

# EE-465 - W5 3-PHASE VSI CARRIER BASED PWM

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# EE-465 INVERTER STAGE

We will look into:

- ▶ 2L VSI operating principles
- ▶ Carrier-based PWM
- ▶ Zero-sequence injection principles
- ▶ Other multilevel topologies

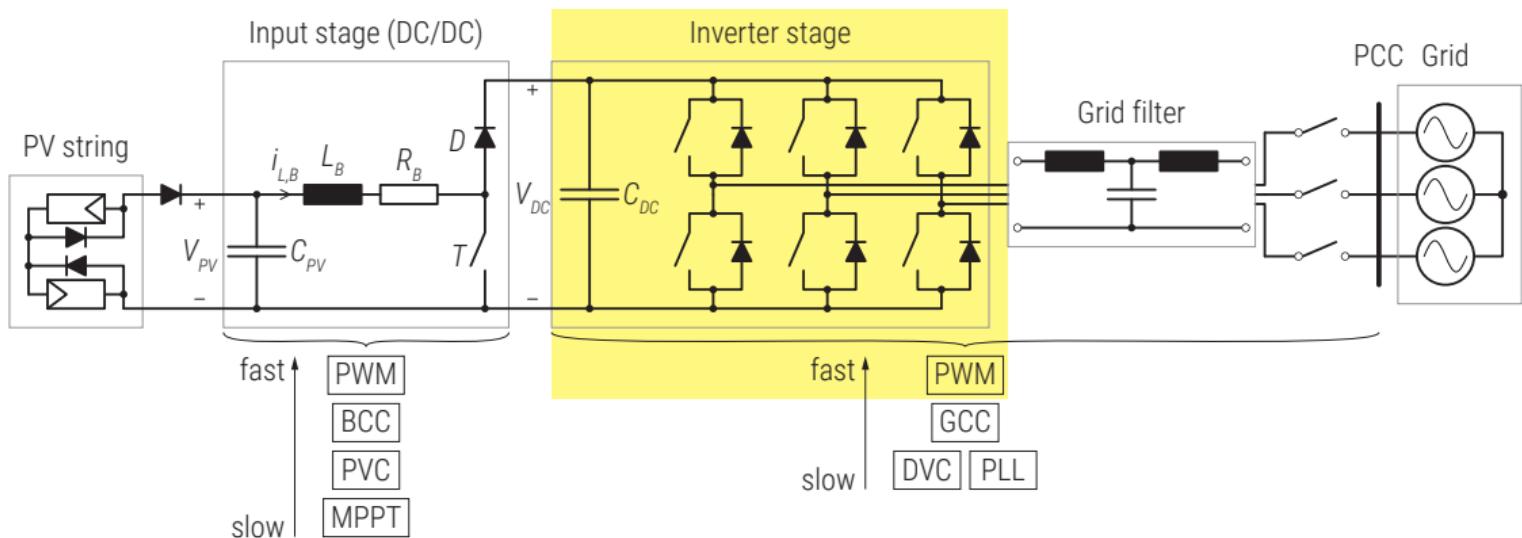
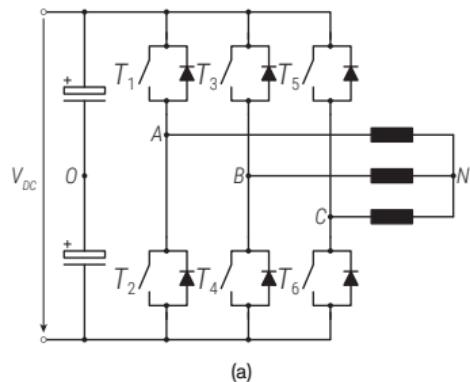


Figure 1 PV double-stage grid connected converter.

# 3-PHASE 2-L INVERTER

- ▶ Obtained by combining  $3 \times 2\text{-L}$  phase-legs
- ▶  $N$  and  $O$  are not connected together! - but can be used as references for various calculations
- ▶ 3-phase load can be brought in only a limited number of configurations
- ▶ 3-phase 2-level inverter has only 8 switching states (configurations)



(a)

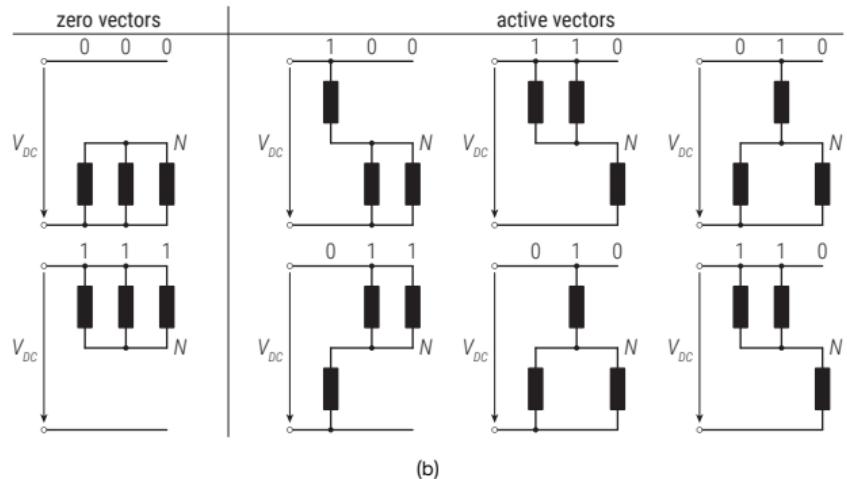


Figure 2 (a) 2L three-phase inverter scheme and (b)  $2^3 = 8$  switch combinations.

# 3-PHASE 2-L INVERTER

Table 1 Instantaneous phase to neutral and common mode voltages for all 8 space vectors, assuming identical phase impedances  $Z$ .

	$s_A$	$s_B$	$s_C$	$v_{AN}$	$v_{BN}$	$v_{CN}$	$v_{NO}$
$\mathbf{V}_0$	0	0	0	0	0	0	$-V_{DC}/2$
$\mathbf{V}_1$	1	0	0	$2V_{DC}/3$	$-V_{DC}/3$	$-V_{DC}/3$	$-V_{DC}/6$
$\mathbf{V}_2$	1	1	0	$V_{DC}/3$	$V_{DC}/3$	$-2V_{DC}/3$	$V_{DC}/6$
$\mathbf{V}_3$	0	1	0	$-V_{DC}/3$	$2V_{DC}/3$	$-V_{DC}/3$	$-V_{DC}/6$
$\mathbf{V}_4$	0	1	1	$-2V_{DC}/3$	$V_{DC}/3$	$V_{DC}/3$	$V_{DC}/6$
$\mathbf{V}_5$	0	0	1	$-V_{DC}/3$	$-V_{DC}/3$	$2V_{DC}/3$	$-V_{DC}/6$
$\mathbf{V}_6$	1	0	1	$V_{DC}/3$	$-2V_{DC}/3$	$V_{DC}/3$	$V_{DC}/6$
$\mathbf{V}_7$	1	1	1	0	0	0	$V_{DC}/2$

