

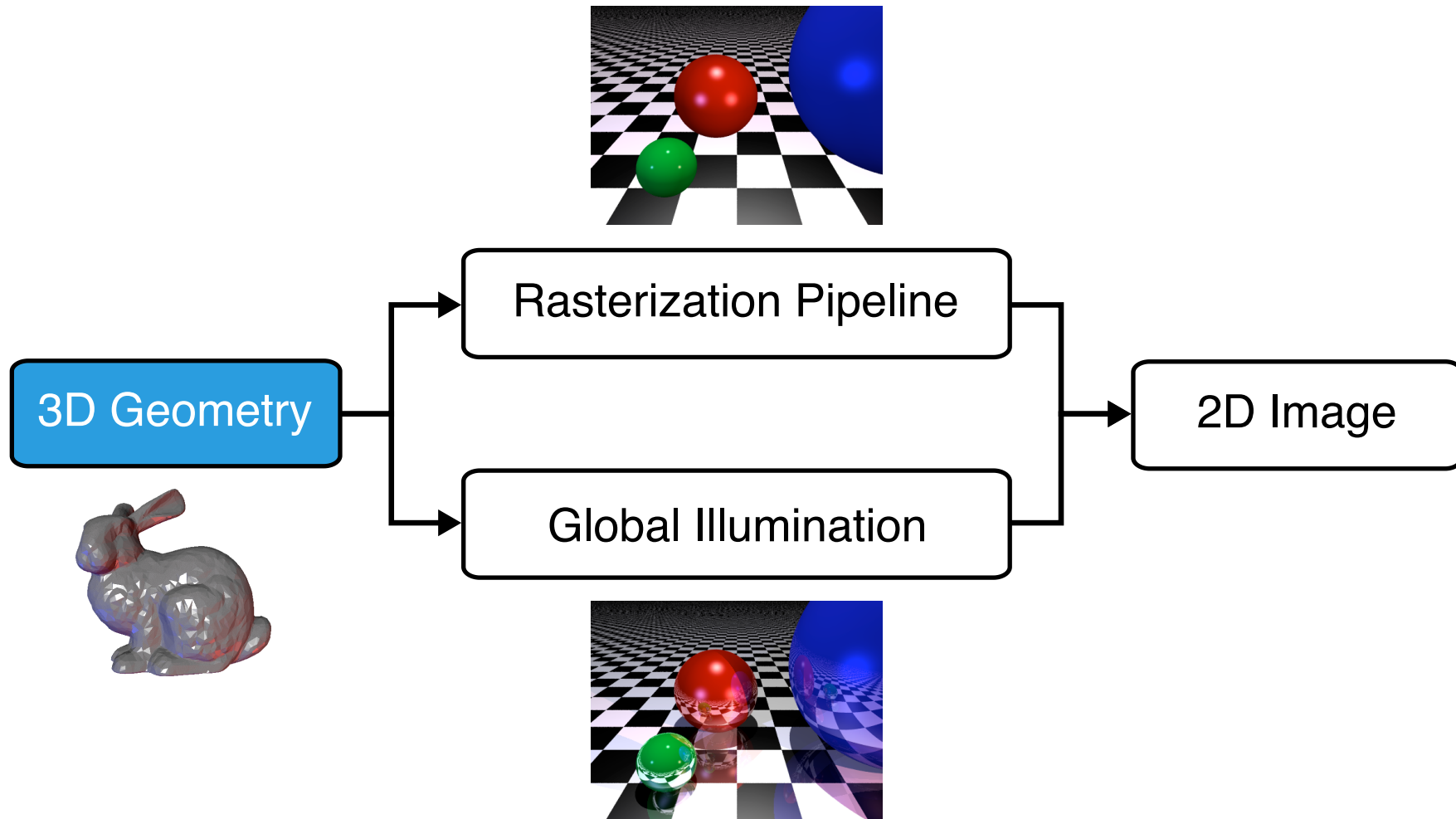
Computer Graphics

Freeform Surfaces I

Mark Pauly

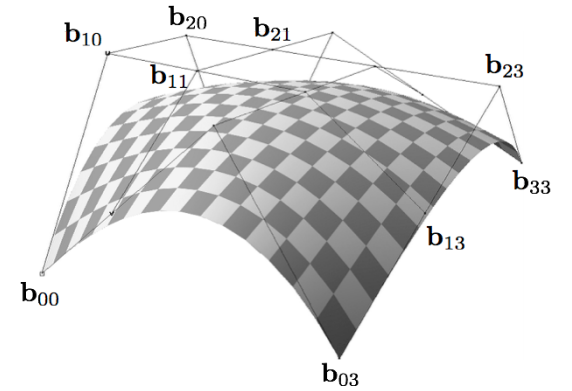
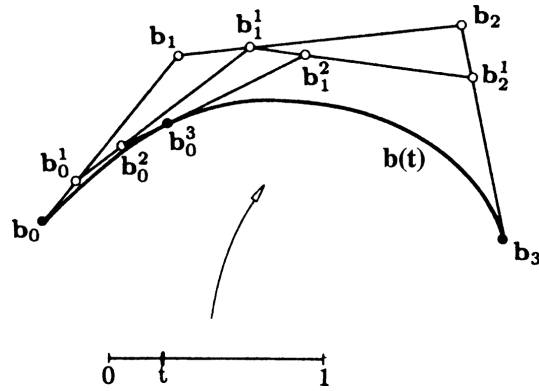
Geometric Computing Laboratory

