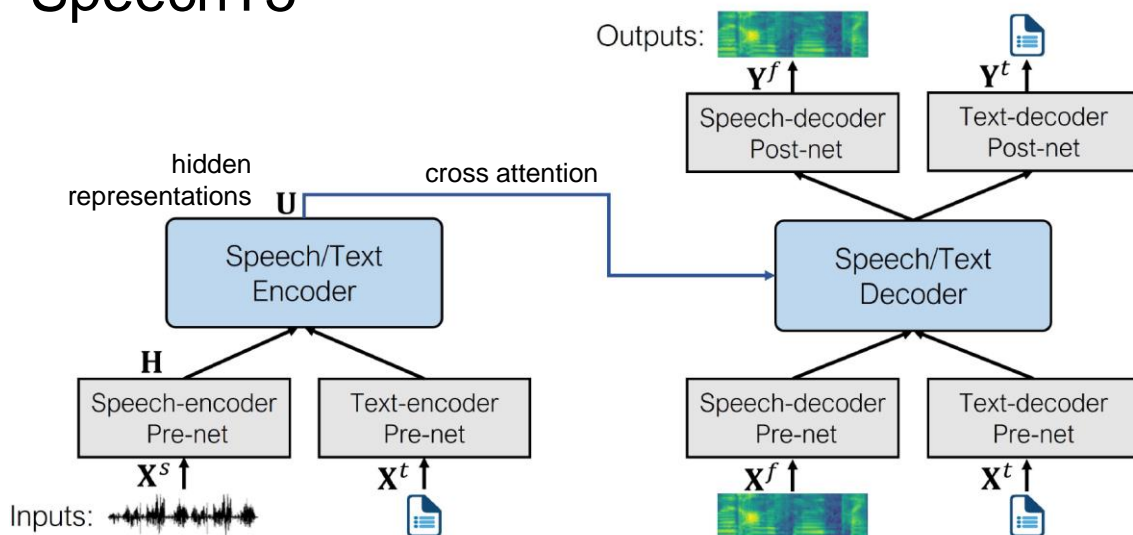
*“[...] problems such as getting stuck in repeat loops, not transcribing the first or last few words of an audio segment, or complete hallucination where the model will output a transcript entirely unrelated to the actual audio.”*

# SpeechT5: joint pre-training



[arXiv:2110.07205](https://arxiv.org/abs/2110.07205)

## SpeechT5



[arXiv:2110.07205](https://arxiv.org/abs/2110.07205)

slido

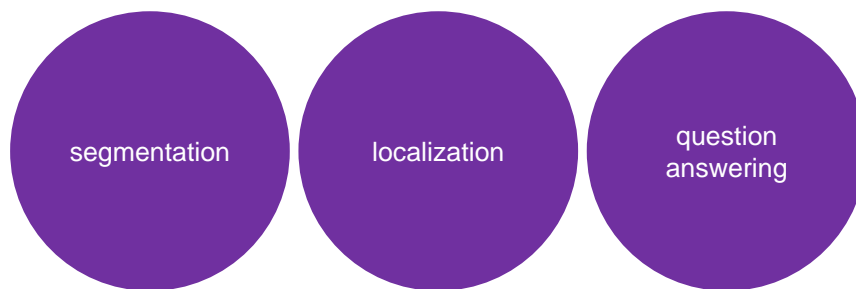


Would you like to ask any questions about your mini-project?

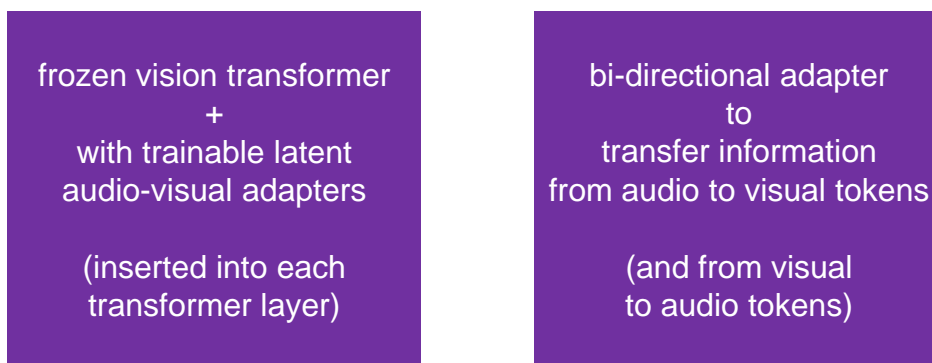
① Start presenting to display the poll results on this slide.

