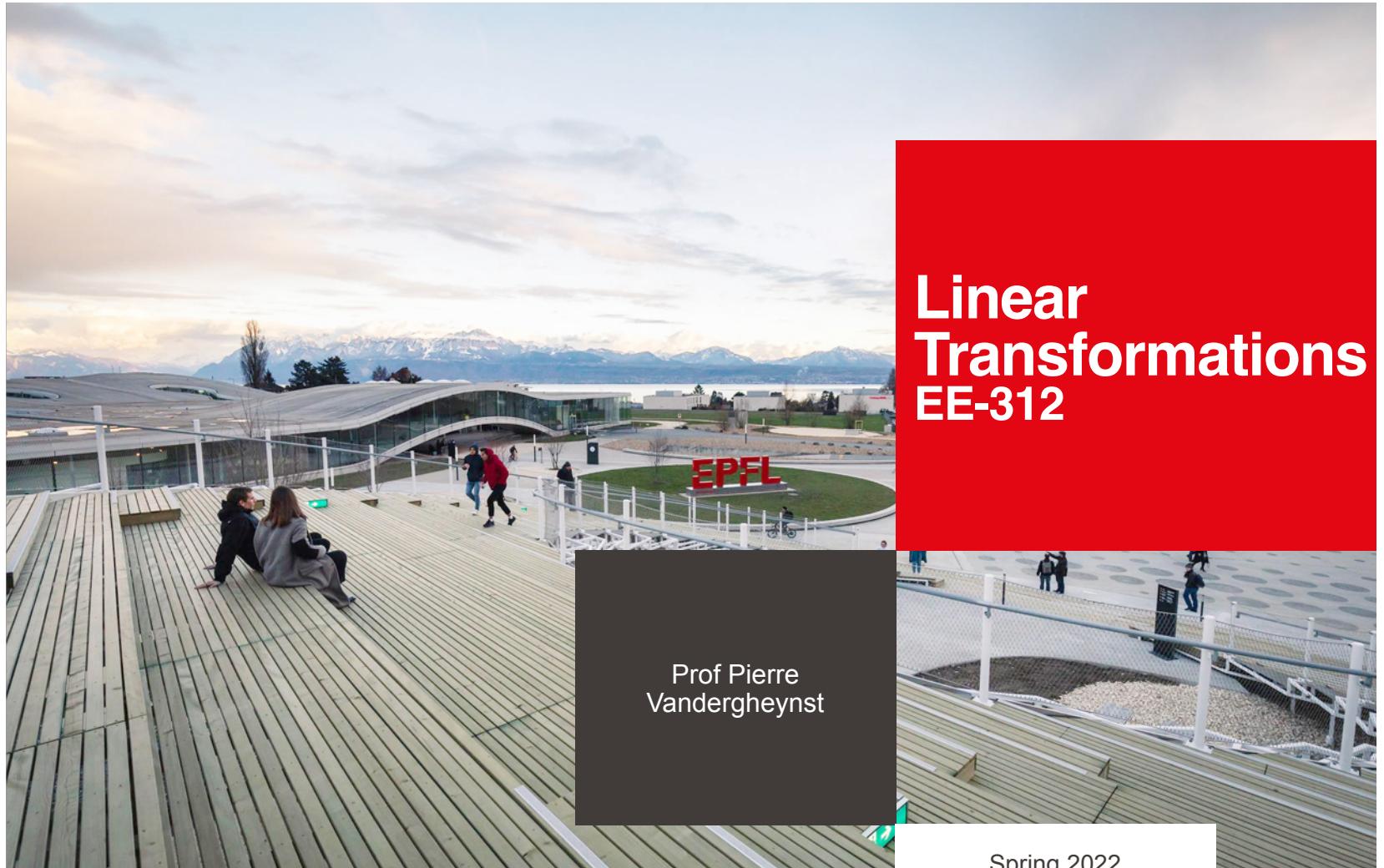


EPFL

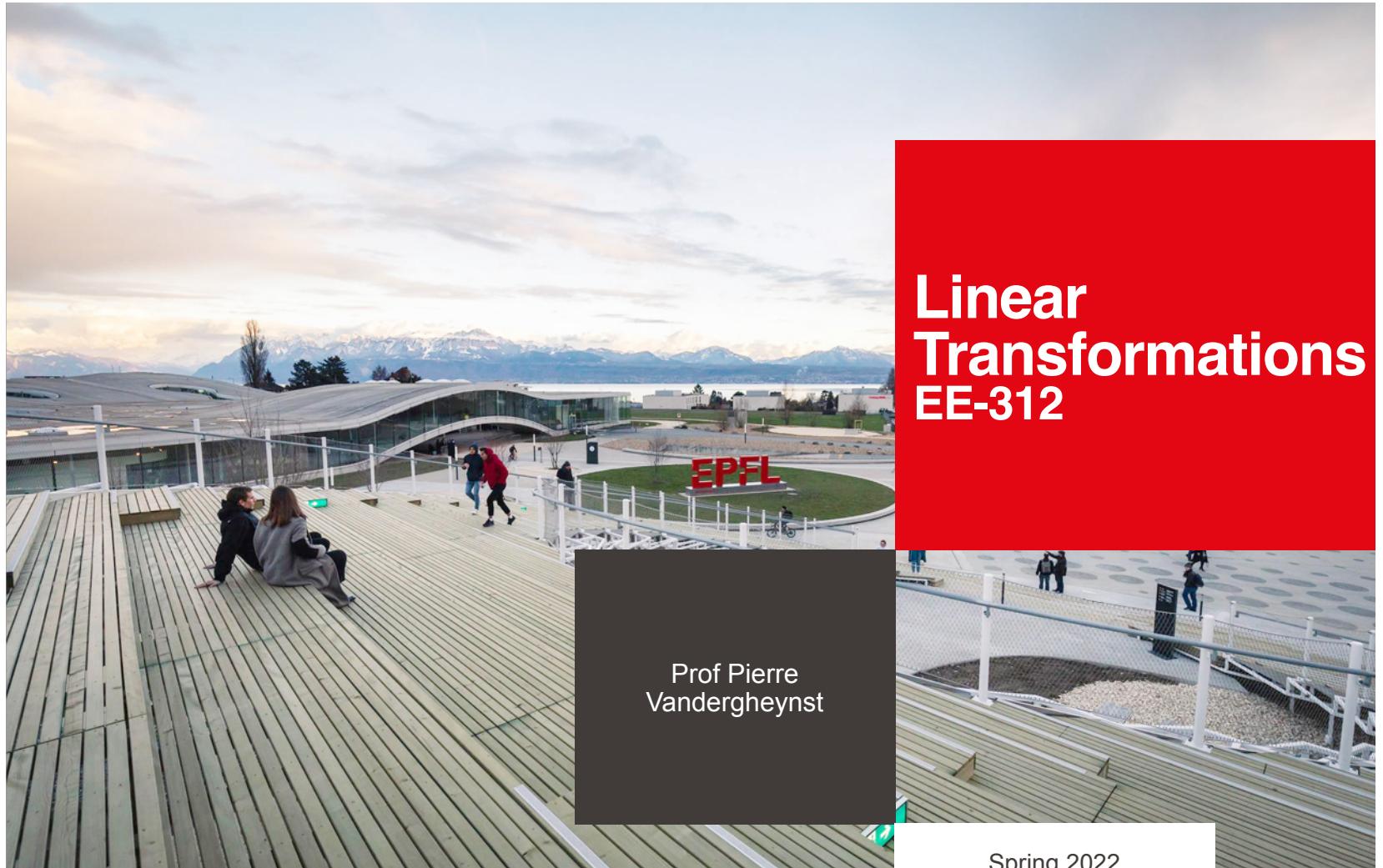


Prof Pierre
Vandergheynst

Spring 2022

**Linear
Transformations
EE-312**

EPFL



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$$P_1(0), P_2(0)$$

$$\int_{-1}^1 dx R(x) P_2(x)$$

$$a_0, \dots, a_{n-1}$$

$$\hat{a}_0 = \frac{a_0}{\|a_0\|}$$

$$\hat{a}_1 = a_1 - \langle a_1, a_0 \rangle a_0$$

$$a_i(x) \text{ Gram-Schmidt}$$

$$a_0 \perp \hat{a}_0$$

