

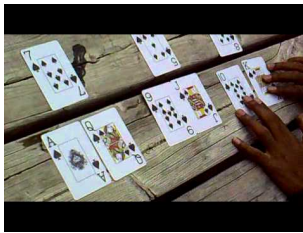
Algorithms: Elementary Data Structures

Ola Svensson



School of Computer and Communication Sciences

Lecture 7, 11.03.2025



RECALL LAST LECTURE

HEAPS

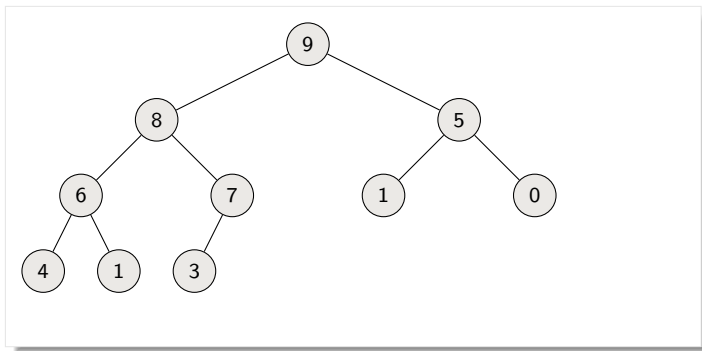
HEAPSORT

PRIORITY QUEUES

(Binary) heap data structure

Heap A (not garbage-collected storage) is a **nearly complete binary tree**

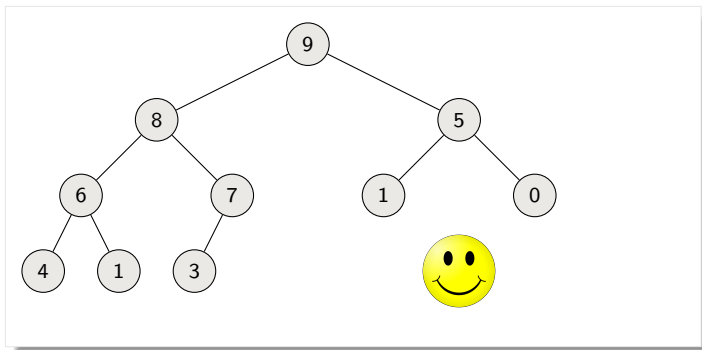
(Max)-Heap property: **key of i 's children is smaller or equal to i 's key**



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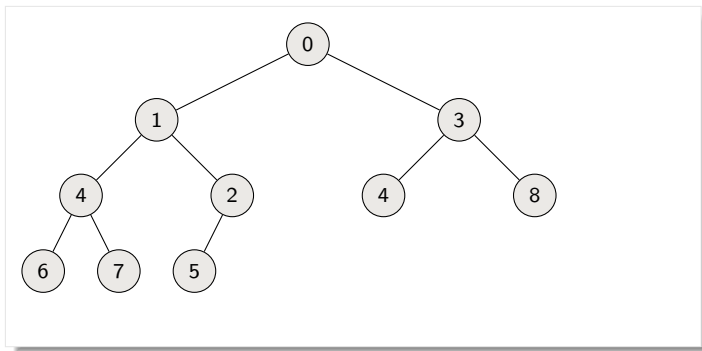
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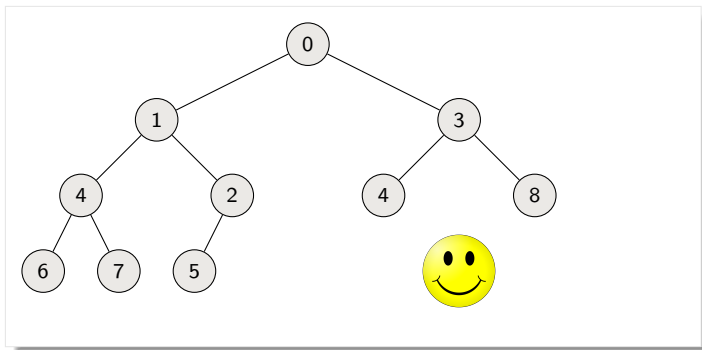
(Min)-Heap property: **key of i 's children is greater or equal to i 's key**



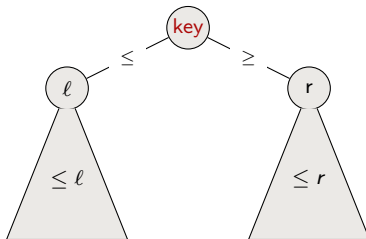
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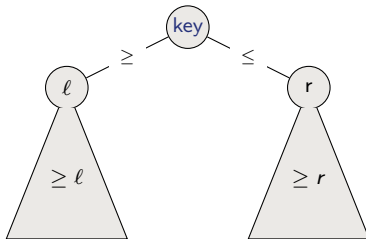
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Max-Heap \Rightarrow maximum element is the root



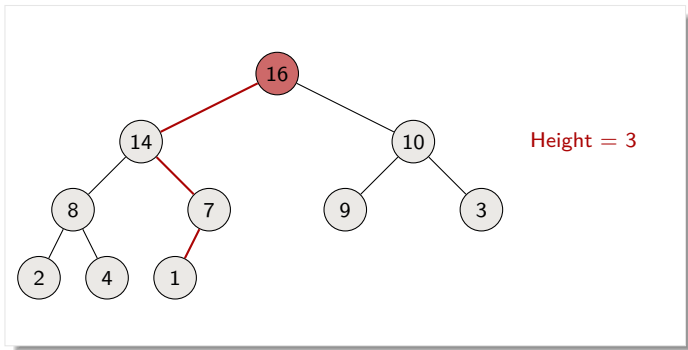
Min-Heap \Rightarrow minimum element is the root



Height of a heap

Height of node = # of edges on a longest simple path from the node down to a leaf

Height of heap = height of root = $\Theta(\log n)$



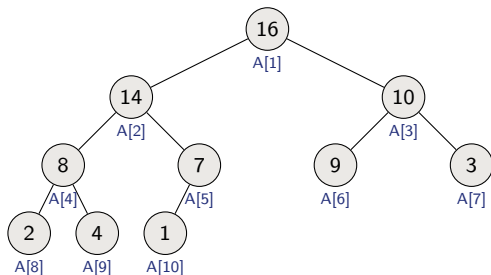
How to store a heap/tree?

~~pointer to left and right children~~

Use that tree is almost complete to store it in array

A =

16	14	10	8	7	9	3	2	4	1
----	----	----	---	---	---	---	---	---	---



In this representation:

ROOT is A[1]

LEFT(i) = ???

RIGHT(i) = ???

PARENT(i) = ???

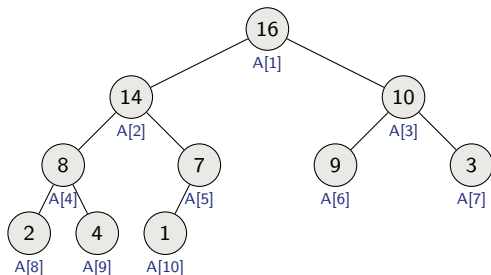
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In this representation:

ROOT is $A[1]$

LEFT(i) = $2i$

RIGHT(i) = ???

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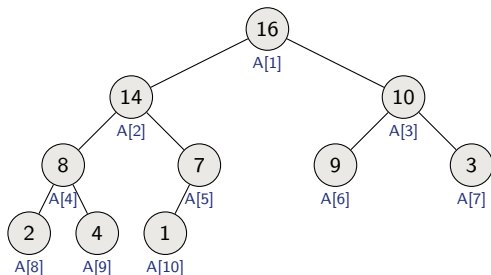
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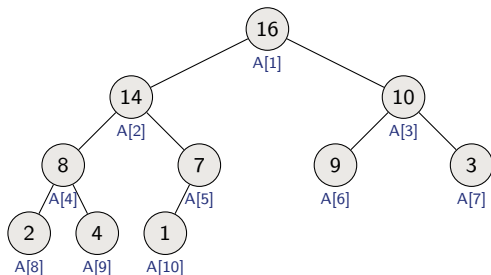
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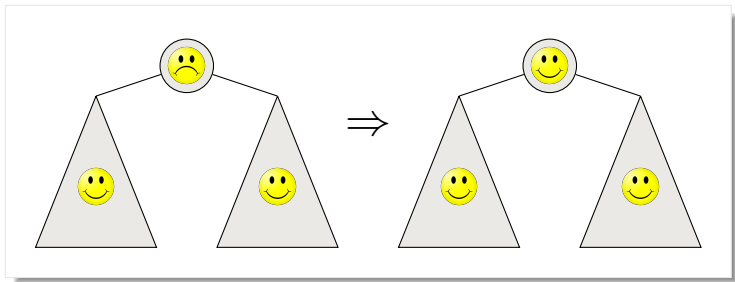
PARENT(i) = $\lfloor i/2 \rfloor$

BUILDING AND MANIPULATING HEAPS

Maintaining the heap property

MAX-HEAPIFY is important for manipulating heaps:

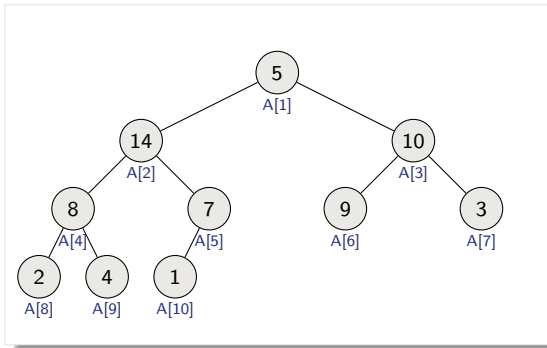
Given an i such that the subtrees of i are heaps, it ensures that the subtree rooted at i is a heap satisfy the heap property



MAX-HEAPIFY(A, i, n)

Algorithm:

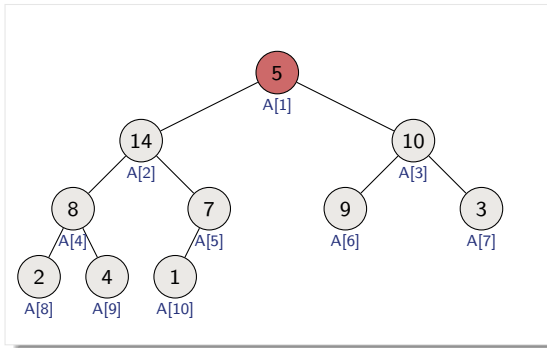
- ▶ Compare $A[i]$, $A[\text{LEFT}(i)]$, $A[\text{RIGHT}(i)]$
- ▶ If necessary, swap $A[i]$ with the largest of the two children to preserve heap property
- ▶ Continue this process of comparing and swapping down the heap, until subtree rooted at i is max-heap



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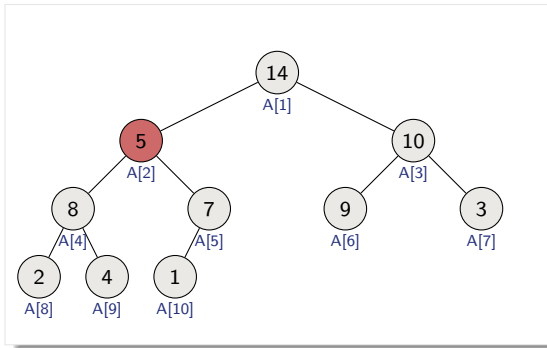
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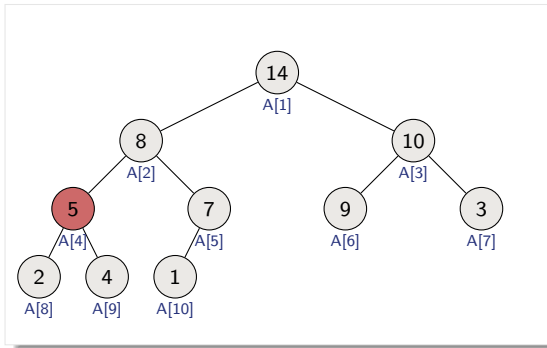
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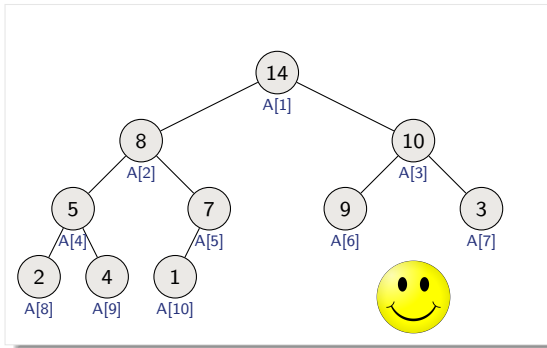
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Pseudo-code and analysis

MAX-HEAPIFY(A, i, n)