# Audio-visual transformer

# Transformers for audio-visual tasks

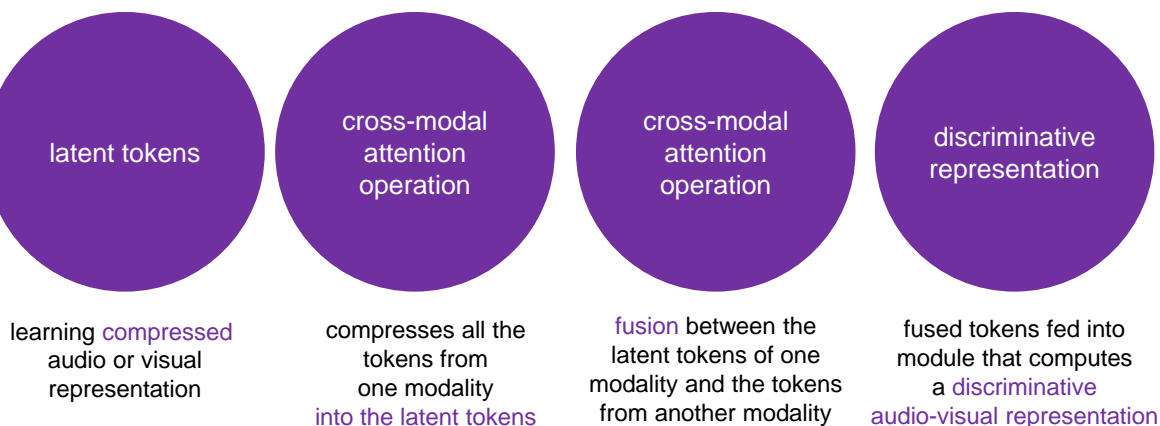


## Audio-visual fusion



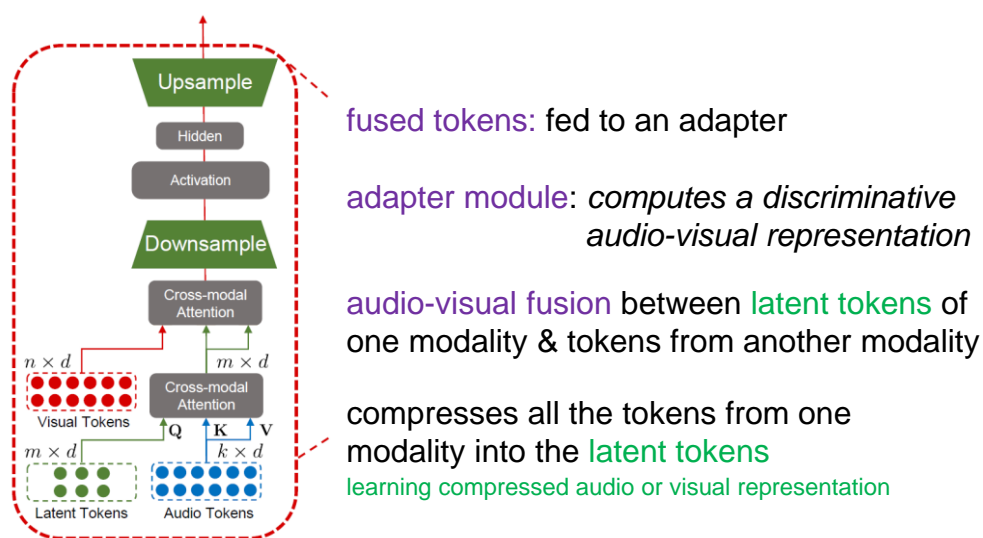
[arXiv:2212.07983](https://arxiv.org/abs/2212.07983)

## Adapter: four high-level components

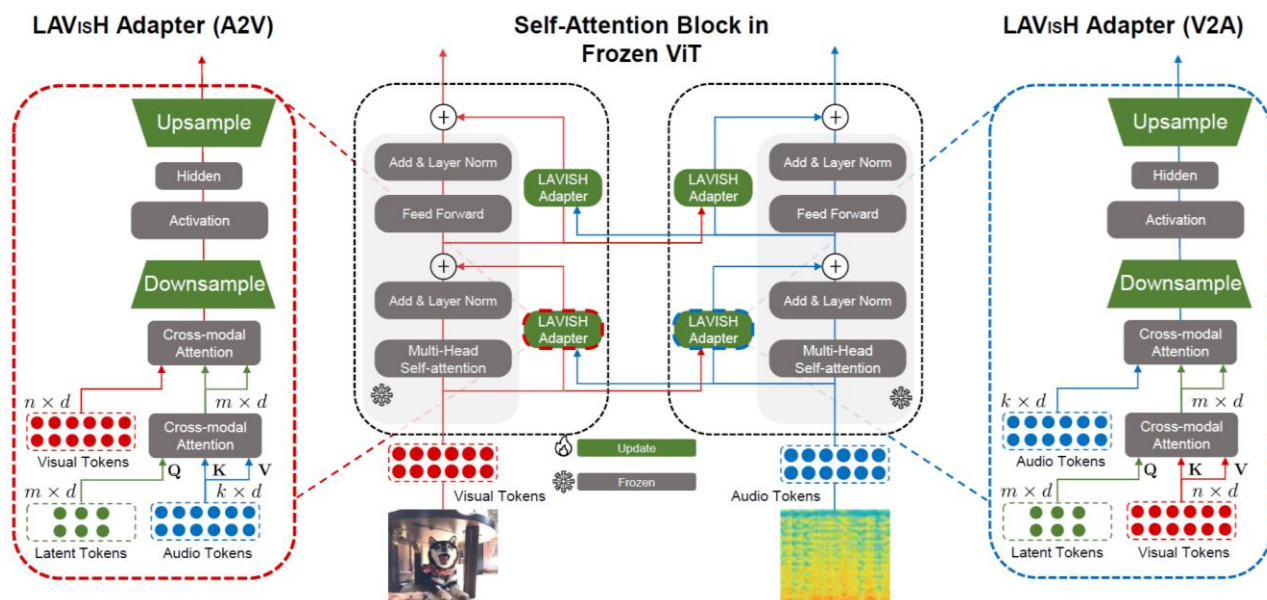


[arXiv:2212.07983](https://arxiv.org/abs/2212.07983)

## Audio to visual adapter



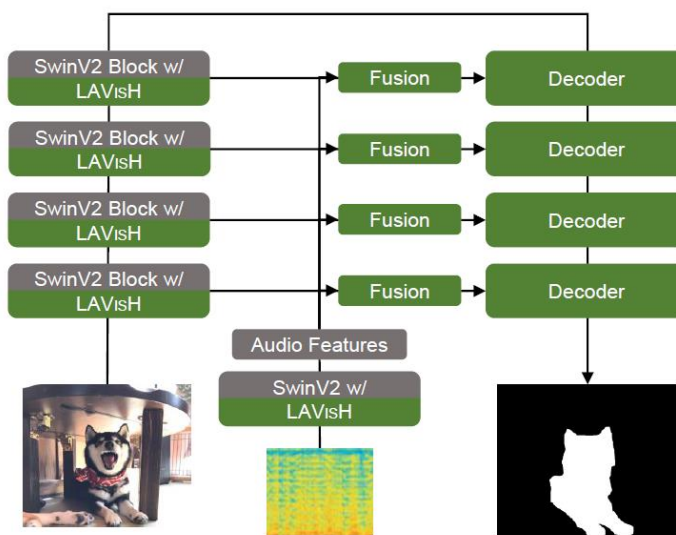
[arXiv:2212.07983](https://arxiv.org/abs/2212.07983)