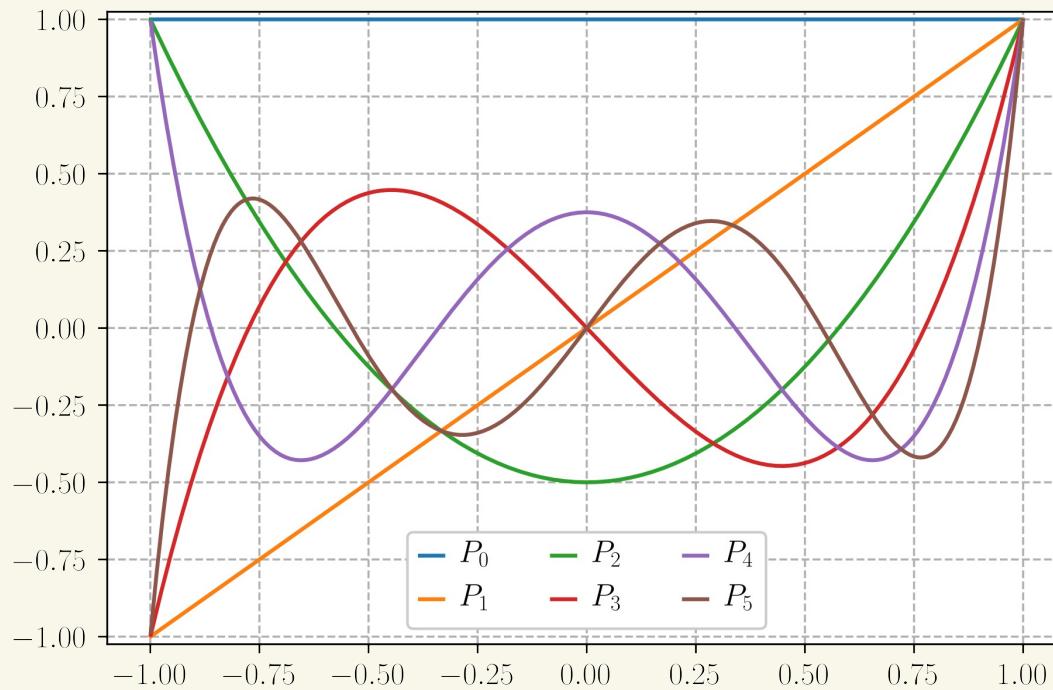
$$a_1 - \langle a_1, a_0 \rangle a_0 = \hat{a}_1$$

$$q_1(x) = \frac{\hat{a}_1(x)}{\|\hat{a}_1(x)\|}$$

$$\sqrt{\langle \hat{a}_1, \hat{a}_1 \rangle}$$

$$\langle \hat{a}_1, a_0 \rangle = \langle a_1, a_0 \rangle$$

$$- \langle a_1, a_0 \rangle \underbrace{\langle a_0, a_0 \rangle}_2$$



Legendre.

$$\int_{-1}^1 dx f(x)$$
$$\int_{-1}^1 dx (1-x^2) f(x)$$

Linear Transformations

This is probably the most intuitive view of linear algebra and among its most useful applications

A mapping between two vector spaces, that satisfies the axiom of linearity

$(\mathcal{V}, \mathbb{F})$ and $(\mathcal{W}, \mathbb{F})$ two vector spaces. $\mathcal{L} : \mathcal{V} \mapsto \mathcal{W}$ is a **linear transformation** IFF

$$\mathcal{L}(\alpha v_1 + \beta v_2) = \alpha \mathcal{L}(v_1) + \beta \mathcal{L}(v_2) \quad \forall \alpha, \beta \in \mathbb{F} \text{ and } v_1, v_2 \in \mathcal{V}$$

