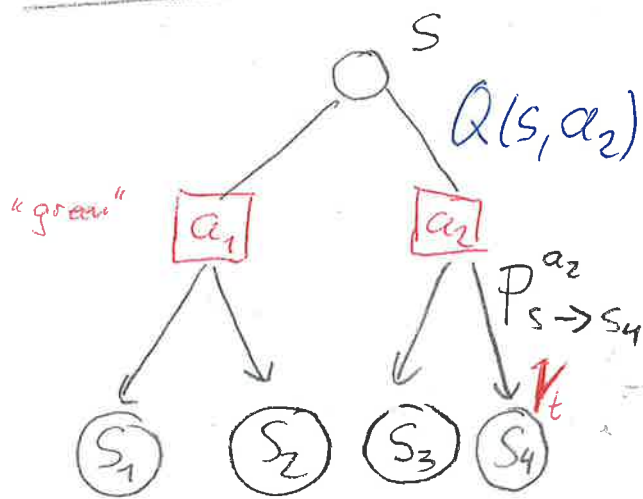


Blackboard RL1 : Q-values



"branching ratio"

Transition probability

$$P_{S \rightarrow S_4}^{a_2} = P(s' = S_4 | a_2, S)$$

↑
next state

- actual reward at time t : r_t
- expected reward for this "branch"

$$R_{S \rightarrow S_4}^{a_2} = E(r_t | s' = S_4, a_2, S)$$

↑ reward received ↑ end up in S_4 ↑ take a_2 ↑ start in S

- expected reward for action a_2

$$Q(S, a_2) = E(r_t | a_2, S)$$

$$= \sum_{s'} P_{S \rightarrow s'}^{a_2} \cdot R_{S \rightarrow s'}^{a_2}$$

↑ all possible "next states"

(Def Q)

- distinguish r_t from $R_{S \rightarrow s'}^{a_2}$! for example
- | | | |
|-----------|-----------|-----------------------|
| $r_t = 4$ | with Prob | $P_r(r=4 S, a, s')$ |
| $r_t = 1$ | " " | $P_r(r=1 S, a, s')$ |
| $r_t = 0$ | " " | $P_r(r=0 S, a, s')$ |

Blackboard RL1-3 : Stranger Proof (Blackboard 2)

Convergence in expectation (perspective of "batch" update)

theorem (i) :

if $E[\Delta \hat{Q}(s,a) | s,a] = 0$ (H)

then $E[\hat{Q}(s,a) | s,a] = \hat{Q}(s,a) = \sum_{s'} P_{s \rightarrow s'}^a R_{s \rightarrow s'} = Q(s,a)$

proof : update formul ^ = moment estimate

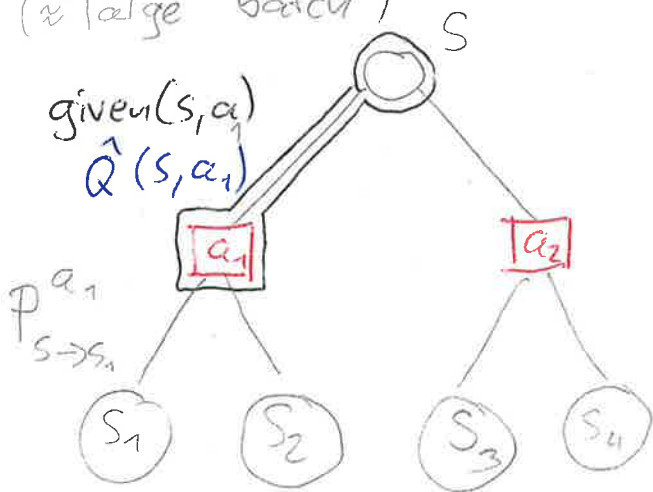
$$E[\Delta \hat{Q}(s,a) | s,a] = E[\underbrace{\eta \cdot (r_t - \hat{Q}(s,a))}_{\text{linear}} | s,a]$$

possible futures with correct statistical weight (x "large batch")

given s and a

$$= \eta \cdot E[r_t | s,a] - \eta E[\hat{Q}(s,a) | s]$$

$$= \eta \cdot \sum_{s'} P_{s \rightarrow s'}^a R_{s \rightarrow s'} - \eta E[\hat{Q}(s,a) | s]$$