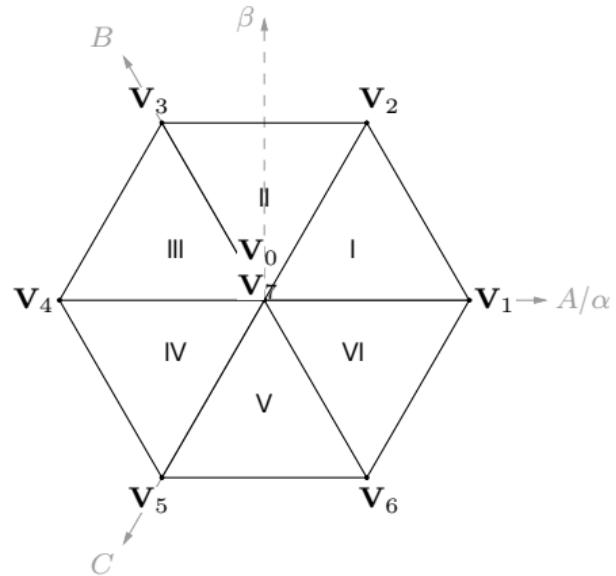


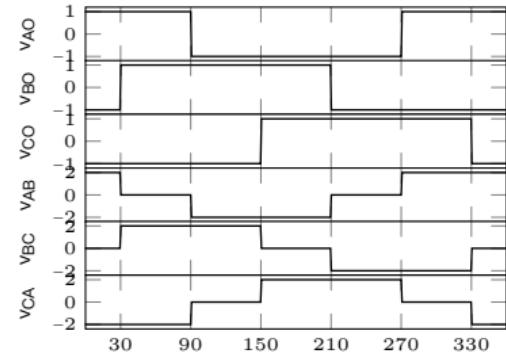
Figure 3 Voltage synthesis capability for a 2-L 3-ph inverter.

# SQUARE-WAVE (SIX-STEP) OPERATION FOR 2-L INVERTERS

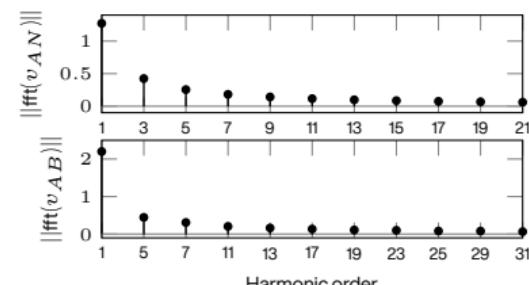
- ▶ Leg voltage is a simple square-wave type - contains all odd harmonics
- ▶ Only the active vectors are used (6 out of 8)
- ▶ Each leg is driven by  $180^\circ$  pulse,  $120^\circ$  delay between the phase-legs
- ▶ It is described by a geometric progression. In phase  $a$ , the voltage with respect to the negative bus terminal is:

$$v_A(t) = V_{DC} \frac{2}{\pi} \left( \frac{\pi}{4} + \frac{1}{3} \sin(3\omega_0 t) + \frac{1}{5} \sin(5\omega_0 t) + \dots \right)$$

- ▶ The magnitudes of the harmonics are  $\|v[k]\|_{\text{phase}} = V_{DC} \frac{2}{\pi} \frac{1}{k}, k \in \{1, 3, 5, \dots\}$
- ▶ Line-to-line voltage can be determined by subtracting phase voltages, leading to cancellation of triplen harmonics:  $v_{AB}(t) = V_{DC} \frac{2\sqrt{3}}{\pi} \left( \sin(\omega_0 t + \pi/6) + \frac{1}{5} \sin(5\omega_0 t - \pi/6) + \frac{1}{7} \sin(7\omega_0 t + \pi/6) + \dots \right)$
- ▶ The magnitudes of the harmonics are  $\|v[k]\|_{\text{line}} = V_{DC} \frac{2\sqrt{3}}{\pi} \frac{1}{k}, k \in \{1, 5, 7, \dots\}$
- ▶ Inverter does frequency control / voltage control through external DC link control
- ▶  $M = 4/\pi \approx 1.27$



(a)



(b)

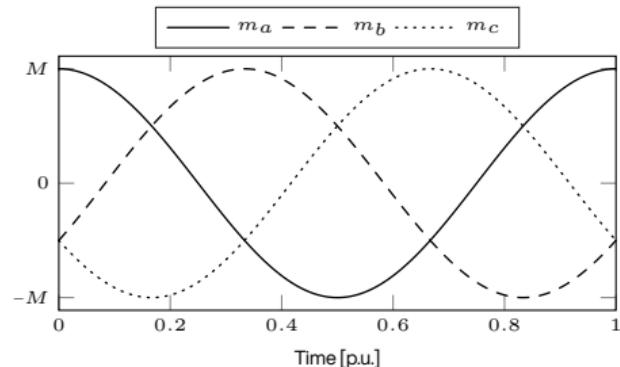
# SINUSOIDAL PWM - SPWM

- ▶ Normally, we want sinusoidal line-to-line voltages
- ▶ Fundamental three-phase reference signals:

$$\begin{cases} v_a^* = V_m \cos(\omega t) \\ v_b^* = V_m \cos(\omega t - 2\pi/3) \\ v_c^* = V_m \cos(\omega t + 2\pi/3) \end{cases}$$

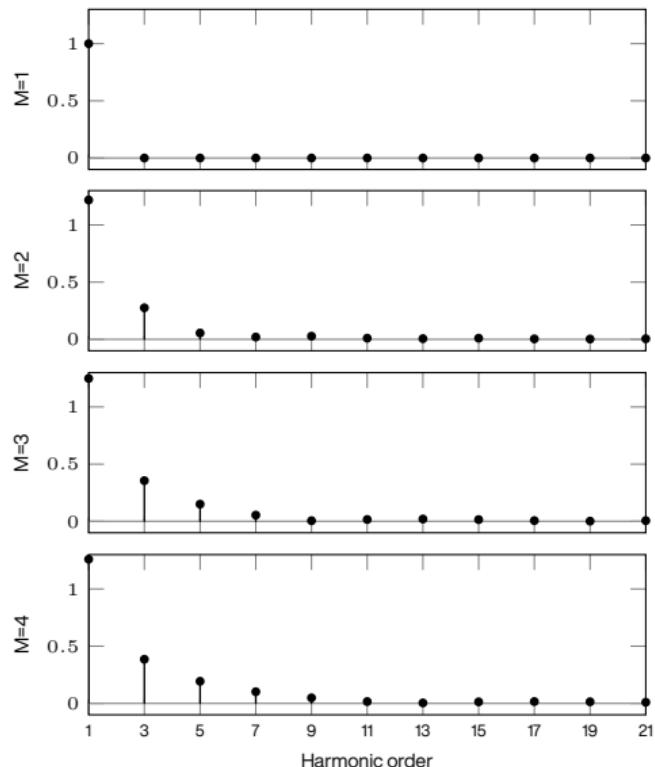
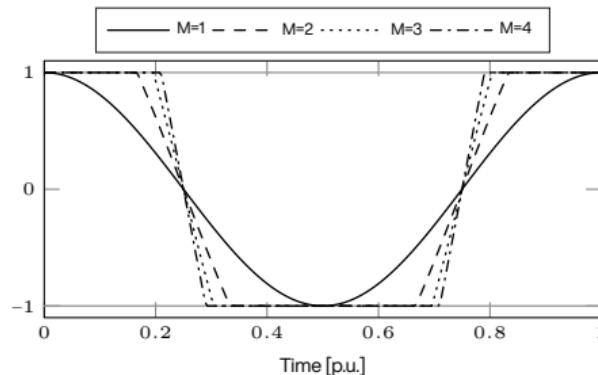
- ▶ The modulation index is defined as  $M = \frac{V_m}{V_{DC}/2}$
- ▶ It relates the output peak phase voltage and  $V_{DC}$
- ▶ Reference normalization:

$$\begin{cases} m_a^* = M \cos(\omega t) \\ m_b^* = M \cos(\omega t - 2\pi/3) \\ m_c^* = M \cos(\omega t + 2\pi/3) \end{cases}$$