Examples: $(\mathcal{V}, \mathbb{F}) = (\mathcal{P}^n, \mathbb{R})$, $(\mathcal{W}, \mathbb{F}) = (\mathcal{P}^{n-1}, \mathbb{R})$

$$\mathcal{L}(v) = v'$$

Most revealing is the case of a linear trans. between two euclidean vector spaces

$L: V \longrightarrow W$

$\{v_i\}_{i=1, \dots, n}$ ONB

$\{w_j\}_{j=1, \dots, m}$ ONB

$$L v_i = \sum_{j=1}^m \beta_j w_j = \sum_{j=1}^m \underbrace{\langle w_j, L v_i \rangle}_{A[j,i]} w_j$$

$$f \in V \quad f = \sum_{i=1}^n \alpha_i v_i = \sum_{i=1}^n \langle v_i, f \rangle v_i$$

$$g = Lf = \sum_{i=1}^n \alpha_i L v_i = \sum_{i=1}^n \alpha_i \sum_{j=1}^m A[j,i] w_j$$

$$\beta_k = \langle w_k, g \rangle = \sum_{i=1}^n \alpha_i \sum_{j=1}^m A[j,i] \langle w_k, w_j \rangle = \sum_{i=1}^n \alpha_i \sum_j A[j,i] \delta_{kj} \\ = \sum_i \alpha_i A[k,i] = (A\alpha)_k$$

$f \rightarrow \alpha$

$Lf \rightarrow \beta$

$\beta = A\alpha$

Linear Transformations

Most revealing is the case of a linear trans. between two euclidean vector spaces

Classic: a linear transformation of vectors, visualised as “arrows”

I strongly advise you check [3blue1brown's youtube channel](#)
“Essence of Linear Algebra”, for great pedagogical visualisations

*“Unfortunately, no one can be told what the Matrix is.
You have to see it for yourself.”*
Morpheus

Linear Transformations

Linear System and Linear Dynamical System

$$\frac{d}{dt}x(t) = Ax(t), \quad x \in \mathbb{R}^n \text{ and } A \in \mathbb{R}^{n \times n}$$

Examples: $n = 1, \frac{d}{dt}x(t) = ax(t) \Rightarrow x(t) = x(0)e^{at}$ reminds you of something ?

$$n = 2,$$

$$\begin{aligned} \frac{d}{dt}x_1(t) &= a_{11}x_1(t) + a_{12}x_2(t) \\ \frac{d}{dt}x_2(t) &= a_{21}x_1(t) + a_{22}x_2(t) \end{aligned}$$

predation

Linearised “predator-prey” model

Linear Transformations

A mapping between two vector spaces, that satisfies the axiom of linearity
(\mathcal{V}, \mathbb{F}) and (\mathcal{W}, \mathbb{F}) two vector spaces. $\mathcal{L} : \mathcal{V} \mapsto \mathcal{W}$ is a **linear transformation** IFF
$$\mathcal{L}(\alpha v_1 + \beta v_2) = \alpha \mathcal{L}(v_1) + \beta \mathcal{L}(v_2) \quad \forall \alpha, \beta \in \mathbb{F} \text{ and } v_1, v_2 \in \mathcal{V}$$