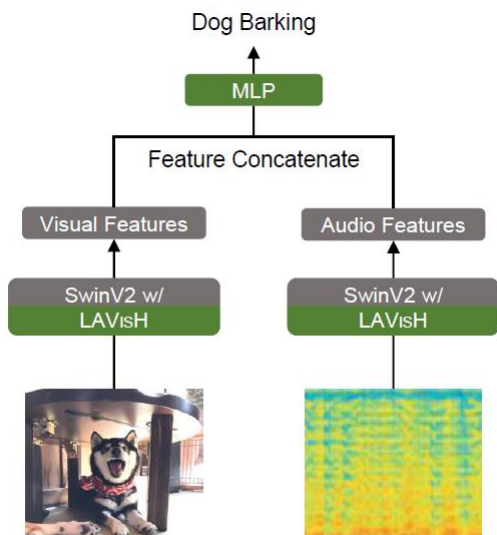
LAViSH: latent audio-visual hybrid

[arXiv:2212.07983](https://arxiv.org/abs/2212.07983)

## Audio-visual segmentation

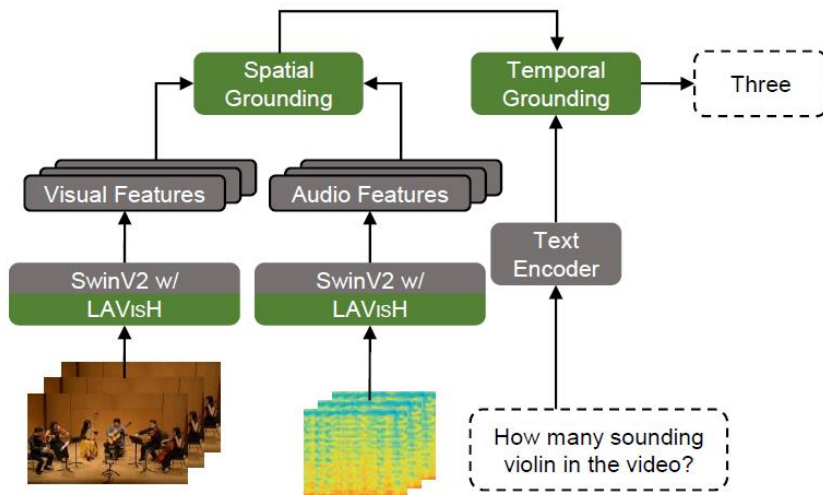
[arXiv:2212.07983](https://arxiv.org/abs/2212.07983)

## Audio-visual event localization



[arXiv:2212.07983](https://arxiv.org/abs/2212.07983)

## Audio-visual question answering



[arXiv:2212.07983](https://arxiv.org/abs/2212.07983)

# Vision and language models

CM3Leon



image  
tokenizer

256 × 256 image  
1024 tokens from  
vocabulary of 8192

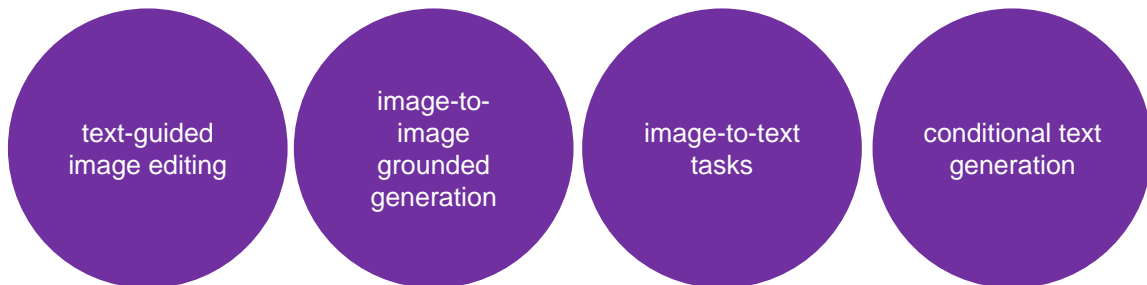


text  
tokenizer

vocabulary size of 56320  
special token `<break>`  
to indicate a transition  
between modalities

[arXiv:2309.02591](https://arxiv.org/abs/2309.02591)

## CM3Leon: enabled tasks

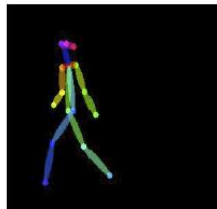


## Text-guided image editing



[arXiv:2309.02591](https://arxiv.org/abs/2309.02591)

# Image-to-image grounded generation



Extracted (openpose) pose



"Businessman in city street"



"A boy running on the grass of a soccer field"



"Young girl running on mountain trail with wild flowers"



"Beautiful women walking on the beach at sunset"

[arXiv:2309.02591](https://arxiv.org/abs/2309.02591)

# Image-to-text tasks



**Caption:** Describe the given image

**Long Caption:** Describe the given image in very detail

**VQA:** Question: what time of the day is the photo taken?

**Reasoning:** Question: Does this passage describe the weather or the climate? Context: Figure: Des Moines. The temperature recorded ...Please explain your answer.



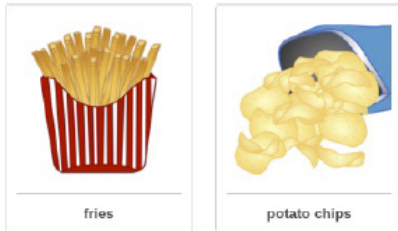
A beautiful view of a city from across a river.

A view of tall buildings in a city. The photo is taken from a park across a river. We can see a bridge over the river.

Sunset time

Weather. Because the atmosphere is the layer of air that surrounds Earth. Both weather and climate tell you about the atmosphere. ...

# Conditional text generation



Instruction: Question: Which property do these two objects have in common?

Context: Select the best answer.

Options: (A) shiny (B) salty

Answer: Let's think step-by-step:

CM3Leon Output: Think about each object. Potato chips have a salty taste. The pretzel is salty. So the answer is (B).