# OVERMODULATION

- ▶ Normally, we have carrier bounded to  $\pm 1$  range
- ▶ SPWM is bounded by  $M_{\max} = 1$ , else low-order harmonics appear
- ▶ Non-triplet harmonics are difficult to filter out (low filter cut-off frequency required, means large filters!)
- ▶ In the worst case, it becomes six-step (square-wave) modulation



# ZERO-SEQUENCE INJECTION

- ▶ From power systems theory for three-phase system (if  $\omega = \text{cst}$ ): there exists a linear decomposition into positive, negative and zero sequence of balanced (with same amplitude) symmetrical components (with  $\pm 120^\circ$  shift)
- ▶ In star-connected systems, no zero-sequence current can flow  $\rightarrow$  degree of freedom to be used for extending the DC bus utilization, i.e. allow  $M_{\max} > 1$
- ▶ Zero-sequence component is obtained as:  $m_{zs} = (m_a + m_b + m_c)/3$

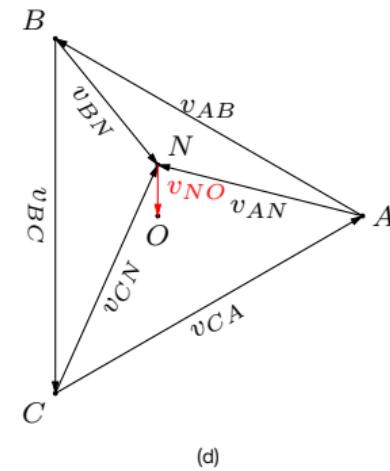
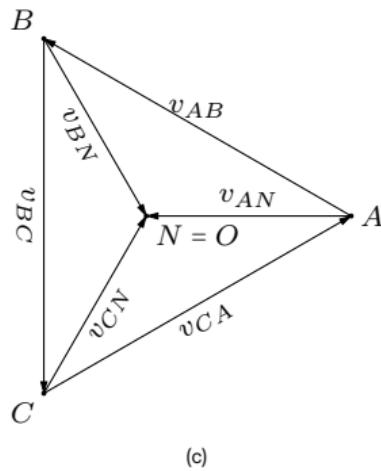


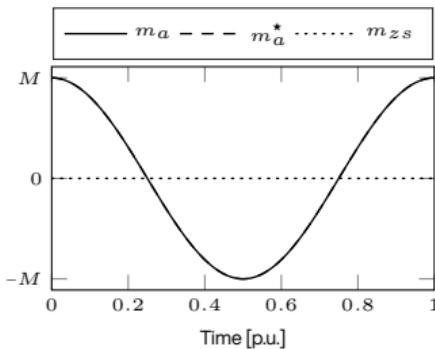
Figure 4 (a) no zero-sequence signal and (b) zero sequence signal, with line-to-line voltage preservation.

# ZERO SEQUENCE SIGNAL INJECTION

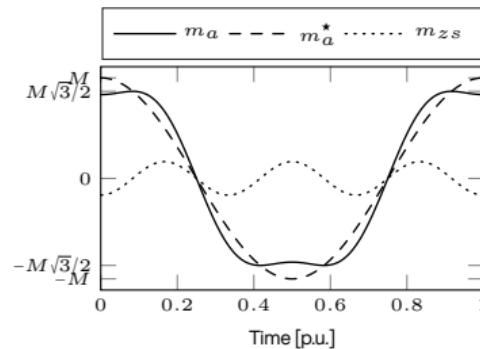
- The zero-sequence injection is defined as:

$$\begin{cases} m_a = M \cos(\omega t) + m_{zs} \\ m_b = M \cos(\omega t - 2\pi/3) + m_{zs} \\ m_c = M \cos(\omega t + 2\pi/3) + m_{zs} \end{cases}$$

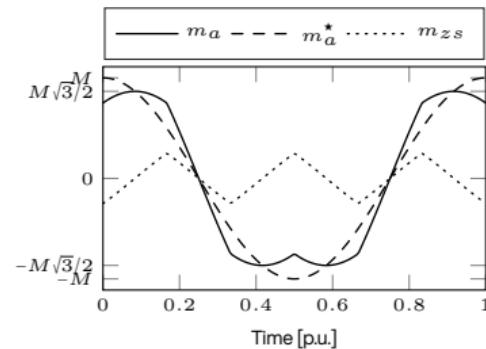
- The harmonic distortion will be reduced, as no low-order non triplen harmonics are injected, contrary to the six-step modulation
- The zero-sequence signal doesn't appear in the line-to-line voltages as the triplen harmonics cancel each other:  $v_{AB} = v_{AN} - v_{BN}$
- No zero-sequence current will flow in star-connected loads



(a)



(b)



(c)

Figure 5 Zero-sequence injection methods illustration: (a) sinusoidal PWM, (b) third harmonic injection and (c) min/max injection.

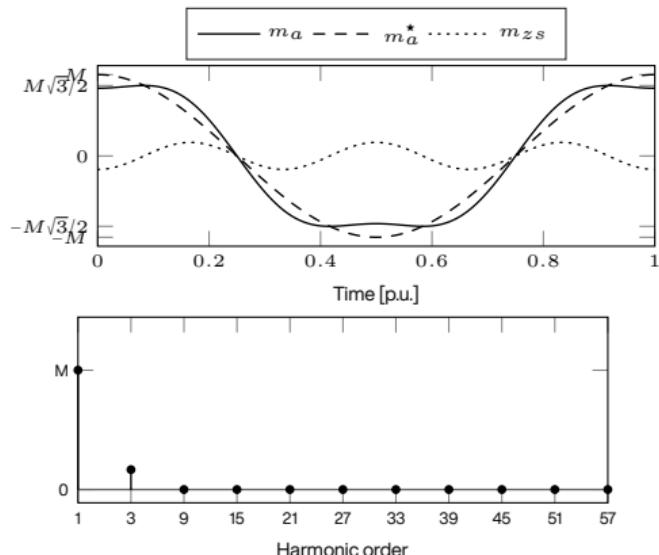
# THIRD HARMONIC INJECTION

- ▶ The third harmonic is the lowest triplen harmonic. It might very likely have the largest impact.
- ▶ Let  $b$  the relative amount of third harmonic that we want to add to the fundamental
- ▶ Taking phase  $a$  as example:  
$$m_a^* = M \cos(\omega t) + bM \cos(3\omega t)$$
- ▶ Extreme of the function is found by equalizing the derivative to 0:

