

Algorithms: Recall Binary Search Trees and a Dynamic Programming

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EPFL School of Computer and Communication Sciences

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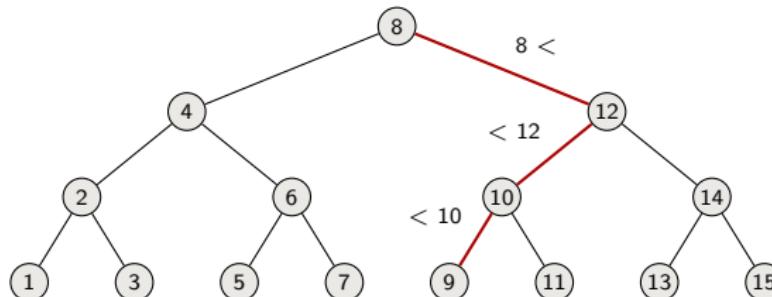


RECALL BINARY SEARCH TREES

Binary Search Trees

Key property:

- ▶ If y is in the left subtree of x then $y.key < x.key$
- ▶ If y is in the right subtree of x then $y.key \geq x.key$

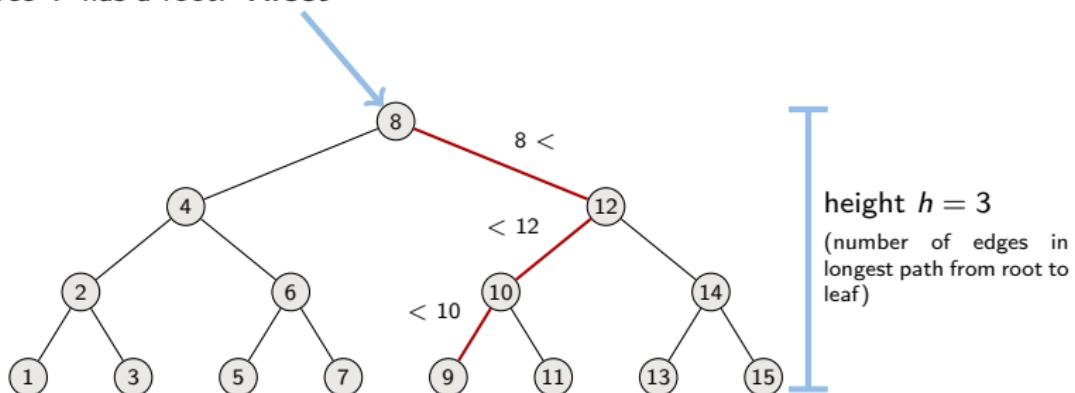


Binary Search Trees

Key property:

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Tree T has a root: $T.root$

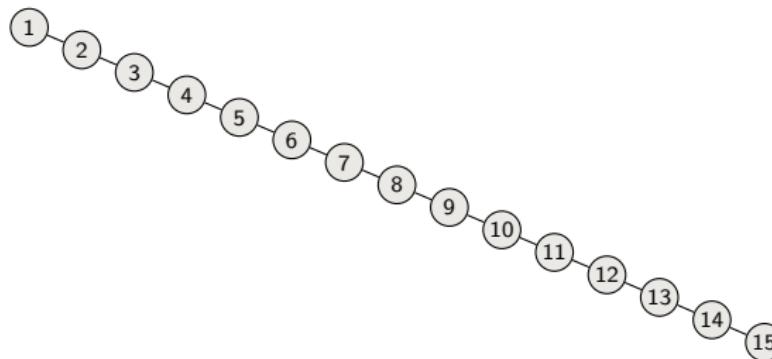


Binary Search Trees

Encodes a strategy whatever number we look for

Key property:

- ▶ If y is in the left subtree of x then $y.key < x.key$
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height $h = 14$

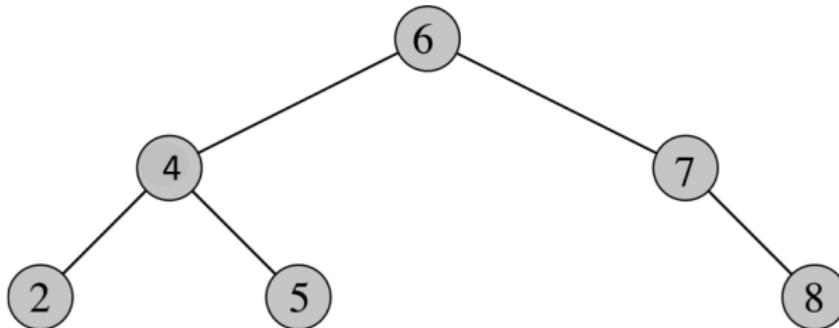
(number of edges in
longest path from root to
leaf)

Basic operations take time proportional to height: $O(h)$

QUERYING A BINARY SEARCH TREE

(Searching, Minimum, Maximum, Successor, Predecessor)

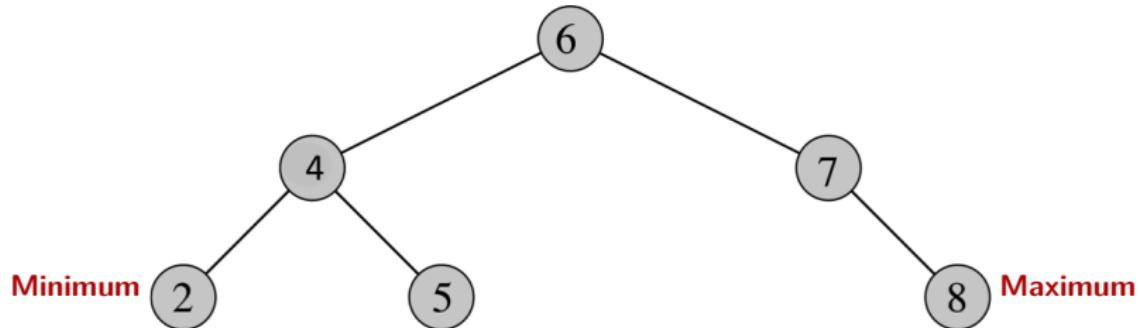
Searching



What is the running time? $O(h)$

```
TREE-SEARCH( $x, k$ )
  if  $x == \text{NIL}$  or  $k == \text{key}[x]$ 
    return  $x$ 
  if  $k < x.\text{key}$ 
    return TREE-SEARCH( $x.\text{left}, k$ )
  else return TREE-SEARCH( $x.\text{right}, k$ )
```

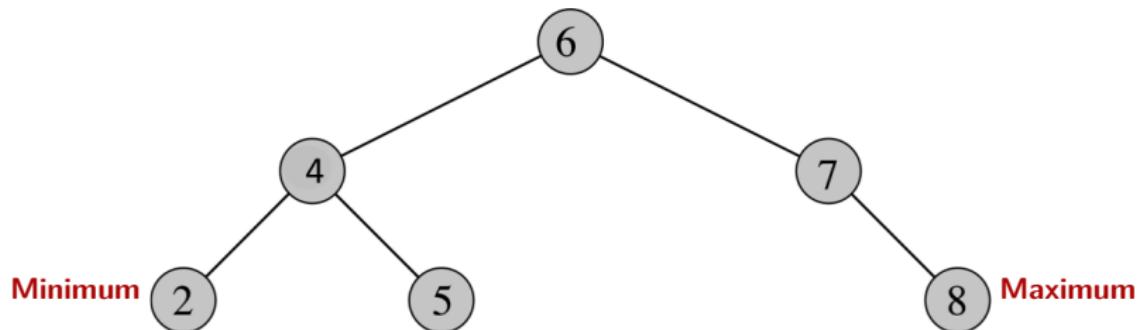
Minimum and Maximum



By key property:

- ▶ Minimum is located in leftmost node
- ▶ Maximum is located in rightmost node

Minimum and Maximum

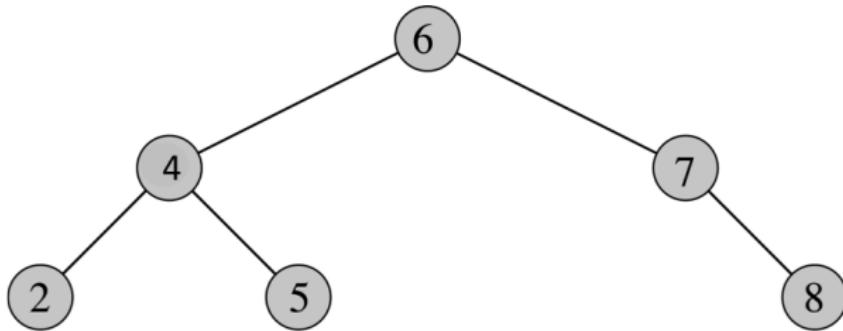


What is the running time? $O(h)$

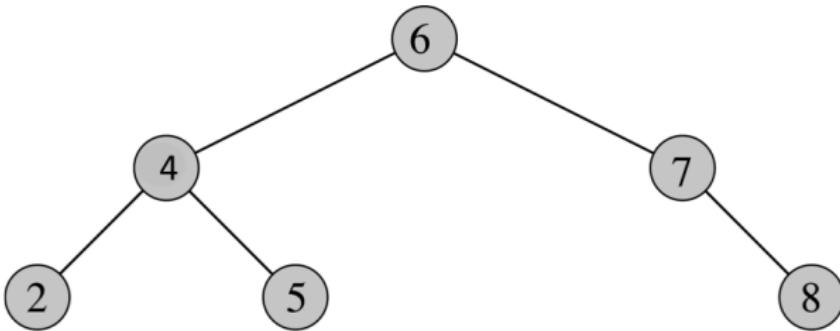
```
TREE-MINIMUM( $x$ )
  while  $x.left \neq \text{NIL}$ 
     $x = x.left$ 
  return  $x$ 
```

```
TREE-MAXIMUM( $x$ )
  while  $x.right \neq \text{NIL}$ 
     $x = x.right$ 
  return  $x$ 
```

Successor

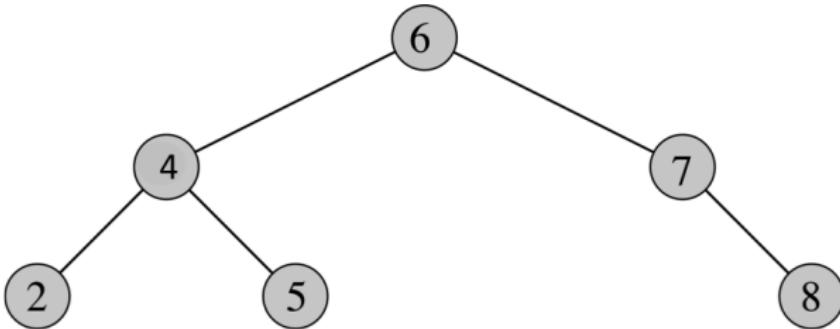


Successor



Successor of a node x is the node y such that $y.key$ is the
“smallest key” $> x.key$

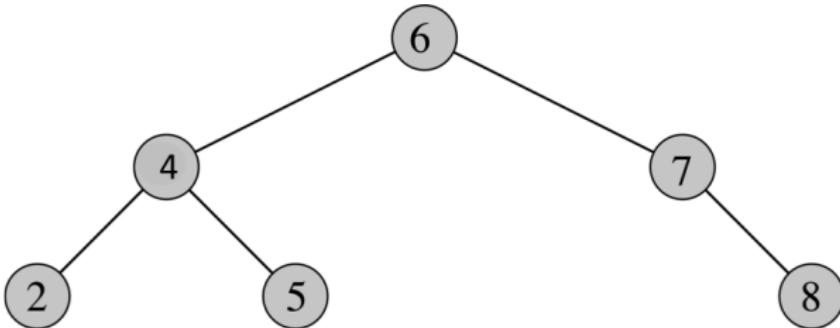
Successor



Successor of a node x is the node y such that $y.key$ is the
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- ▶ What is the successor of 6?

Successor

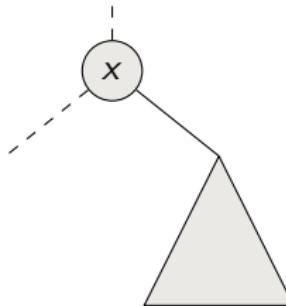


Successor of a node x is the node y such that $y.key$ is the
“smallest key” $> x.key$

- ▶ What is the successor of 6?
- ▶ What is the successor of 5?