[arXiv:2309.02591](https://arxiv.org/abs/2309.02591)

# Conditional text generation

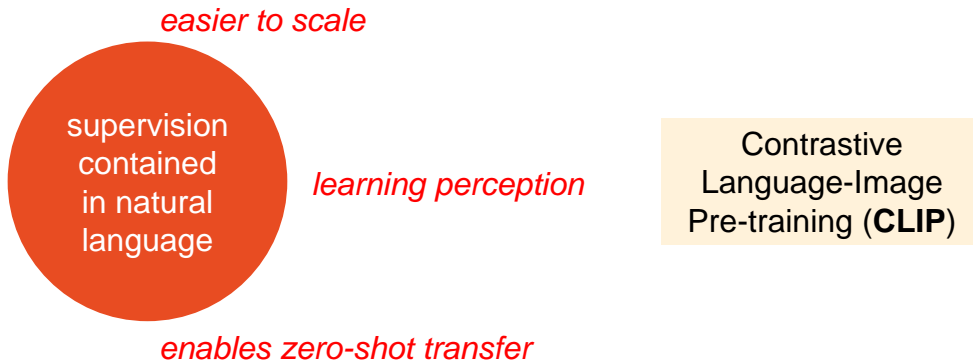


Instruction: Describe all the objects in the given image in very detail.

CM3Leon Output: A street sign is on a metal pole. The sign is blue with white writing. There is a red light on the pole. The sky is a bright blue. There are cars parked on the street. There are trees on the side of the street. There are buildings on the side of the street.

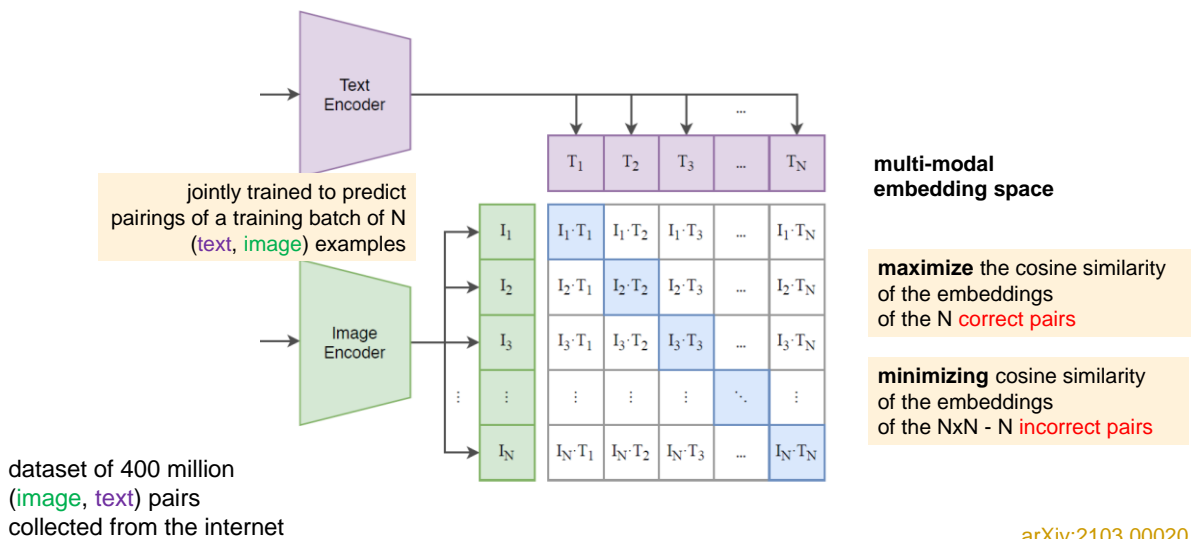
[arXiv:2309.02591](https://arxiv.org/abs/2309.02591)

# Natural language as a training signal

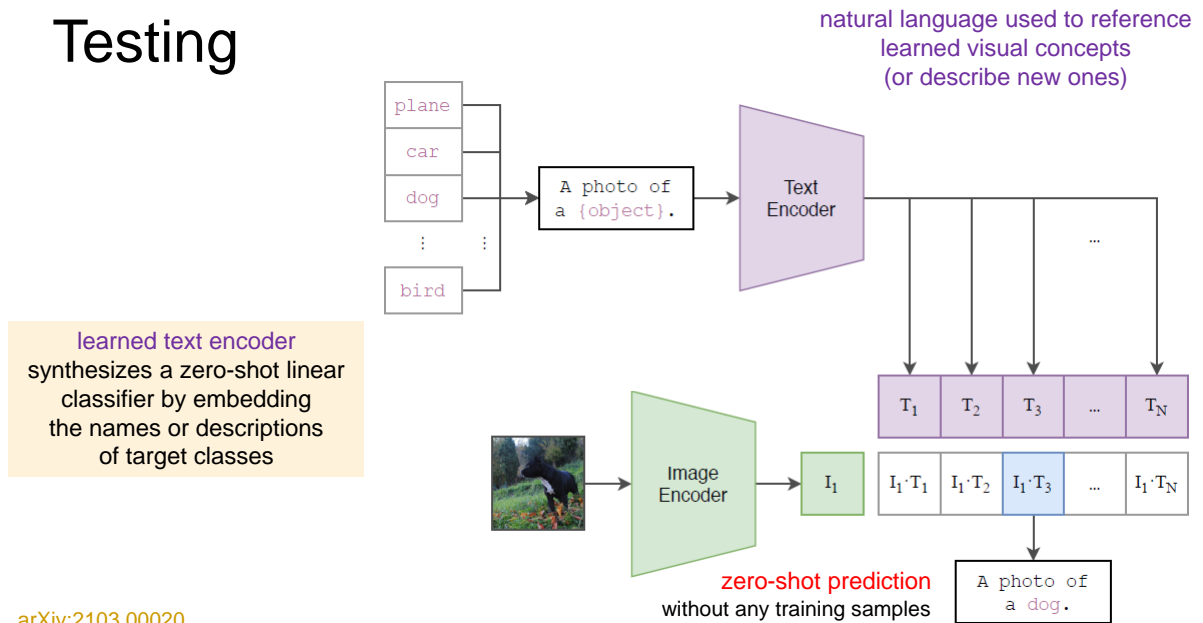


[arXiv:2103.00020](https://arxiv.org/abs/2103.00020)