$l = \text{LEFT}(i)$

$r = \text{RIGHT}(i)$

if $l \leq n$ and $A[l] > A[i]$

$largest = l$

else $largest = i$

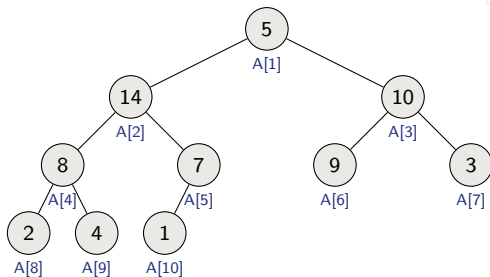
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MAX-HEAPIFY($A, largest, n$)



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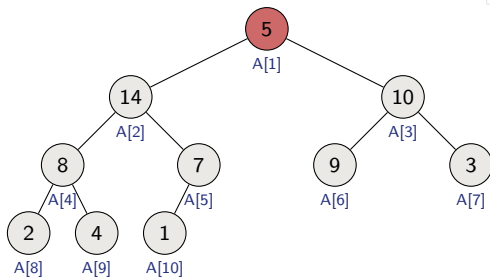
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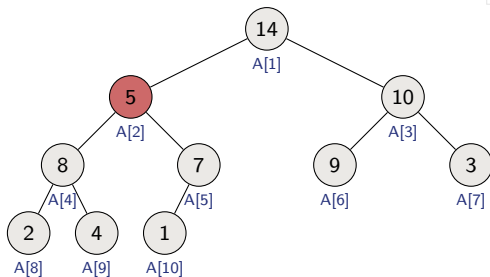
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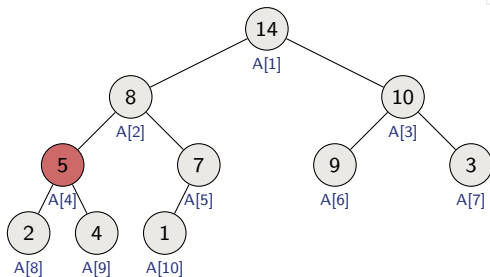
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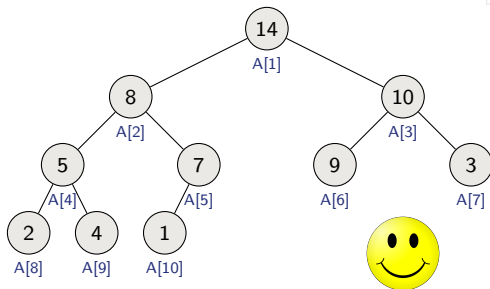
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Running time?

Space?

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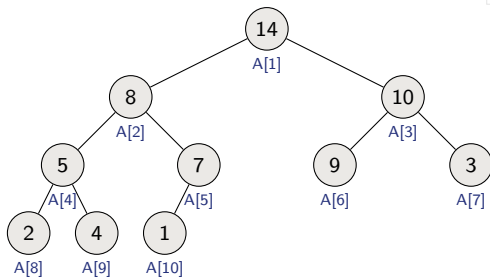
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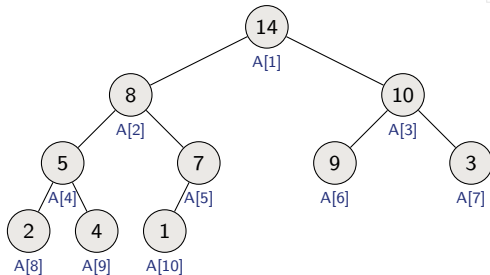


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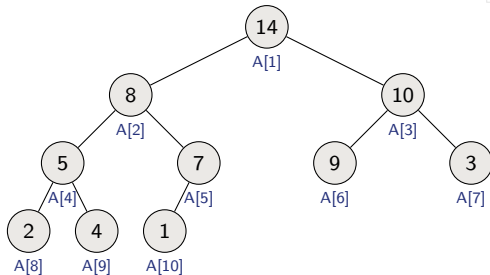
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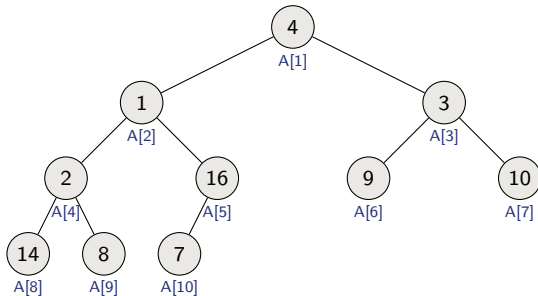


Building a heap

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BUILD-MAX-HEAP( $A, n$ )  
  for  $i = \lfloor n/2 \rfloor$  downto 1  
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Given unordered array A of length n , BUILD-MAX-HEAP outputs a heap

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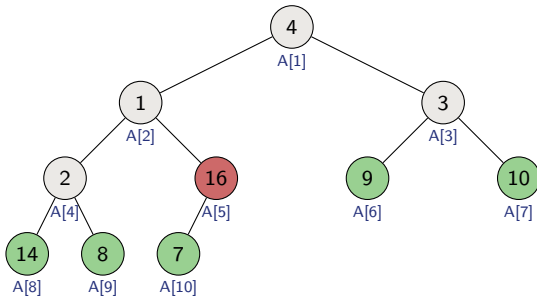


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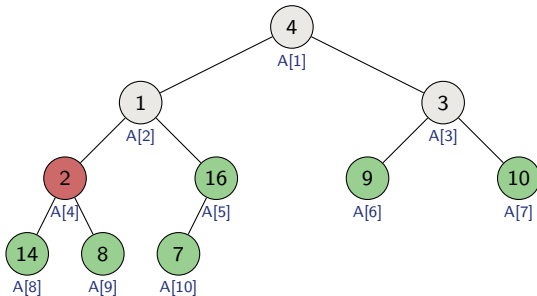


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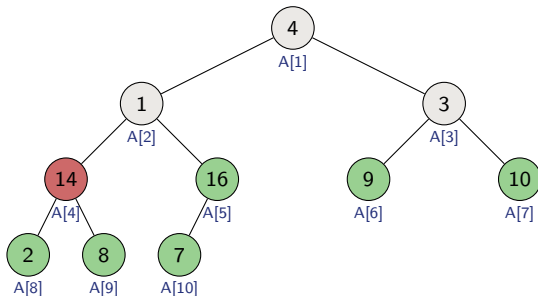


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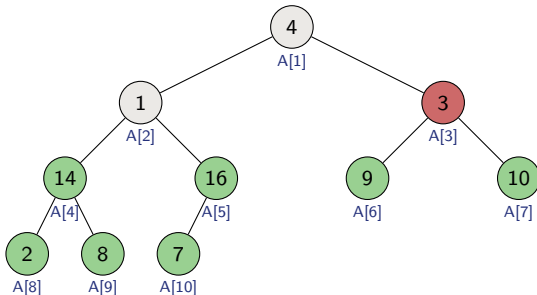


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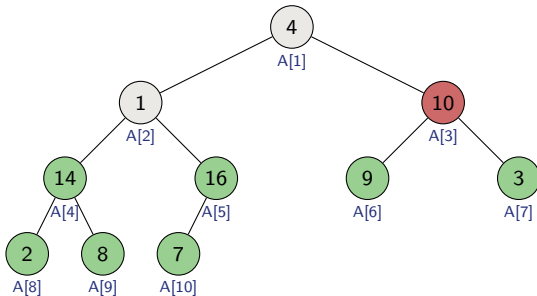


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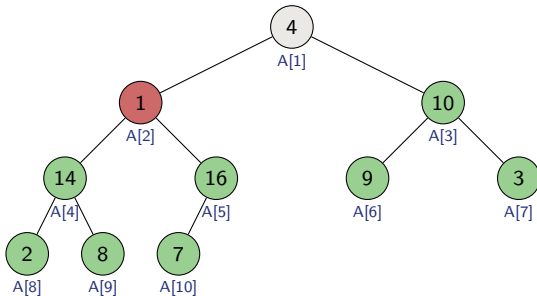
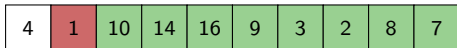
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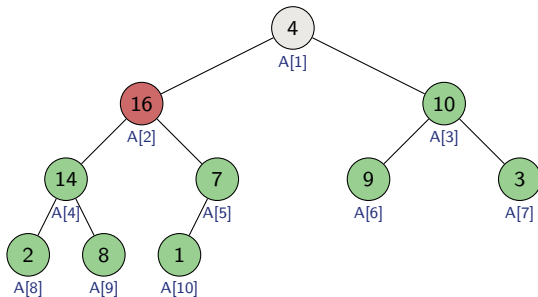
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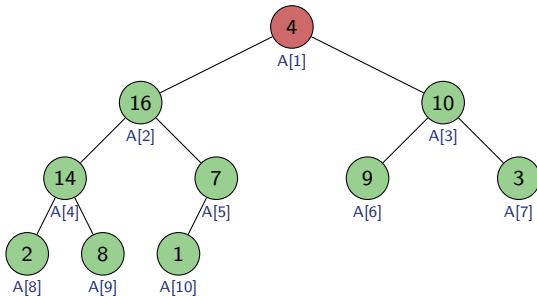
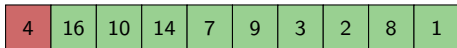
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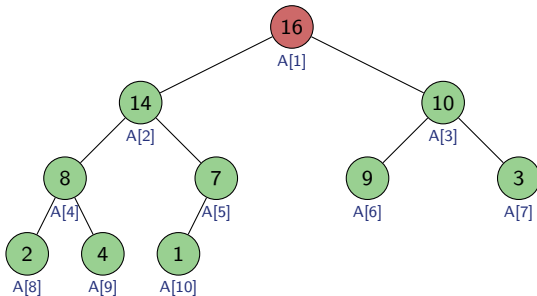
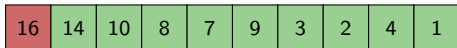
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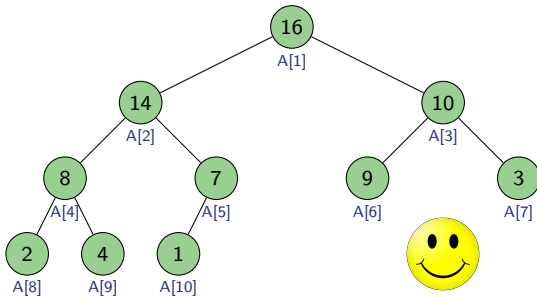


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Simple bound: $O(n)$ calls to MAX-HEAPIFY, each of which takes $O(\lg n)$ time $\Rightarrow O(n \lg n)$ in total


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Tighter analysis: Time to run MAX-HEAPIFY is linear in the height of the node it's run on. Hence, the time is bounded by

$$\sum_{h=0}^{\lg n} \{\# \text{ nodes of height } h\} O(h) = O\left(n \sum_{h=0}^{\lg n} \frac{h}{2^h}\right),$$

which is $O(n)$ since $\sum_{h=0}^{\infty} \frac{h}{2^h} = \frac{1/2}{(1-1/2)^2} = 2$.