Two cases when finding successor of x :

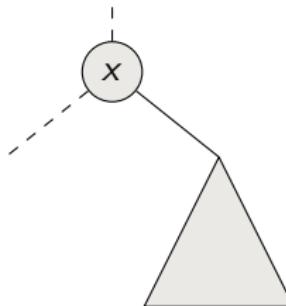
Case 1: x has a non-empty right subtree



Two cases when finding successor of x :

Case 1: x has a non-empty right subtree

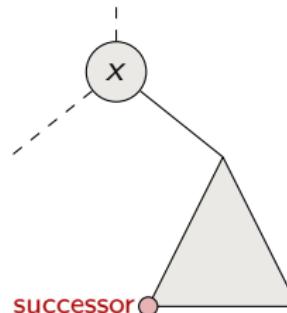
x 's successor is the minimum in
the right subtree



Two cases when finding successor of x :

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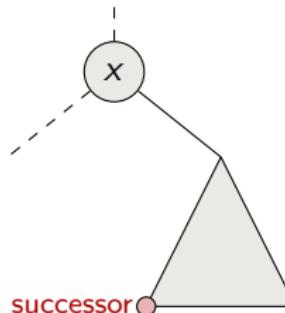
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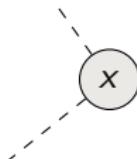
Two cases when finding successor of x :

Case 1: x has a non-empty right subtree

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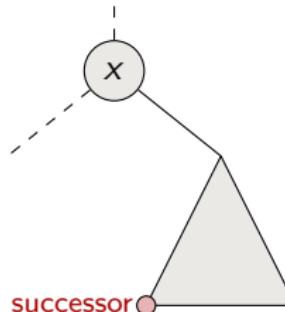
Case 2: x has an empty right subtree



Two cases when finding successor of x :

Case 1: x has a non-empty right subtree

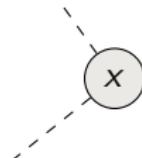
x 's successor is the minimum in the right subtree



Case 2: x has an empty right subtree

As long as we go to the left up the tree we're visiting smaller keys

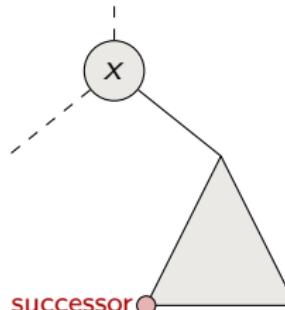
x 's successor is y is the node that x is the predecessor of
(x is the maximum in y 's left subtree)



Two cases when finding successor of x :

Case 1: x has a non-empty right subtree

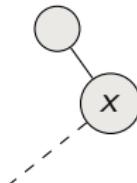
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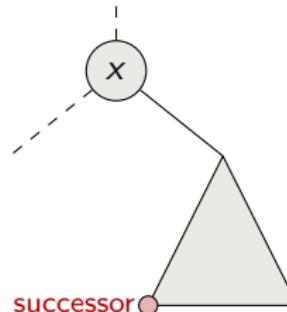
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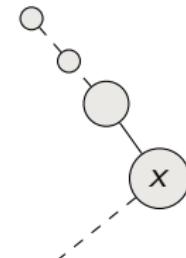
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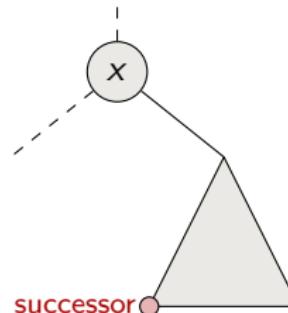
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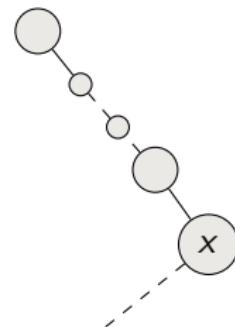
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Case 2: x has an empty right subtree

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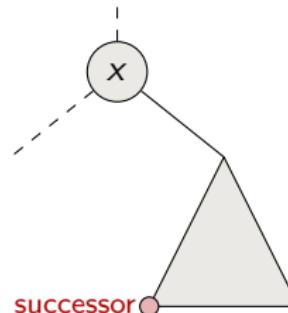
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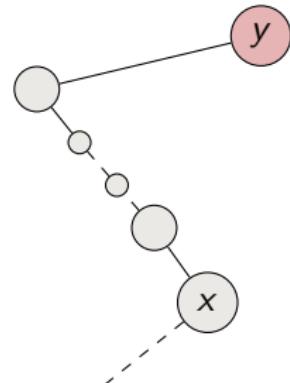
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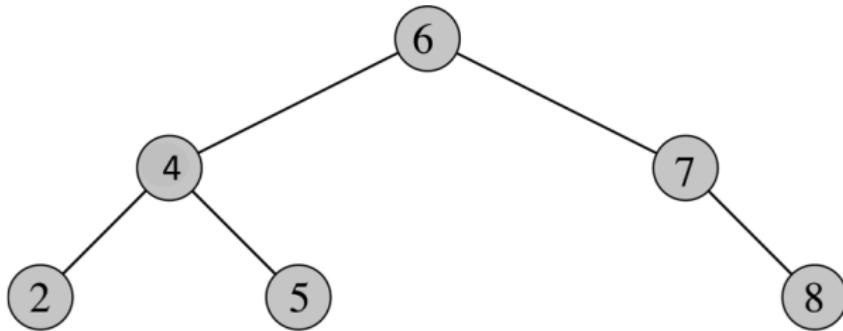
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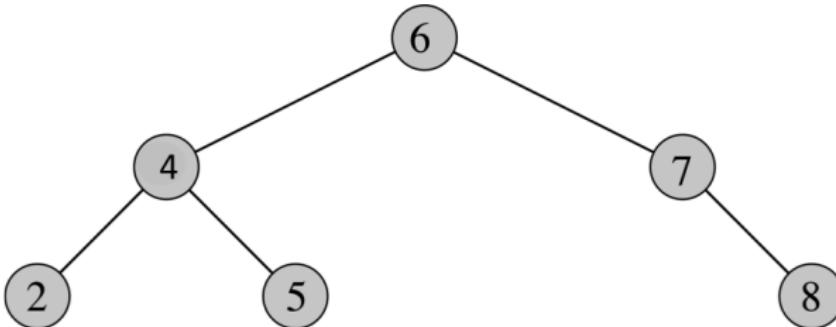
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Successor (Predecessor is symmetric)

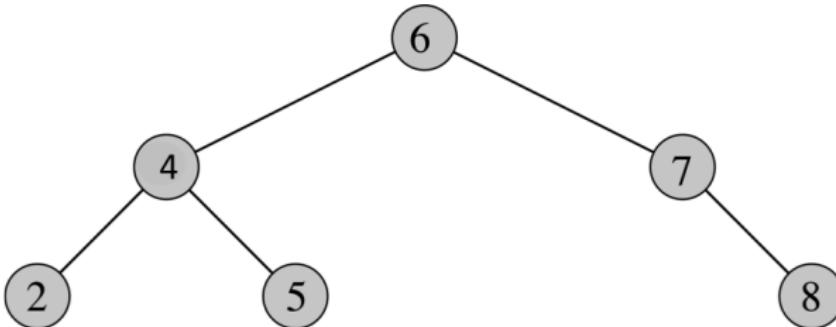


Successor (Predecessor is symmetric)



```
TREE-SUCCESSOR( $x$ )
  if  $x.right \neq \text{NIL}$ 
    return TREE-MINIMUM( $x.right$ )
   $y = x.p$ 
  while  $y \neq \text{NIL}$  and  $x == y.right$ 
     $x = y$ 
     $y = y.p$ 
  return  $y$ 
```

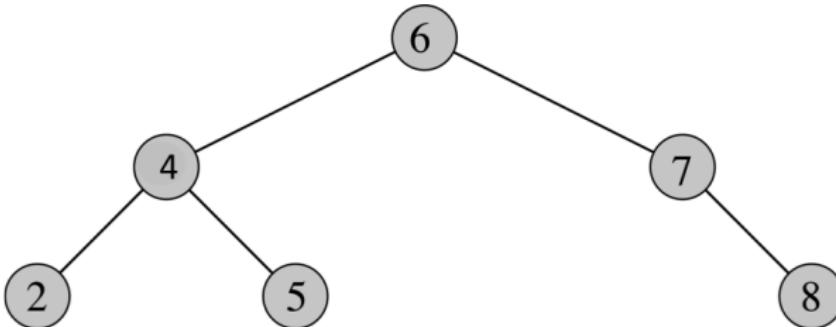
Successor (Predecessor is symmetric)



What is the running time?

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Successor (Predecessor is symmetric)



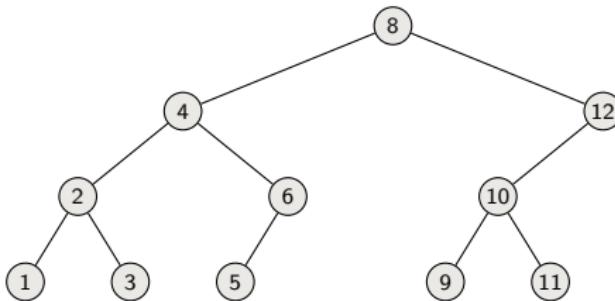
What is the running time? $O(h)$

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PRINTING A BINARY SEARCH TREE

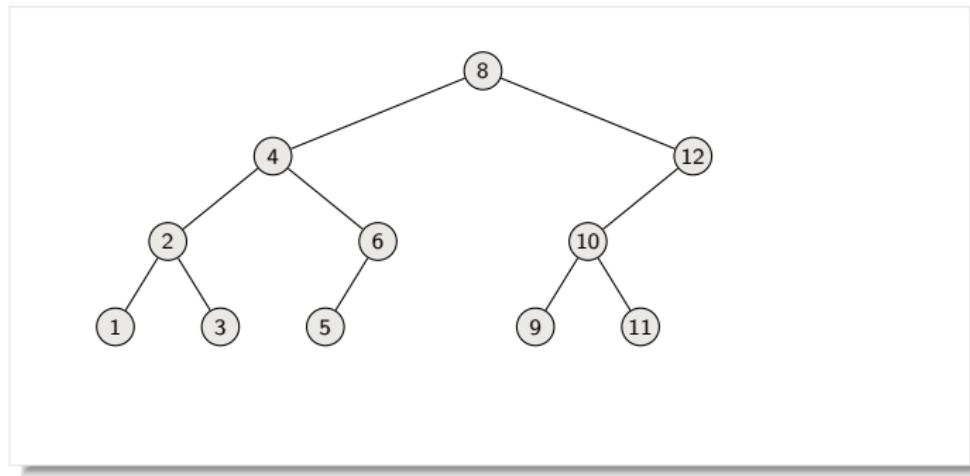
(Inorder, Preorder, Postorder)

Printing Inorder (Idea)



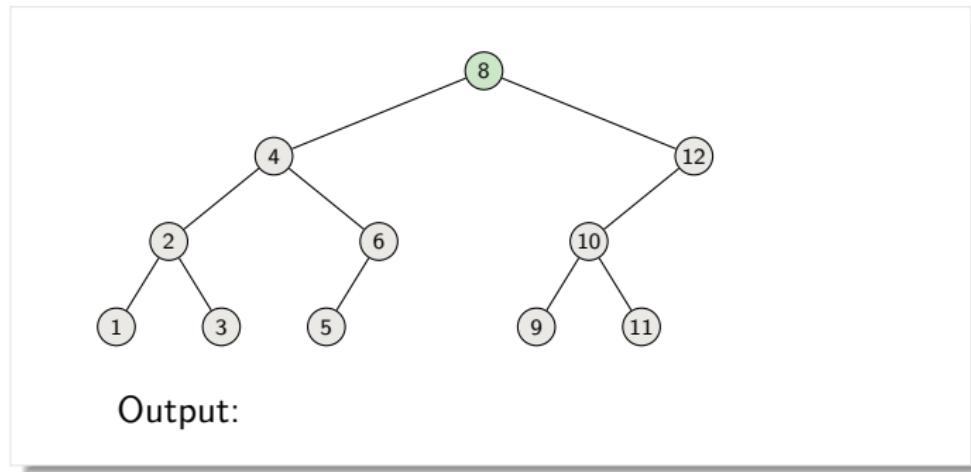
Printing Inorder (Idea)

- ▶ Print left subtree recursively
- ▶ Print root
- ▶ Print right subtree recursively