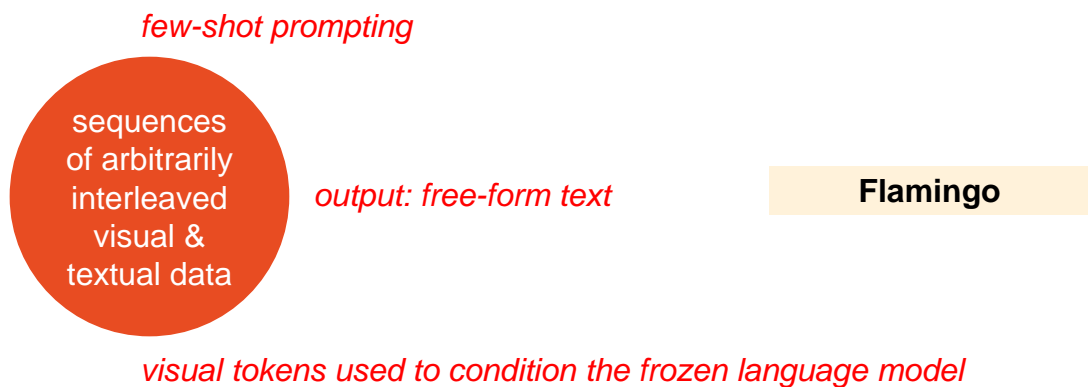
## Contrastive language-image pre-training