If you decorate the two vector spaces with bases V and W

$$\forall u \in \mathcal{V} \quad u = \sum_i \alpha_i v_i \quad \mathcal{L}u = \sum_i \alpha_i \mathcal{L}v_i = (\mathcal{L}V)\alpha \quad \text{concatenate all vectors } \mathcal{L}v_i \text{ as matrix } \mathcal{L}V$$

$$\begin{aligned} \mathcal{L}v_i \in \mathcal{W} \quad \mathcal{L}v_i &= \sum_j w_j \beta_{ji} & \xrightarrow{\text{blue arrow}} & \mathcal{L}u = (\mathcal{L}V)\alpha \\ &= WB_i & \xrightarrow{\text{i-th column of B}} & = WB\alpha & \xrightarrow{\text{blue arrow}} & \mathcal{L} = WB \end{aligned}$$

holds $\forall \alpha$

Linear Transformations

In particular for two euclidian vector spaces $\mathcal{V} = \mathbb{R}^n$, $\mathcal{W} = \mathbb{R}^m$

$$\begin{aligned}\mathcal{L}u &= (\mathcal{L}V)\alpha \\ &= WB\alpha\end{aligned}$$

pick canonical bases $\mathcal{L} = B \in \mathbb{R}^{m \times n}$
any matrix is a linear transformation
between two vector euclidean spaces

what happens if we change basis ?

The four fundamental subspaces

$A : \mathcal{V} \rightarrow \mathcal{W}$ a linear transformation

The **range** (or the image) of A $\mathcal{R}(A) = \{w \in \mathcal{W} : w = Av \text{ for some } v \in \mathcal{V}\}$