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Initialization:

- ▶ Each node $\lfloor n/2 \rfloor + 1, \lfloor n/2 \rfloor + 2, \dots, n$ is a leaf which is the root of a trivial max-heap
- ▶ Since $i = \lfloor n/2 \rfloor$ before the first iteration of the **for** loop, the invariant is initially true

Correctness

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Loop invariant: At start of every iteration of **for** loop, each node $i + 1, i + 2, \dots, n$ is root of a max-heap

Maintenance:

Correctness

```
BUILD-MAX-HEAP( $A, n$ )  
  for  $i = \lfloor n/2 \rfloor$  downto 1  
    MAX-HEAPIFY( $A, i, n$ )
```

Loop invariant: At start of every iteration of **for** loop, each node $i + 1, i + 2, \dots, n$ is root of a max-heap

Maintenance:

- ▶ Children of node i are indexed higher than i , so by the loop invariant, they are both roots of max-heaps

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BUILD-MAX-HEAP( $A, n$ )  
  for  $i = \lfloor n/2 \rfloor$  downto 1  
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```

Loop invariant: At start of every iteration of **for** loop, each node $i + 1, i + 2, \dots, n$ is root of a max-heap

Maintenance:

- ▶ Children of node i are indexed higher than i , so by the loop invariant, they are both roots of max-heaps
- ▶ Therefore, MAX-HEAPIFY makes node i a max-heap root (so $i, i + 1, \dots, n$ are all roots of max-heaps)


```
BUILD-MAX-HEAP( $A, n$ )  
  for  $i = \lfloor n/2 \rfloor$  downto 1  
    MAX-HEAPIFY( $A, i, n$ )
```

Loop invariant: At start of every iteration of **for** loop, each node $i + 1, i + 2, \dots, n$ is root of a max-heap

Maintenance:

- ▶ Children of node i are indexed higher than i , so by the loop invariant, they are both roots of max-heaps
- ▶ Therefore, MAX-HEAPIFY makes node i a max-heap root (so $i, i + 1, \dots, n$ are all roots of max-heaps)
- ▶ Hence, the invariant stays true when decrementing i at the beginning of the next iteration

Correctness

```
BUILD-MAX-HEAP( $A, n$ )  
  for  $i = \lfloor n/2 \rfloor$  downto 1  
    MAX-HEAPIFY( $A, i, n$ )
```

Loop invariant: At start of every iteration of **for** loop, each node $i + 1, i + 2, \dots, n$ is root of a max-heap

Termination:

Correctness

```
BUILD-MAX-HEAP( $A, n$ )  
  for  $i = \lfloor n/2 \rfloor$  downto 1  
    MAX-HEAPIFY( $A, i, n$ )
```

Loop invariant: At start of every iteration of **for** loop, each node $i + 1, i + 2, \dots, n$ is root of a max-heap

Termination:

- ▶ When $i = 0$, the loop terminates

```
BUILD-MAX-HEAP( $A, n$ )  
  for  $i = \lfloor n/2 \rfloor$  downto 1  
    MAX-HEAPIFY( $A, i, n$ )
```

Loop invariant: At start of every iteration of **for** loop, each node $i + 1, i + 2, \dots, n$ is root of a max-heap

Termination:

- ▶ When $i = 0$, the loop terminates
- ▶ By the loop invariant, each node, notably node 1, is the root of a max-heap

HEAPSORT

The heapsort algorithm

- ▶ Builds a max-heap from the array
- ▶ Starting with the root (the maximum element), the algorithm places the maximum element into the correct place in the array by swapping it with the element in the last position in the array
- ▶ “Discard” this last node (knowing that it is in its correct place) by decreasing the heap size, and calling `MAX-HEAPIFY` on the new (possibly incorrectly-placed) root
- ▶ Repeat this “discarding” process until only one node (the smallest element) remains, and therefore is in the correct place in the array

Example

HEAPSORT(A, n)

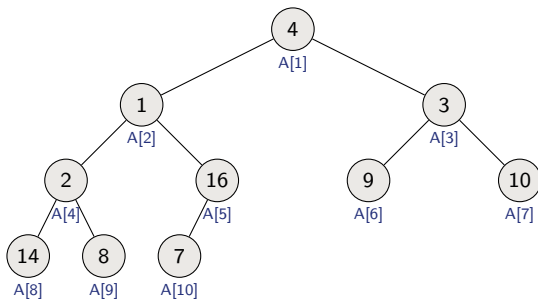
BUILD-MAX-HEAP(A, n)

for $i = n$ **downto** 2

 exchange $A[1]$ with $A[i]$

 MAX-HEAPIFY($A, 1, i - 1$)

4	1	3	2	16	9	10	14	8	7
---	---	---	---	----	---	----	----	---	---



Example

HEAPSORT(A, n)

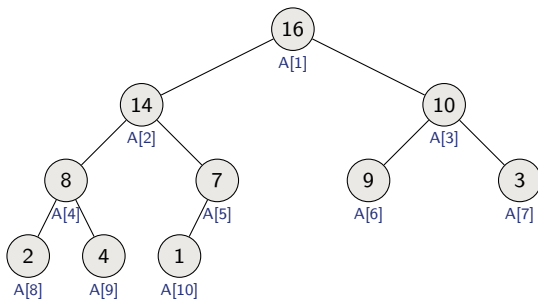
BUILD-MAX-HEAP(A, n)

for $i = n$ **downto** 2

exchange $A[1]$ with $A[i]$

MAX-HEAPIFY($A, 1, i - 1$)

16	14	10	8	7	9	3	2	4	1
----	----	----	---	---	---	---	---	---	---



Example

HEAPSORT(A, n)

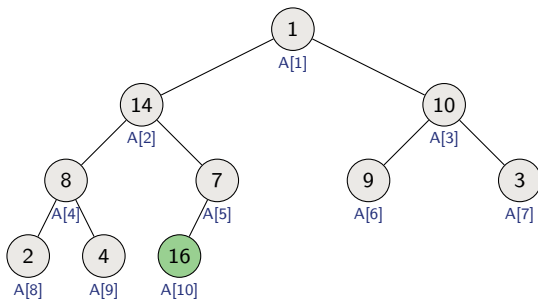
BUILD-MAX-HEAP(A, n)

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 exchange $A[1]$ with $A[i]$

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1	14	10	8	7	9	3	2	4	16
---	----	----	---	---	---	---	---	---	----



Example

HEAPSORT(A, n)

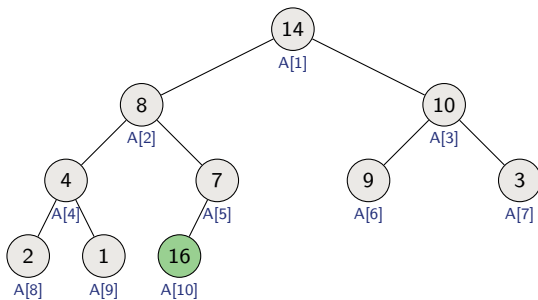
BUILD-MAX-HEAP(A, n)

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14	8	10	4	7	9	3	2	1	16
----	---	----	---	---	---	---	---	---	----



Example

HEAPSORT(A, n)

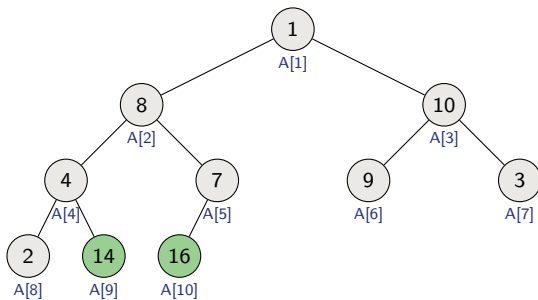
BUILD-MAX-HEAP(A, n)

for $i = n$ **downto** 2

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1	8	10	4	7	9	3	2	14	16
---	---	----	---	---	---	---	---	----	----



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HEAPSORT(A, n)

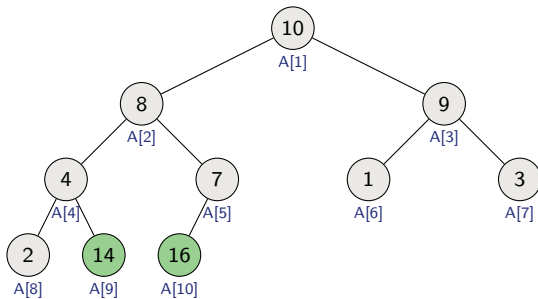
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exchange $A[1]$ with $A[i]$

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10	8	9	4	7	1	3	2	14	16
----	---	---	---	---	---	---	---	----	----



Example

HEAPSORT(A, n)

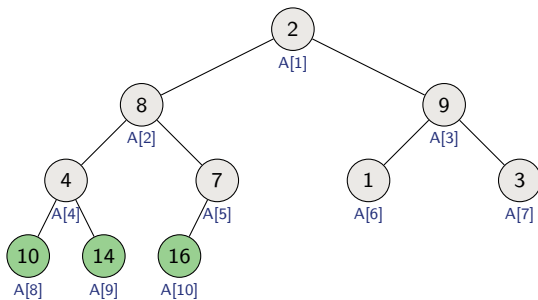
BUILD-MAX-HEAP(A, n)

for $i = n$ **downto** 2

 exchange $A[1]$ with $A[i]$

 MAX-HEAPIFY($A, 1, i - 1$)

2	8	9	4	7	1	3	10	14	16
---	---	---	---	---	---	---	----	----	----



Example

HEAPSORT(A, n)

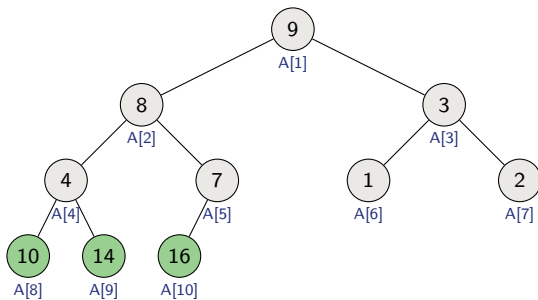
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9	8	3	4	7	1	2	10	14	16
---	---	---	---	---	---	---	----	----	----



Example

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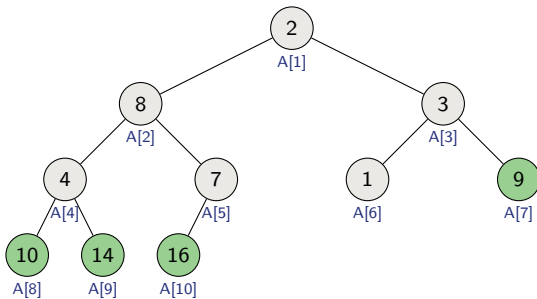
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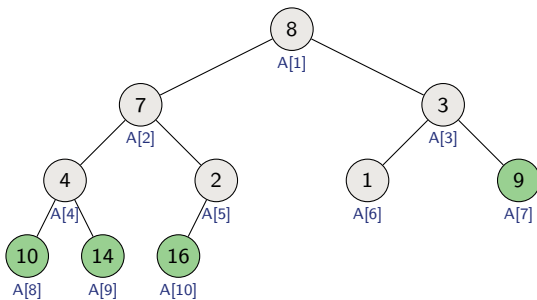
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HEAPSORT(A, n)

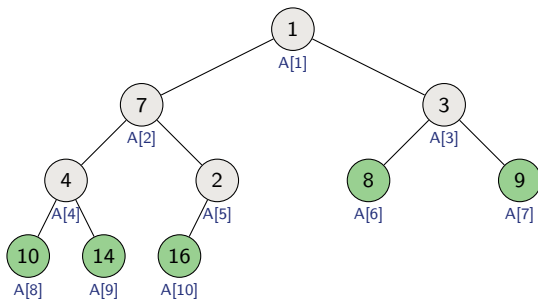
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1	7	3	4	2	8	9	10	14	16
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Example

HEAPSORT(A, n)

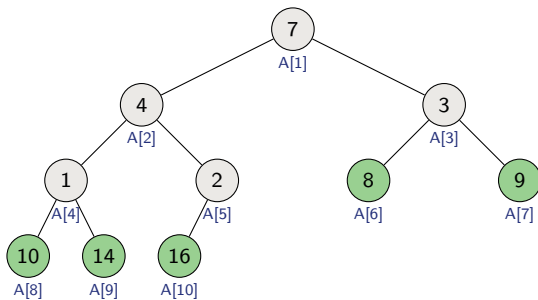
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7	4	3	1	2	8	9	10	14	16
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Example

HEAPSORT(A, n)

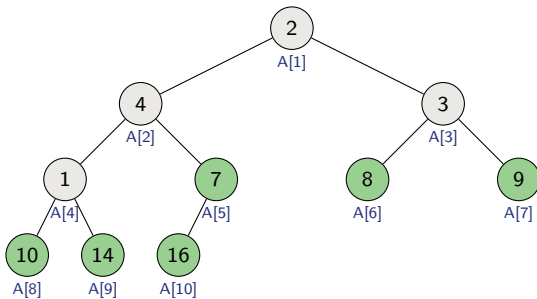
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2	4	3	1	7	8	9	10	14	16
---	---	---	---	---	---	---	----	----	----



Example

HEAPSORT(A, n)

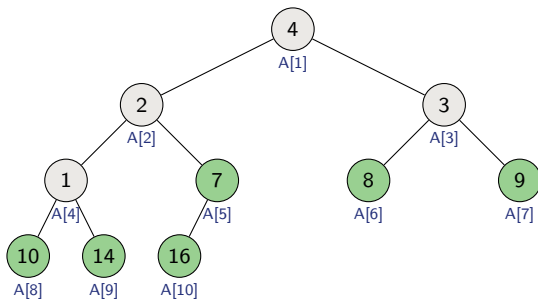
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4	2	3	1	7	8	9	10	14	16
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Example

HEAPSORT(A, n)

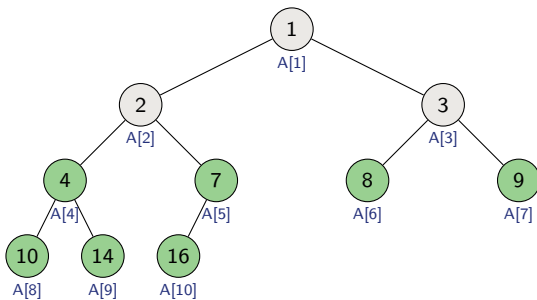
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HEAPSORT(A, n)