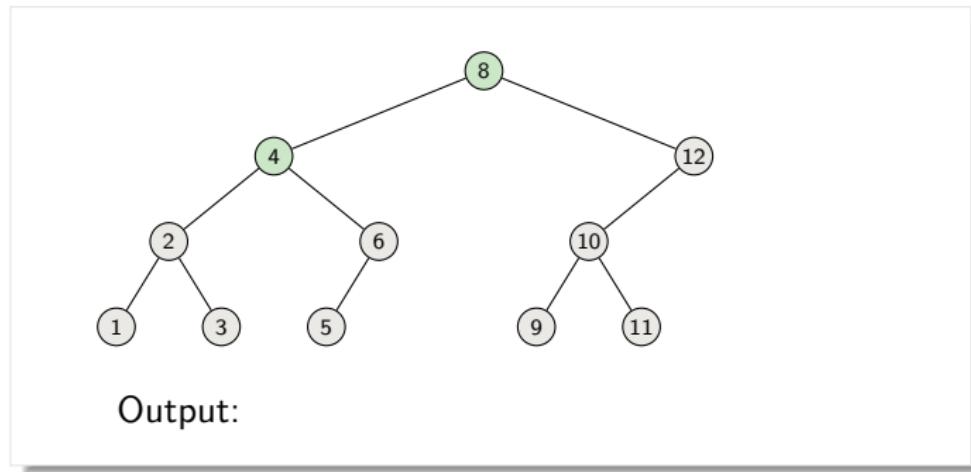
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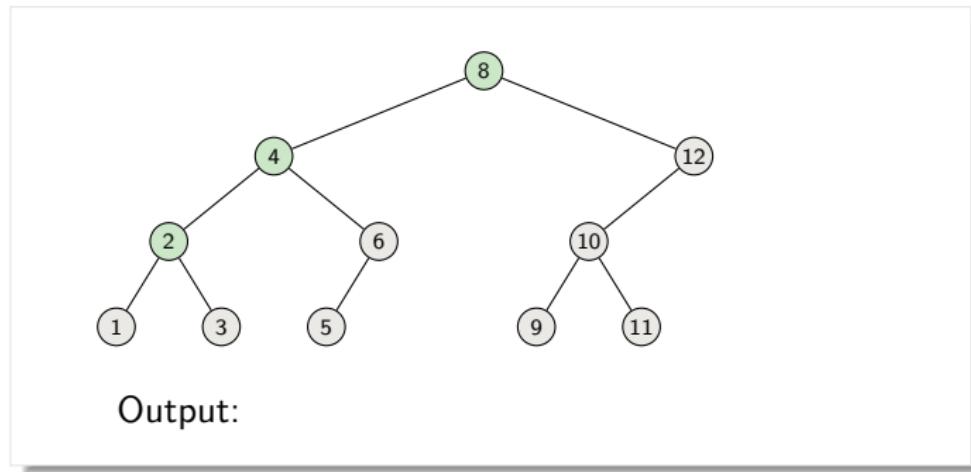
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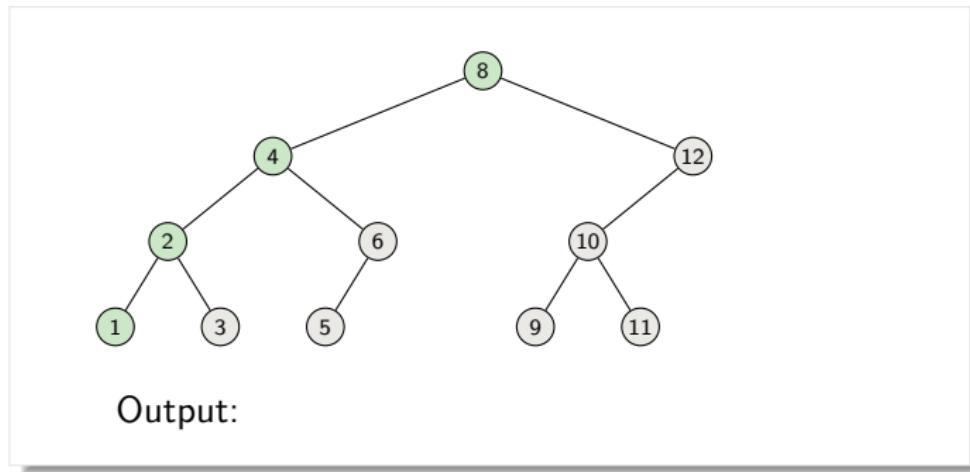
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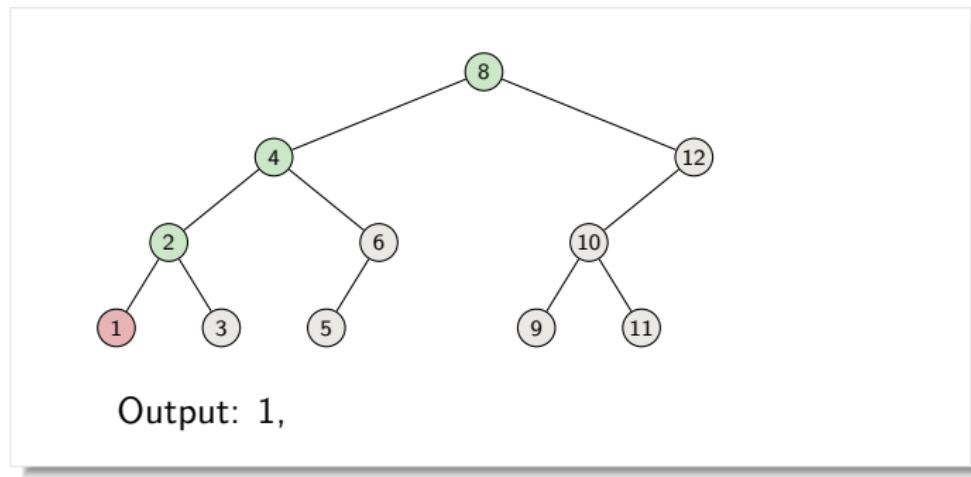
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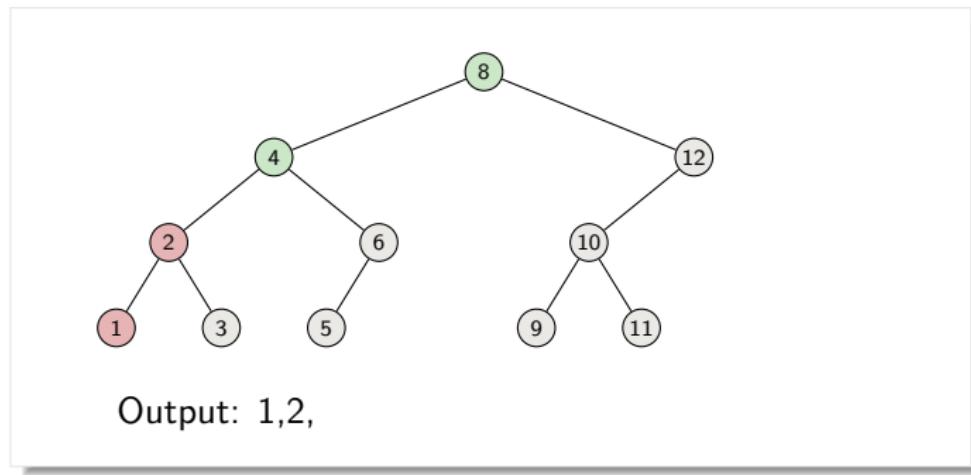
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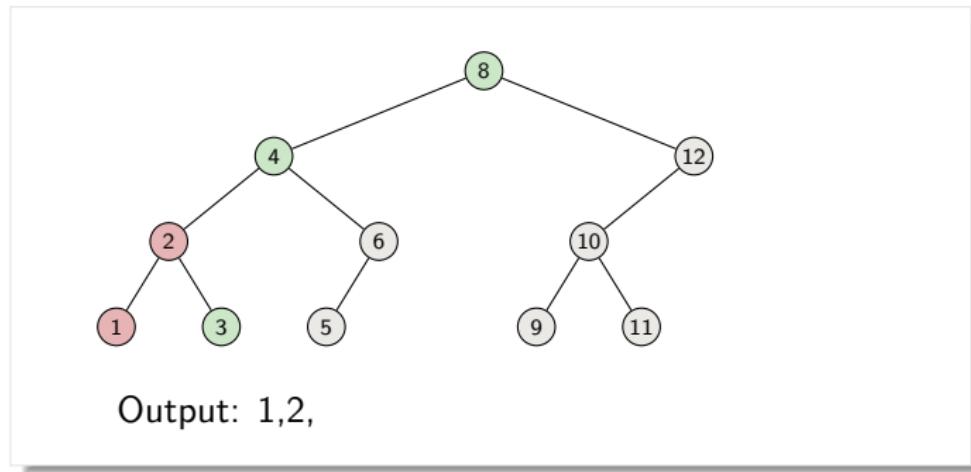
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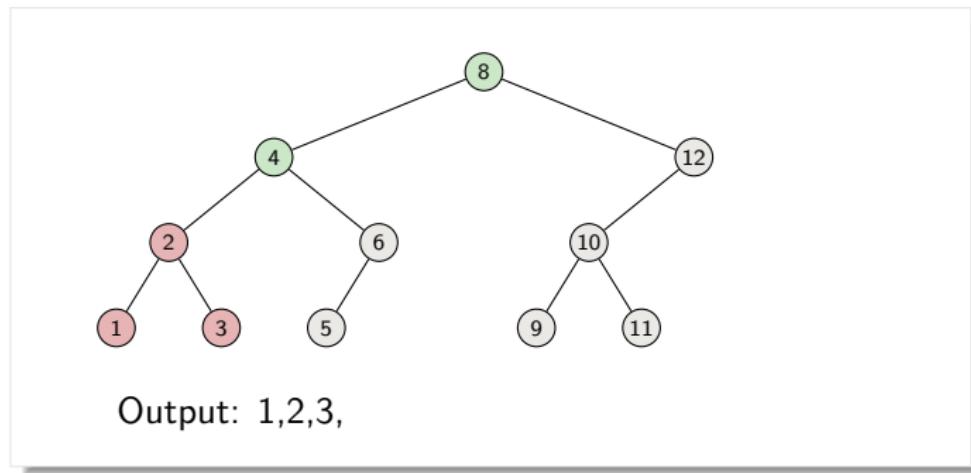
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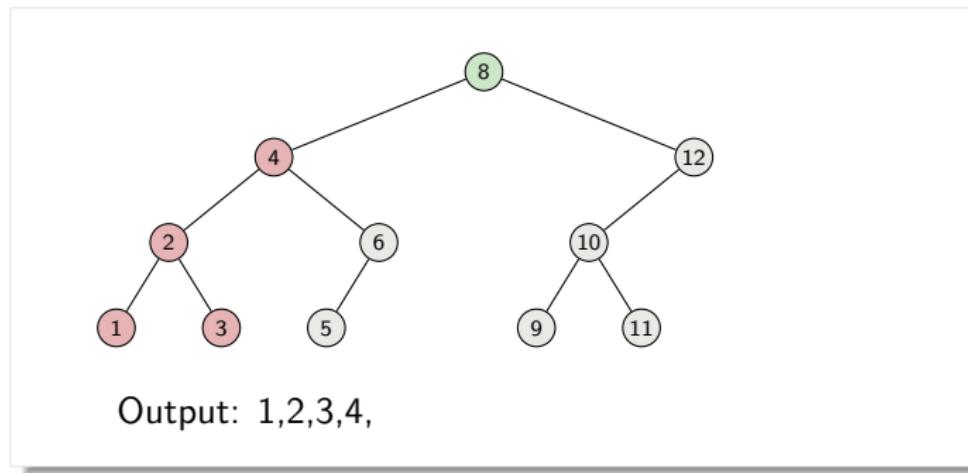
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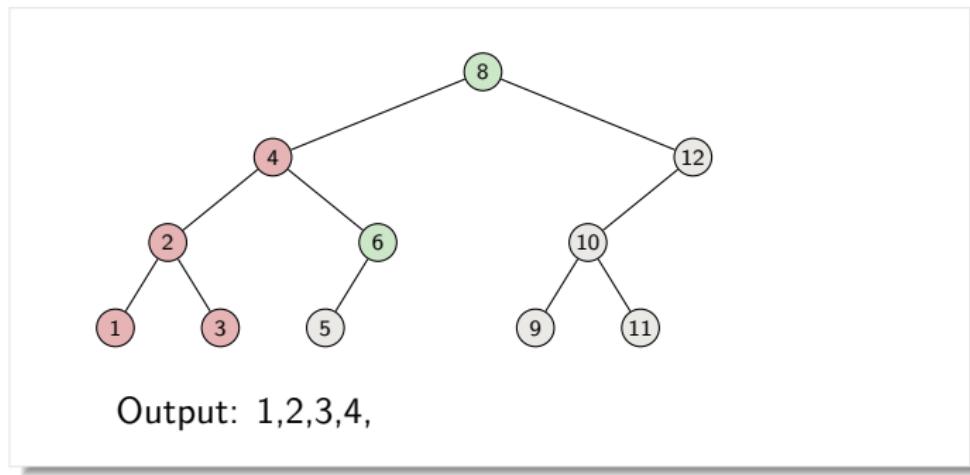
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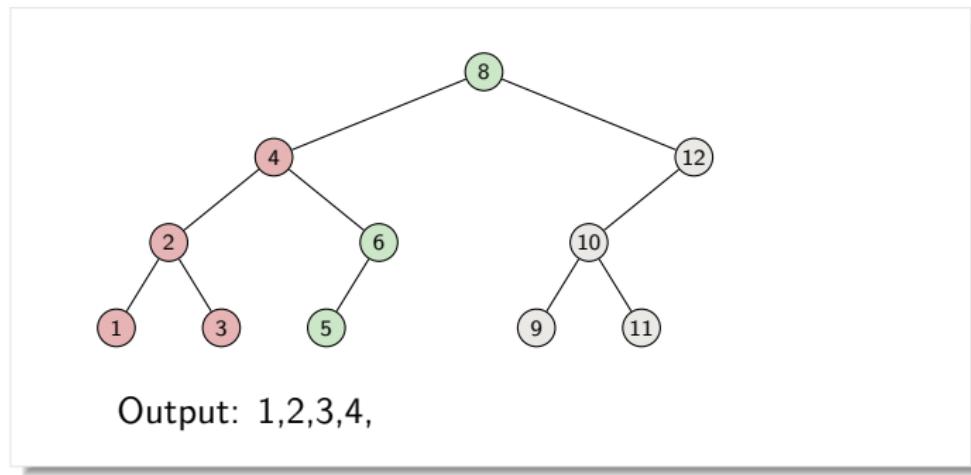
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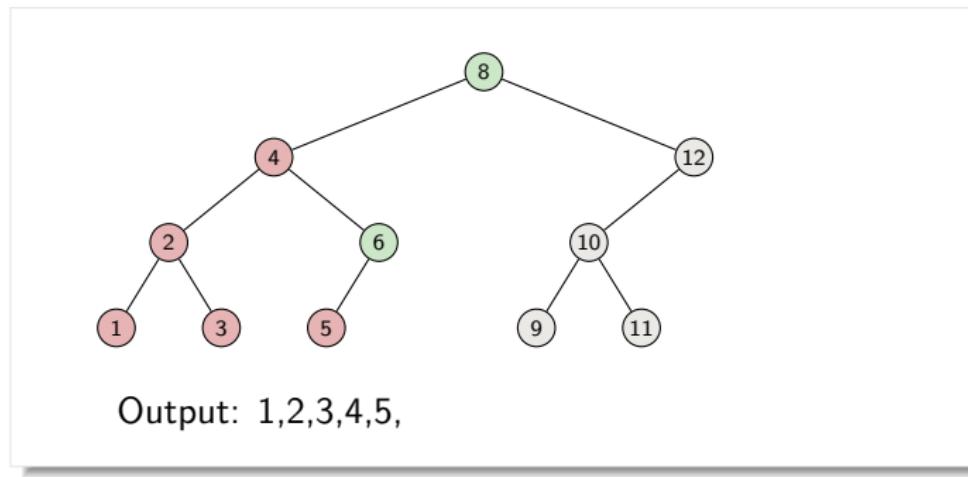
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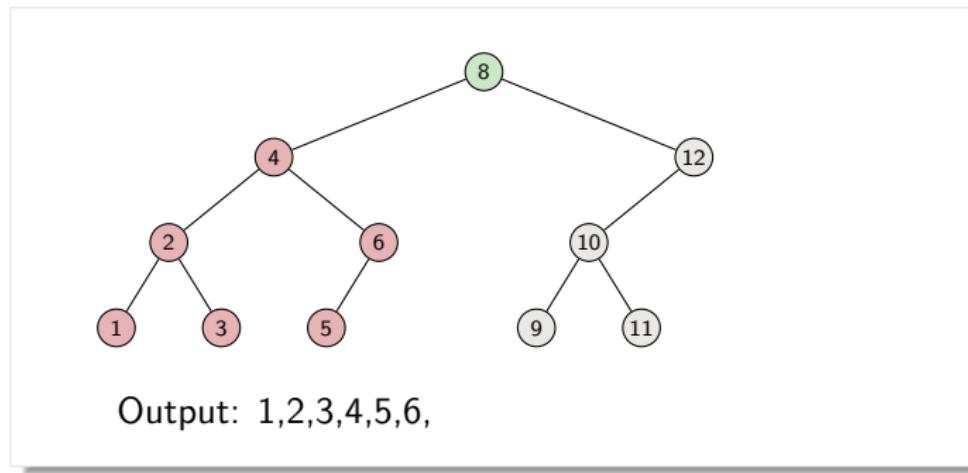
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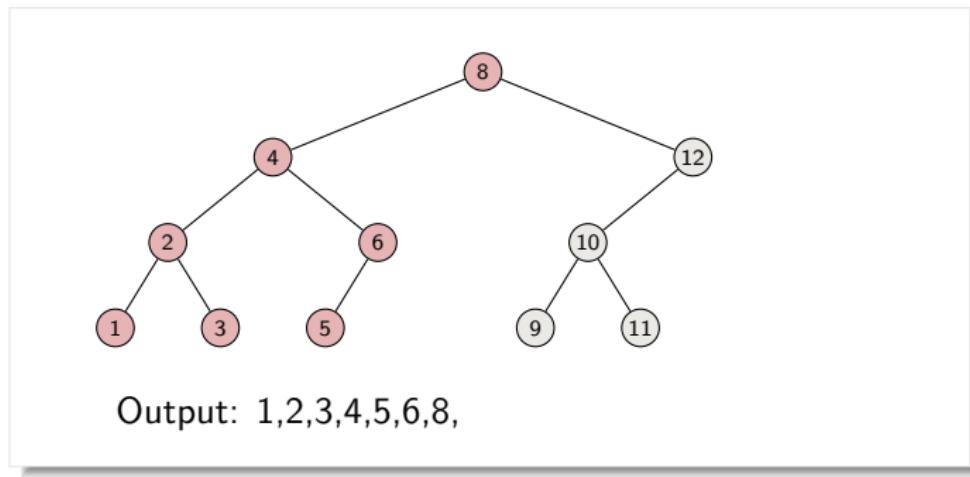
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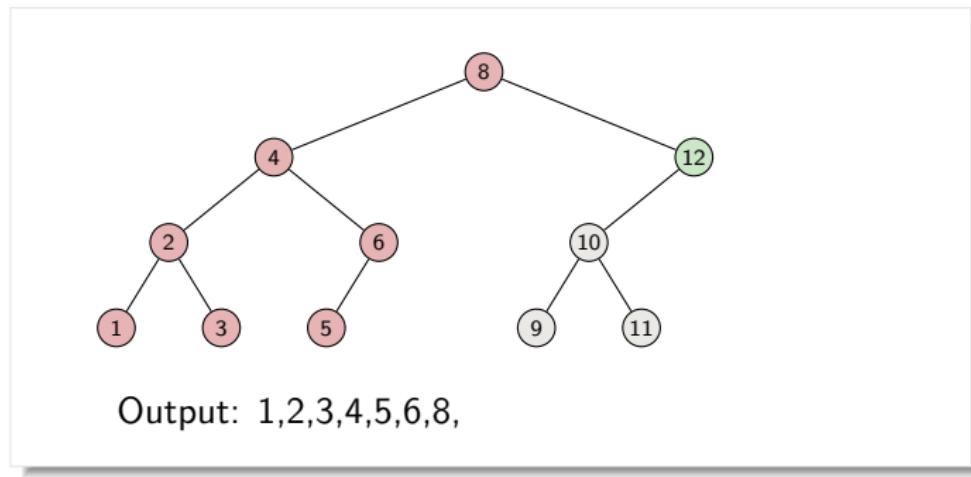
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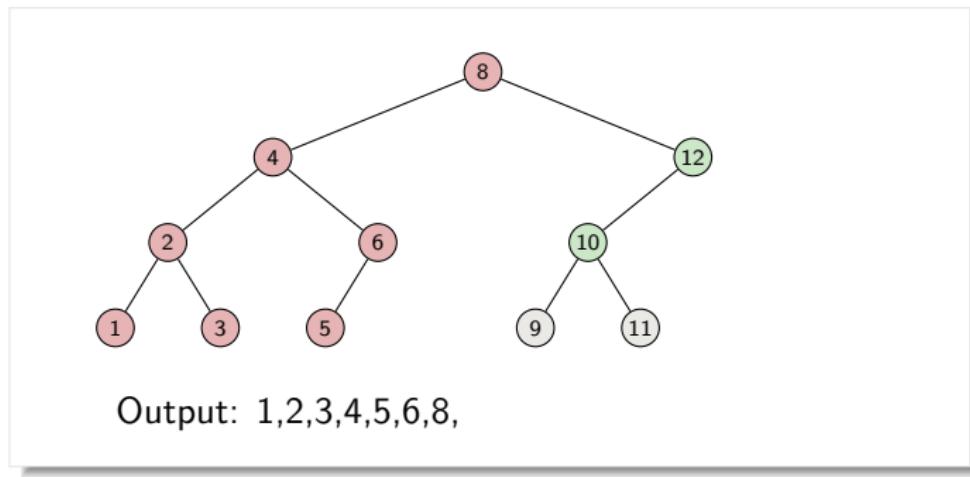
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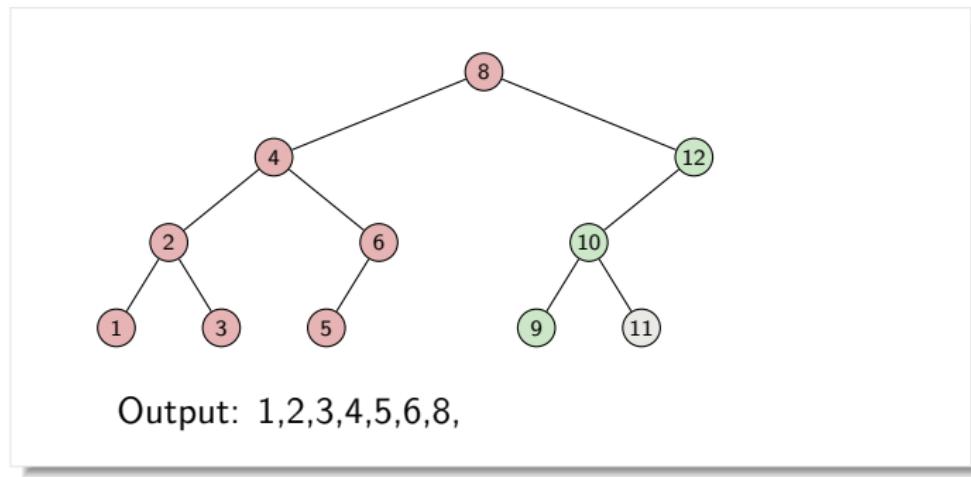
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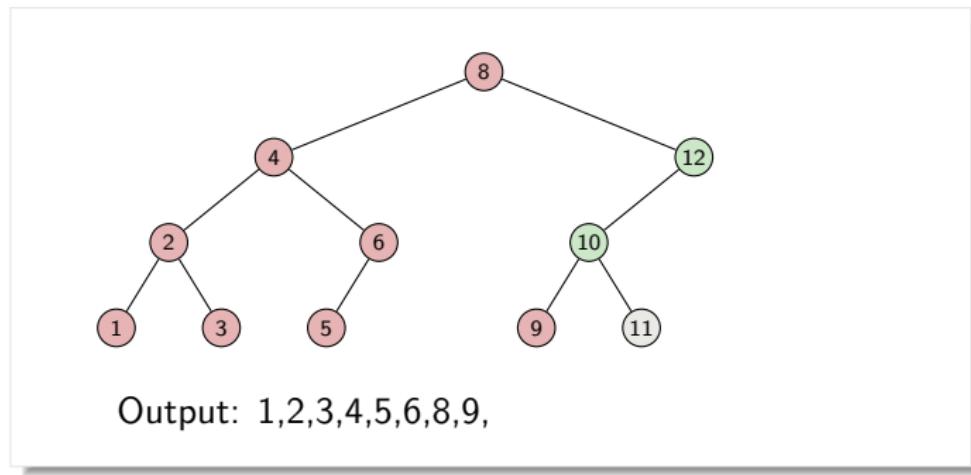
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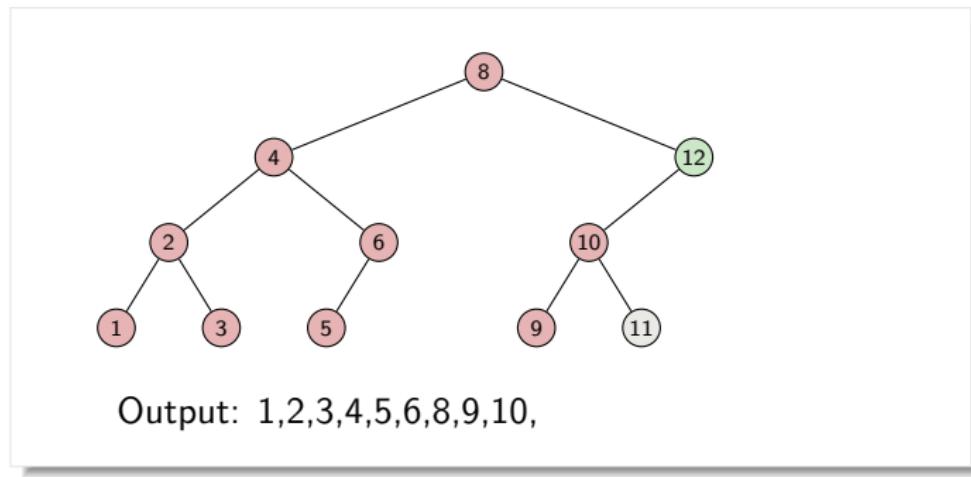
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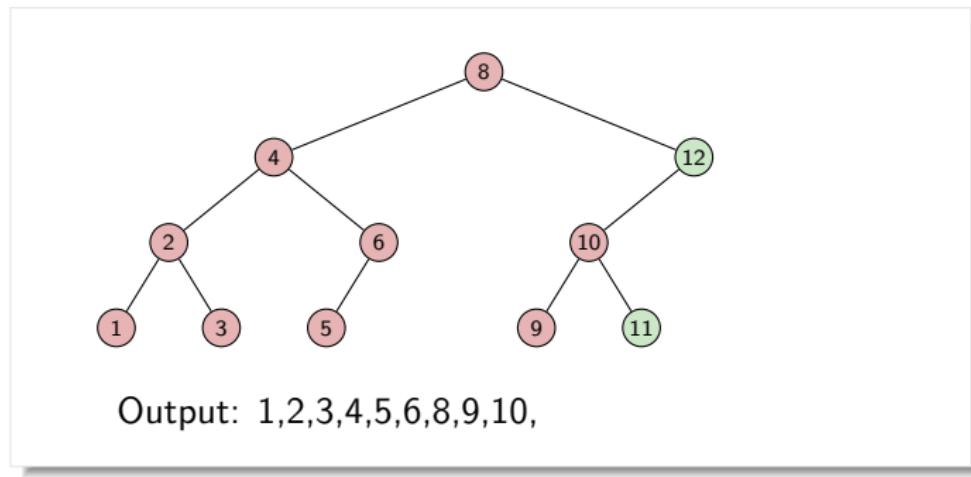
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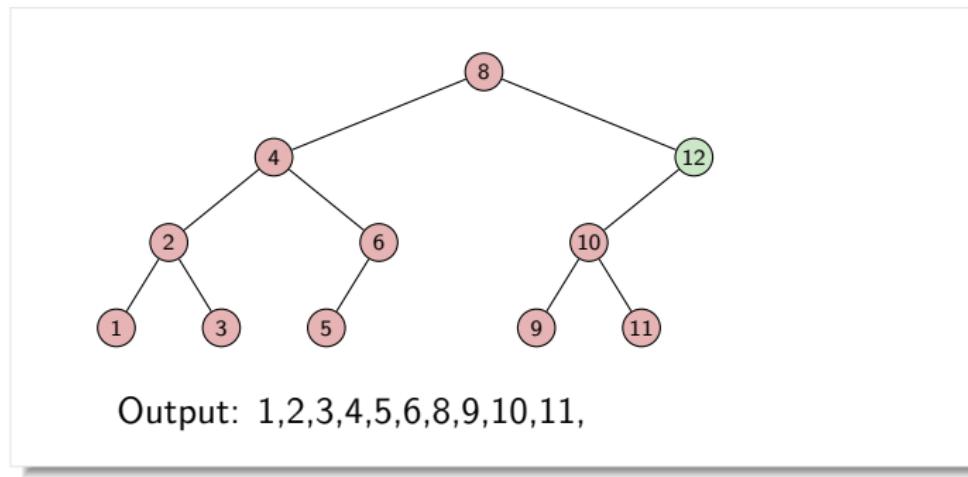
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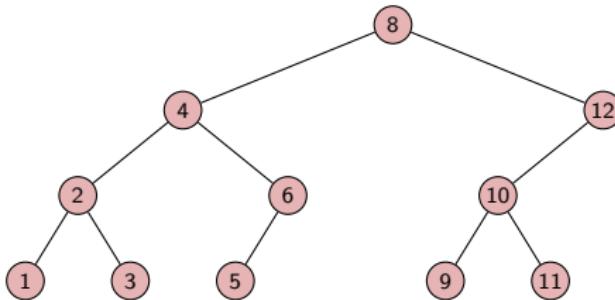
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Printing Inorder (Idea)