$$\mathcal{R}(A) = \{Av : v \in \mathcal{V}\}$$

$$\mathcal{R}(A) \subseteq \mathcal{W}$$

$$Av = w$$

$$w \in \mathcal{R} + \mathcal{N}_0$$

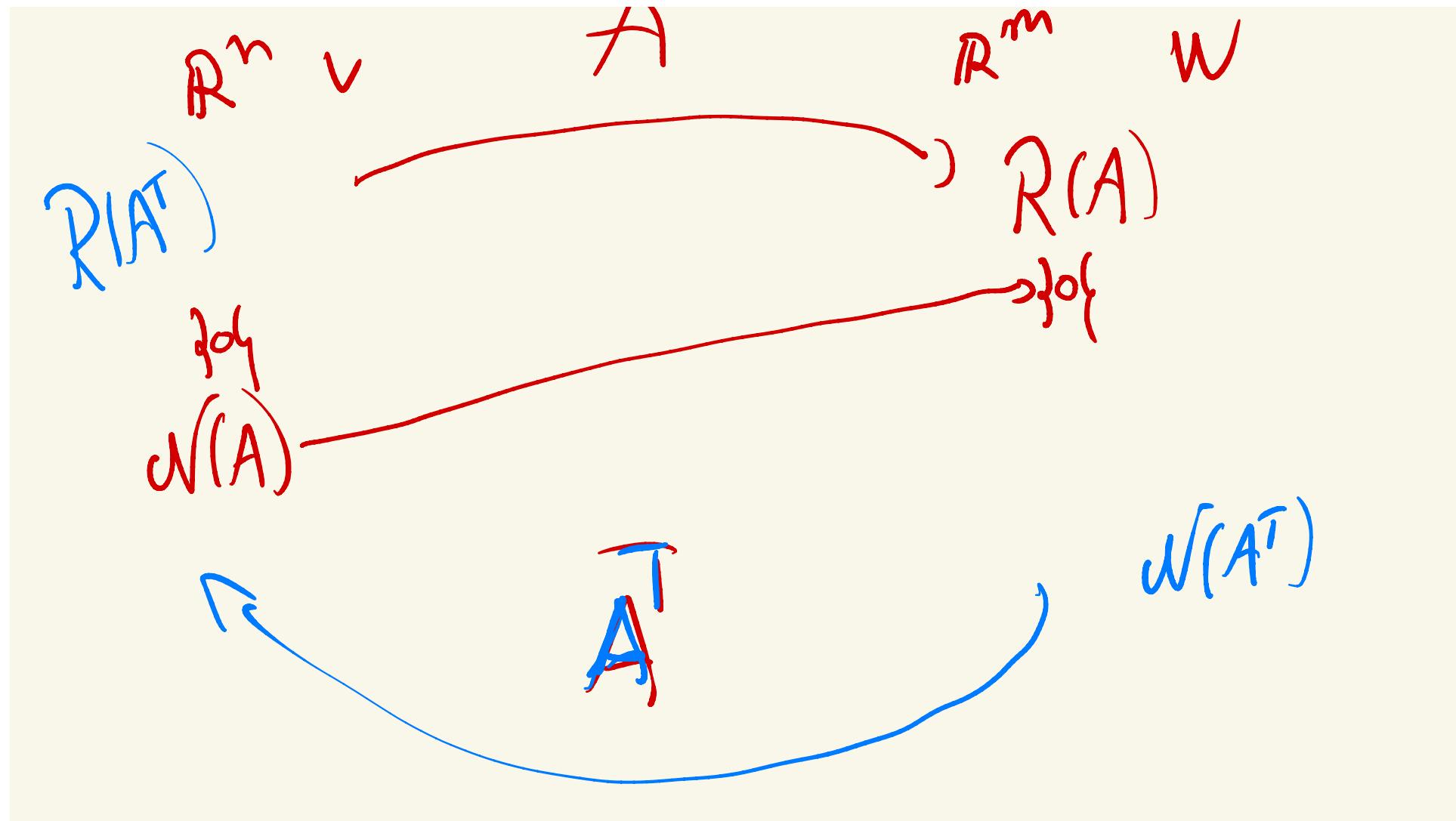
$$w \in \mathcal{R}(A)$$

The **nullspace** (or the kernel) of A $\mathcal{N}(A) = \{v \in \mathcal{V} : Av = 0\}$

$$\mathcal{N}(A) \subseteq \mathcal{V}$$

$$Av = 0$$

$$A \in \mathbb{R}^{m \times n}, \quad A = [a_1, \dots, a_n] \Rightarrow \mathcal{R}(A) = \text{Sp}(A)$$



The four fundamental subspaces

For any $x \in \mathcal{N}(A)$

$$\begin{aligned} Ax = 0 \Rightarrow y^T Ax = 0 \quad \forall y \in R^m \\ \Rightarrow (A^T y)^T x = 0 \\ \Rightarrow x \in \mathcal{R}(A^T)^\perp \end{aligned} \qquad \longrightarrow \qquad \mathcal{N}(A)^\perp = \mathcal{R}(A^T)$$

For any $y \in \mathcal{N}(A^T)$

$$\begin{aligned} A^T y = 0 \Rightarrow x^T A^T y = 0 \quad \forall x \in R^n \\ \Rightarrow (Ax)^T y = 0 \\ \Rightarrow y \in \mathcal{R}(A)^\perp \end{aligned} \qquad \longrightarrow \qquad \mathcal{R}(A)^\perp = \mathcal{N}(A^T)$$

The four fundamental subspaces

Why are they so “fundamental” ?

They are linked to fundamental properties of A as a linear transformation

Let $A : \mathcal{V} \rightarrow \mathcal{W}$

A is **onto (or surjective)** if $\mathcal{R}(A) = \mathcal{W}$

A is **1-to-1 (or injective)** if $\mathcal{N}(A) = 0$

Equivalently:

$$a) \quad Av_1 = Av_2 \Rightarrow v_1 = v_2$$

$$b) \quad v_1 \neq v_2 \Rightarrow Av_1 \neq Av_2$$

Matrix Rank

Let $A : \mathcal{V} \rightarrow \mathcal{W}$

A is **onto** (or **surjective**) if $\mathcal{R}(A) = \mathcal{W}$

A is **1-to-1** (or **injective**) if $\mathcal{N}(A) = 0$

The dimension of these subspaces is of particular significance !

Ans $\forall n \in \mathbb{W}$

$\text{rank}(A) = \dim(\mathcal{R}(A))$ and is the maximum number of independent columns
column rank!