$$\frac{dm_a}{dt} = -M\omega \sin(\omega t) - b3M\omega \sin(3\omega t) = 0$$

$$b = -\frac{\sin(\omega t)}{3 \sin(3\omega t)}$$

- ▶ The peak of the modulating signal is found at  $\omega t = \pi/6$
- ▶ Result:  $b = -\frac{\sin(\pi/6)}{3 \sin(3\pi/6)} = -\frac{\sin(\pi/6)}{3} = -1/6$
- ▶ At peak value:  
$$M_{\max} \cos(\omega t) + bM_{\max} \cos(3\omega t) = 1 \rightarrow M_{\max} = \frac{1}{\cos(\pi/6)}$$
- ▶ The increase is around 15 %:  $M_{\max} = \frac{1}{\cos(\pi/6)} = \frac{2}{\sqrt{3}} \approx 1.15$



# MIN/MAX SIGNAL INJECTION

- ▶ It is not convenient to inject a third harmonic, as the magnitude and frequency of the reference signal cannot be directly determined from the instantaneous sampled modulation index references
- ▶ The harmonic content is an infinite sum of odd triplen harmonics!

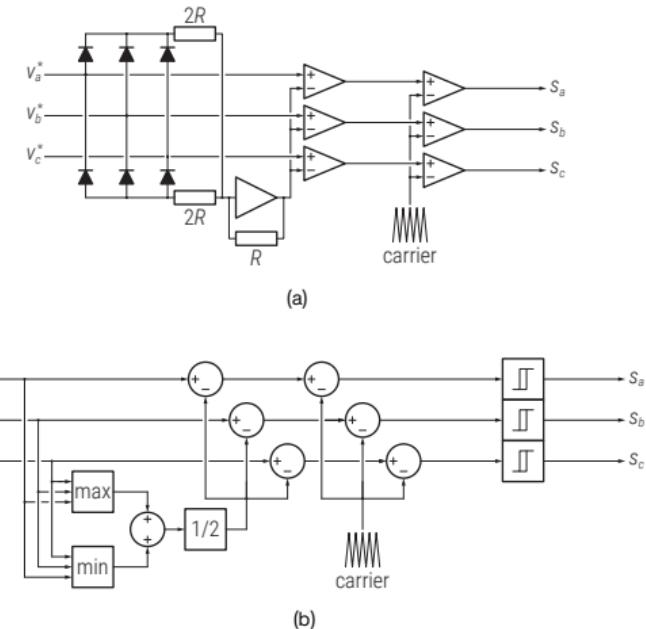
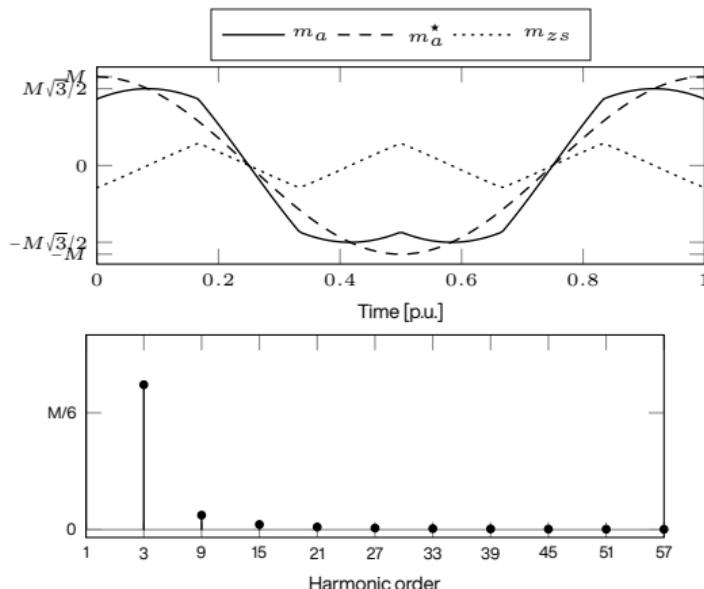


Figure 6 Min/max zero-sequence injection: (a) analog scheme and (b) digital PWM.

# DISCONTINUOUS PWM - DPWM

- ▶ Depending on the load type (resistive, inductive, capacitive), switching losses ( $\sim v \cdot i$ ) are high when the load current is large
- ▶ Discontinuous PWM avoids switching for a certain time in a period ( $2 \times 60^\circ$ )
- ▶ That region has to be adapted depending on the load type
- ▶  $M_{\max} = 2/\sqrt{3}$
- ▶ Not switching = clamping one phase voltage to  $V_{DC}$  or 0

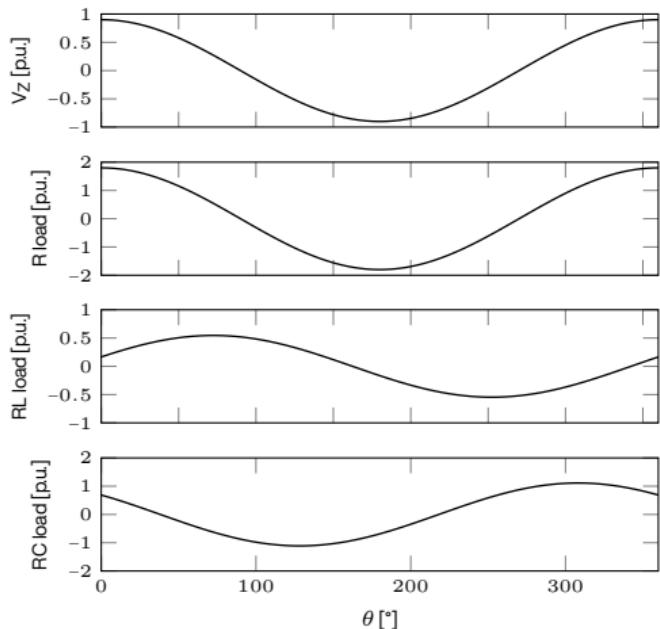


Figure 7 Load types: resistive (current in phase), inductive (current lagging) and capacitive (current leading).