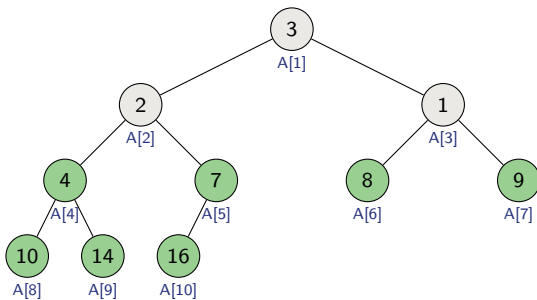
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3	2	1	4	7	8	9	10	14	16
---	---	---	---	---	---	---	----	----	----



Example

HEAPSORT(A, n)

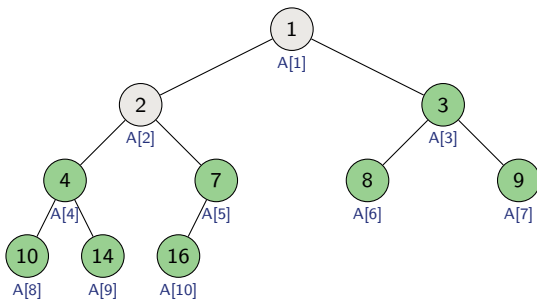
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1	2	3	4	7	8	9	10	14	16
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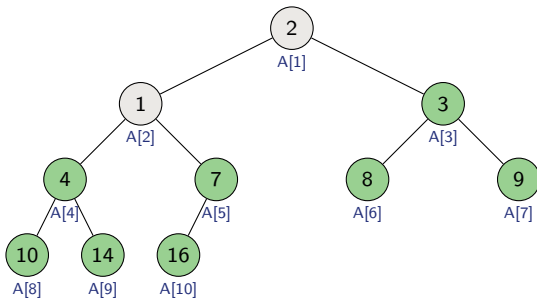
BUILD-MAX-HEAP(A, n)

for $i = n$ **downto** 2

exchange $A[1]$ with $A[i]$

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2	1	3	4	7	8	9	10	14	16
---	---	---	---	---	---	---	----	----	----



Example

HEAPSORT(A, n)

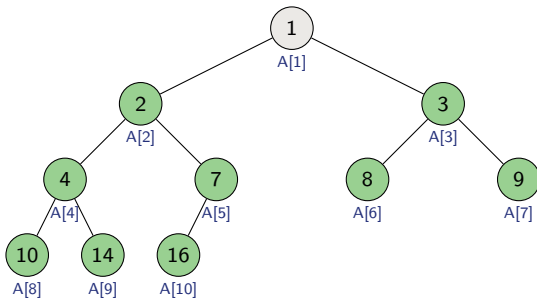
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1	2	3	4	7	8	9	10	14	16
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Example

HEAPSORT(A, n)

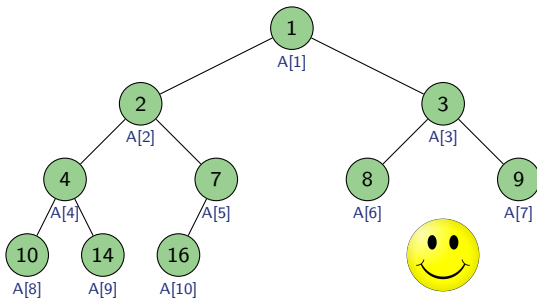
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Analysis of Heapsort

HEAPSORT(A, n)

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Analysis of Heapsort

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- ▶ BUILD-MAX-HEAP: $O(n)$

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- ▶ BUILD-MAX-HEAP: $O(n)$
- ▶ **for** loop: $n - 1$ times
- ▶ exchange elements: $O(1)$
- ▶ MAX-HEAPIFY: $O(\lg n)$

Analysis of Heapsort

HEAPSORT(A, n)

BUILD-MAX-HEAP(A, n)

for $i = n$ **downto** 2

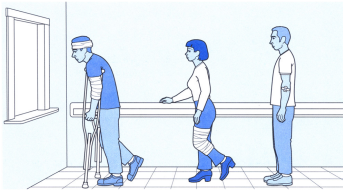
 exchange $A[1]$ with $A[i]$

 MAX-HEAPIFY($A, 1, i - 1$)

- ▶ BUILD-MAX-HEAP: $O(n)$
- ▶ **for** loop: $n - 1$ times
- ▶ exchange elements: $O(1)$
- ▶ MAX-HEAPIFY: $O(\lg n)$

Total time: $O(n \lg n)$

HEAP IMPLEMENTATION OF PRIORITY QUEUE



Priority Queue

- ▶ Maintains a dynamic set S of elements
- ▶ Each set element has a **key** — an associated value that regulates its importance

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assume $k \geq x$'s current key value

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Example max-priority queue application: schedule jobs on shared computer

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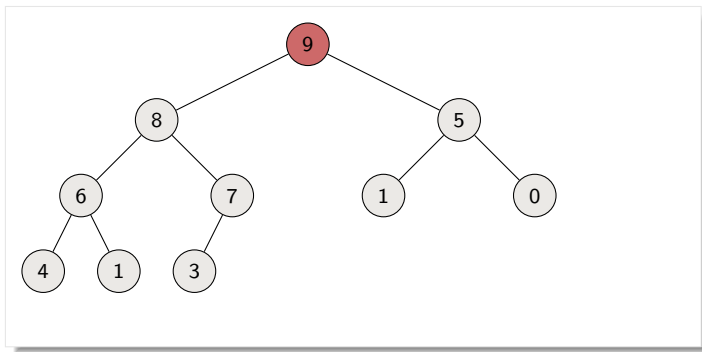
Example max-priority queue application: schedule jobs on shared computer

Heaps efficiently implement priority queues

Finding maximum element

```
HEAP-MAXIMUM(A)  
  return A[1]
```

Simply return the root in time $\Theta(1)$



Extracting maximum element

HEAP-EXTRACT-MAX(A, n)

if $n < 1$

error “heap underflow”

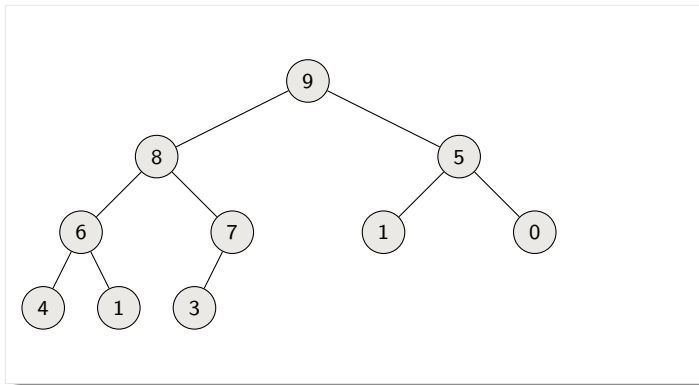
$max = A[1]$

$A[1] = A[n]$

$n = n - 1$

MAX-HEAPIFY($A, 1, n$)

return max



Extracting maximum element

1. Make sure heap is not empty

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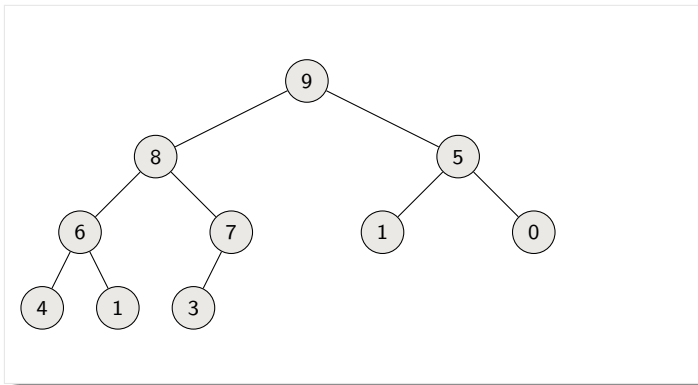
$max = A[1]$

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MAX-HEAPIFY($A, 1, n$)

return max



Extracting maximum element

1. Make sure heap is not empty
2. Make a copy of the maximum element (the root)

HEAP-EXTRACT-MAX(A, n)

if $n < 1$

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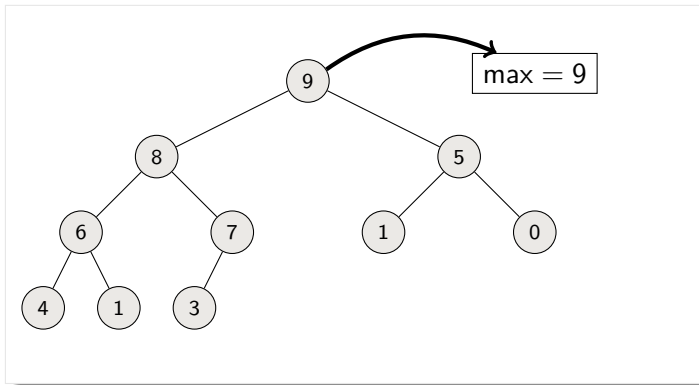
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Extracting maximum element

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3. Make the last node in the tree the new root

HEAP-EXTRACT-MAX(A, n)

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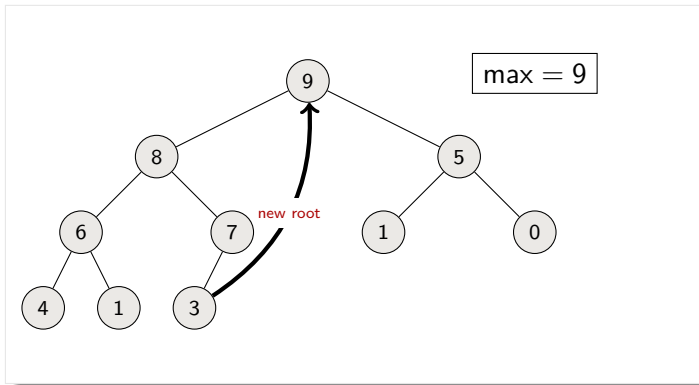
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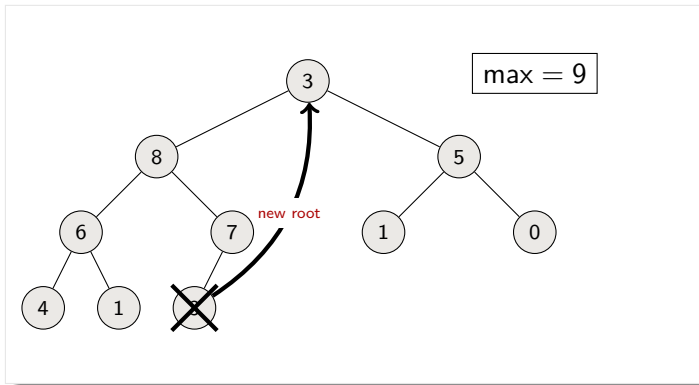
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Extracting maximum element

1. Make sure heap is not empty
2. Make a copy of the maximum element (the root)
3. Make the last node in the tree the new root
4. Re-heapify the heap, with one fewer node

HEAP-EXTRACT-MAX(A, n)

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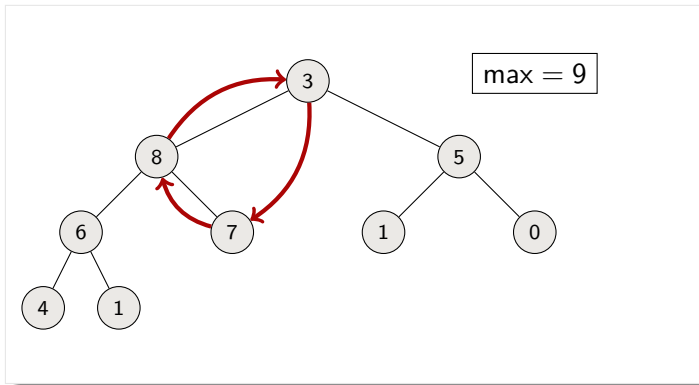
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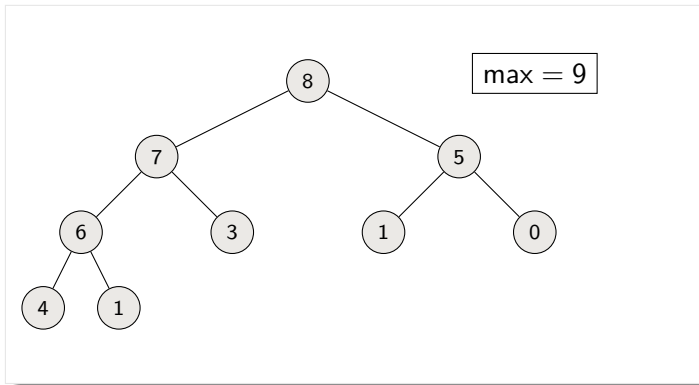
$max = A[1]$

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$n = n - 1$

MAX-HEAPIFY($A, 1, n$)

return max



Extracting maximum element

1. Make sure heap is not empty
2. Make a copy of the maximum element (the root)
3. Make the last node in the tree the new root
4. Re-heapify the heap, with one fewer node
5. Return the copy of the maximum element