Note: $\dim(\mathcal{R}(A^T))$ is the maximum number of independent rows **row rank!**

$\text{nullity}(A) = \dim(\mathcal{N}(A))$

$$\mathbb{R}^n \xrightarrow{\quad N(A)^\perp = R(A^T) \quad} \mathbb{R}^m$$

$$N(A) \oplus N(A)^\perp = \mathbb{R}^n$$

$$\mathbb{R}^m \xrightarrow{\quad R(A) \quad} \mathbb{R}^n$$

$$R(A)^\perp = N(A^T) \oplus N(A^T)^\perp = \mathbb{R}^m$$

$$\text{rank}(A) = \dim(R(A))$$

$$\text{nullity}(A) = \dim N(A)$$

$$n = \dim N(A) + \dim R(A^T) = \text{nullity}(A) + \text{rank}(A^T)$$

Fabricamos $T: \mathbb{R}^n \rightarrow \mathbb{R}^m$

$$N(A)^\perp \rightarrow R(A)$$

$$T(x) = A(x)$$

$$Tx = Ax$$

$N(T) \in \{0\}$ Teste injektivit 
 $R(T) \neq R(A)$ Test auf surjektiv

Bijections
 von $N(A)^\perp$ das $R(A)$

$T: U \rightarrow Q$

Prenons une base de $N(A)^\perp$ $\nu_i, i=1, \dots, n$

une base de $R(A)$ $\boxed{\begin{array}{l} (T\nu_i) \text{ sont une base de } R(A) \\ (i=1, \dots, n) \end{array}}$

CONTRA

Supposons $T\nu_i, i=1, \dots, n$ sont lin. dép

$$T\nu_i = \sum_{k=1}^n \alpha_k T\nu_k$$

$$T(\nu_i - \sum_{k=1}^n \alpha_k \nu_k) = 0 \Leftrightarrow \nu_i = \sum_{k=1}^n \alpha_k \nu_k$$

Impossible car ν_i sont une base !!

$$\Rightarrow \dim R(A) = n = \dim N(A)^\perp = \dim R(A)^\perp = n$$

Matrix Rank

And all these characterisations are equivalent !

$$A : \mathbb{R}^n \rightarrow \mathbb{R}^m \quad \dim(\mathcal{R}(A)) = \dim(\mathcal{N}(A)^\perp) = \dim(\mathcal{R}(A^T))$$

$\text{row rank of } A = \text{column rank of } A = n - \text{nullity}(A)$

Second part of theorem already proved before.