# DISCONTINUOUS PWM - DPWM

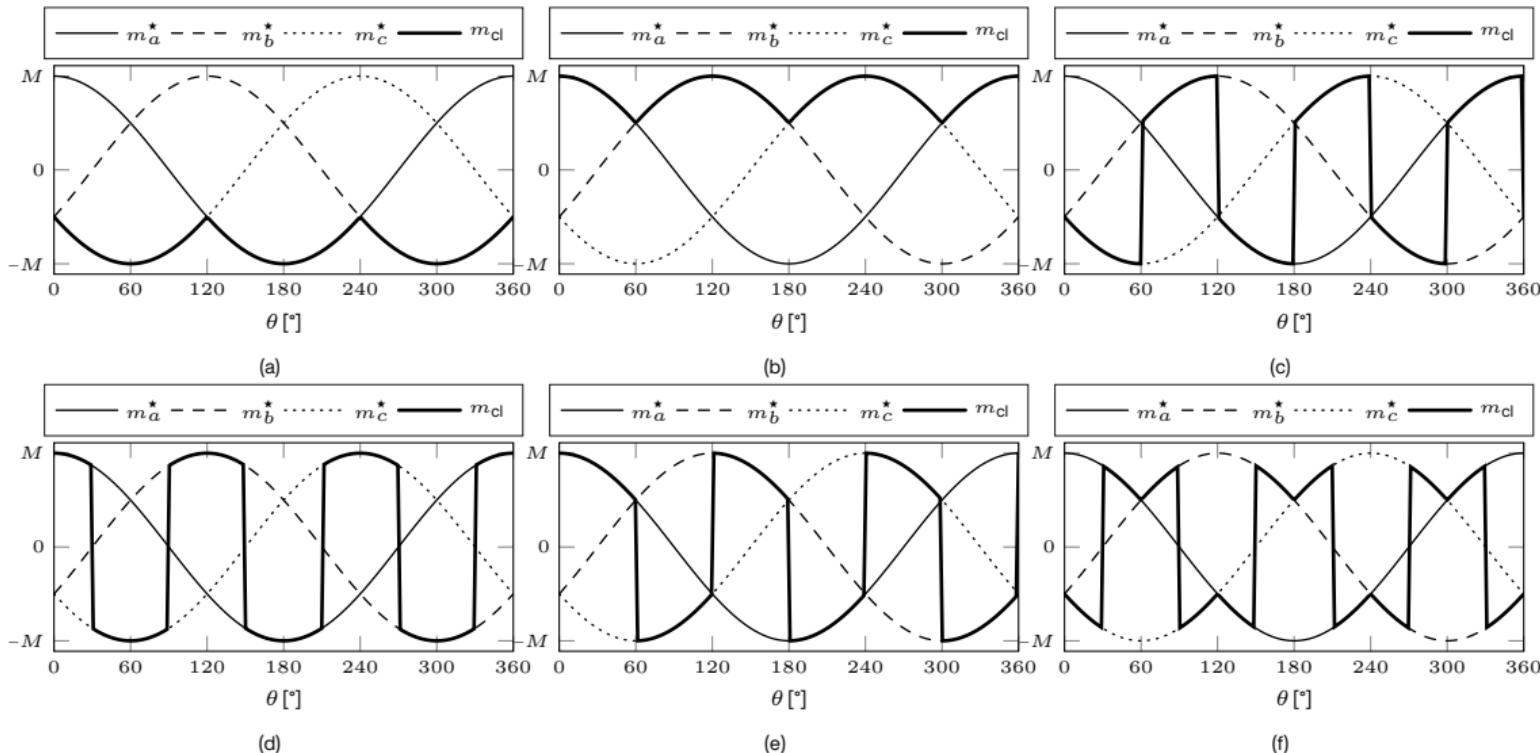


Figure 8 Discontinuous PWM clamping regions: (a) DPWMMIN, (b) DPWMMAX, (c) DPWMO, (d) DPWM1, (e) DPWM2 and (f) DPWM3.

# DISCONTINUOUS PWM - DPWM

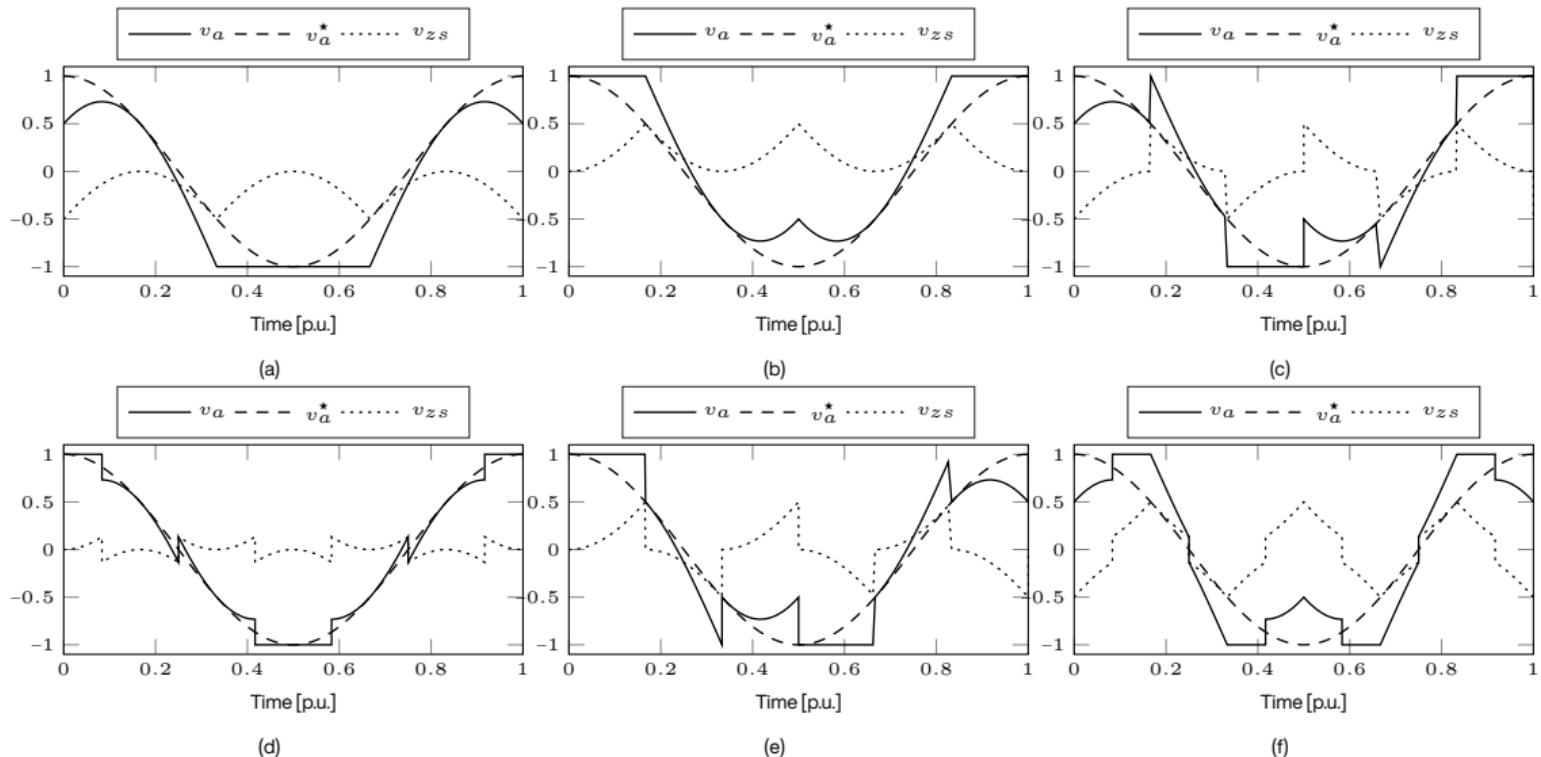
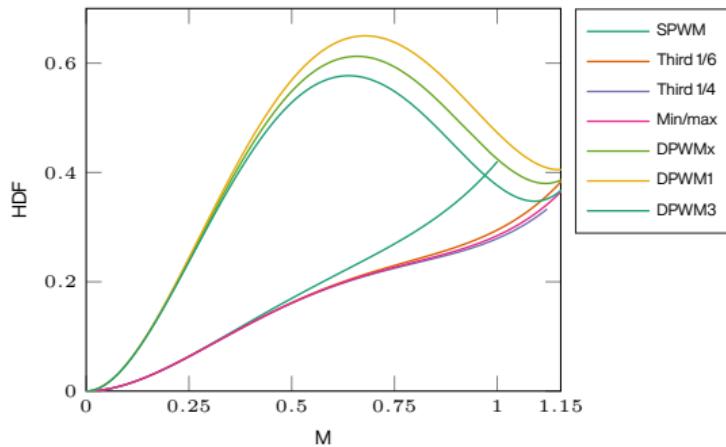