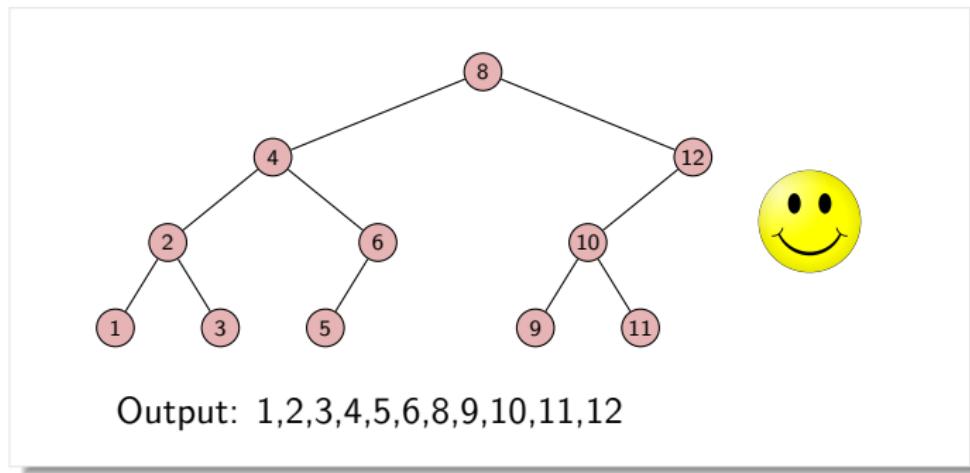
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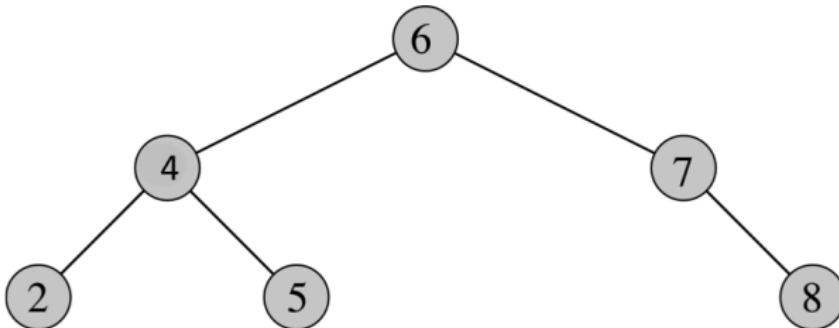
Output: 1,2,3,4,5,6,8,9,10,11,12