# Testing



## VLM for few-shot learning

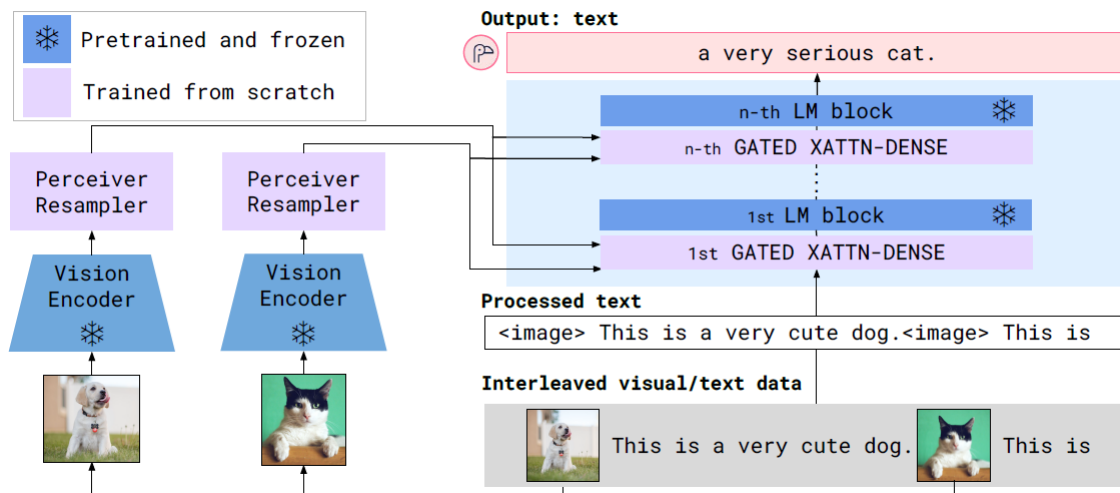


VLM: Vision and Language Model

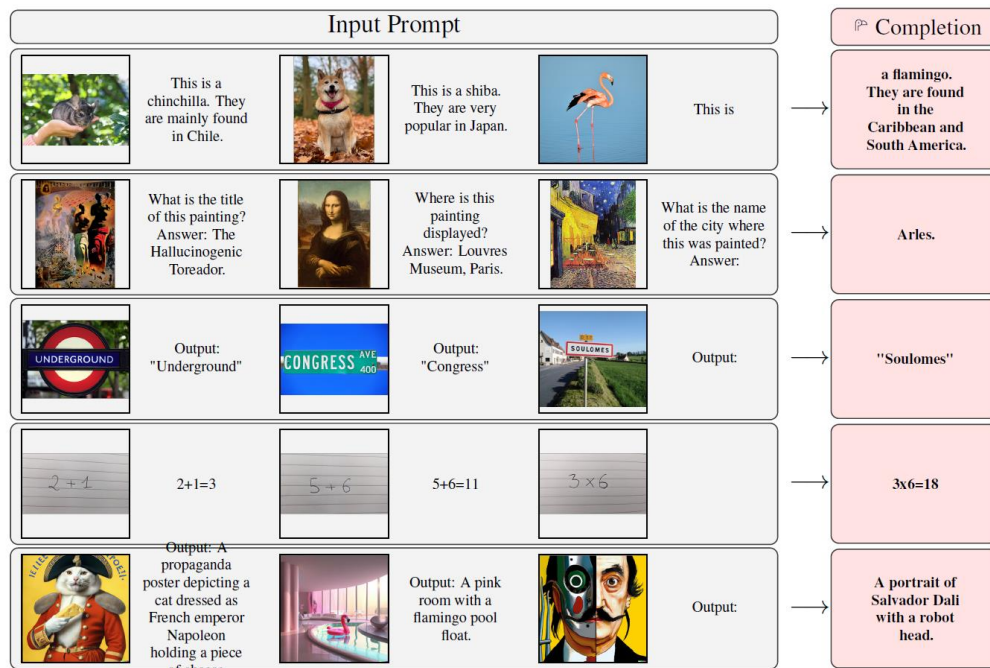
arXiv:2204.14198

# Architecture overview

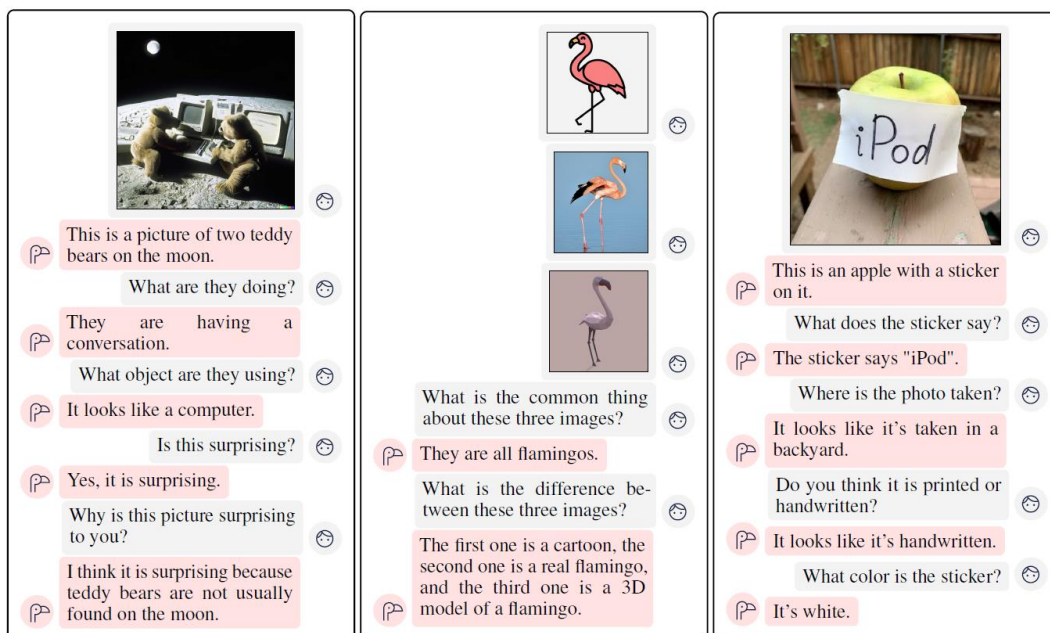
visual tokens condition  
the frozen language model



[arXiv:2204.14198](https://arxiv.org/abs/2204.14198)

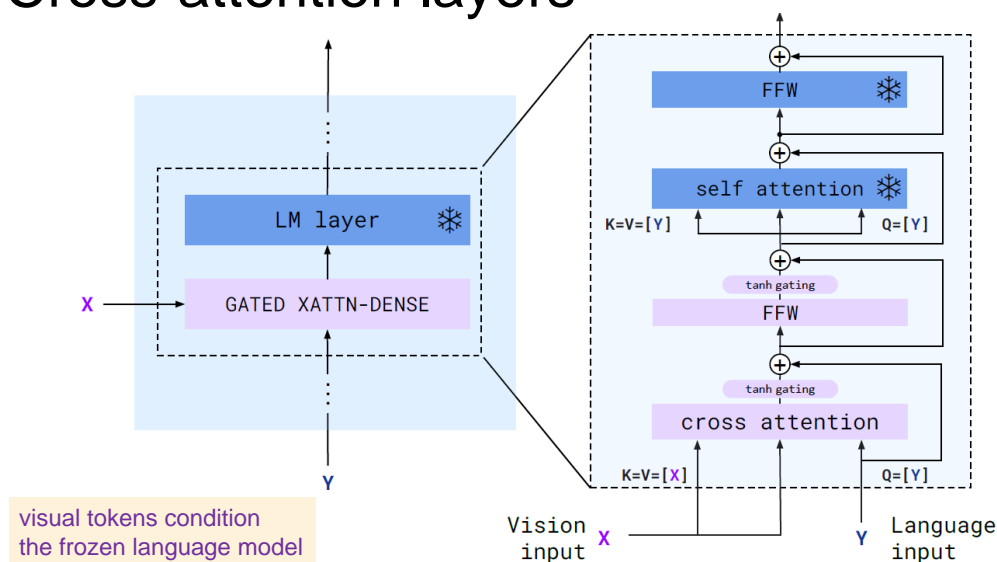


[arXiv:2204.14198](https://arxiv.org/abs/2204.14198)