HEAP-EXTRACT-MAX(A, n)

if $n < 1$

error “heap underflow”

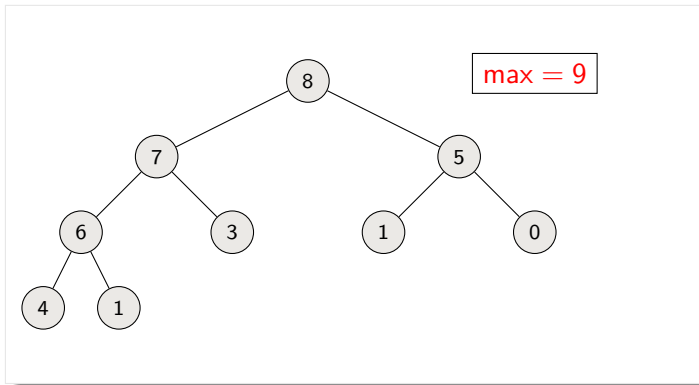
$max = A[1]$

$A[1] = A[n]$

$n = n - 1$

MAX-HEAPIFY($A, 1, n$)

return max



Extracting maximum element

1. Make sure heap is not empty
2. Make a copy of the maximum element (the root)
3. Make the last node in the tree the new root
4. Re-heapify the heap, with one fewer node
5. Return the copy of the maximum element

HEAP-EXTRACT-MAX(A, n)

if $n < 1$

error “heap underflow”

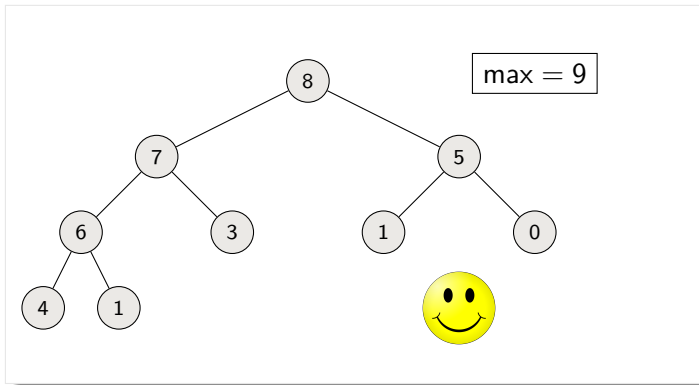
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Extracting maximum element

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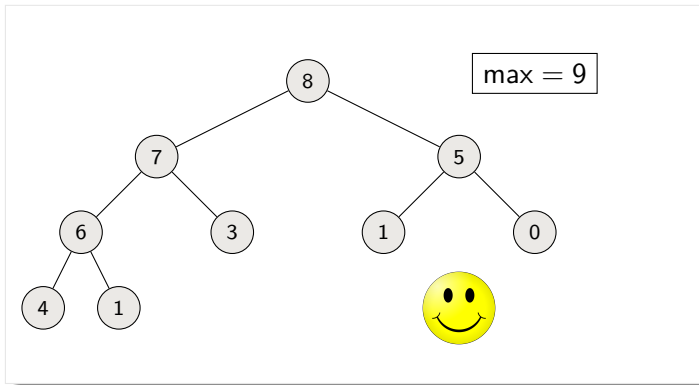
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Extracting maximum element

Analysis: Constant-time assignments plus time for MAX-HEAPIFY

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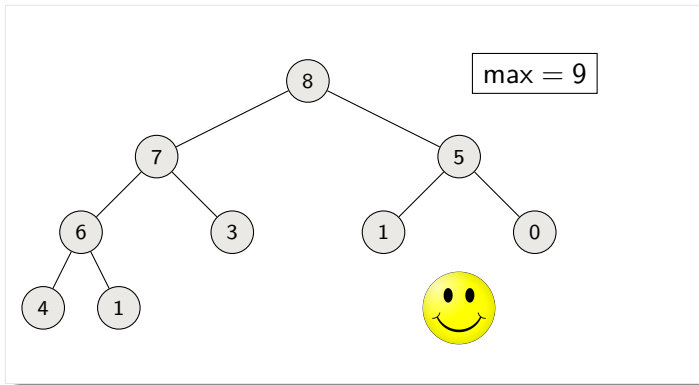
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Hence, it runs in time $O(\lg n)$

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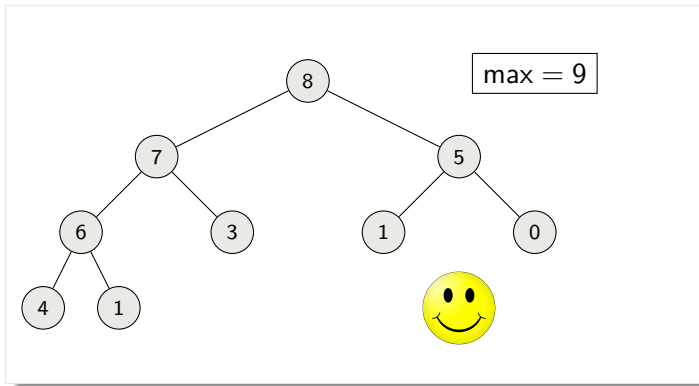
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Increasing key value

Given a heap A , index i , and new value key

HEAP-INCREASE-KEY(A, i, key)

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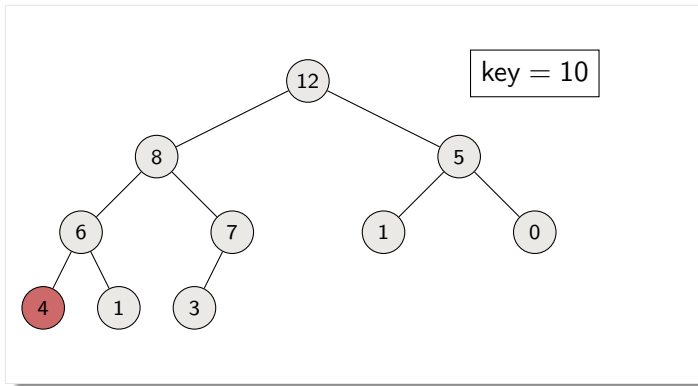
error “new key is smaller than current key”

$A[i] = key$

while $i > 1$ and $A[\text{PARENT}(i)] < A[i]$

exchange $A[i]$ with $A[\text{PARENT}(i)]$

$i = \text{PARENT}(i)$



Increasing key value

Given a heap A , index i , and new value key

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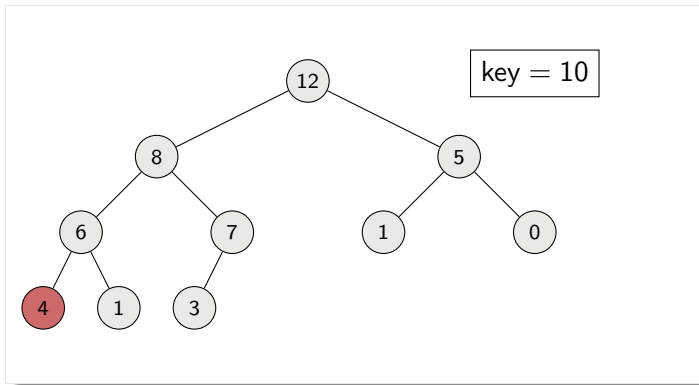
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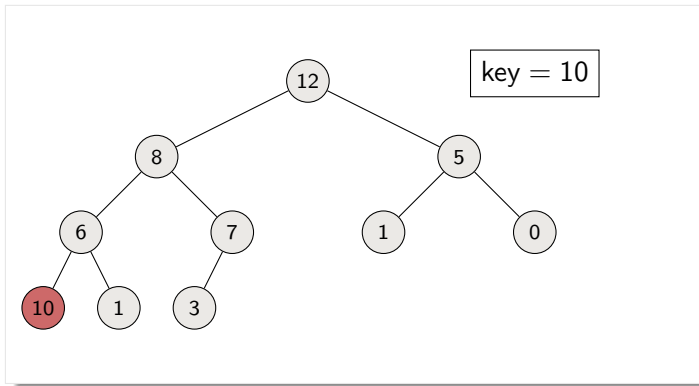
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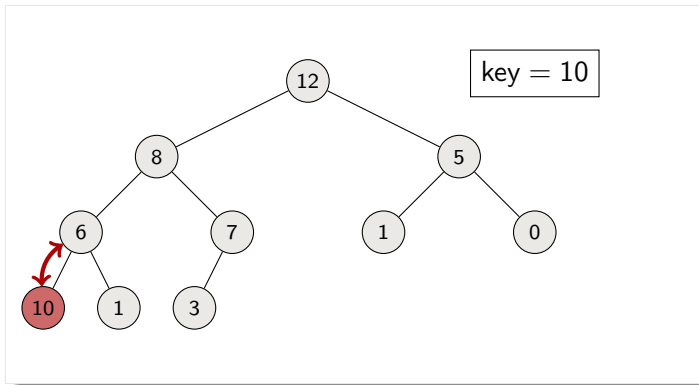
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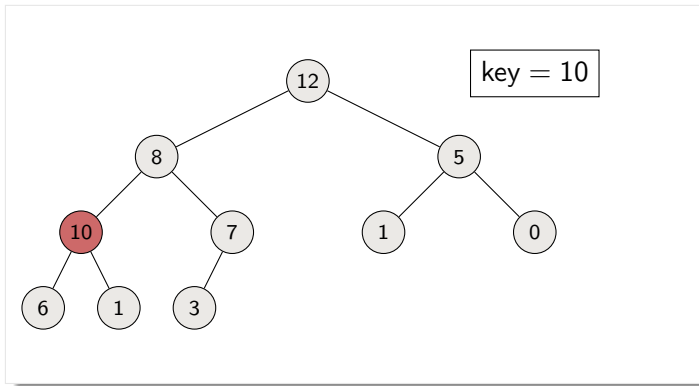
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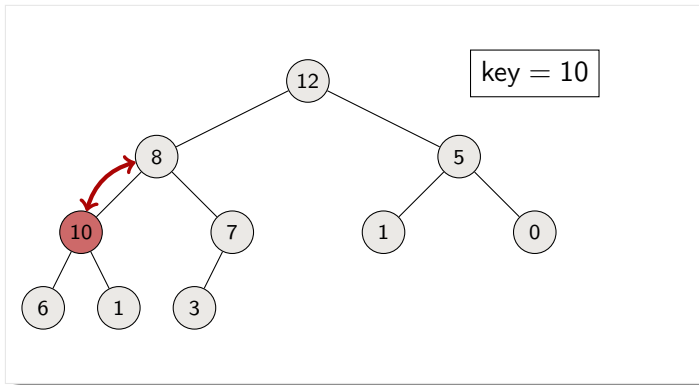
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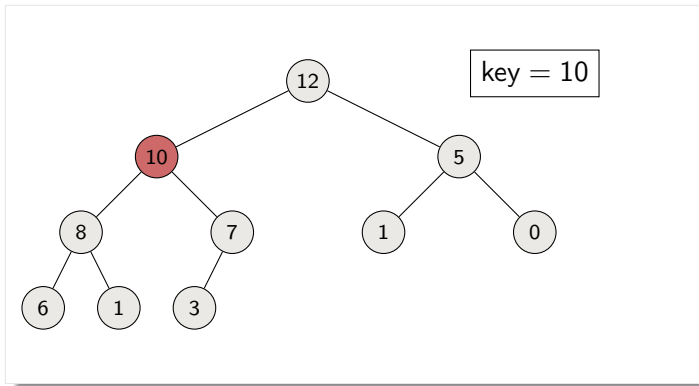
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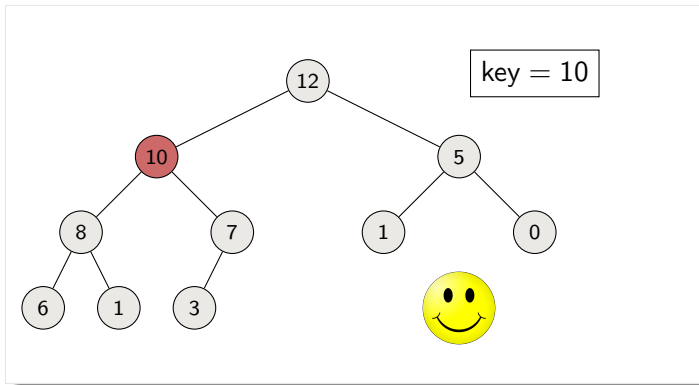
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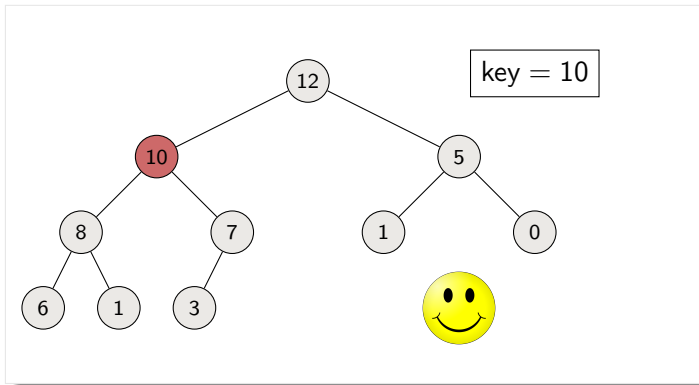
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Upward path from node i has length $O(\lg n)$ in an n -element heap