Printing Inorder (Idea)

- ▶ Print left subtree recursively
- ▶ Print root
- ▶ Print right subtree recursively

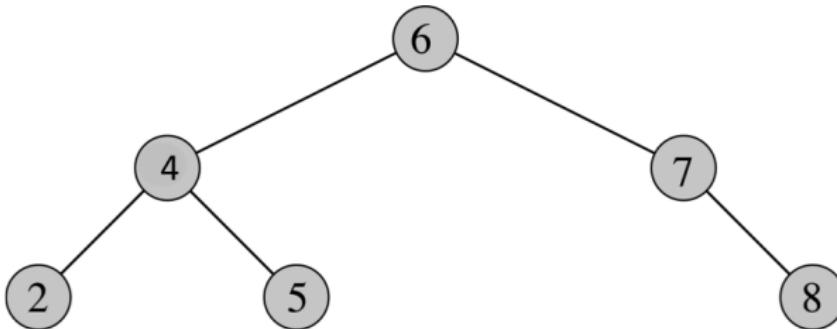


Inorder tree walk



```
INORDER-TREE-WALK( $x$ )
  if  $x \neq \text{NIL}$ 
    INORDER-TREE-WALK( $x.left$ )
    print  $key[x]$ 
    INORDER-TREE-WALK( $x.right$ )
```

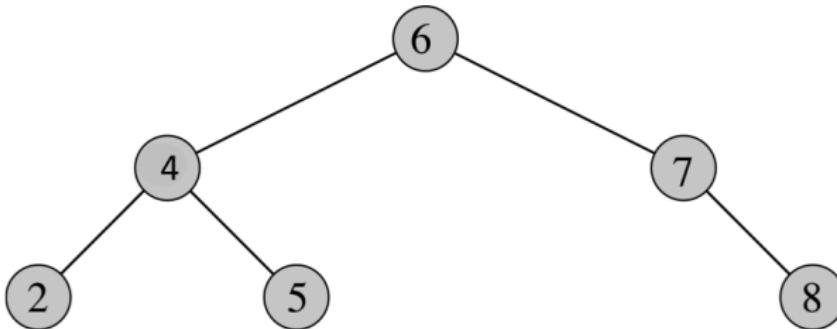
Inorder tree walk



What is the running time?

```
INORDER-TREE-WALK( $x$ )
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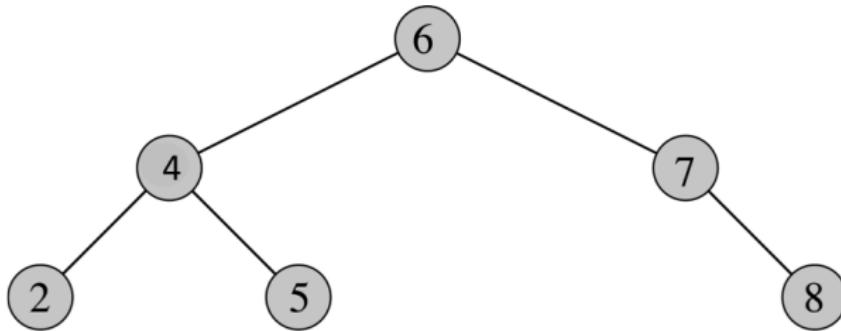
Inorder tree walk



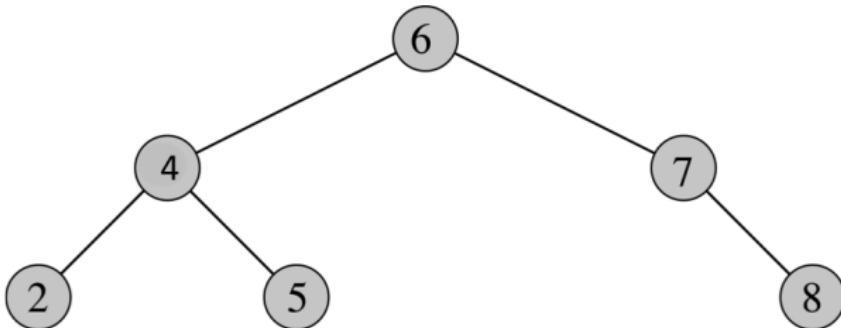
What is the running time? $\Theta(n)$

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INORDER-TREE-WALK( $x$ )
  if  $x \neq \text{NIL}$ 
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    print  $\text{key}[x]$ 
    INORDER-TREE-WALK( $x.\text{right}$ )
```

Printing Preorder and Postorder



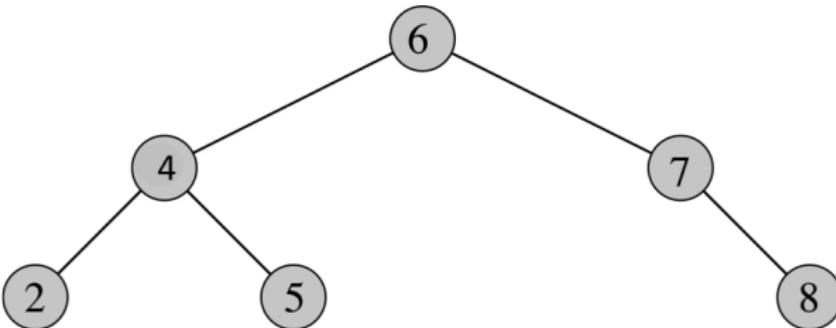
Printing Preorder and Postorder



PREORDER-TREE-WALK(x)

1. **if** $x \neq \text{NIL}$
2. **print** $\text{key}[x]$
3. PREORDER-TREE-WALK($x.\text{left}$)
4. PREORDER-TREE-WALK($x.\text{right}$)

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POSTORDER-TREE-WALK(x)

1. **if** $x \neq \text{NIL}$
2. POSTORDER-TREE-WALK($x.\text{left}$)
3. POSTORDER-TREE-WALK($x.\text{right}$)
4. **print** $\text{key}[x]$

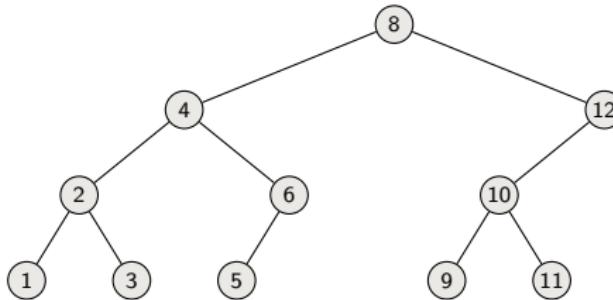
MODIFYING A BINARY SEARCH TREE

(**Insertion and Deletion**)

Idea of inserting z

- ▶ Search for $z.key$
- ▶ When arrived at nil insert z at that position

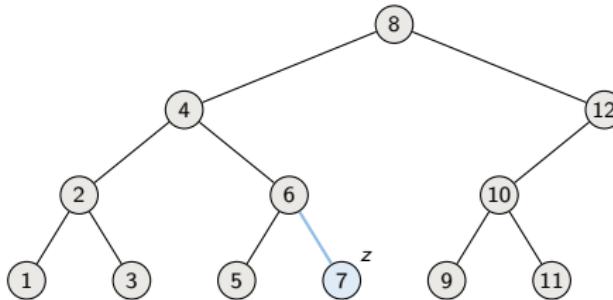
Ex: insert z with key 7



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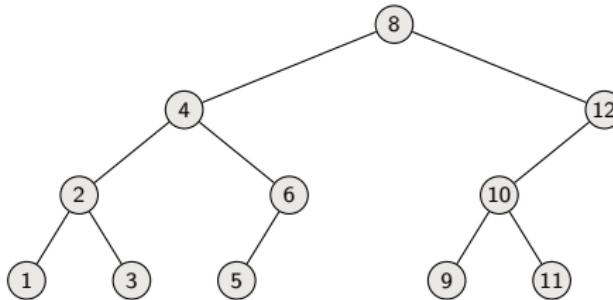
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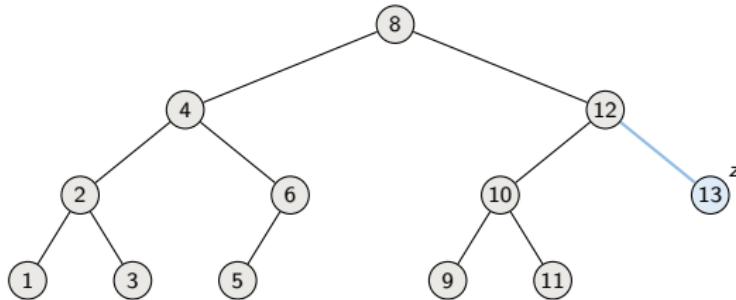
Ex: insert z with key 13



Idea of inserting z

- ▶ Search for $z.key$
- ▶ When arrived at nil insert z at that position

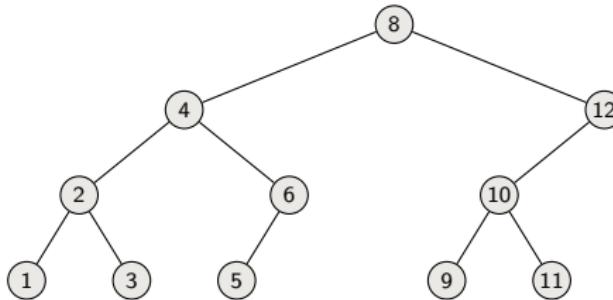
Ex: insert z with key 13



Idea of inserting z

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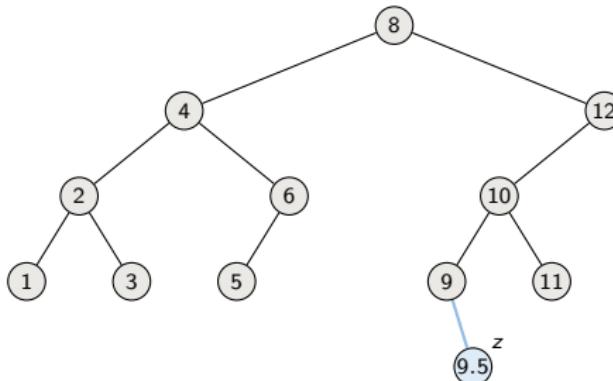
Ex: insert z with key 9.5