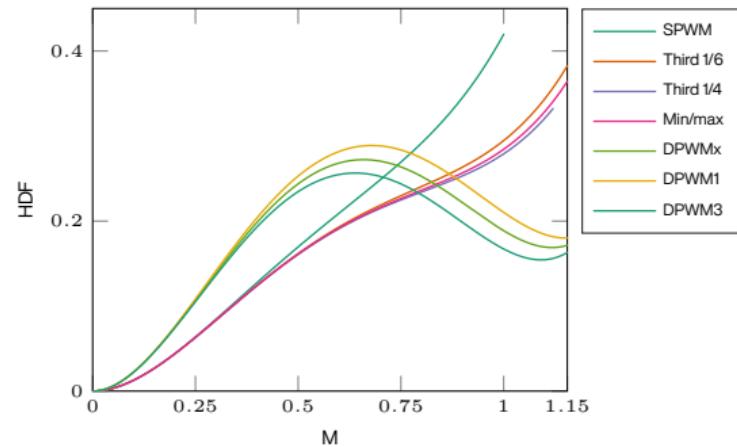
Figure 9 Discontinuous PWM,  $M = 1$ : (a) DPWMMIN, (b) DPWMMAX, (c) DPWM0, (d) DPWM1, (e) DPWM2 and (f) DPWM3.

# HARMONIC DISTORTION FACTOR - HDF

- ▶ Figure of merit for harmonic losses caused by switching harmonics
- ▶ DPWM schemes allow for effective increase of switching frequency of 1.5 times of CPWM
- ▶ Switching losses of CPWM and DPWM can be maintained at the same level



(a)



(b)

Figure 10 HDF plot for: (a)  $f_{sw,CPPWM} = f_{sw,DPWM}$  and (b)  $f_{sw,CPPWM} = 2f_{sw,DPWM}/3$ .

# EFFECTIVE MODULATION INDEX

- ▶ In overmodulation region ( $M > 1$  for SPWM or  $M > 2/\sqrt{3}$  for zero-sequence injection methods), the real modulation index (i.e. fundamental term of the Fourier series) is not anymore given by a linear expression
- ▶ The effective modulation index saturation at  $4/\pi$  (six-step modulation)

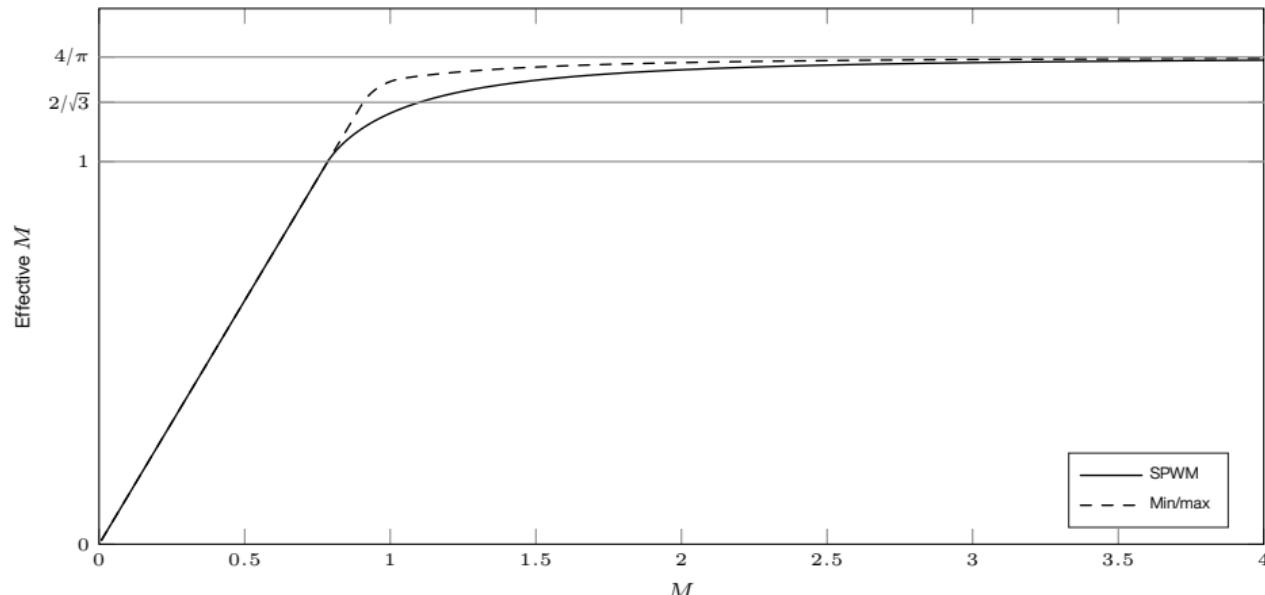


Figure 11 Effective modulation index in linear and overmodulation regions.

# MULTILEVEL CONVERTERS

- Advantages

- Higher DC link voltage accessible with same semiconductor technology
- Improved resolution/quality of the output voltage with lower  $f_{sw}$

- Drawbacks

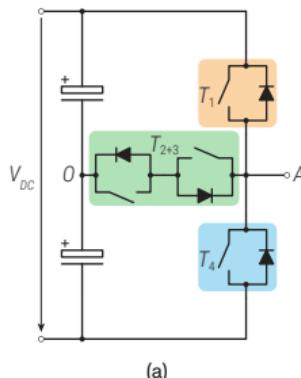
- Higher complexity in the modulator
- Device failure

- Examples of three-level topologies

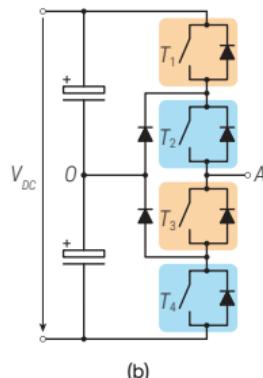
- 3L Neutral Point Piloted (Holtz 1977)
- 3L Neutral Point Clamped (Nabae 1981)
- 3L Flying Capacitor (Meynard 1992)

- Can be extended to  $> 3\text{-L}$

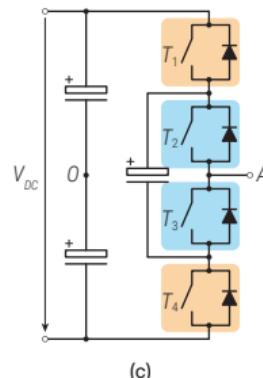
- Intermediate voltage levels must be kept balanced



(a)



(b)

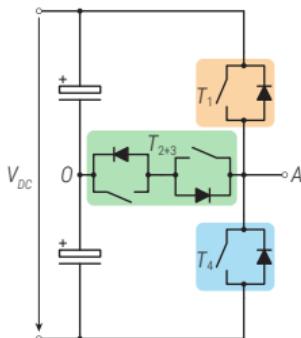


(c)

Figure 12 Multilevel phase-legs: (a) 3L NPP, (b) 3L NPC and (c) 3L FC.