Overview



Overview

1. Freeform Curves
2. Freeform Surfaces
3. Freeform Deformation

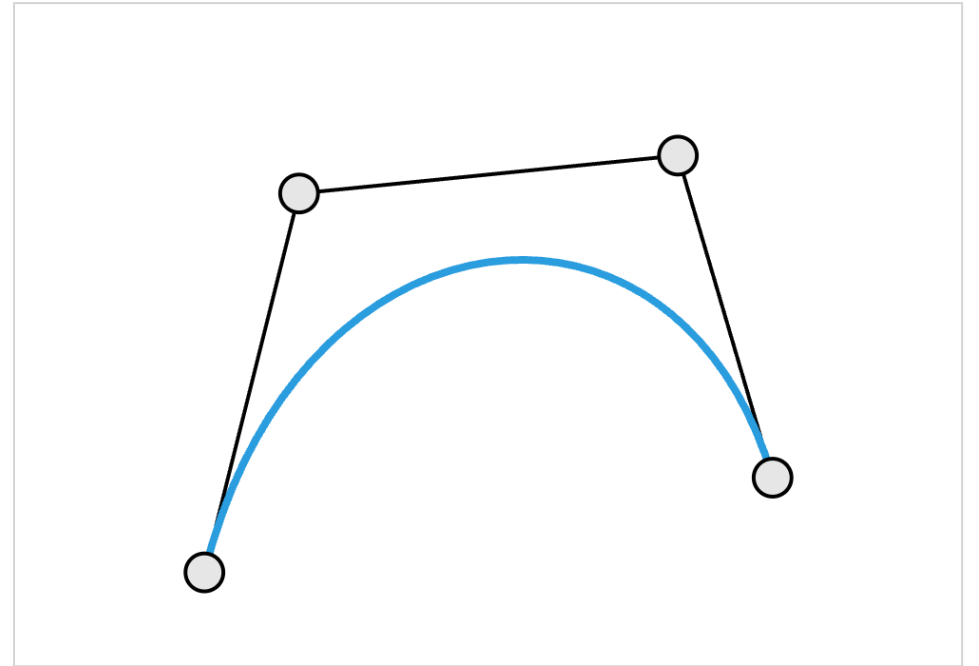


Freeform Curves

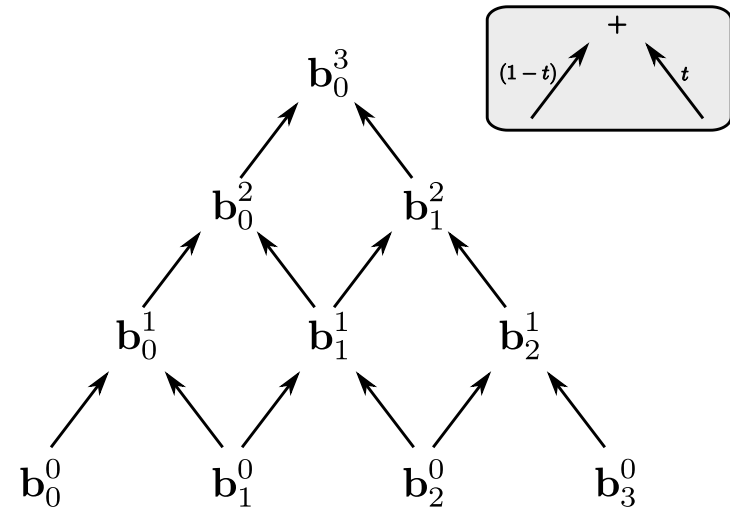
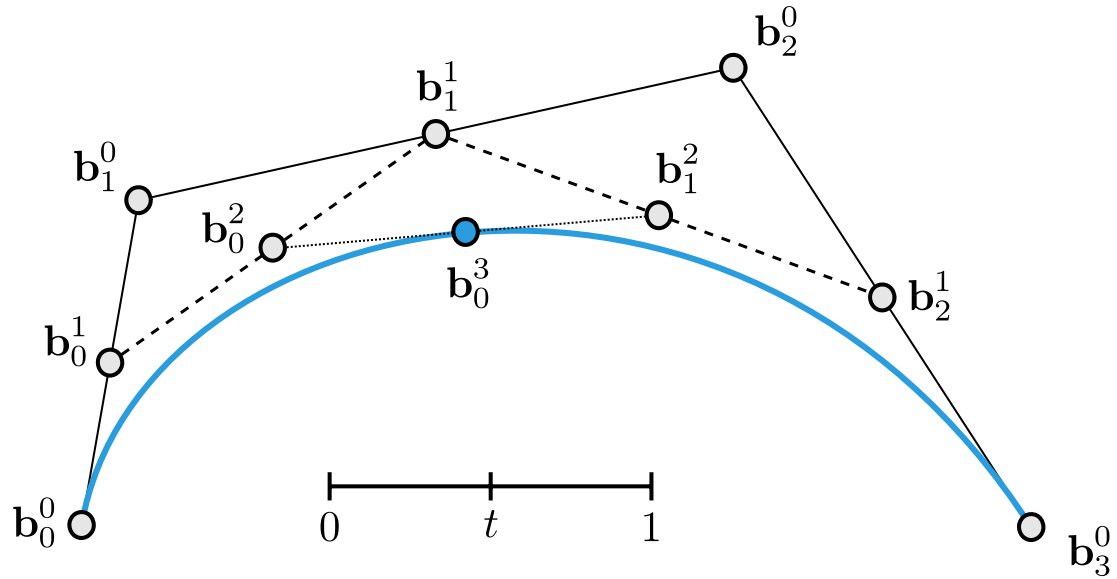
Bezier Curves

$$\mathbf{x}(t) = \sum_{i=0}^n \mathbf{b}_i B_i^n(t)$$

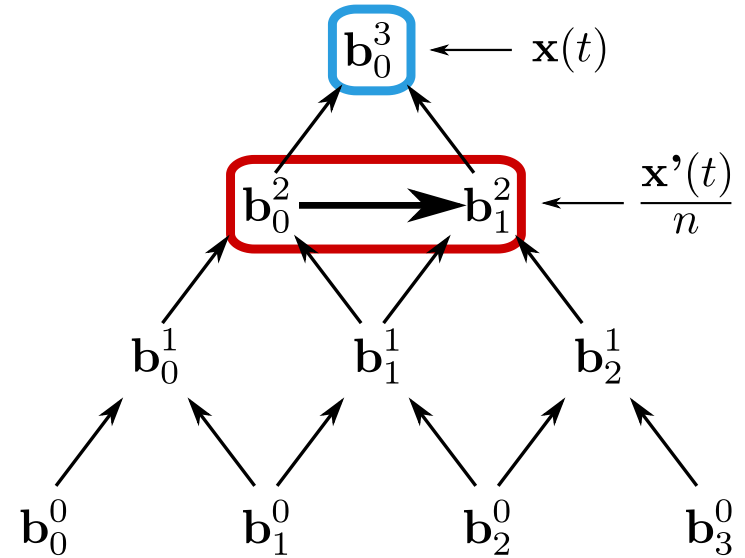
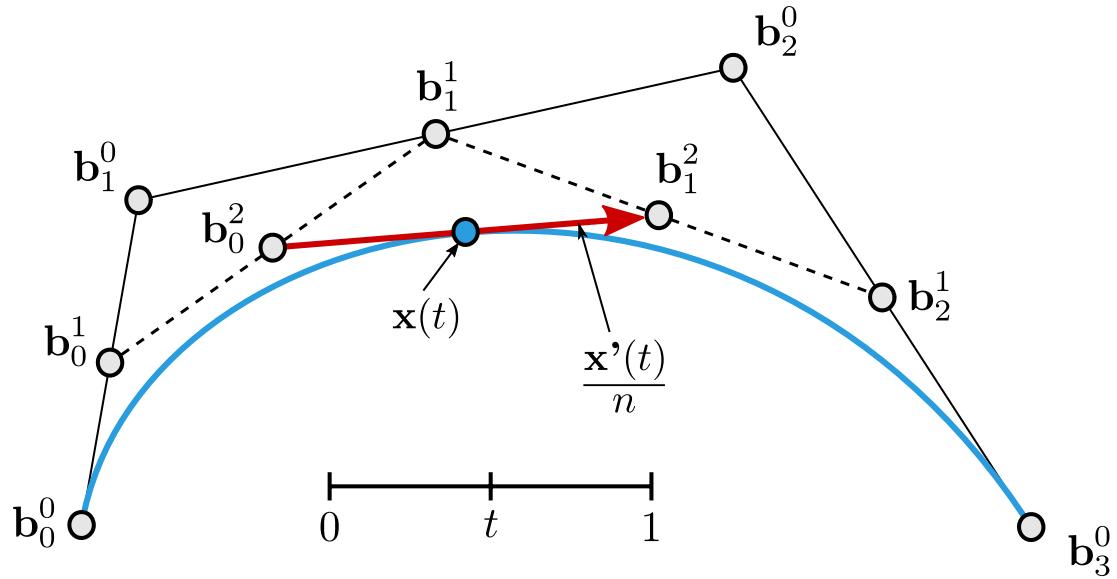
- Polynomial curve
- Affine combination
- Convex hull
- Pseudo-local control
- Endpoint interpolation