Idea of inserting z

- ▶ Search for $z.key$
- ▶ When arrived at nil insert z at that position

Ex: insert z with key 9.5



Insertion

```
TREE-INSERT( $T, z$ )  
   $y = \text{NIL}$   
   $x = T.\text{root}$   
  while  $x \neq \text{NIL}$   
     $y = x$   
    if  $z.\text{key} < x.\text{key}$   
       $x = x.\text{left}$   
    else  $x = x.\text{right}$   
   $z.p = y$   
  if  $y == \text{NIL}$   
     $T.\text{root} = z$       // tree  $T$  was empty  
  elseif  $z.\text{key} < y.\text{key}$   
     $y.\text{left} = z$   
  else  $y.\text{right} = z$ 
```

“search” phase

“insert” phase

Insertion

The diagram illustrates the `TREE-INSERT` algorithm. It is divided into two main phases: the "search" phase and the "insert" phase. The "search" phase is enclosed in a curly brace on the left, and the "insert" phase is also enclosed in a curly brace on the left. The algorithm itself is enclosed in a rectangular box.

```
TREE-INSERT( $T, z$ )
   $y = \text{NIL}$ 
   $x = T.\text{root}$ 
  while  $x \neq \text{NIL}$ 
     $y = x$ 
    if  $z.\text{key} < x.\text{key}$ 
       $x = x.\text{left}$ 
    else  $x = x.\text{right}$ 
   $z.p = y$ 
  if  $y == \text{NIL}$ 
     $T.\text{root} = z$       // tree  $T$  was empty
  elseif  $z.\text{key} < y.\text{key}$ 
     $y.\text{left} = z$ 
  else  $y.\text{right} = z$ 
```

What is the running time?

Insertion

The diagram illustrates the execution flow of the `TREE-INSERT` algorithm. It is divided into two main phases: the "search" phase and the "insert" phase. The "search" phase is enclosed in a curly brace on the left, and the "insert" phase is enclosed in a curly brace below it. The algorithm itself is enclosed in a rectangular box.

```
TREE-INSERT( $T, z$ )
   $y = \text{NIL}$ 
   $x = T.\text{root}$ 
  while  $x \neq \text{NIL}$ 
     $y = x$ 
    if  $z.\text{key} < x.\text{key}$ 
       $x = x.\text{left}$ 
    else  $x = x.\text{right}$ 
   $z.p = y$ 
  if  $y == \text{NIL}$ 
     $T.\text{root} = z$       // tree  $T$  was empty
  elseif  $z.\text{key} < y.\text{key}$ 
     $y.\text{left} = z$ 
  else  $y.\text{right} = z$ 
```

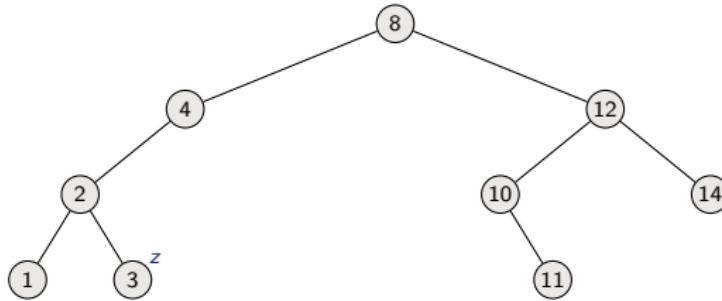
What is the running time? $O(h)$

Idea of deletion

Conceptually 3 cases:

- If z has no children, remove it

Ex: Delete z

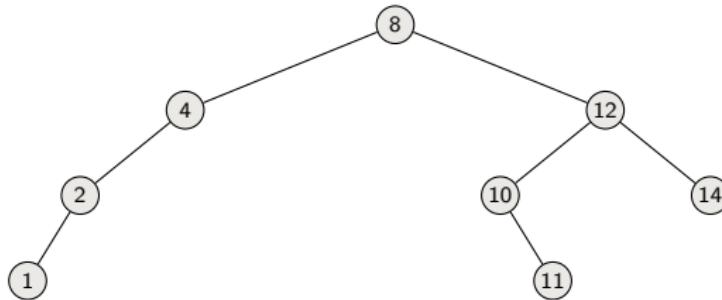


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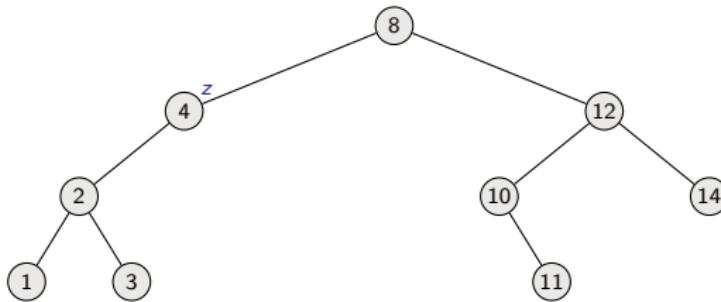


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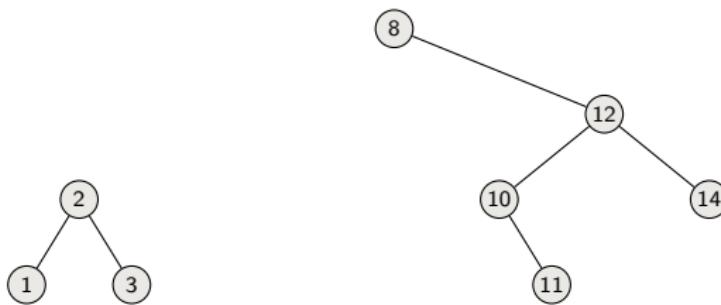


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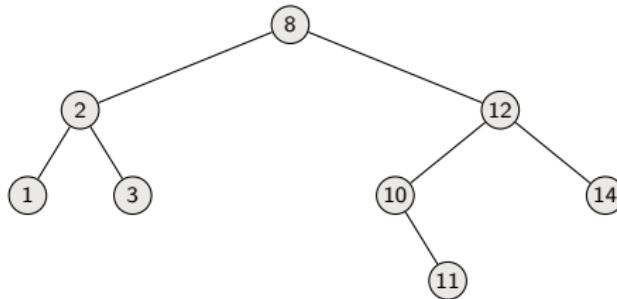


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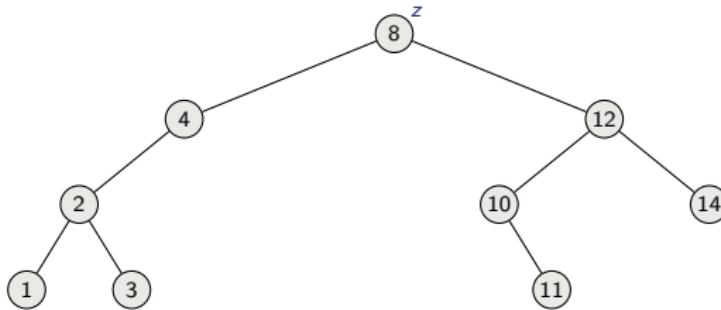


Idea of deletion

Conceptually 3 cases:

- ▶ If z has no children, remove it
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- ▶ If z has two children, then find its successor y and replace z by y

Ex: Delete z

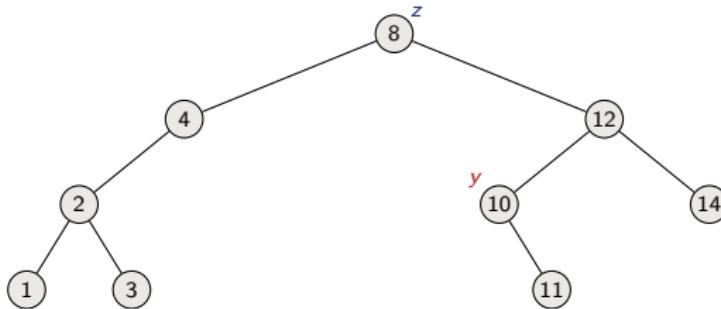


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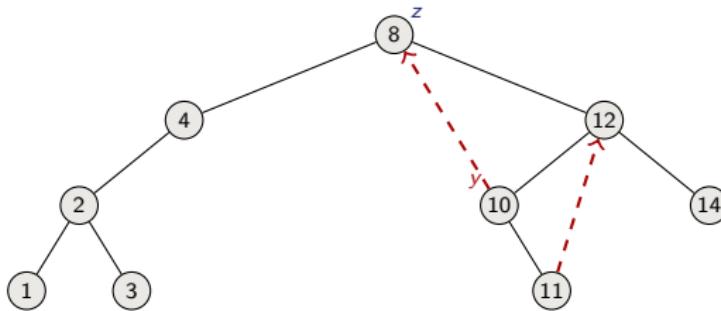


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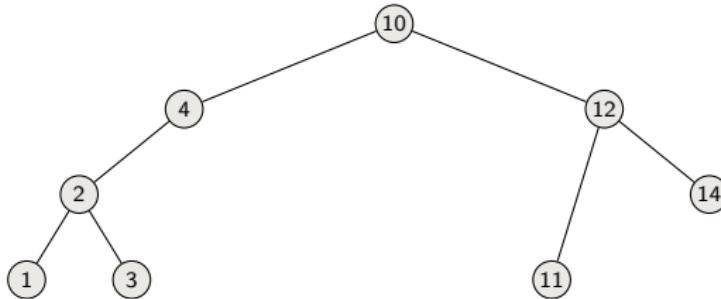


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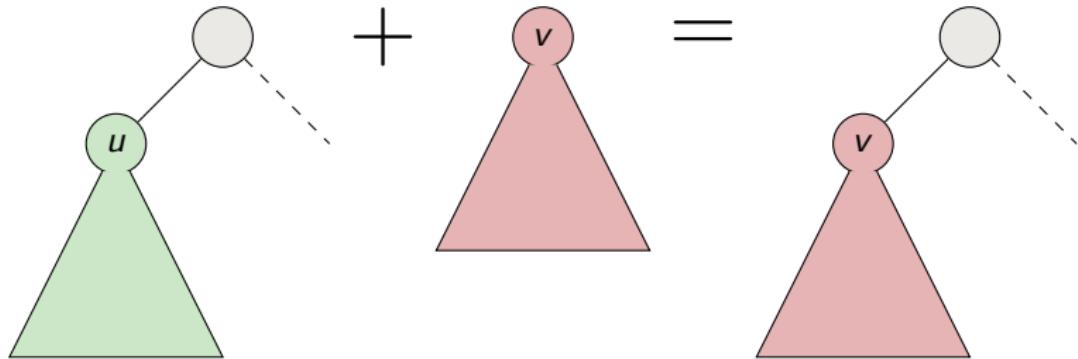
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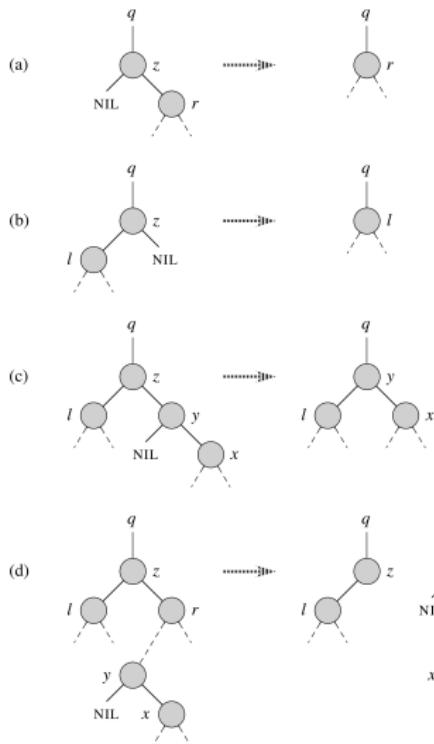
Deletion Implementation: Transplant

```
TRANSPLANT( $T, u, v$ )
  if  $u.p == \text{NIL}$ 
     $T.root = v$ 
  elseif  $u == u.p.left$ 
     $u.p.left = v$ 
  else  $u.p.right = v$ 
  if  $v \neq \text{NIL}$ 
     $v.p = u.p$ 
```

$\text{TRANSPLANT}(T, u, v)$ replaces subtree rooted at u with that rooted at v



Deletion Procedure



TREE-DELETE(T, z)

if $z.left == \text{NIL}$

TRANSPLANT($T, z, z.right$)

// z has no left child

elseif $z.right == \text{NIL}$

TRANSPLANT($T, z, z.left$)

// z has just a left child

else *// z has two children.*

$y = \text{TREE-MINIMUM}(z.right)$

// y is z's successor

if $y.p \neq z$

// y lies within z's right subtree but is not the root of this

TRANSPLANT($T, y, y.right$)

$y.right = z.right$

$y.right.p = y$

// Replace z by y.