# MULTILEVEL CONVERTERS

3-L NPP



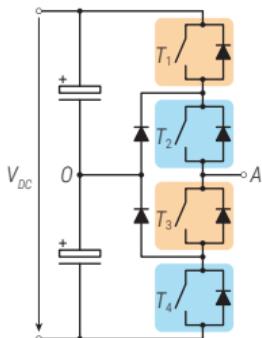
$s_1$	$s_4$	$v_{AO}$
0	1	$-V_{DC}/2$
1	0	0
0	1	0
1	0	$V_{DC}/2$

► Switching logic

$$\triangleright s_{2+3} = \text{and}(\bar{s}_1, \bar{s}_4)$$

► Can operate as 2L

3-L NPC

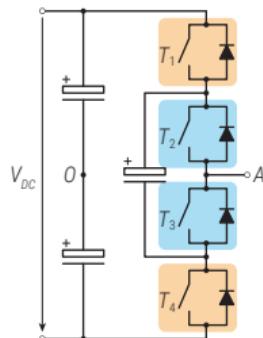


$s_1$	$s_2$	$v_{AO}$
0	0	$-V_{DC}/2$
1	0	0
0	1	0
1	1	$V_{DC}/2$

► Switching logic

$$\begin{aligned} \triangleright s_3 &= \bar{s}_1 \\ \triangleright s_4 &= \bar{s}_2 \end{aligned}$$

3-L FC



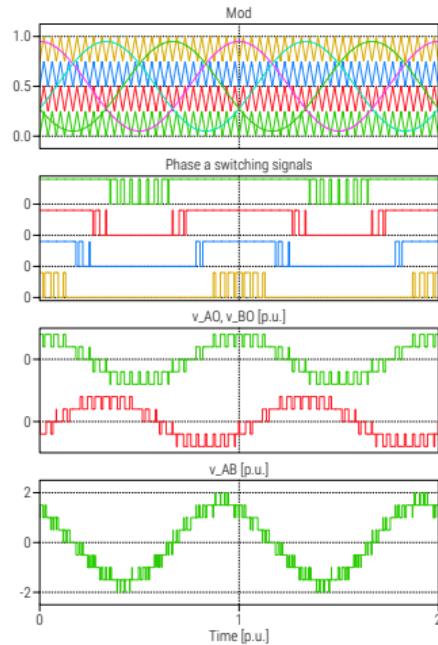
$s_1$	$s_2$	$v_{AO}$
0	0	$-V_{DC}/2$
1	0	0
0	1	0
1	1	$V_{DC}/2$

► Switching logic

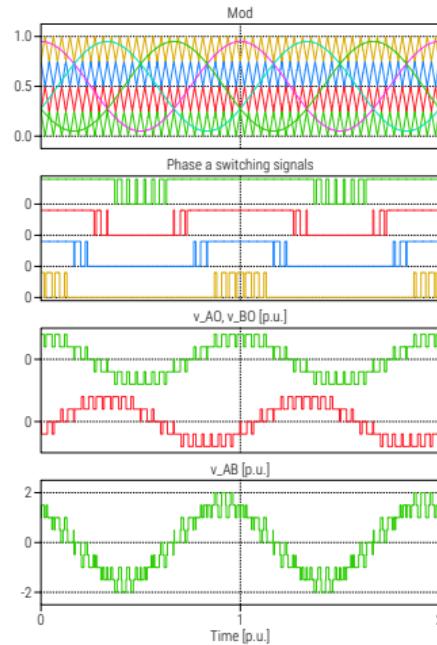
$$\begin{aligned} \triangleright s_3 &= \bar{s}_2 \\ \triangleright s_4 &= \bar{s}_1 \end{aligned}$$

# MULTILEVEL MODULATION METHODS

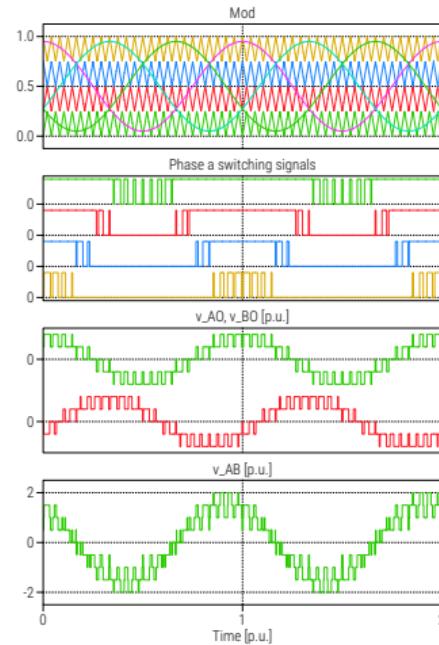
- One carrier assigned per pair of complementary switches



(a)



(b)

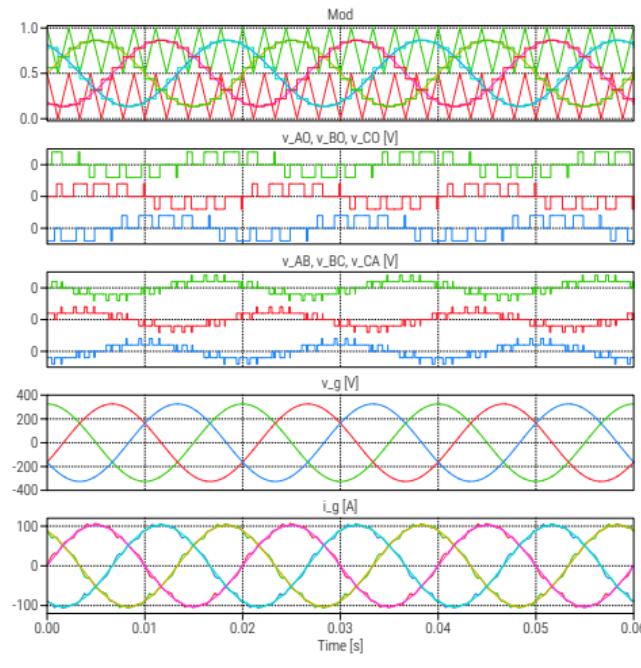


(c)