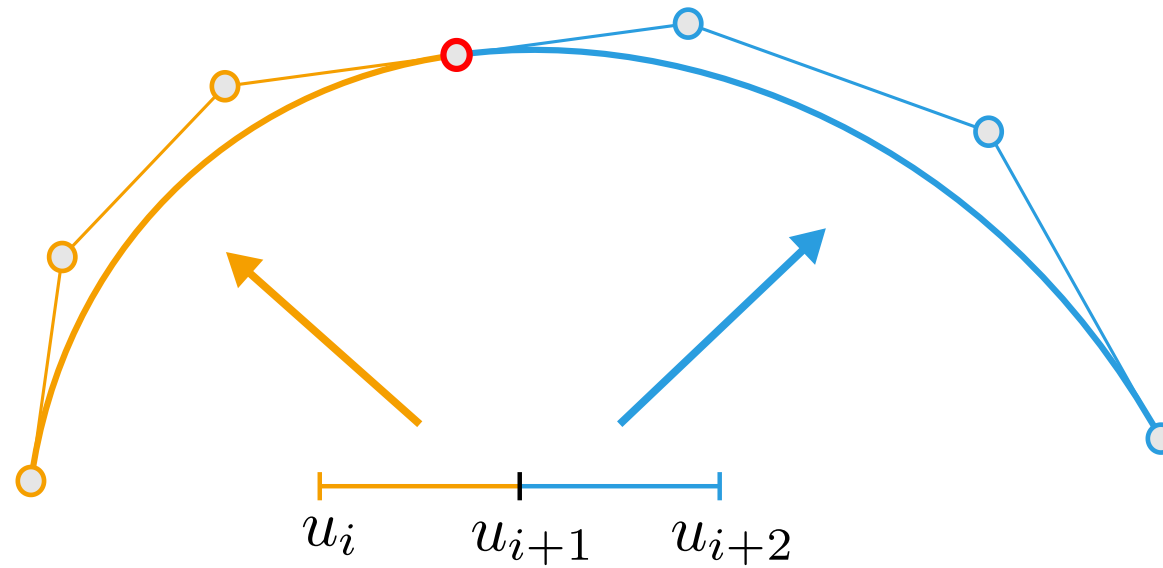
de Casteljau Algorithm



Derivative of a Bezier Curve

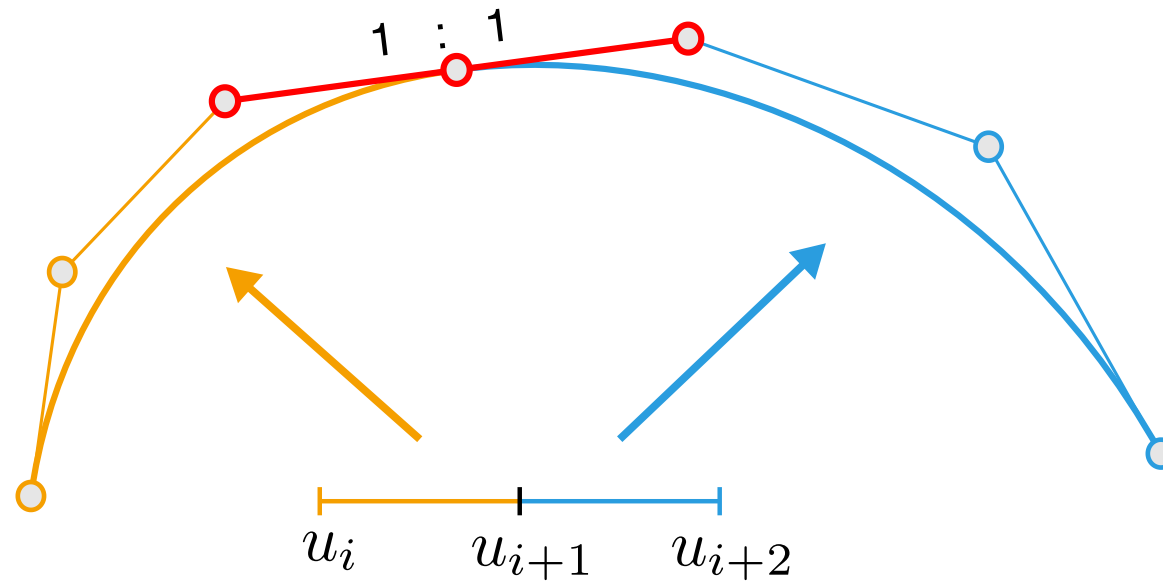


Piecewise Bezier Curves



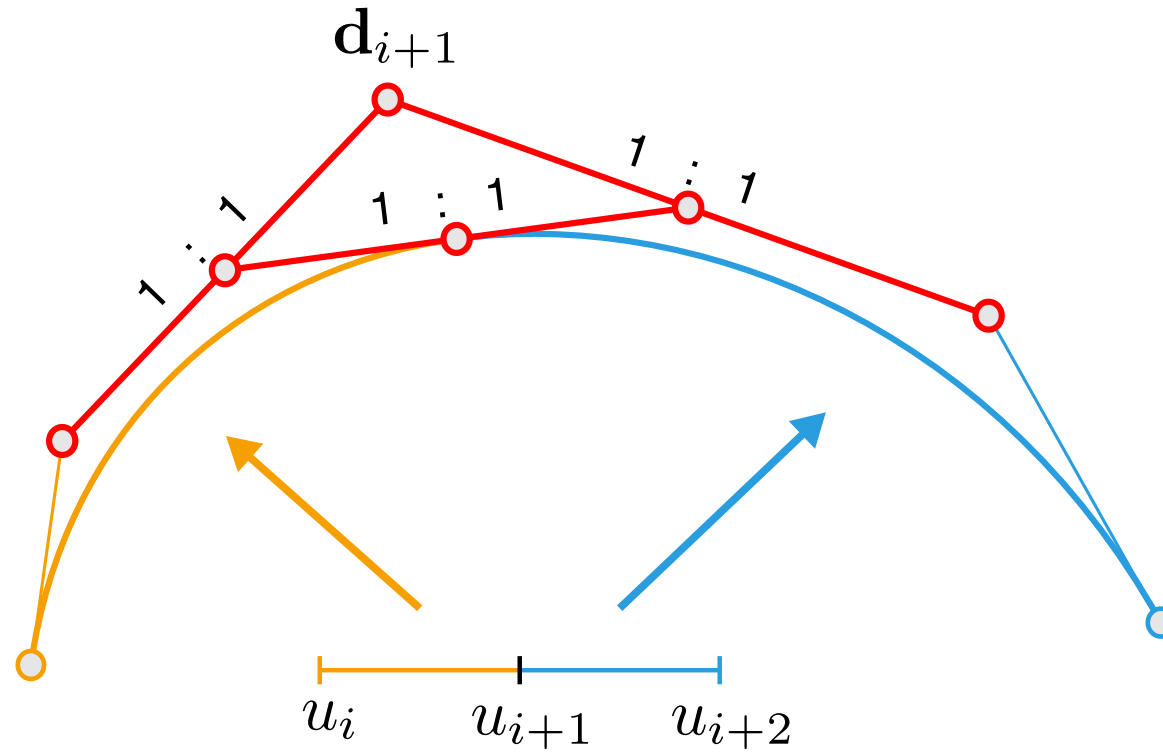
C^0 continuity: $\mathbf{a}_n = \mathbf{b}_0$

Piecewise Bezier Curves



$$C^1 \text{ continuity: } \mathbf{a}_n = \mathbf{b}_0 = \frac{1}{2}(\mathbf{a}_{n-1} + \mathbf{b}_1)$$

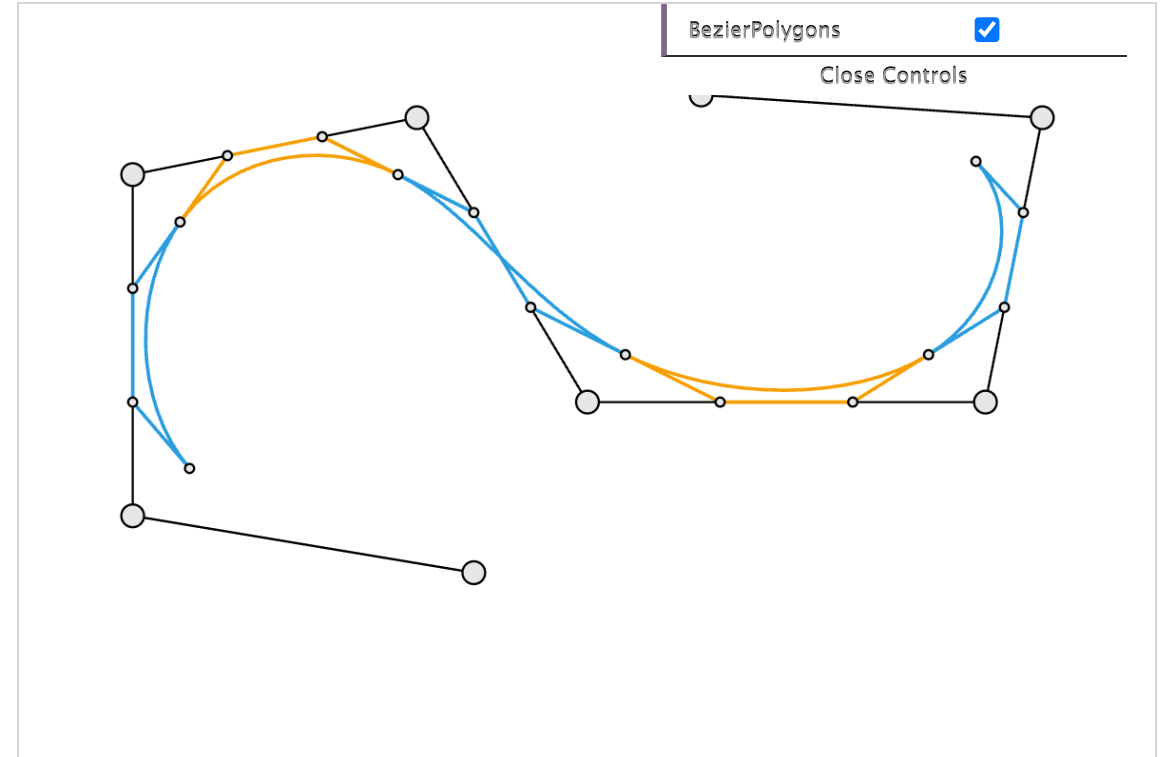
Piecewise Bezier Curves



C^2 continuity: A-frame construction

Bezier Curves vs. B-Spline Curves

- Disadvantages of Bezier curves
 - Adding more DoFs raises degree
 - High-degree polynomials tend to oscillate
 - Only pseudo-local control
- Splines overcome these problems
 - Low-degree curve segments avoid oscillations
 - Connect segments with C^{n-1} smoothness
 - Allows for local modifications
 - No more endpoint interpolation