arXiv:2204.14198

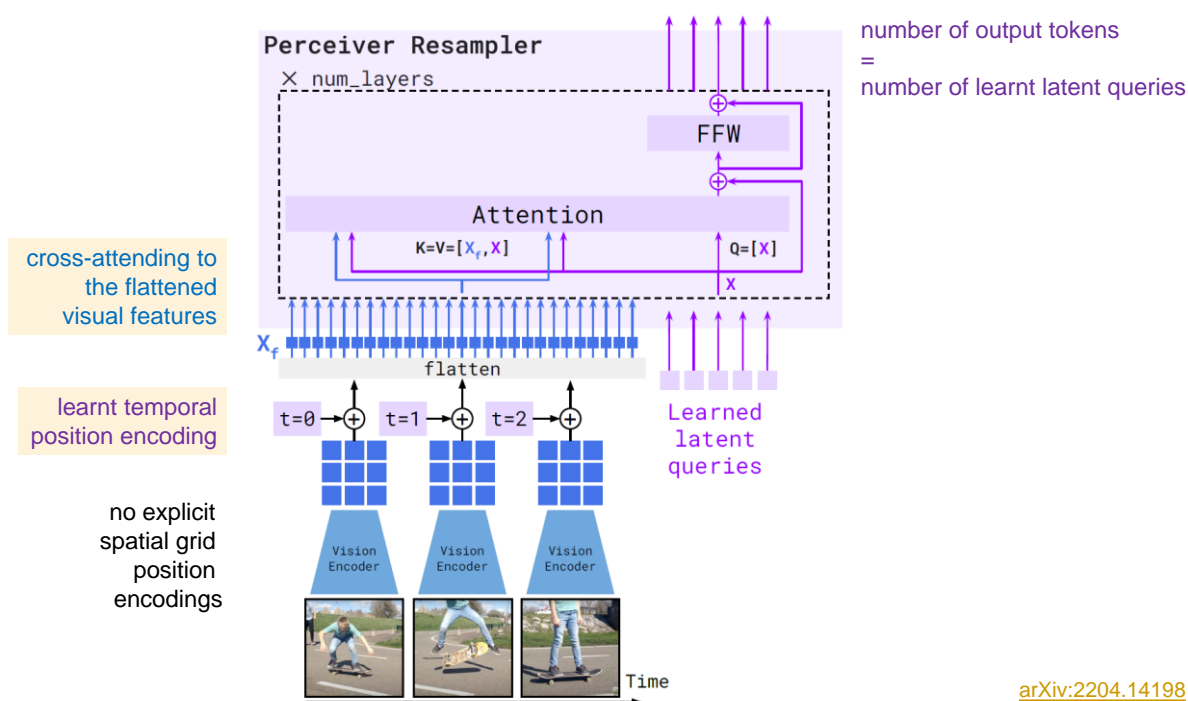
## Cross-attention layers



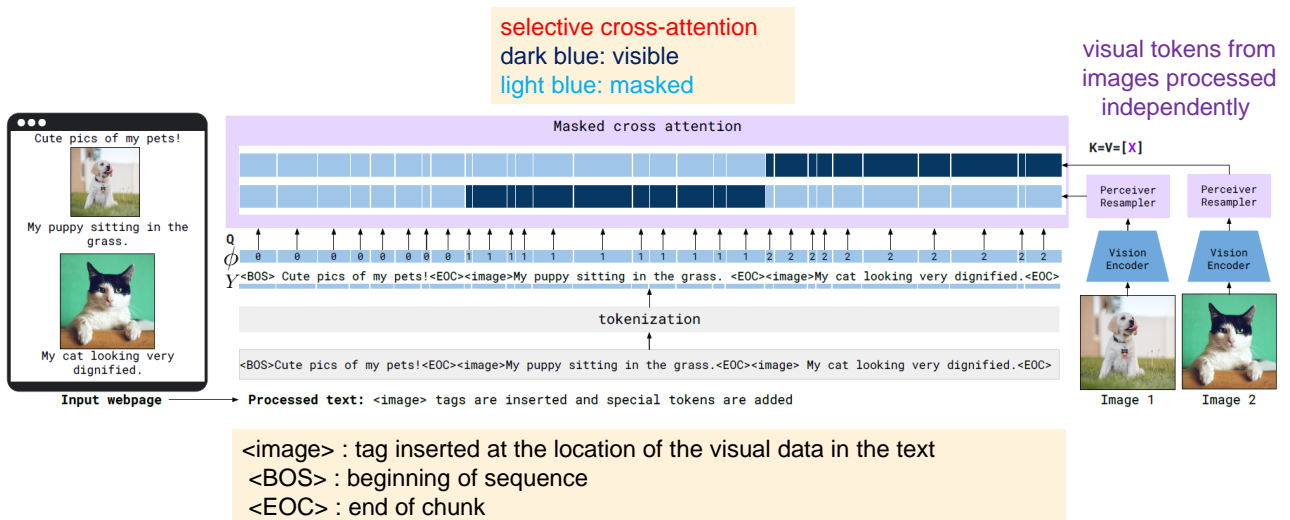
arXiv:2204.14198

*“Future work is required to better understand the effect of these added layers on the optimization dynamics and on the model itself.”*

[arXiv:2204.14198](https://arxiv.org/abs/2204.14198)



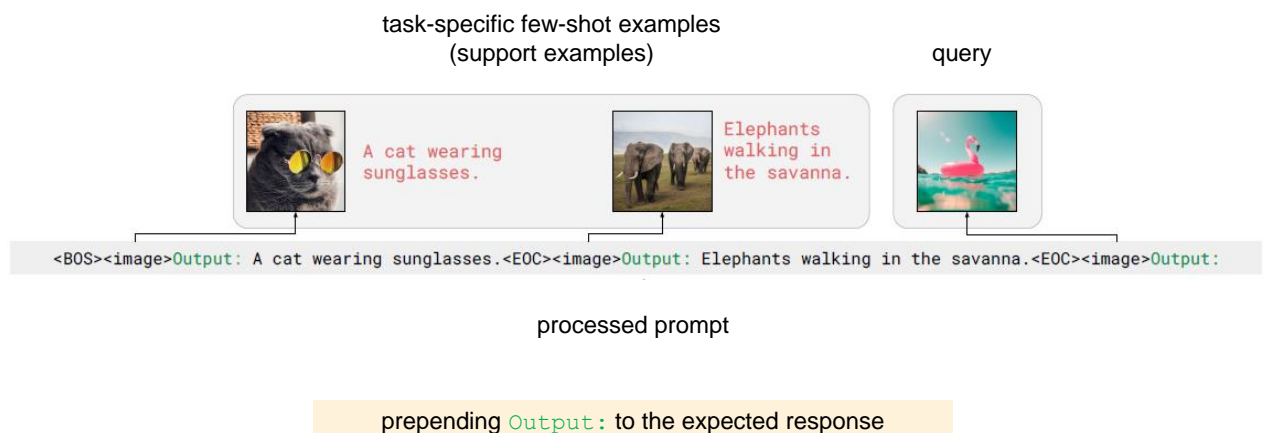
# Text interleaved with images/videos



[arXiv:2204.14198](https://arxiv.org/abs/2204.14198)

## Vision-to-text task

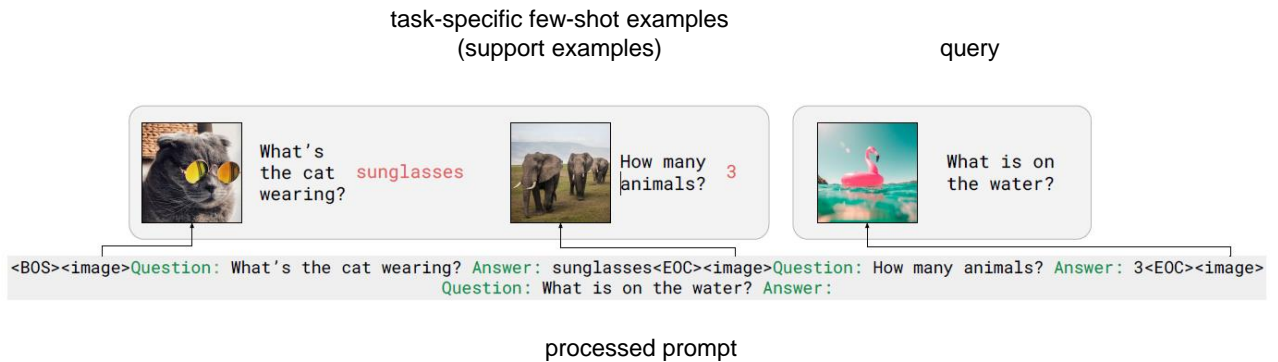
input: vision  
output: text



[arXiv:2204.14198](https://arxiv.org/abs/2204.14198)