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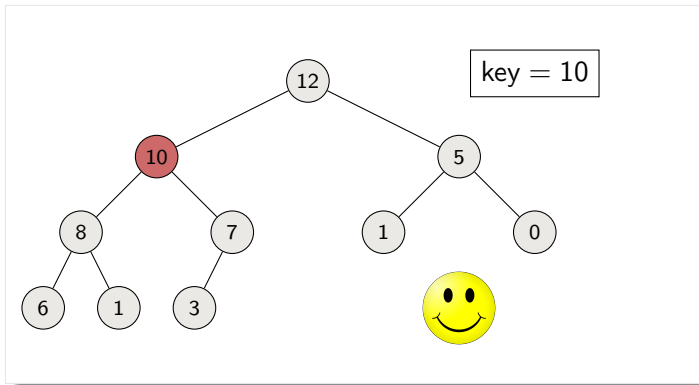
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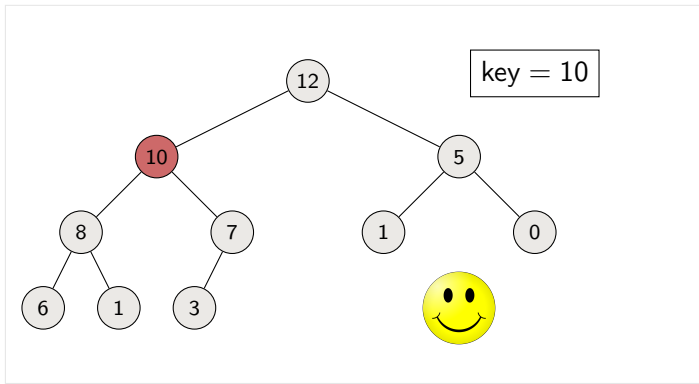
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Inserting into the heap

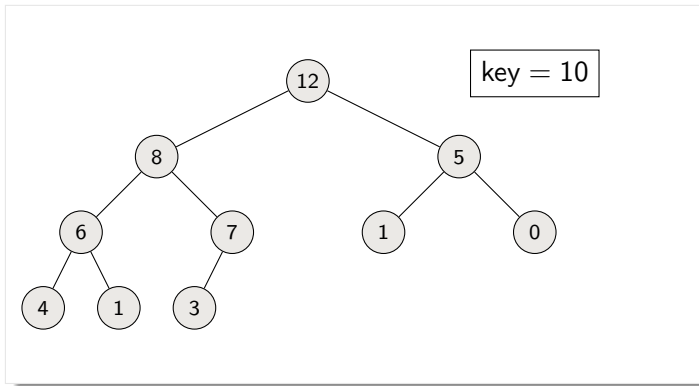
Given a new *key* to insert into heap

MAX-HEAP-INSERT(A, key, n)

$n = n + 1$

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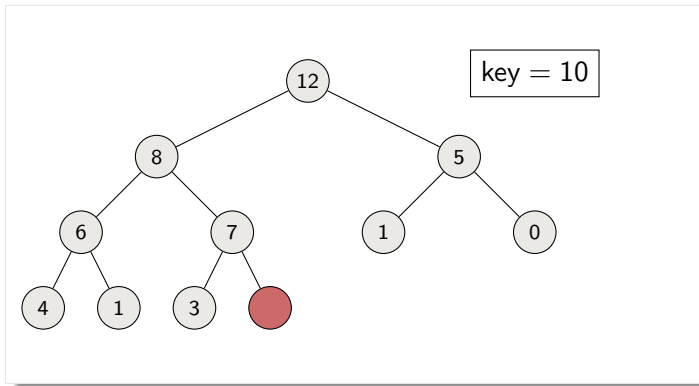
1. Increment the heap size

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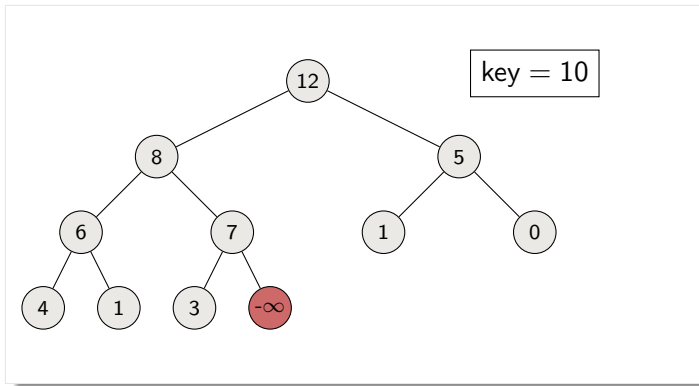
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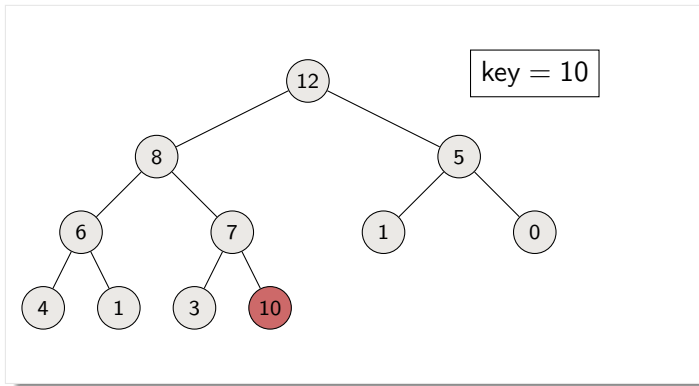
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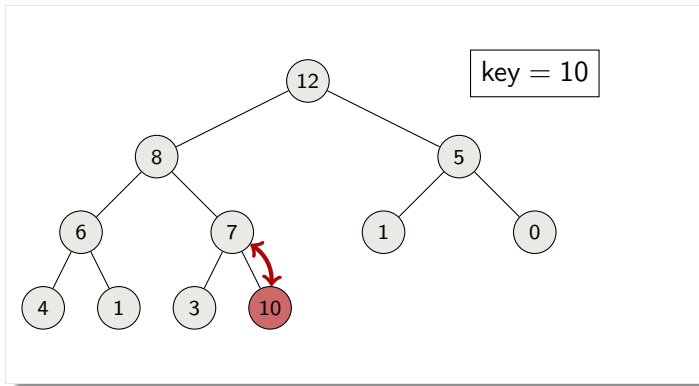
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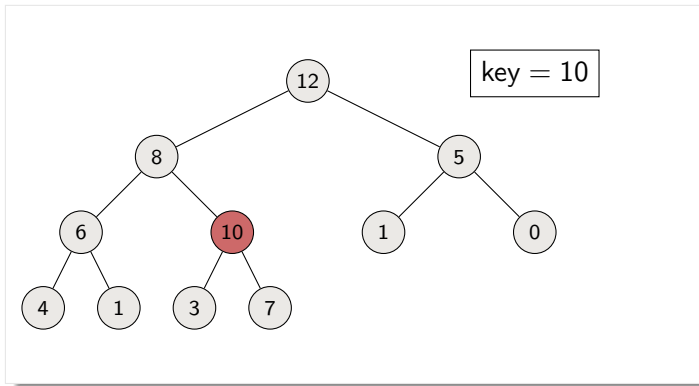
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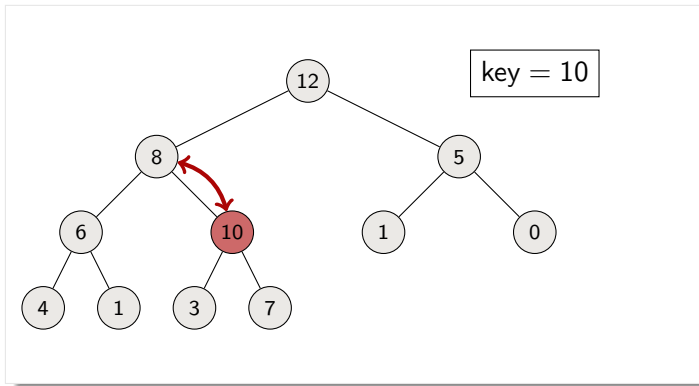
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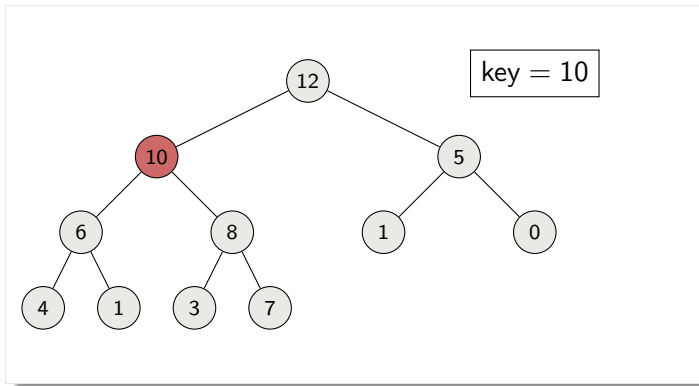
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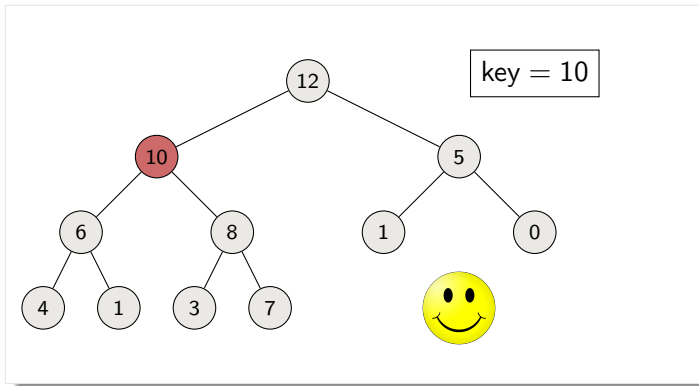
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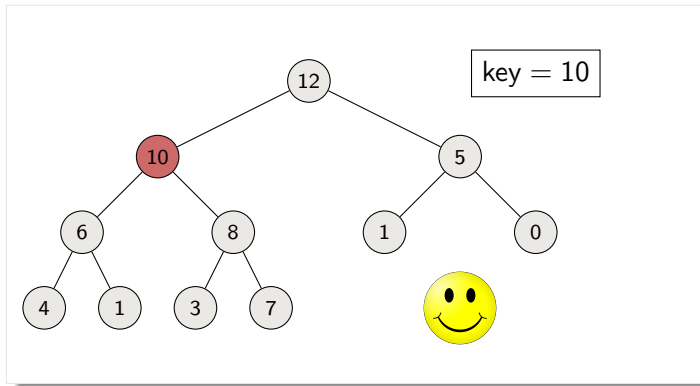
Analysis:

MAX-HEAP-INSERT(A, key, n)

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Inserting into the heap

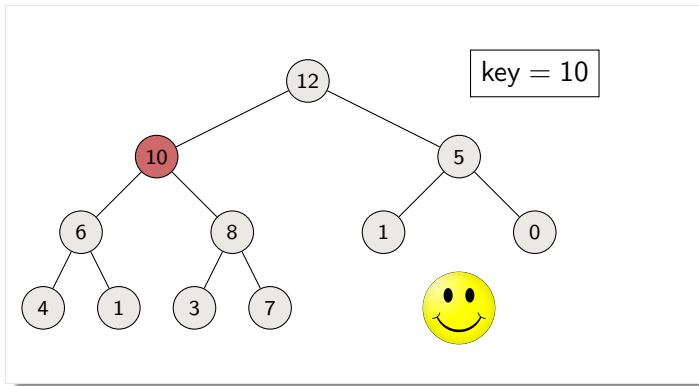
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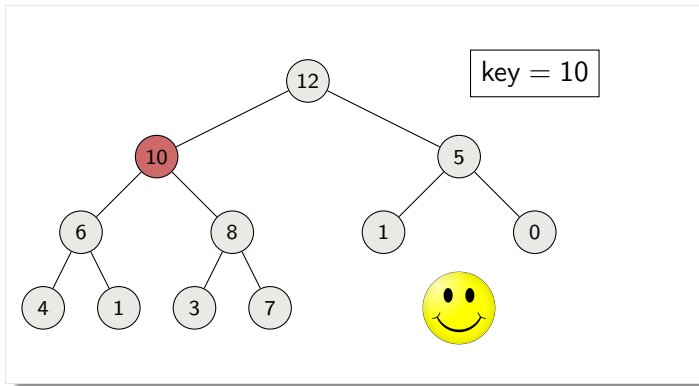
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- ▶ Min-priority queues are implemented with min-heaps similarly

Elementary Data Structures



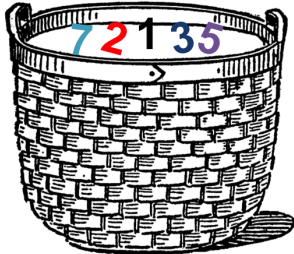
Algorithm



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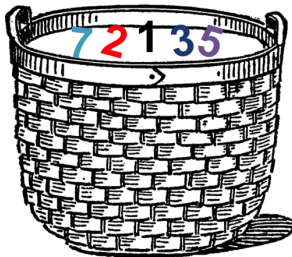
Data structures = dynamic sets of items



Data structure containing numbers

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What kind of operations do we want to do?