Freeform Surfaces

Parametric Surfaces

- Parametric surface $\mathbf{x}(u, v)$:

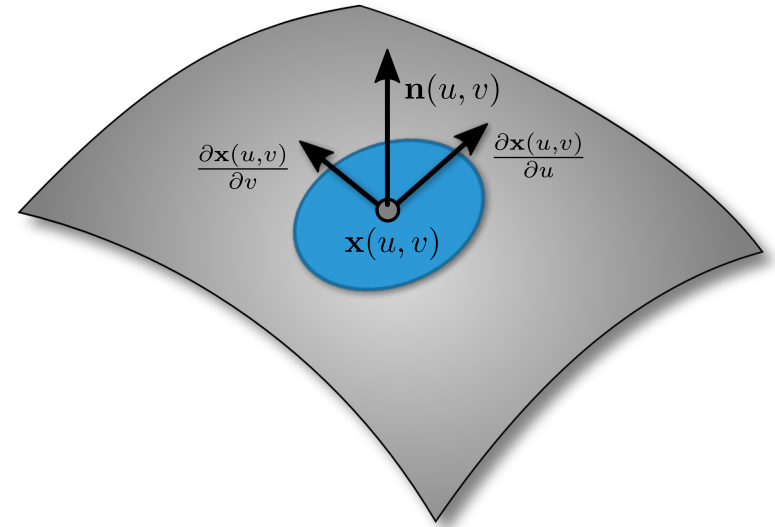
$$\mathbf{x}(u, v) = (x(u, v), y(u, v), z(u, v))^T$$

- Tangents in u and v direction

$$\frac{\partial}{\partial u} \mathbf{x}(u, v), \quad \frac{\partial}{\partial v} \mathbf{x}(u, v)$$

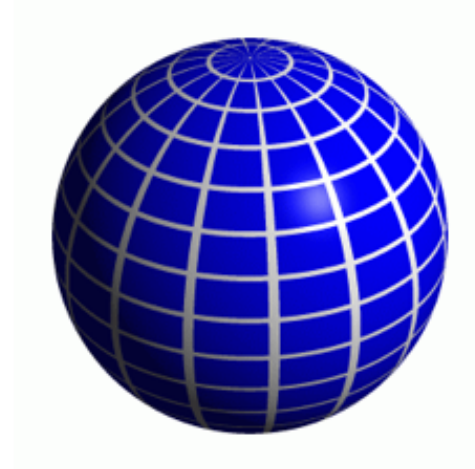
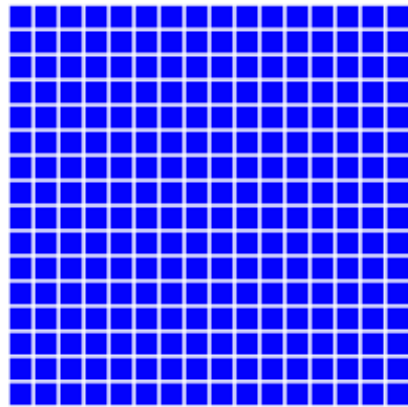
- Normal vector as the normalized cross-product of the two tangent vectors

$$\mathbf{n}(u, v) = \frac{\frac{\partial}{\partial u} \mathbf{x}(u, v) \times \frac{\partial}{\partial v} \mathbf{x}(u, v)}{\left\| \frac{\partial}{\partial u} \mathbf{x}(u, v) \times \frac{\partial}{\partial v} \mathbf{x}(u, v) \right\|}$$



Example: Sphere

$$\mathbf{f}: [0, 2\pi] \times [0, \pi] \rightarrow \mathbb{R}^3 \quad \text{mit} \quad \mathbf{f}(u, v) = \begin{pmatrix} r \cos(u) \sin(v) \\ r \sin(u) \sin(v) \\ r \cos(v) \end{pmatrix}$$

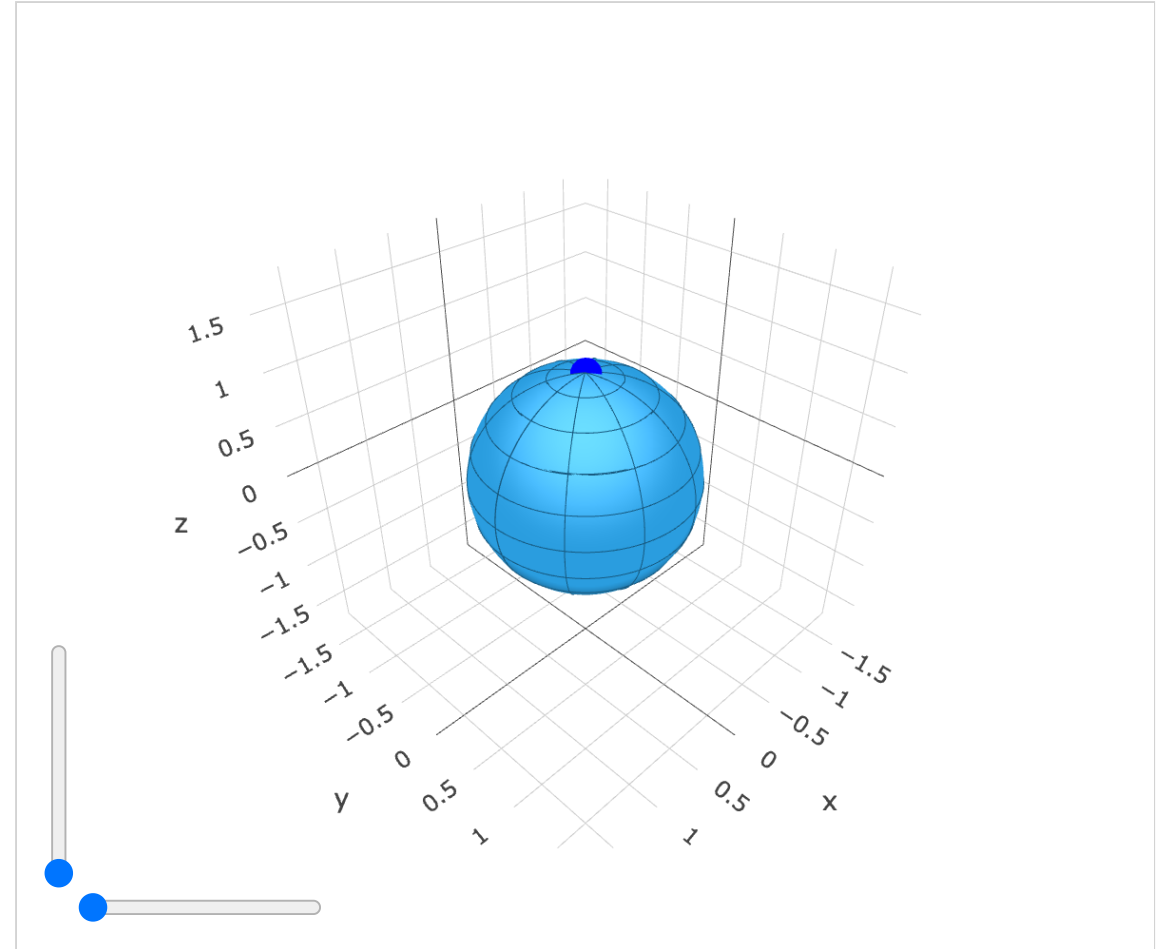


Example: Sphere

$$\mathbf{f}(u, v) = \begin{pmatrix} \cos(u) \sin(v) \\ \sin(u) \sin(v) \\ \cos(v) \end{pmatrix}$$