# Visual question answering task

input: vision + text  
output: text

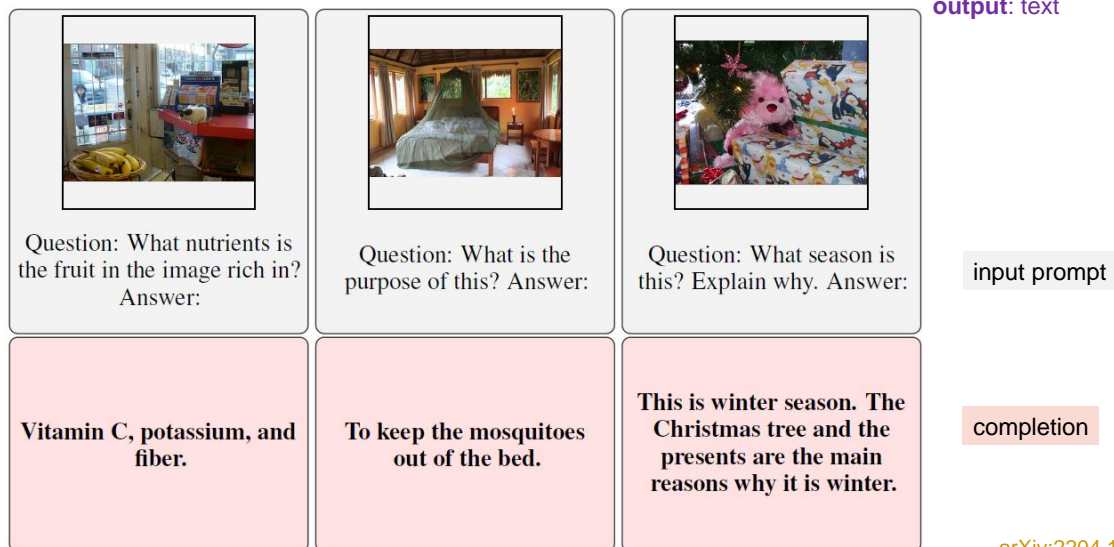


prompting in the format "Question: {question} Answer: {answer}"

[arXiv:2204.14198](https://arxiv.org/abs/2204.14198)

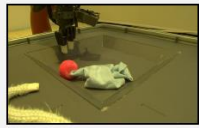
## Simple form of interaction

input: single image + text prompt  
(question or start of a caption)  
output: text



[arXiv:2204.14198](https://arxiv.org/abs/2204.14198)

# Dialogue



What do you think the robot is doing here?

The robot is picking up a ball.

What color is the ball?

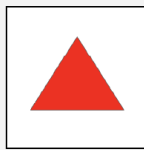
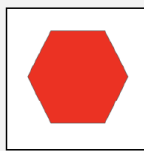
It's red.

I want the ball to be hidden. Is there something the robot can use for that?

The robot can use a cloth to hide the ball.

What color is the cloth?

The cloth is blue.

What is the difference between these two images?

The first one is a triangle and the second one is a hexagon.

Which one has larger internal angles?




The hexagon has larger internal angles.

What color are they?

They are both red.

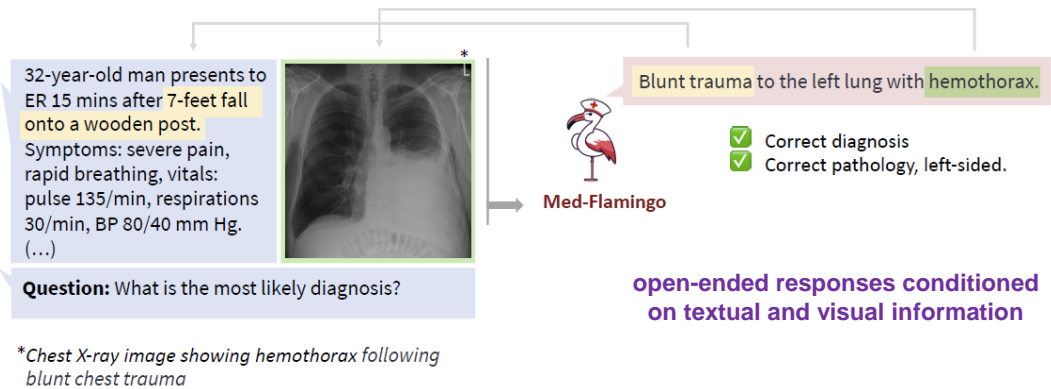
[arXiv:2204.14198](https://arxiv.org/abs/2204.14198)

# Hallucinations

input prompt	 <p>Question: What is on the phone screen? Answer:</p>	 <p>Question: What can you see out the window? Answer:</p>	 <p>Question: Whom is the person texting? Answer:</p>
output	A text message from a friend.	A parking lot.	The driver.

[arXiv:2204.14198](https://arxiv.org/abs/2204.14198)

# Medical generative vision-language model



in-context learning

[arXiv:2307.15189](https://arxiv.org/abs/2307.15189)

# Exercises

# Today's exercise

## Practice.

You will become familiar with **multimodal transformer**: text with categorical and numerical features for classification

## What did we learn today?

- Vision transformer
- Audio transformer
- Audio-visual transformer
- Vision and language models
- Exercises

# EE-559

# Deep Learning

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