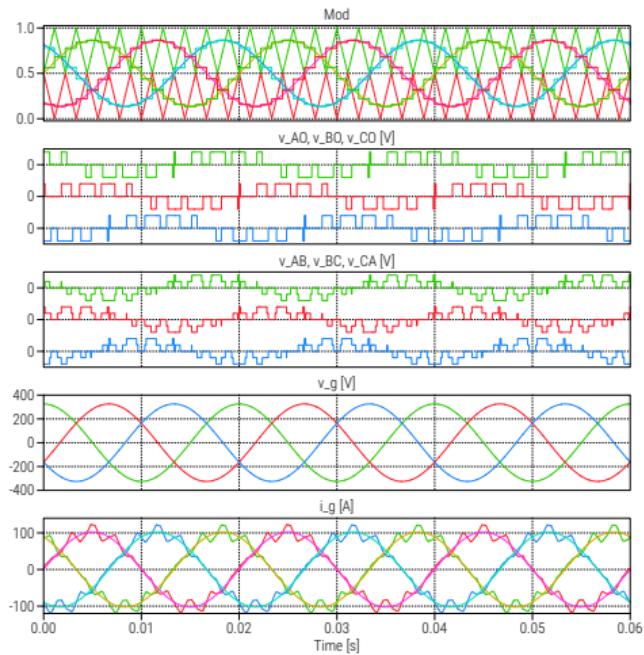
Figure 13 Multilevel PWM methods illustrated for the 5L case for  $f_{sw} = 24 f_g$ : (a) PD-PWM → all carriers in phase, (b) APOD-PWM → 180° shift between carrier bands and (c) POD-PWM → 180° shift between the carrier above and below 0.5.

# 3-L INVERTER WAVEFORMS

- PD-PWM is the best multilevel PWM method (cf. line-to-line voltage waveforms)



(a)



(b)

Figure 14 Typical waveform for a 3L NPC inverter,  $V_{DC} = 800$  V,  $f_{sw} = 450$  Hz,  $S = 50$  kVA,  $\phi = \pi/6$ , asymmetrical sampling: (a) PD-PWM and (b) APOD-PWM (POD-PWM is identical to APOD-PWM for 3L).

# CASCADED H-BRIDGE

- Enhanced reliability (operation with failed cells possible)
- Extension to higher voltages
  - Series-connection of LV cells
  - Externally supplied series-connected cells (McMurray 1969)

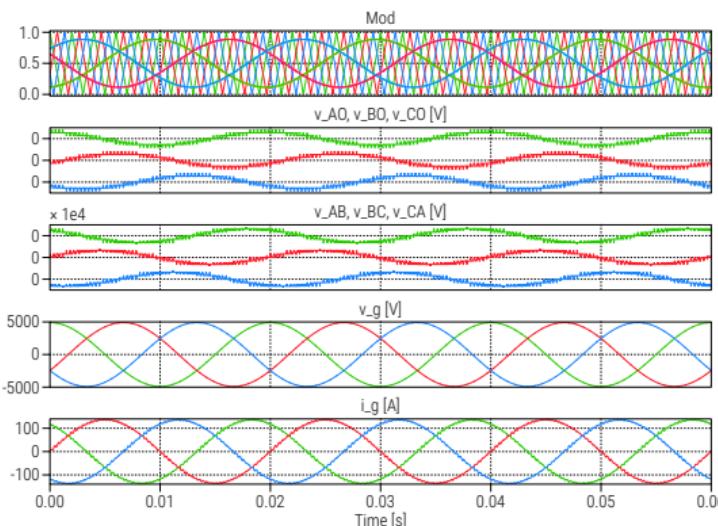


Figure 15 Operation waveforms for  $v_{g,LL} = 6 \text{ kV}$ ,  $S = 1 \text{ MVA}$ ,  $\phi = \pi/6$ ,  $N_{\text{cells}} = 3$ ,  $f_{\text{sw/GBT}} = 500 \text{ Hz}$ , PS-PWM, bipolar modulation for the cell.

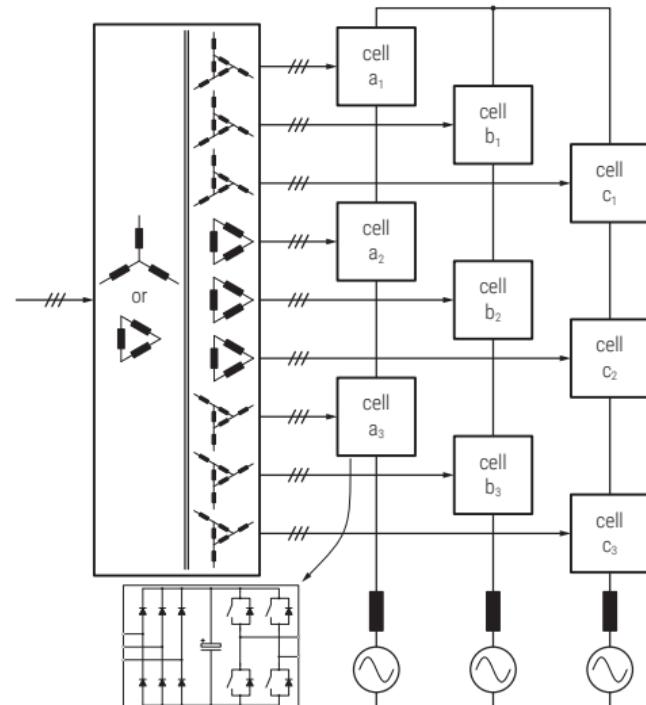


Figure 16 Cascaded H-bridge with externally supplied cells (Robicon drive). Unidirectional power flow!

# MODULAR MULTILEVEL CONVERTER

- ▶ Avoid large bulky transformer(s) of CHB
- ▶ For MV and HV applications
  - ▶ HVDC, grid support & frequency support (STATCOM), frequency conversion (rail interties), MV drives, shaft generator, etc.



Figure 17 HVDC hall from Siemens.

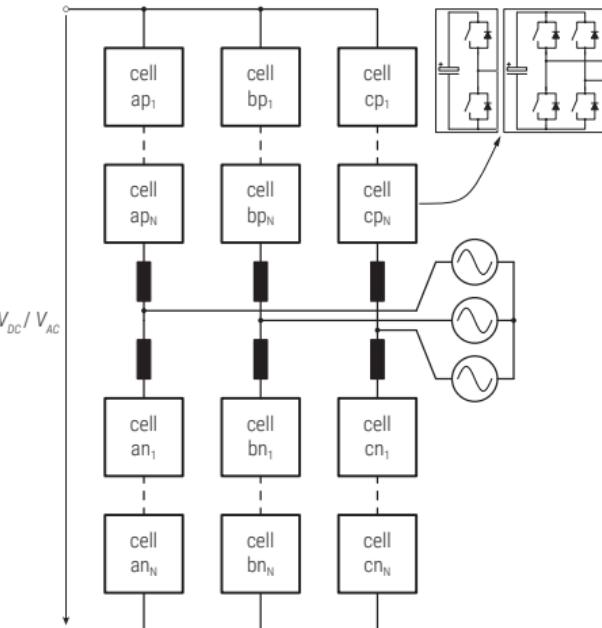


Figure 18 Double-star modular multilevel converter (Marquardt 2002).