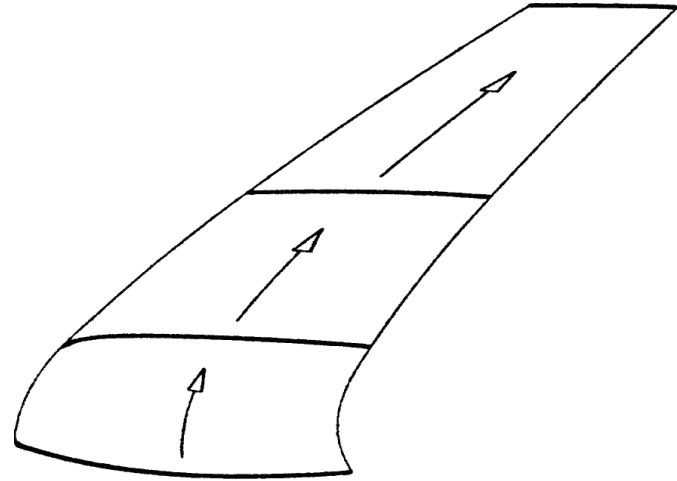
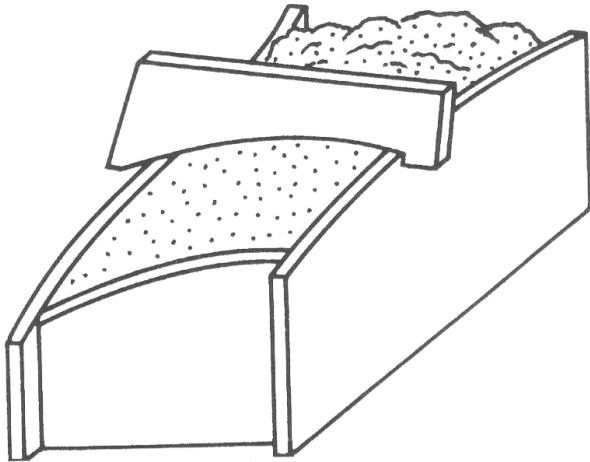
$$\frac{\partial \mathbf{f}}{\partial u}(u, v) = \begin{pmatrix} -\sin(u) \sin(v) \\ \cos(u) \sin(v) \\ 0 \end{pmatrix}$$

$$\frac{\partial \mathbf{f}}{\partial v}(u, v) = \begin{pmatrix} \cos(u) \cos(v) \\ \sin(u) \cos(v) \\ -\sin(v) \end{pmatrix}$$



Tensor Product Surfaces

- Surface is defined by a curve moving through space
- The curve itself might deform as it moves

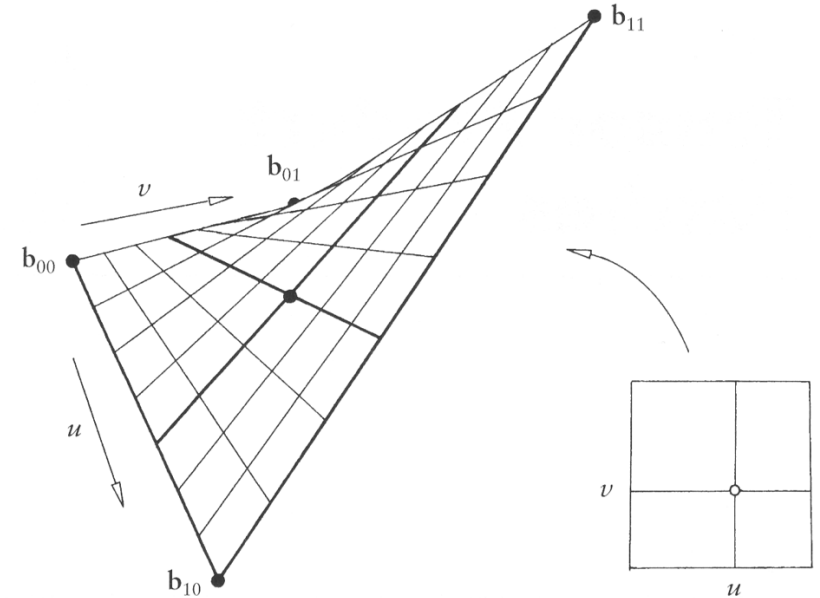


Bilinear Interpolation

- Simplest case is a bilinear patch:

$$\mathbf{x}(u, v) = (1 - u, \quad u) \begin{pmatrix} \mathbf{b}_{00} & \mathbf{b}_{01} \\ \mathbf{b}_{10} & \mathbf{b}_{11} \end{pmatrix} \begin{pmatrix} 1 - v \\ v \end{pmatrix}$$

- Isoparametric curves are straight lines



Bilinear Patch

```
1  # four control points
2  b00 = vector([0.0, 0.0, 0.5])
3  b01 = vector([0.0, 1.0, 0.0])
4  b10 = vector([1.0, -0.2, -0.5])
5  b11 = vector([1.0, 1.2, 0.7])
6
7  # function for bilinear interpolation
8  var('u,v')
9  def x(u,v):
10     return (1-v)*((1-u)*b00 + u*b01) + v*((1-u)*b10 + u*b11)
11
12  # plot it
13  patch = parametric_plot3d( x(u,v), (u,0,1), (v,0,1), color='lightgrey', viewer='threejs')
14
15  # add isolines
16  @interact
17  def _(U=(0.0,1.0), V=(0.0, 1.0)):
18     iso_v = parametric_plot3d( x(u,V), (u,0,1), color='red', thickness=10, viewer='threejs')
19     iso_u = parametric_plot3d( x(U,v), (v,0,1), color='green', thickness=10, viewer='threejs')
20     show( patch + iso_u + iso_v )
```

Evaluate

Language: Sage 

Tensor Product Bezier Surfaces

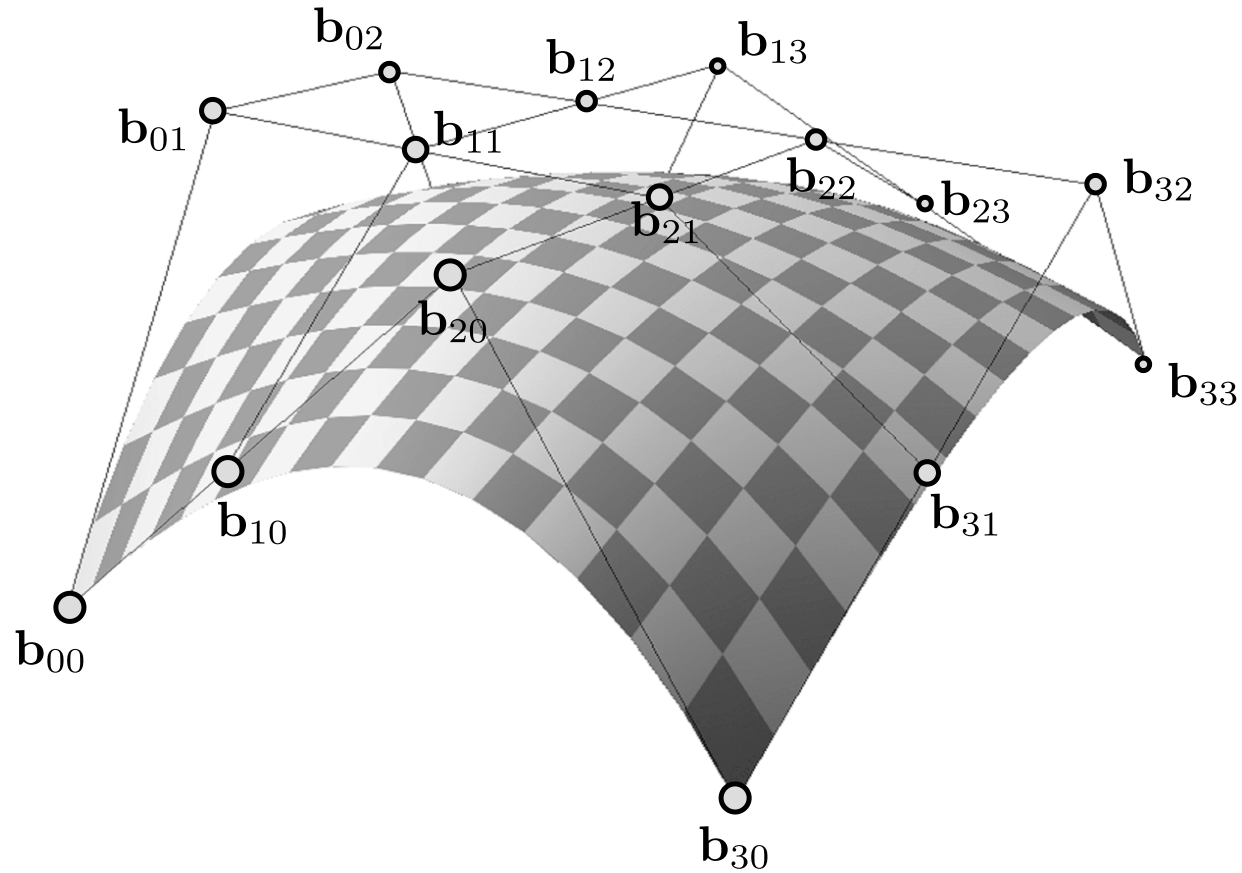
- Let a Bezier curve be given as $\mathbf{x}(u) = \sum_{i=0}^m \mathbf{b}_i B_i^m(u)$
- Control points $\mathbf{b}_i$ move on Bezier curves $\mathbf{b}_i(v)$