TRANSPLANT(T, z, y)

$y.left = z.left$

$y.left.p = y$

Summary of Binary Search Trees



Query operations: Search, Max, Min, Predecessor, Successor: **$O(h)$** time

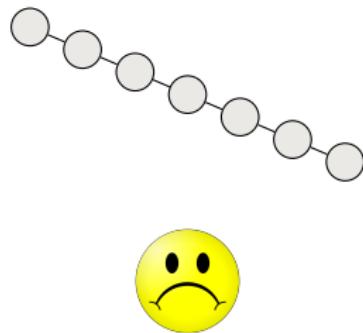
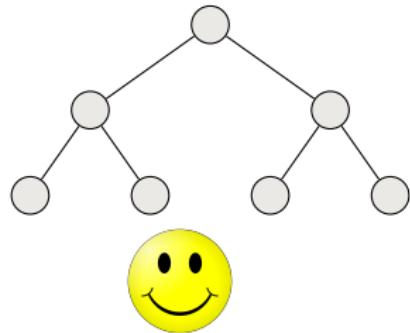
Modifying operations: Insertion, Deletion: **$O(h)$** time

Summary of Binary Search Trees



Query operations: Search, Max, Min, Predecessor, Successor: **$O(h)$** time

Modifying operations: Insertion, Deletion: **$O(h)$** time



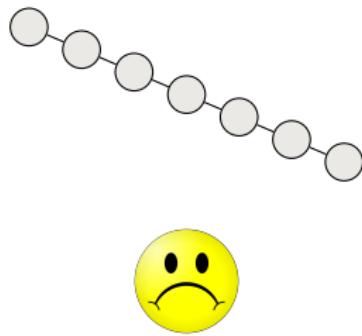
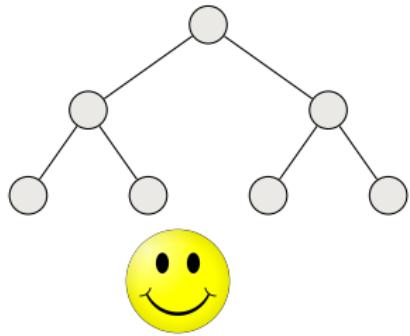
Summary of Binary Search Trees



Query operations: Search, Max, Min, Predecessor, Successor: **$O(h)$** time

Modifying operations: Insertion, Deletion: **$O(h)$** time

Exist efficient procedures to keep tree balanced (AVL trees, red-black trees, etc.)



Comparison of Data Structures

Stacks: Last-in-first-out, Insertion and deletion $O(1)$ time,
Array implementation: fixed capacity

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supports search but $O(n)$ time

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Linked List: No fixed capacity, Insertion and deletion $O(1)$ time,

supports search but $O(n)$ time

Binary Search Trees: No fixed capacity, supports most

operations (insertion, deletion, search, max, min, . . .)

in time $O(\text{height of tree})$

DYNAMIC PROGRAMMING

(An algorithmic paradigm not a way of “programming”)

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What is $2^5 + 3 - \sqrt{16}$?

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Dynamic Programming (DP)

Main idea:

- ▶ Remember calculations already made
- ▶ Saves enormous amounts of computation

Allows to solve many optimization problems

- ▶ Always at least one question in google code jam needs DP

First application: Fibonacci numbers

Sequence of numbers defined 1000 years ago:

$$F_0 = 1$$

$$F_1 = 1$$

$$F_n = F_{n-1} + F_{n-2}$$

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1, 1, 2, 3

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First application: Fibonacci numbers

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1, 1, 2, 3, 5, 8

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First application: Fibonacci numbers

Sequence of numbers defined 1000 years ago:

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1, 1, 2, 3, 5, 8, 13, 21, ?

Calculating the n -th Fibonacci number

Calculating the n -th Fibonacci number

First idea:

`FIB(n)`

1. **if** $n = 0$ or $n = 1$
2. **return** 1
3. **else**
4. **return** `FIB($n - 1$) + FIB($n - 2$)`

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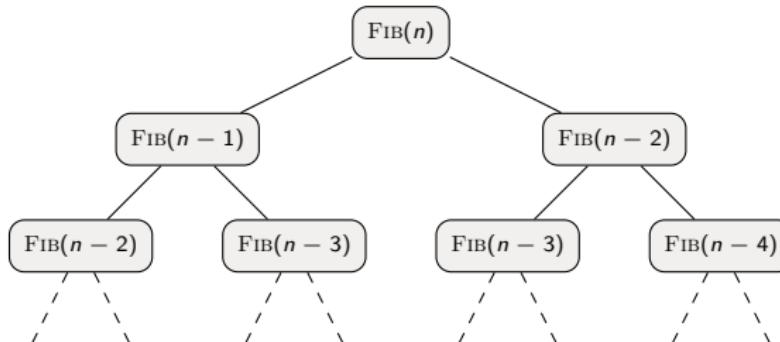
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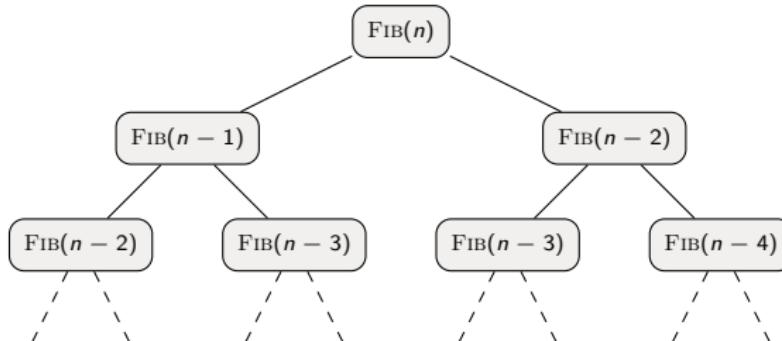
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What is the problem? Same calculations again and again
⇒ exponential time!



The solution

Remember what we have done

The solution

Remember what we have done

Two different ways:

1 Top-down with memoization

- ▶ Solve recursively but store each result in a table
- ▶ **Memoizing** is remembering what we have computed previously

The solution

Remember what we have done

Two different ways:

1 Top-down with memoization

- ▶ Solve recursively but store each result in a table
- ▶ **Memoizing** is remembering what we have computed previously

2 Bottom-up

- ▶ Sort the subproblems and solve the smaller ones first
- ▶ That way, when solving a subproblem, have already solved the smaller subproblems we need

Top-down with memoization: Fibonacci numbers

MEMOIZED-FIB(n)

1. Let $r = [0 \dots n]$ be a new array
2. for $i = 0$ to n
3. $r[i] \leftarrow -\infty$
4. return MEMOIZED-FIB-AUX(n, r)

Top-down with memoization: Fibonacci numbers

```
MEMOIZED-FIB( $n$ )
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```
MEMOIZED-FIB-AUX( $n, r$ )
```

1. if $r[n] \geq 0$
2. return $r[n]$
3. if $n = 0$ or $n = 1$
4. $ans \leftarrow 1$
5. else
6. $ans \leftarrow \text{MEMOIZED-FIB-AUX}(n - 1, r) +$
 MEMOIZED-FIB-AUX($n - 2, r$)
7. $r[n] \leftarrow ans$
8. return $r[n]$

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M-F-A(n, r)

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M-F-A(n, r)

M-F-A($n - 1, r$)

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M-F-A($3, r$)

M-F-A($n - 1, r$)

M-F-A(n, r)

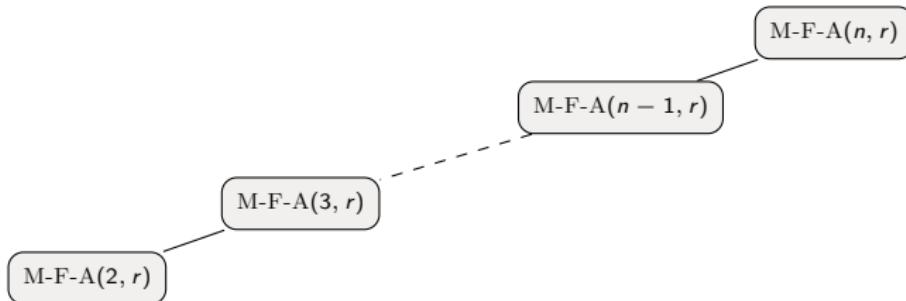
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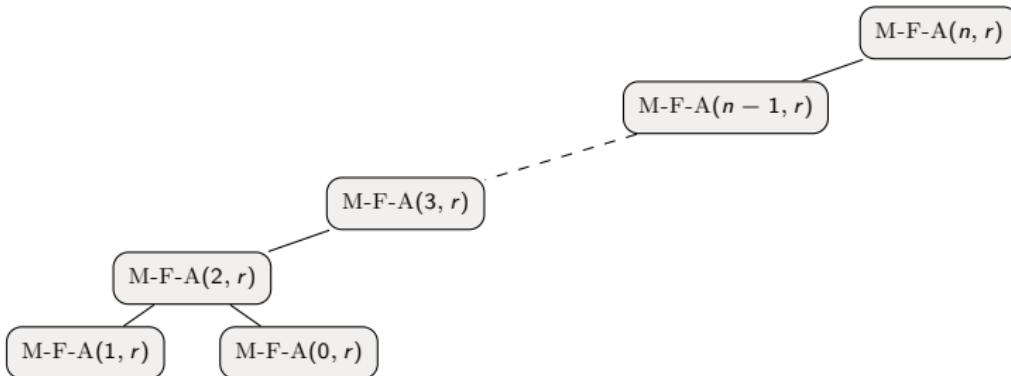
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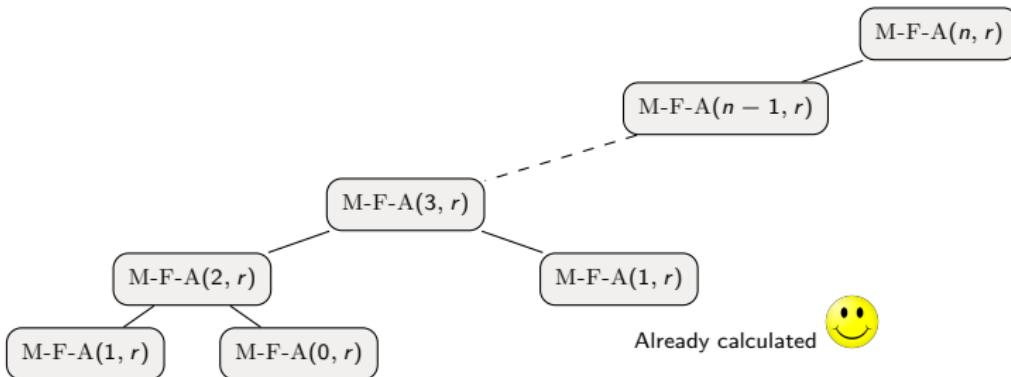
Top-down with memoization: Fibonacci numbers

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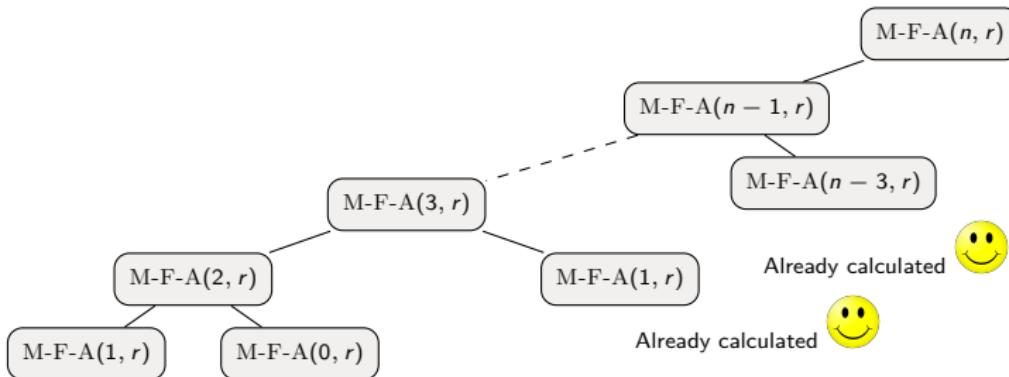
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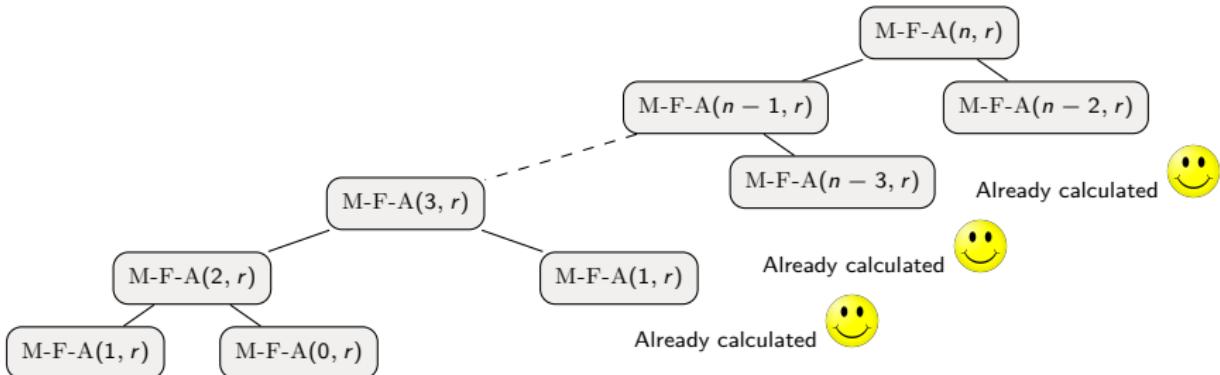
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- ▶ Number of calls to MEMOIZED-FIB-AUX is $\Theta(n)$
- ▶ Total time is thus $\Theta(n)$

Bottom-up: Fibonacci numbers

BOTTOM-UP-FIB(n)

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Example $n = 8$:

$r =$

1							
---	--	--	--	--	--	--	--

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---	---	---	--	--	--	--	--

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---	---	---	---	--	--	--	--

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$$r = \begin{array}{|c|c|c|c|c|c|c|c|c|} \hline 1 & 1 & 2 & 3 & 5 & & & & \\ \hline \end{array}$$

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Time?