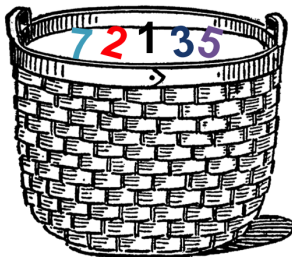


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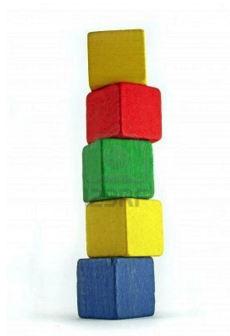
- ▶ **Modifying operations:** insertion, deletion, ...
- ▶ **Query operations:** search, maximum, minimum, ...



Data structure containing numbers

Stacks (last-in, first-out)

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$\text{PUSH}(S, 2), \text{PUSH}(S, 1), \text{POP}(S), \text{PUSH}(S, 3), \text{POP}(S), \text{POP}(S)$

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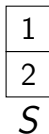
$\boxed{2}$
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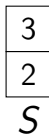
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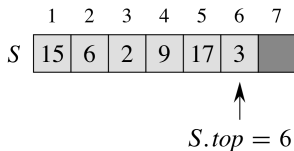
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- ▶ Delete operation called $\text{POP}(S)$

Example:

$\text{PUSH}(S, 2), \text{PUSH}(S, 1), \text{POP}(S), \text{PUSH}(S, 3), \text{POP}(S), \text{POP}(S)$

S

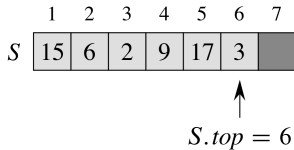
Stacks Implementation



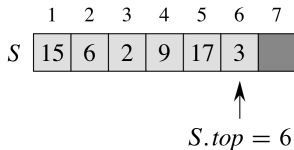
Implementation using arrays: S consists of elements $S[1, \dots, S.top]$

- ▶ $S[1]$ element at the bottom
- ▶ $S[S.top]$ element at the top

Stacks Implementation



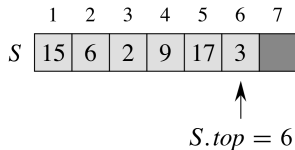
Stacks Implementation



STACK-EMPTY(S)

1. **if** $S.top = 0$
2. **return** TRUE
3. **else return** FALSE

Stacks Implementation



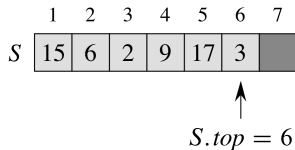
STACK-EMPTY(S)

1. if $S.top = 0$
2. **return** TRUE
3. **else return** FALSE

PUSH(S, x)

1. $S.top \leftarrow S.top + 1$
2. $S[S.top] \leftarrow x$

Stacks Implementation



STACK-EMPTY(S)

1. if $S.top = 0$
2. **return** TRUE
3. **else return** FALSE

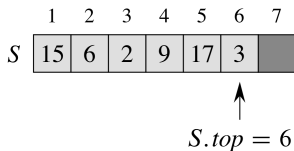
PUSH(S, x)

1. $S.top \leftarrow S.top + 1$
2. $S[S.top] \leftarrow x$

POP(S)

1. **if** STACK-EMPTY(S)
2. **error** "underflow"
3. **else**
4. $S.top \leftarrow S.top - 1$
5. **return** $S[S.top + 1]$

Stacks Implementation



What is the running time of these operations?

STACK-EMPTY(S)

1. **if** $S.top = 0$
2. **return** TRUE
3. **else return** FALSE

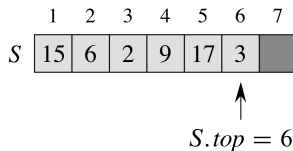
PUSH(S, x)

1. $S.top \leftarrow S.top + 1$
2. $S[S.top] \leftarrow x$

POP(S)

1. **if** STACK-EMPTY(S)
2. **error** "underflow"
3. **else**
4. $S.top \leftarrow S.top - 1$
5. **return** $S[S.top + 1]$

Stacks Implementation



What is the running time of these operations? $O(1)$

STACK-EMPTY(S)

1. if $S.top = 0$
2. **return** TRUE
3. **else return** FALSE

PUSH(S, x)

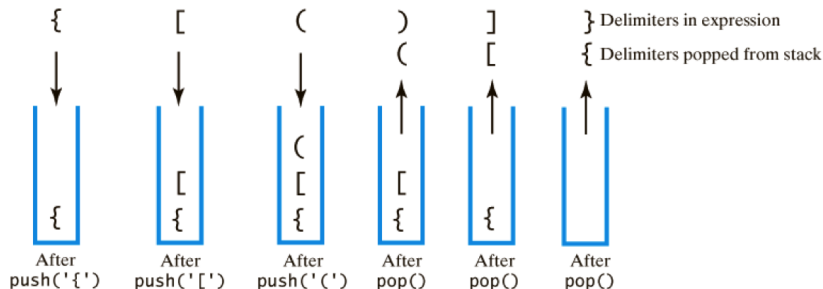
1. $S.top \leftarrow S.top + 1$
2. $S[S.top] \leftarrow x$

POP(S)

1. **if** STACK-EMPTY(S)
2. **error** "underflow"
3. **else**
4. $S.top \leftarrow S.top - 1$
5. **return** $S[S.top + 1]$

Stacks are everywhere in every software

Stacks are everywhere in every software



The contents of a stack during the scan of an expression that contains the balanced delimiters $\{ [()] \}$

$$a\{b[c(d+e)/2-f]+1\}$$

Queues (first-in, first-out)

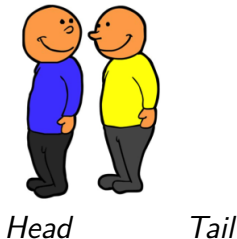
- ▶ Insert operation called $\text{ENQUEUE}(Q, x)$
- ▶ Delete operation called $\text{DEQUEUE}(Q)$



Queues (first-in, first-out)

- ▶ Insert operation called $\text{ENQUEUE}(Q, x)$
- ▶ Delete operation called $\text{DEQUEUE}(Q)$


Example:

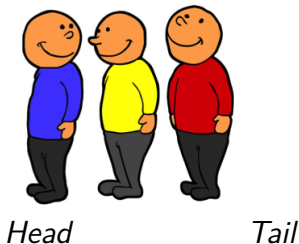


Queues (first-in, first-out)

- ▶ Insert operation called $\text{ENQUEUE}(Q, x)$
- ▶ Delete operation called $\text{DEQUEUE}(Q)$

Example:

$\text{ENQUEUE}(Q,$ ,

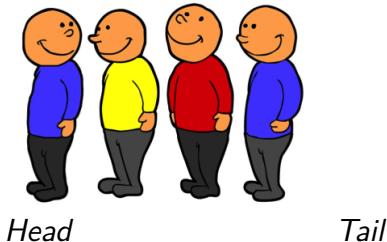


Queues (first-in, first-out)

- ▶ Insert operation called $\text{ENQUEUE}(Q, x)$
- ▶ Delete operation called $\text{DEQUEUE}(Q)$

Example:

$\text{ENQUEUE}(Q, \text{red person}), \text{ENQUEUE}(Q, \text{blue person}),$

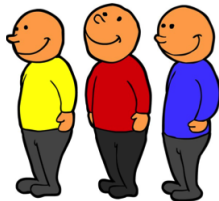


Queues (first-in, first-out)

- ▶ Insert operation called $\text{ENQUEUE}(Q, x)$
- ▶ Delete operation called $\text{DEQUEUE}(Q)$

Example:

$\text{ENQUEUE}(Q, \text{red})$, $\text{ENQUEUE}(Q, \text{blue})$, $\text{DEQUEUE}(Q)$,



Head

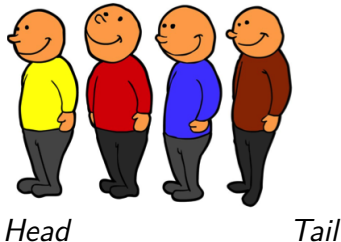
Tail

Queues (first-in, first-out)

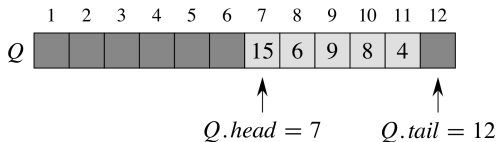
- ▶ Insert operation called $\text{ENQUEUE}(Q, x)$
- ▶ Delete operation called $\text{DEQUEUE}(Q)$

Example:

$\text{ENQUEUE}(Q, \text{red})$, $\text{ENQUEUE}(Q, \text{blue})$, $\text{DEQUEUE}(Q)$, $\text{ENQUEUE}(Q, \text{brown})$



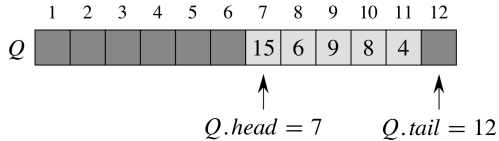
Queue Implementation



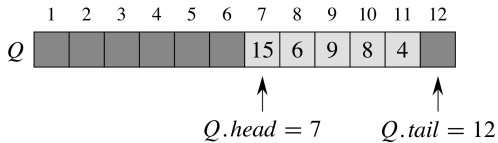
Implementation using arrays: Q consists of elements $S[Q.head, \dots, Q.tail - 1]$

- ▶ $Q.head$ points at the first element
- ▶ $Q.tail$ points at the next location where a newly arrived element will be placed

Queue Implementation



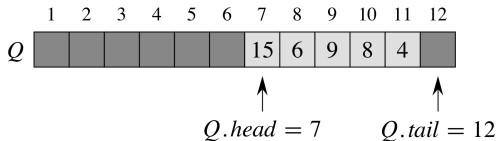
Queue Implementation



ENQUEUE(Q, x)

1. $Q[Q.tail] = x$
2. **if** $Q.tail = Q.length$
3. $Q.tail \leftarrow 1$
4. **else** $Q.tail \leftarrow Q.tail + 1$

Queue Implementation



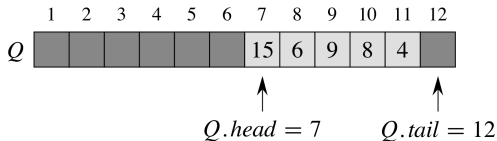
ENQUEUE(Q, x)

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2. **if** $Q.tail = Q.length$
3. $Q.tail \leftarrow 1$
4. **else** $Q.tail \leftarrow Q.tail + 1$

DEQUEUE(Q)

1. $x = Q[Q.head]$
2. **if** $Q.head = Q.length$
3. $Q.head \leftarrow 1$
4. **else** $Q.head \leftarrow Q.head + 1$
5. **return** x

Queue Implementation



What is the running time of these operations?