$$\mathbf{b}_i(v) = \sum_{j=0}^n \mathbf{b}_{i,j} B_j^n(v)$$

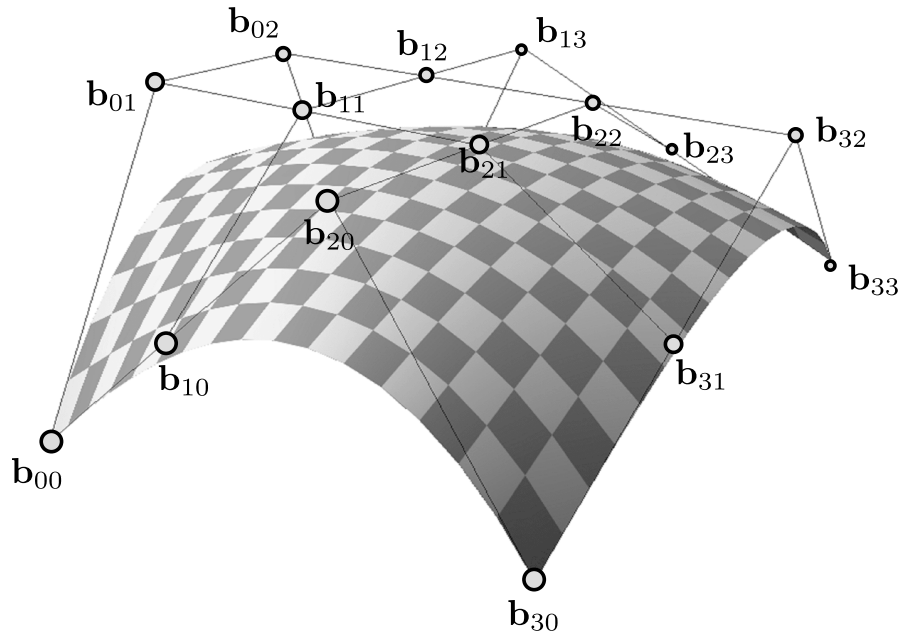
- This defines a tensor product Bezier patch

$$\mathbf{x}(u, v) = \sum_{i=0}^m \sum_{j=0}^n \mathbf{b}_{i,j} B_i^m(u) B_j^n(v)$$

Example: Bicubic Bezier Patch



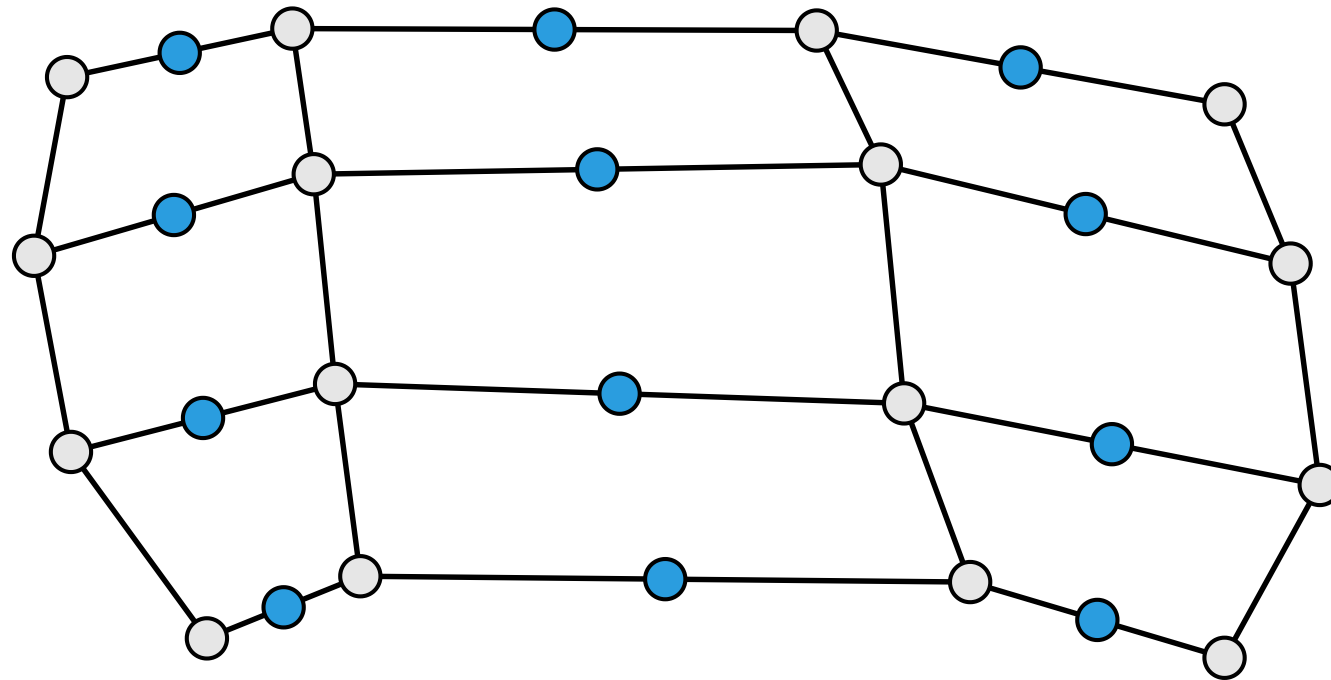
Properties of Bezier Patches



- u - and v -isolines are Bezier curves on the surface
- $\mathbf{x}(u, v)$ is affine combination of control points
- Surface lies in convex hull of control points
- Surface interpolates corners of control grid
- Surface interpolates boundary curves

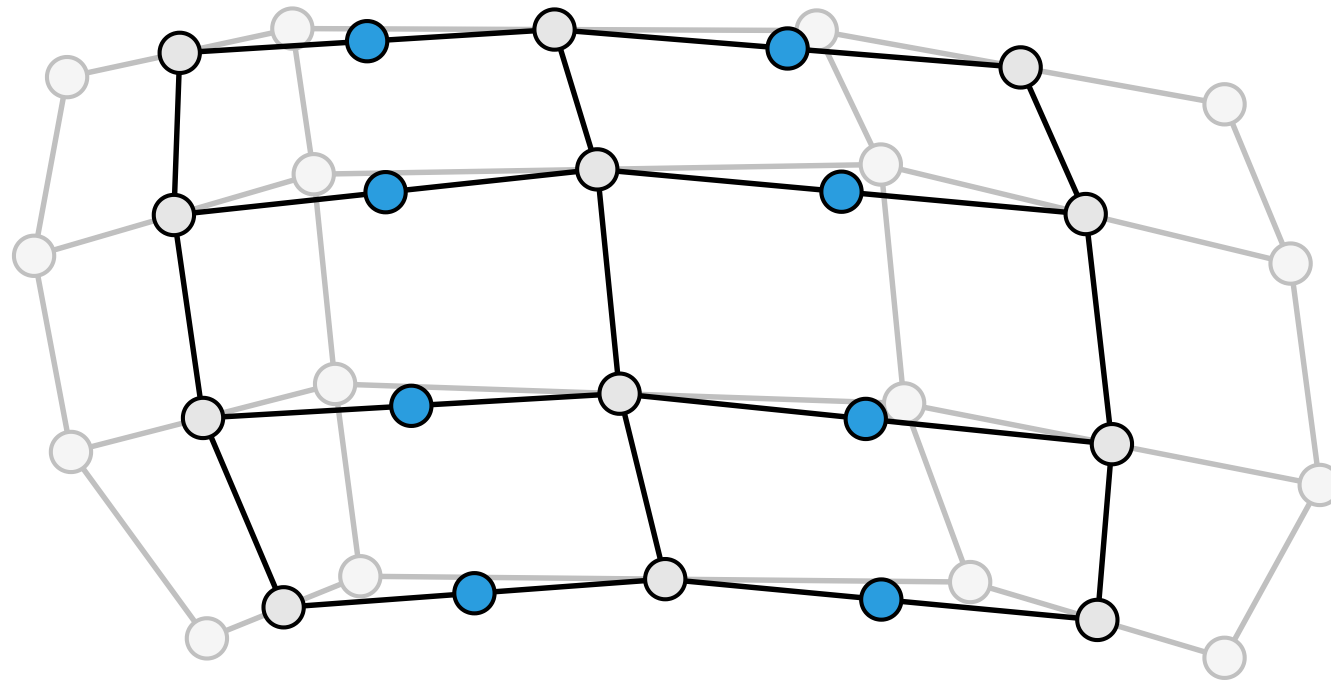
de Casteljau Algorithm

- Apply de Casteljau with parameter u for each row of control points.