$\hat{Q}(s,a)$ is fixed when conditioned on (s,a)
 $\rightarrow$ drop Expected sign

with hypothesis H :

$$0 = \cancel{\eta} \cdot \sum_{s'} P_{s \rightarrow s'}^a R_{s \rightarrow s'} - \cancel{E[\hat{Q}(s,a) | s]}$$

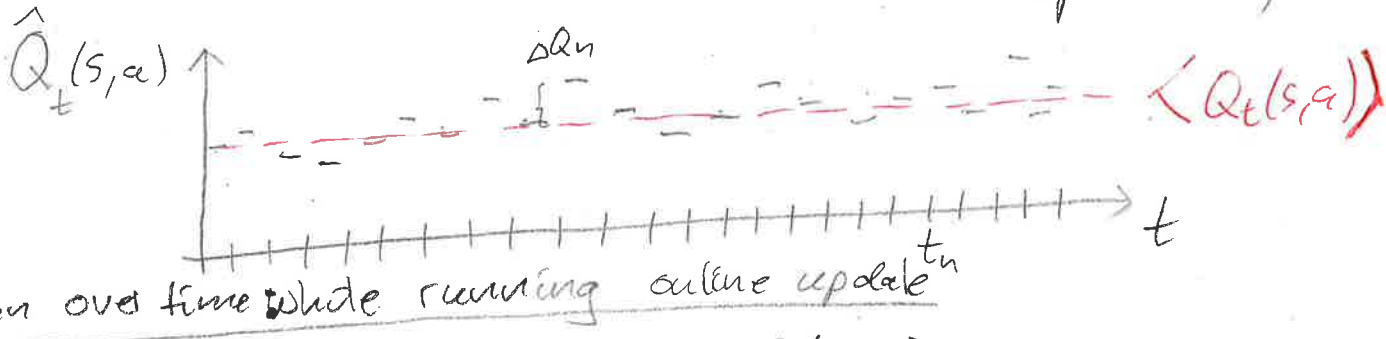
$$\cancel{E[\hat{Q}(s,a) | s,a]} = \sum_{s'} P_{s \rightarrow s'}^a R_{s \rightarrow s'} = Q(s,a) \quad \uparrow \text{(*Def Q)}$$

$\Rightarrow$ estimate $\hat{Q}$ equal "exact Q"

(ii)

convergence of mean

(perspective of "online" update) ③



$$\langle \Delta \hat{Q}(s, a) | s, a \rangle = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{n=1}^N \Delta Q_n(s, a)$$

↑ all time points with (s, a) ↑ update in time step n

theorem (ii)

$$\text{if } \langle \Delta \hat{Q}(s, a) | s, a \rangle_{t|s, a} = 0$$

$$\text{then } \langle \hat{Q}(s, a) \rangle_{t|s, a} = Q(s, a)$$

$$\text{proof: } \langle \Delta \hat{Q}(s, a) | s, a \rangle_{t|s, a} = \eta \langle (r_t - \hat{Q}_t(s, a)) | s, a \rangle_{t|s, a}$$

$$\langle \Delta \hat{Q}(s, a) | s, a \rangle_{t|s, a} = \eta \langle r_t | s, a \rangle_{t|s, a} - \eta \langle \hat{Q}_t(s, a) \rangle_{t|s, a}$$

↓ H

↑ ↑ automatic condition

$$0 = \sum_{s'} P_{s \rightarrow s'}^a R_{s \rightarrow s'}^a - \langle \hat{Q}_t(s, a) \rangle$$

$$\Rightarrow \langle \hat{Q}_t(s, a) \rangle_t = \sum_s P_{s \rightarrow s'}^a R_{s \rightarrow s'}^a \stackrel{(*\text{Def } Q)}{=} Q(s, a)$$

$$\Rightarrow \boxed{\text{mean over time } \langle Q_t \rangle_t = Q \text{ (exact } Q\text{-value)}}$$

Q' Q_u

see