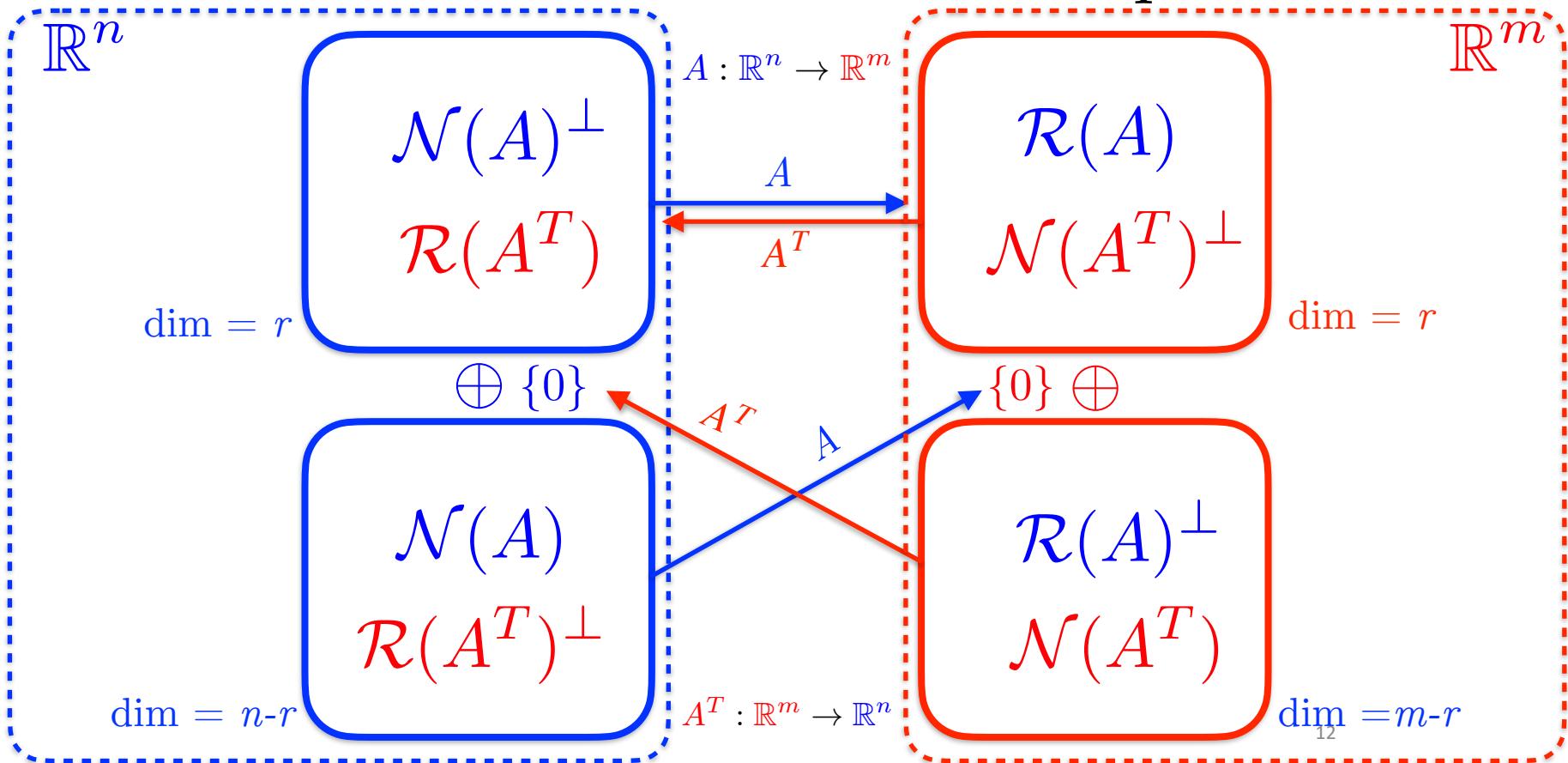
Consider the restriction: $T : \mathcal{N}(A)^\perp \rightarrow \mathcal{R}(A) \quad T\mathbf{v} = A\mathbf{v} \quad \forall \mathbf{v} \in \mathcal{N}(A)^\perp$

Show that T is bijective

Any basis of $\mathcal{N}(A)^\perp$ is mapped to a basis of $\mathcal{R}(A)$ by T

$$\Rightarrow \dim(\mathcal{N}(A)^\perp) = \dim(\mathcal{R}(A))$$

The four fundamental subspaces



A note on invertibility

A linear transformation is **invertible** if and only if it is **bijective** (1-1 and onto)

ex: $T : \mathcal{N}(A)^\perp \rightarrow \mathcal{R}(A)$ $Tv = Av \quad \forall v \in \mathcal{N}(A)^\perp$

Consider $A : \mathbb{R}^n \rightarrow \mathbb{R}^n$ and suppose it has n linearly independent columns $\mathcal{R}(A) = \mathbb{R}^n$
full-rank
 A is onto

$$\forall y \in \mathbb{R}^n \exists x_1, \dots, x_n \text{ s.t. } y = a_1 x_1 + \dots + a_n x_n$$

unique

A is 1-1 $y = Ax$  depends on A and y

$$x = A^{-1}y$$

linear

$A : \mathcal{V} \rightarrow \mathcal{W}$ is **invertible** if and only if it is **bijective**.

If A is invertible then $\dim(\mathcal{V}) = \dim(\mathcal{W})$

$A : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is invertible (non-singular) if and only if $\text{rank}(A) = n$

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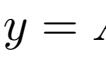
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