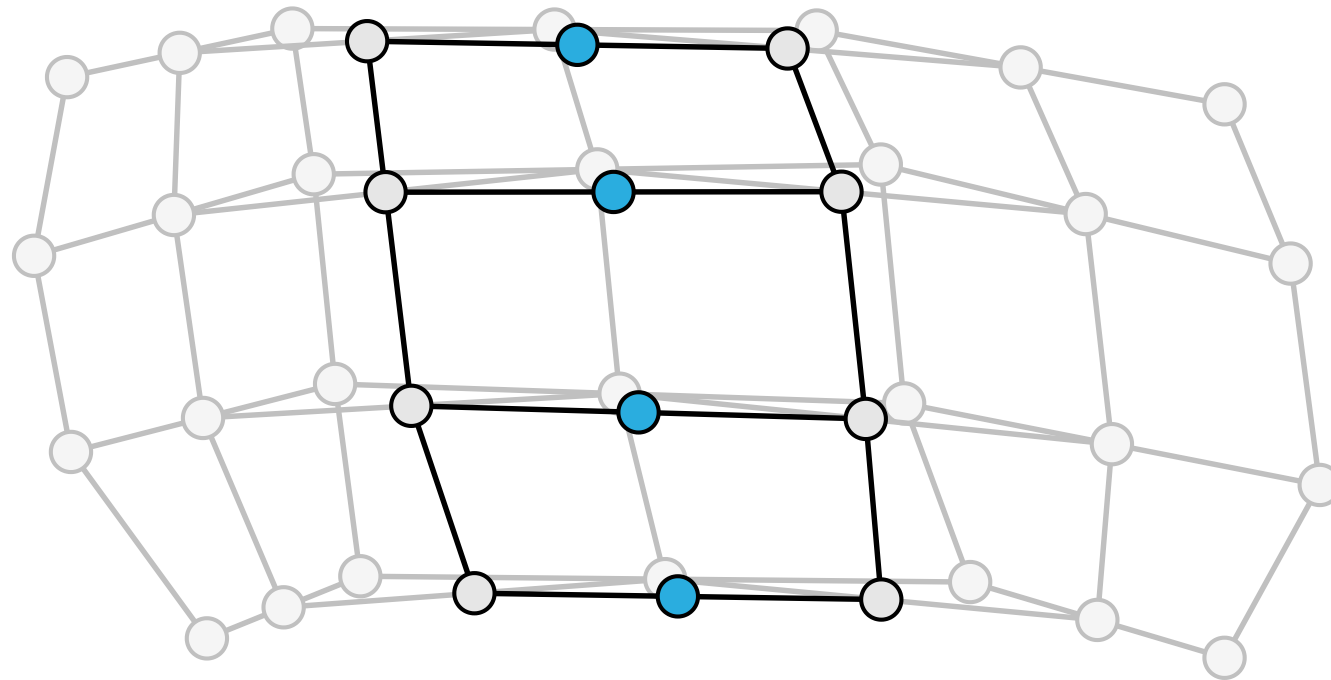
de Casteljau Algorithm

- Apply de Casteljau with parameter u for each row of control points.



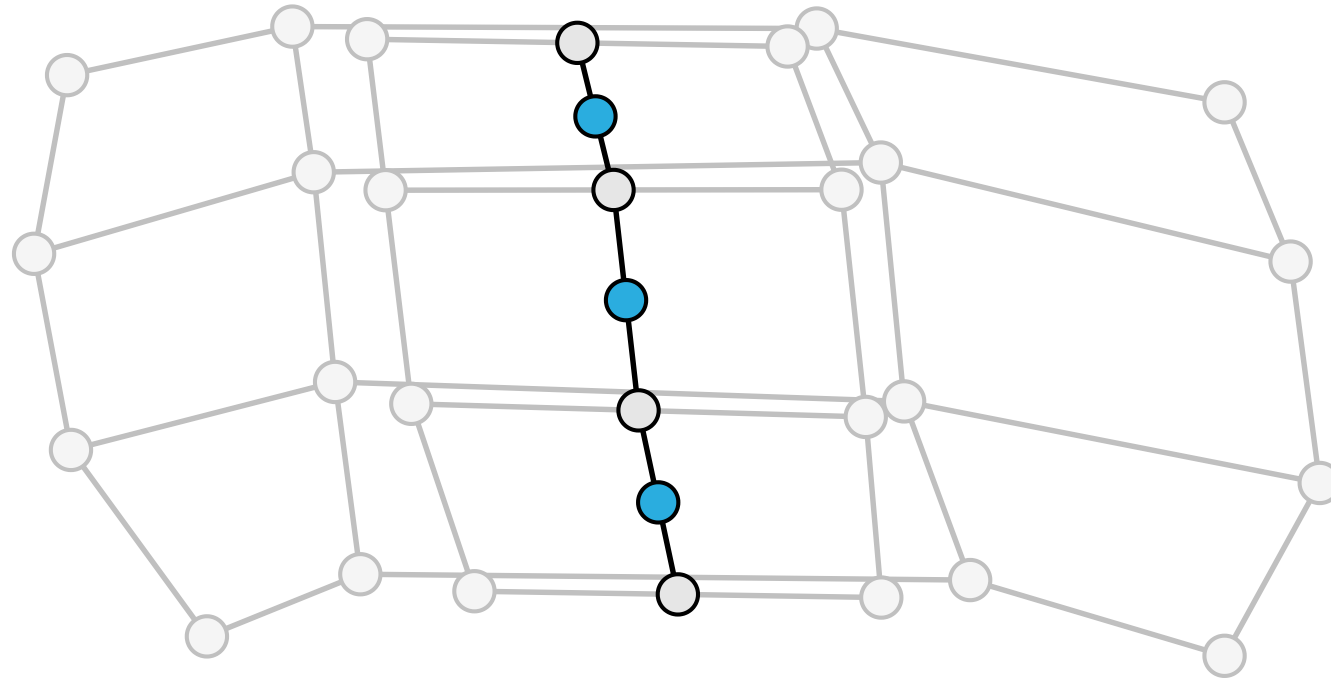
de Casteljau Algorithm

- Apply de Casteljau with parameter u for each row of control points.



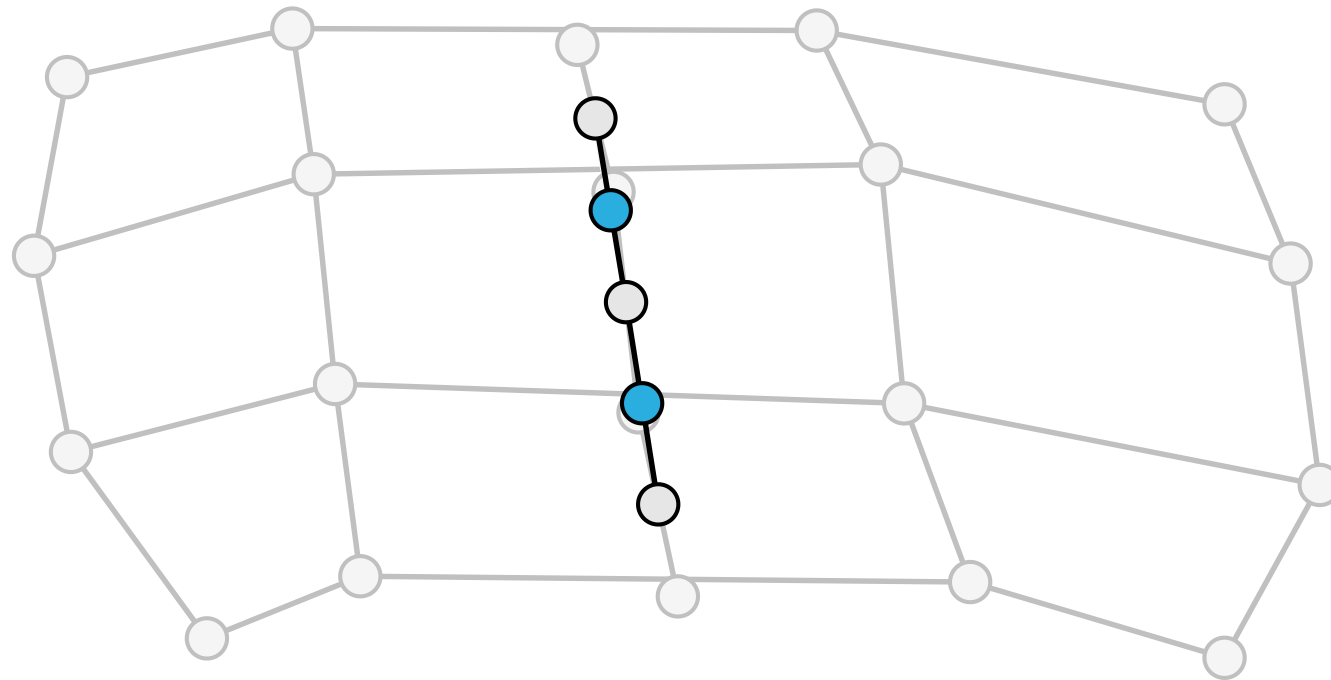
de Casteljau Algorithm

- Apply de Casteljau with parameter v to remaining column.