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Time? $\Theta(n)$

Summary

- ▶ We had a recursive formulation of our problem

$$F_0 = 1$$

$$F_1 = 1$$

$$F_n = F_{n-1} + F_{n-2}$$

- ▶ Introduced memory (array r)
- ▶ Filled in table “top-down with memoization” or with “bottom-up”

Key elements in designing a DP-algorithm

Optimal substructure

- ▶ Show that a solution to a problem consists of **making a choice**, which leaves one or several subproblems to solve

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Overlapping subproblems

- ▶ A naive recursive algorithm may revisit the same (sub)problem over and over.
- ▶ **Top-down with memoization**
Solve recursively but store each result in a table
- ▶ **Bottom-up**
Sort the subproblems and solve the smaller ones first; that way, when solving a subproblem, have already solved the smaller subproblems we need



ROD CUTTING

Rod cutting

Instance:

- A length n of a metal rod.
- A table of prices p_i for rods of lengths $i = 1, \dots, n$.

length i	1	2	3	4	5	6	7	8	9	10
price p_i	1	5	8	9	10	17	17	20	24	30

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(a)



(b)



(c)



(d)



(e)



(f)



(g)



(h)

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- ▶ There 2^{n-1} possible solutions—either cut or do not cut after every length unit.

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Theorem

If:

- ▶ *the leftmost cut in an optimal solution is after i units.*
- ▶ *an optimal way to cut a solution of size $n - i$ is into rods of sizes: s_1, s_2, \dots, s_k .*

Then, an optimal way to cut our rod is into rods of sizes: i, s_1, s_2, \dots, s_k .

Proof of Structural Theorem

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Hence, $i + \sum_{j=1}^k s_j = n$.

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Hence, $p_i + \sum_{j=1}^k p_{s_j} \geq p_i + \sum_{j=1}^\ell p_{o_j}$.

First Algorithm

If we let $r(n)$ be the optimal revenue from a rod of length n , then, by the structural theorem, we can express $r(n)$ recursively as follows

$$r(n) = \begin{cases} 0 & \text{if } n = 0 , \\ \max_{1 \leq i \leq n} \{p_i + r(n - i)\} & \text{otherwise if } n \geq 1 . \end{cases}$$

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CUT-ROD( $p, n$ )
  if  $n == 0$ 
    return 0
   $q = -\infty$ 
  for  $i = 1$  to  $n$ 
     $q = \max(q, p[i] + \text{CUT-ROD}(p, n - i))$ 
  return  $q$ 
```

Problem

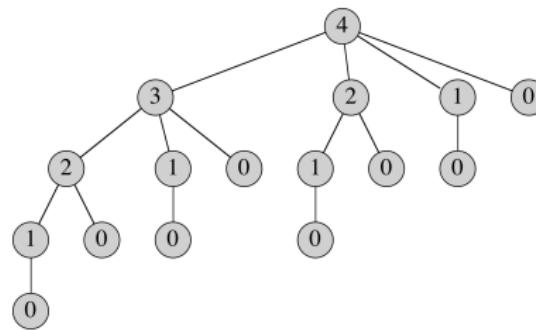
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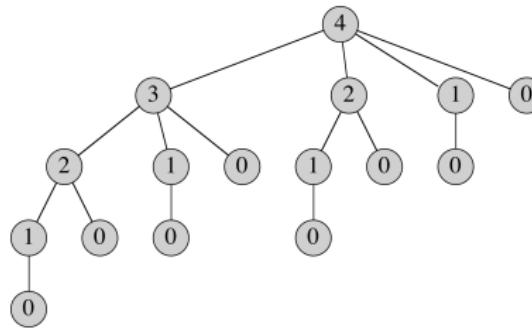
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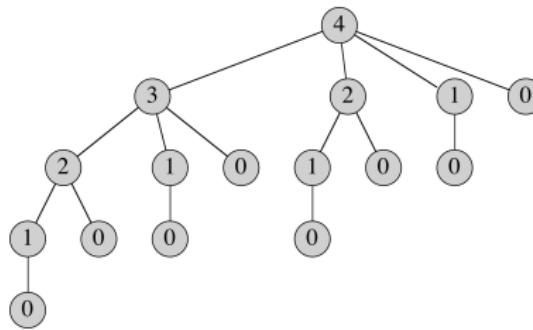
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Problem

- ▶ The procedure is extremely inefficient—in fact exponential.
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- ▶ The procedure repeatedly calculates the same profits.
- ▶ Dynamic programming can save the extra calculations.

Top-Down Dynamic Programming

General Approach

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- ▶ Keep the recursive structure of the pseudocode.

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Pseudocode

```
MEMOIZED-CUT-ROD( $p, n$ )
  let  $r[0 \dots n]$  be a new array
  for  $i = 0$  to  $n$ 
     $r[i] = -\infty$ 
  return MEMOIZED-CUT-ROD-AUX( $p, n, r$ )
```

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Pseudocode

MEMOIZED-CUT-ROD-AUX(p, n, r)

```
if  $r[n] \geq 0$ 
    return  $r[n]$ 
if  $n == 0$ 
     $q = 0$ 
else  $q = -\infty$ 
    for  $i = 1$  to  $n$ 
         $q = \max(q, p[i] + \text{MEMOIZED-CUT-ROD-AUX}(p, n - i, r))$ 
     $r[n] = q$ 
return  $q$ 
```

MEMOIZED-CUT-ROD(p, n)

```
let  $r[0..n]$  be a new array
for  $i = 0$  to  $n$ 
     $r[i] = -\infty$ 
return MEMOIZED-CUT-ROD-AUX( $p, n, r$ )
```

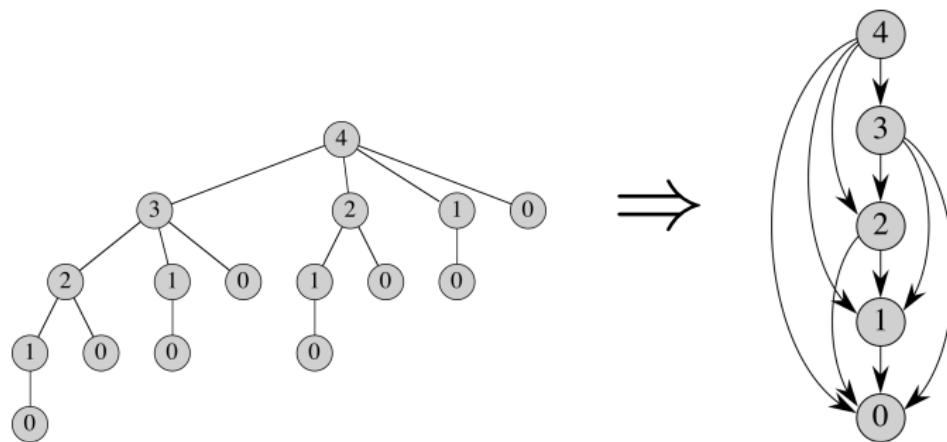
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Memoization helps us avoid recalculations.

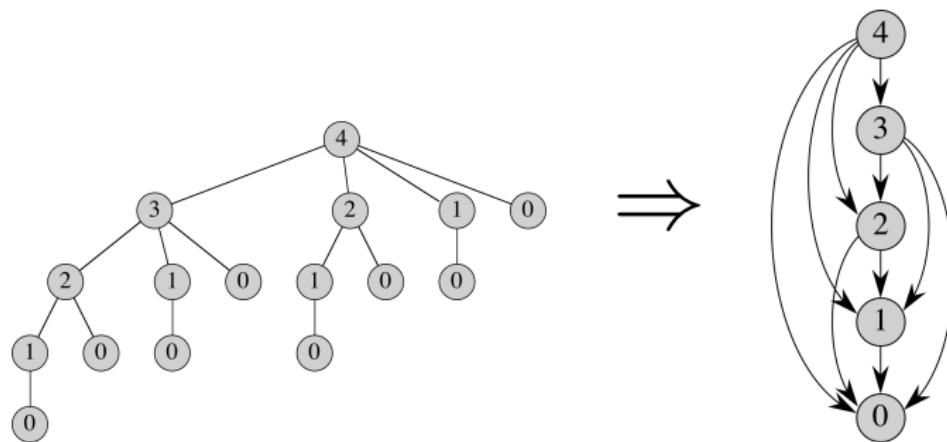
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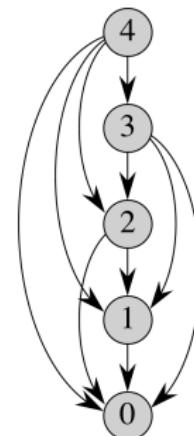
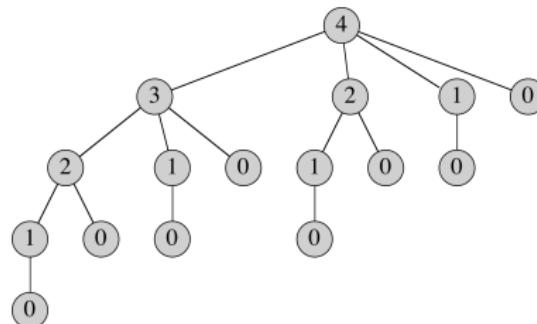


One can think of all the recursive calls using a memoized value as additional parents of the call generating this value.

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Subproblem Graph



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Time Complexity

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- The initialization takes $O(n)$ time.

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MEMOIZED-CUT-ROD( $p, n$ )
```

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    let  $r[0..n]$  be a new array
```

```
    for  $i = 0$  to  $n$ 
```

```
         $r[i] = -\infty$ 
```

```
    return MEMOIZED-CUT-ROD-AUX( $p, n, r$ )
```

Time Complexity

- ▶ The initialization takes $O(n)$ time.
- ▶ Processing each sub-problem takes linear time in the number of sub-problems it evokes.

```
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  if  $r[n] \geq 0$ 
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  if  $n == 0$ 
     $q = 0$ 
  else  $q = -\infty$ 
    for  $i = 1$  to  $n$ 
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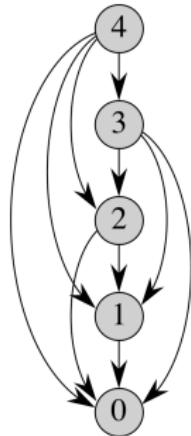
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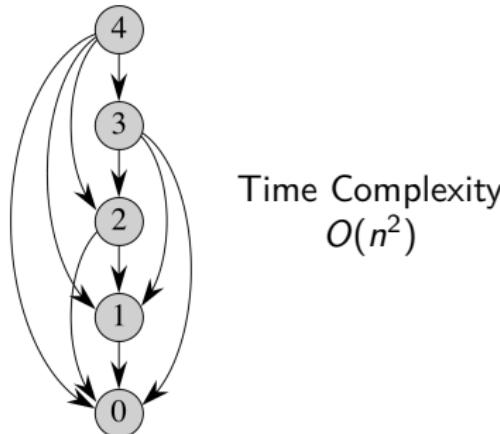
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Pseudocode

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BOTTOM-UP-CUT-ROD( $p, n$ )
    let  $r[0..n]$  be a new array
     $r[0] = 0$ 
    for  $j = 1$  to  $n$ 
         $q = -\infty$ 
        for  $i = 1$  to  $j$ 
             $q = \max(q, p[i] + r[j - i])$ 
         $r[j] = q$ 
    return  $r[n]$ 
```

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Time Complexity
 $O(n^2)$

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Approach

- ▶ Each cell of the memoization table corresponds to a decision: the location of the left most cut.
- ▶ Store the decision corresponding to every cell in a separate table.

Reconstructing an Optimal Solution (cont.)

EXTENDED-BOTTOM-UP-CUT-ROD(p, n)

let $r[0..n]$ and $s[0..n]$ be new arrays

$r[0] = 0$

for $j = 1$ **to** n

$q = -\infty$

for $i = 1$ **to** j

if $q < p[i] + r[j - i]$

$q = p[i] + r[j - i]$

$s[j] = i$

$r[j] = q$

return r and s

Reconstructing an Optimal Solution (cont.)

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return r and s

Output

i	0	1	2	3	4	5	6	7	8
r[i]	0	1	5	8	10	13	17	18	22
s[i]	0	1	2	3	2	2	6	1	2

Summary

- We had a recursive formulation for the optimal value for our problem

$$r(n) = \begin{cases} 0 & \text{if } n = 0 , \\ \max_{1 \leq i \leq n} \{p_i + r(n - i)\} & \text{otherwise if } n \geq 1 . \end{cases}$$

- Speed up the calculations by filling in a table either “top-down with memoization” or with “bottom-up”.
- Recovered an optimal solution using an additional table.

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- ▶ How can a given amount of money be made with the least number of coins of given denominations?

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Formally:

Input: n distinct coin denominators (integers)

$0 < w_1 < w_2 < \dots < w_n$ and an amount W (the change) which is also a positive integer.

Output: The minimum number of coins needed in order to make the change:

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Example: On input $w_1 = 1, w_2 = 2, w_3 = 5$ and $W = 8$, the output should be 3 since the best way of giving 8 is $x_1 = x_2 = x_3 = 1$.

Summary

- ▶ Identify choices and optimal substructure
- ▶ Write optimal solution recursively as a function of smaller subproblems
- ▶ Use top-down with memoization or bottom-up to solve the recursion efficiently (without repeatedly solving the same subproblems)