

Thm For every NFA $N = (Q, \Sigma, \delta, q_0, F)$
has equivalent DFA M

$$L(N) = L(M)$$

Proof: $M = (2^Q, \Sigma, \tilde{\delta}, \{q_0\}, \tilde{F})$

$$\tilde{\delta}(A, a) = \bigcup_{q \in A} \delta(q, a)$$

$$\tilde{F} = \{A \in 2^Q : A \cap F \neq \emptyset\}$$

Correctness claim: M 's state after $x \in \Sigma^*$
is $\tilde{\delta}(\{q_0\}, x) = \boxed{A}$

$\Updownarrow$

N 's possible states after x is $\boxed{A}$

Base case: $x = \varepsilon : \tilde{\delta}(\{q_0\}, \varepsilon) = \underbrace{\{q_0\}}_{A}$

Inductive step. Assume claim holds for x ,
want to prove it for $x.a$

$A = N$'s possible states after

$$\tilde{\delta}(\{q_0\}, x.a) = \tilde{\delta}(\underbrace{\tilde{\delta}(\{q_0\}, x)}_{A}, a) \xrightarrow{\Sigma}$$

$= A = N$'s possible states
after x

(def)

$$= \bigcup_{q \in A} \delta(q, a)$$

$q \in A$

N 's possible
after $x.a$