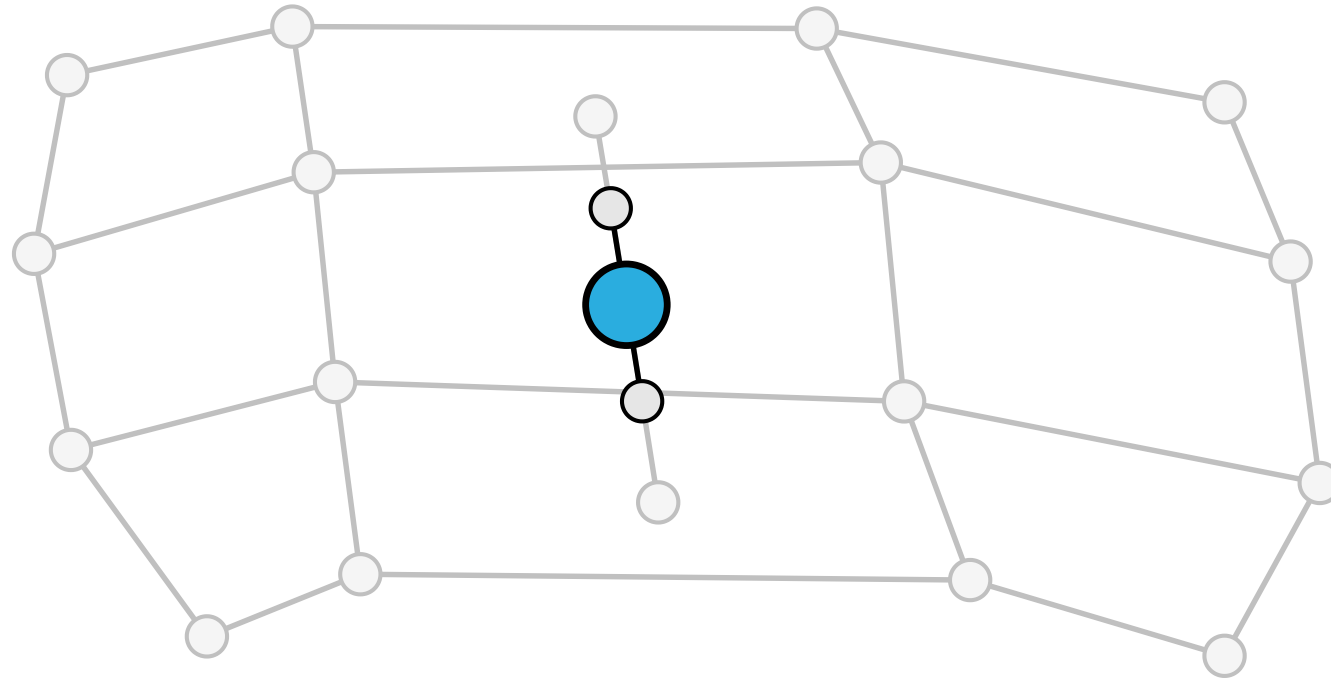
de Casteljau Algorithm

- Apply de Casteljau with parameter v to remaining column.



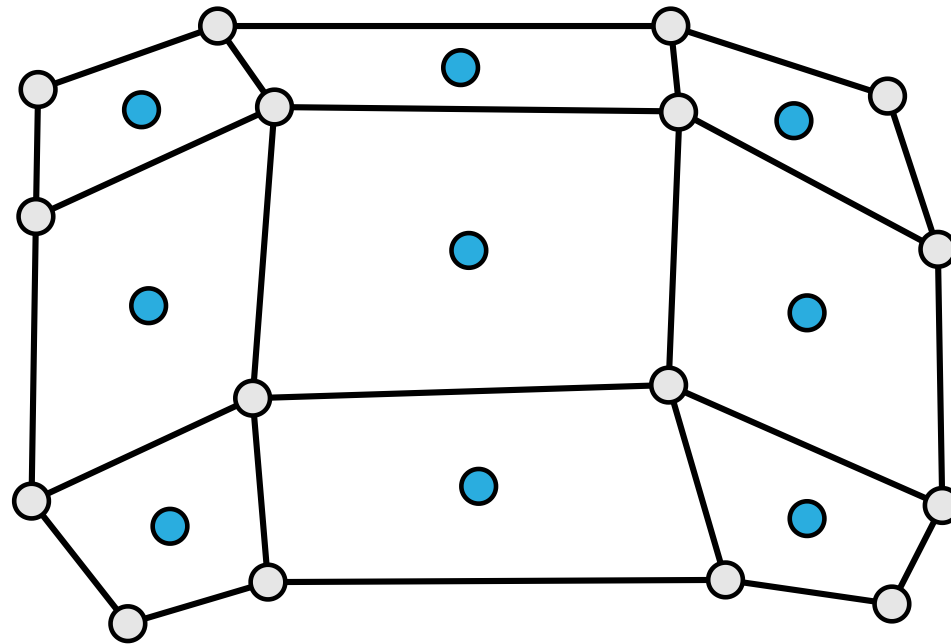
de Casteljau Algorithm

- Apply de Casteljau with parameter v to remaining column.



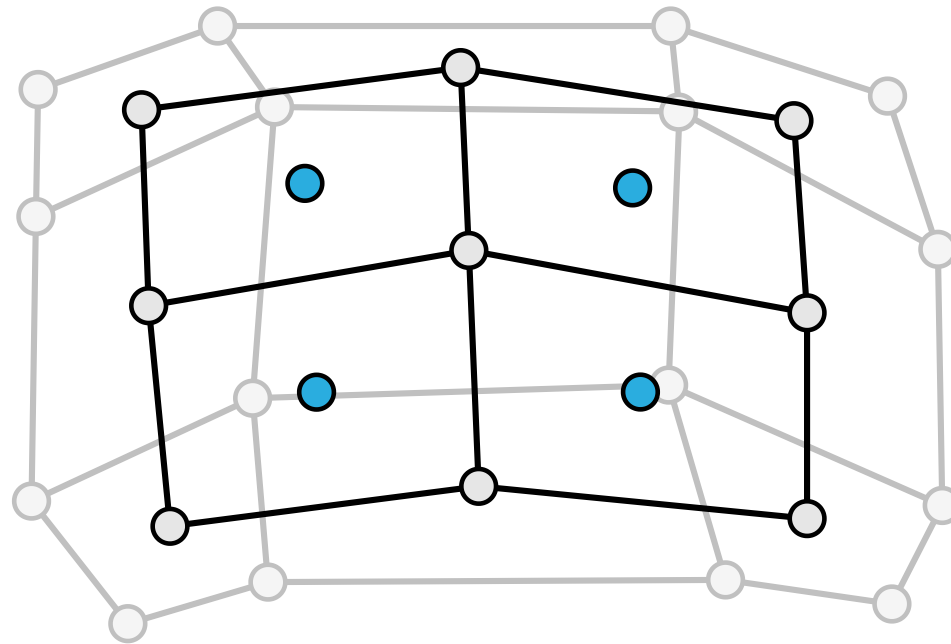
de Casteljau Algorithm for $n = m$

- Construct 2D pyramid using repeated bilinear interpolation.



de Casteljau Algorithm for $n = m$

- Construct 2D pyramid using repeated bilinear interpolation.



de Casteljau Algorithm for $n = m$

- Construct 2D pyramid using repeated bilinear interpolation.