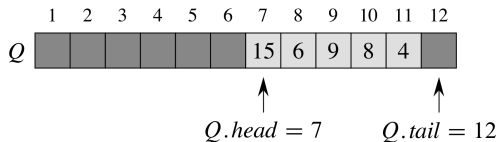
ENQUEUE(Q, x)

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2. **if** $Q.head = Q.length$
3. $Q.head \leftarrow 1$
4. **else** $Q.head \leftarrow Q.head + 1$
5. **return** x

Queue Implementation



What is the running time of these operations? $O(1)$

ENQUEUE(Q, x)

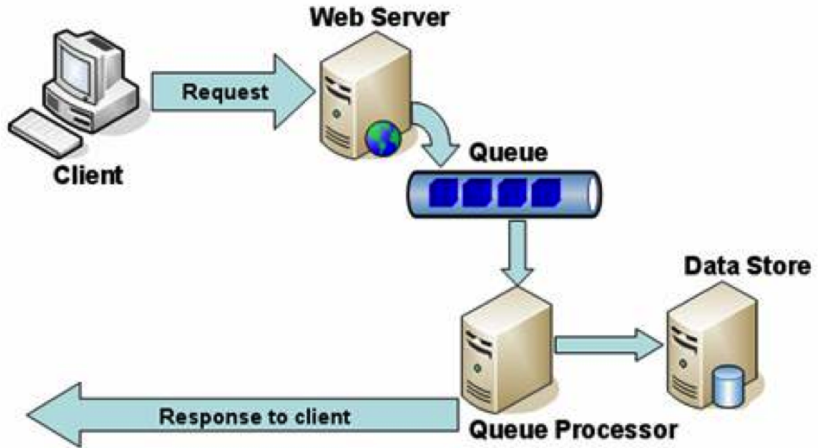
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2. **if** $Q.tail = Q.length$
3. $Q.tail \leftarrow 1$
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DEQUEUE(Q)

1. $x = Q[Q.head]$
2. **if** $Q.head = Q.length$
3. $Q.head \leftarrow 1$
4. **else** $Q.head \leftarrow Q.head + 1$
5. **return** x

Applications of Queues

One example: **Web server**



Stacks and Queues

Positives

Negatives

Stacks and Queues

Positives

- ▶ Very efficient
- ▶ Natural operations

Negatives

Stacks and Queues

Positives

- ▶ Very efficient
- ▶ Natural operations

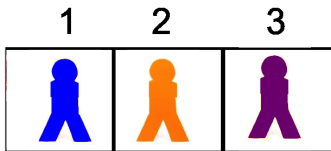
Negatives

- ▶ Limited support: for example, no search
- ▶ Implementations using arrays have a *fixed* capacity

Linked List

Objects are arranged in a linear order

Not indexes in array



But pointers in each object

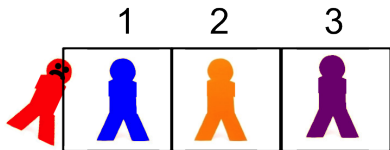


Linked List

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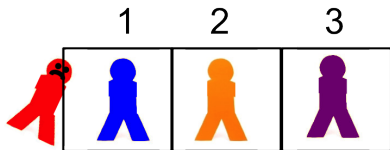


Linked List

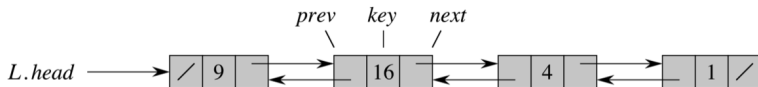
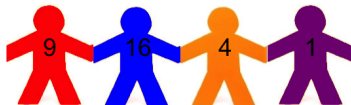
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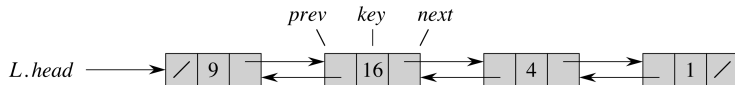
Linked List



A list can be

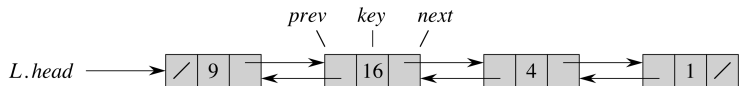
- ▶ Single linked or double linked
- ▶ Sorted or unsorted
- ▶ etc.

Searching a Linked List



Task: Given k return pointer to first element with key k

Searching a Linked List

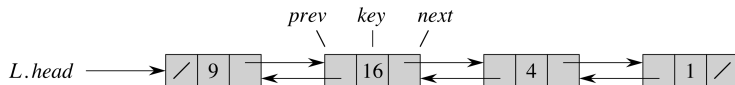


Task: Given k return pointer to first element with key k

LIST-SEARCH(L, K)

1. $x \leftarrow L.head$
2. **while** $x \neq nil$ and $x.key \neq k$
3. $x \leftarrow x.next$
4. **return** x

Searching a Linked List



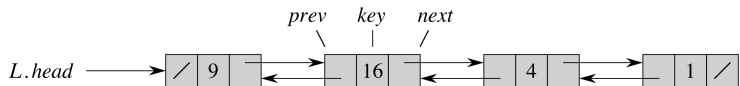
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Running time?

Searching a Linked List



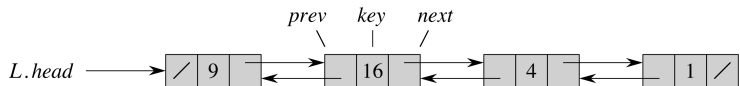
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Running time? $O(n)$

Searching a Linked List



Task: Given k return pointer to first element with key k

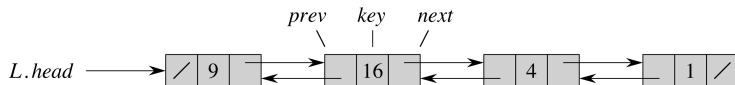
LIST-SEARCH(L, k)

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4. **return** x

Running time? $O(n)$

What if no element with key k exists?

Searching a Linked List



Task: Given k return pointer to first element with key k

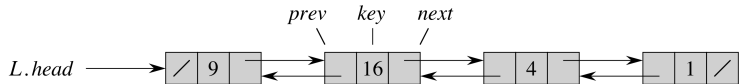
LIST-SEARCH(L, k)

1. $x \leftarrow L.head$
2. **while** $x \neq nil$ and $x.key \neq k$
3. $x \leftarrow x.next$
4. **return** x

Running time? $O(n)$

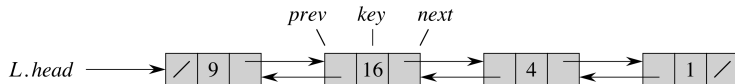
What if no element with key k exists? **returns nil**

Inserting into a Linked List



Task: Insert a new element x

Inserting into a Linked List

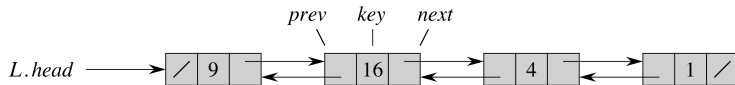


Task: Insert a new element x

LIST-INSERT(L, x)

1. $x.next \leftarrow L.head$
2. **if** $L.head \neq nil$
3. $L.head.prev \leftarrow x$
4. $L.head \leftarrow x$
5. $x.prev = NIL$

Inserting into a Linked List



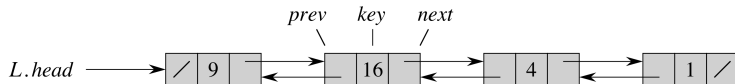
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Running time?

Inserting into a Linked List



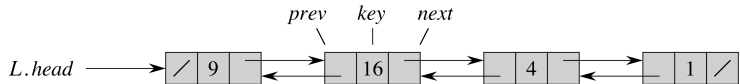
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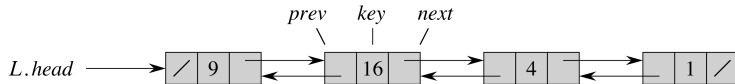
Running time? $O(1)$

Deleting From a Linked List



Task: Given a pointer to an element x remove it from L

Deleting From a Linked List

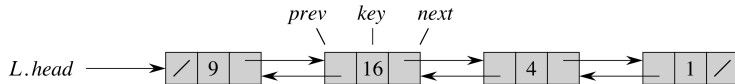


Task: Given a pointer to an element x remove it from L

LIST-DELETE(L, x)

1. **if** $x.prev \neq nil$
2. $x.prev.next \leftarrow x.next$
3. **else** $L.head \leftarrow x.next$
4. **if** $x.next \neq nil$
5. $x.next.prev \leftarrow x.prev$

Deleting From a Linked List



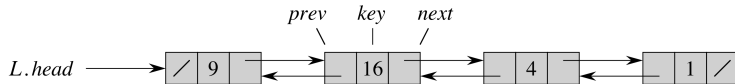
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LIST-DELETE(L, x)

1. **if** $x.prev \neq nil$
2. $x.prev.next \leftarrow x.next$
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5. $x.next.prev \leftarrow x.prev$

Running time?

Deleting From a Linked List



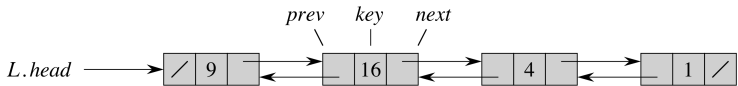
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LIST-DELETE(L, x)

1. **if** $x.prev \neq nil$
2. $x.prev.next \leftarrow x.next$
3. **else** $L.head \leftarrow x.next$
4. **if** $x.next \neq nil$
5. $x.next.prev \leftarrow x.prev$

Running time? $O(1)$

Sentinels



Note: If x is in the middle of the list then

LIST-DELETE(L, x)

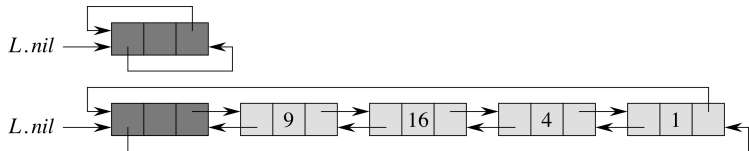
1. **if** $x.\text{prev} \neq \text{nil}$
2. $x.\text{prev}.\text{next} \leftarrow x.\text{next}$
3. **else** $L.\text{head} \leftarrow x.\text{next}$
4. **if** $x.\text{next} \neq \text{nil}$
5. $x.\text{next}.\text{prev} \leftarrow x.\text{prev}$

simplified

LIST-DELETE'(L, x)

1. $x.\text{prev}.\text{next} \leftarrow x.\text{next}$
2. $x.\text{next}.\text{prev} \leftarrow x.\text{prev}$

Sentinels



LIST-DELETE(L, X)

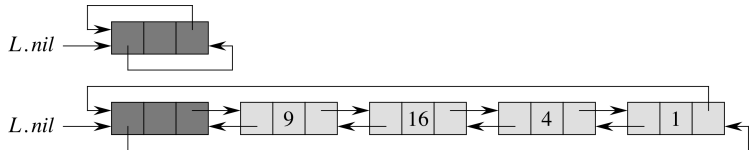
1. **if** $x.\text{prev} \neq \text{nil}$
2. $x.\text{prev}.\text{next} \leftarrow x.\text{next}$
3. **else** $L.\text{head} \leftarrow x.\text{next}$
4. **if** $x.\text{next} \neq \text{nil}$
5. $x.\text{next}.\text{prev} \leftarrow x.\text{prev}$

simplified

LIST-DELETE'(L, X)

1. $x.\text{prev}.\text{next} \leftarrow x.\text{next}$
2. $x.\text{next}.\text{prev} \leftarrow x.\text{prev}$

Sentinels



simplified

LIST-INSERT(L, x)

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2. **if** $L.head \neq nil$
3. $L.head.prev \leftarrow x$
4. $L.head \leftarrow x$
5. $x.prev = NIL$

LIST-INSERT'(L, x)

1. $x.next \leftarrow L.nil.next$
2. $L.nil.next.prev \leftarrow x$
3. $L.nil.next \leftarrow x$
4. $x.prev \leftarrow L.nil$

Summary Linked List

- ▶ Dynamic data structure without predefined capacity
- ▶ Insertion: $O(1)$
- ▶ Deletion: $O(1)$ (if double linked)
 - ▶ Question in book: can you do it for single linked?
- ▶ Search: $O(n)$

Summary Linked List

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Summary

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Summary

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 INSERT(S, x): $O(\lg n)$

Summary

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 - INSERT(S, x): $O(\lg n)$
 - MAXIMUM(S):

Summary

- ▶ Heaps efficiently implement priority queues
 - INSERT(S, x): $O(\lg n)$
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Summary

- ▶ Heaps efficiently implement priority queues

INSERT(S, x): $O(\lg n)$

MAXIMUM(S): $O(1)$

EXTRACT-MAX(S):

Summary

- ▶ Heaps efficiently implement priority queues

INSERT(S, x): $O(\lg n)$

MAXIMUM(S): $O(1)$

EXTRACT-MAX(S): $O(\lg n)$

Summary

- ▶ Heaps efficiently implement priority queues

INSERT(S, x): $O(\lg n)$

MAXIMUM(S): $O(1)$

EXTRACT-MAX(S): $O(\lg n)$

INCREASE-KEY(S, x, k):

Summary

- ▶ Heaps efficiently implement priority queues
 - $\text{INSERT}(S, x): O(\lg n)$
 - $\text{MAXIMUM}(S): O(1)$
 - $\text{EXTRACT-MAX}(S): O(\lg n)$
 - $\text{INCREASE-KEY}(S, x, k): O(\lg n)$
- ▶ Min-priority queues are implemented with min-heaps similarly
- ▶ Stacks, Queues and Linked lists
 - ▶ Good at specific operations for specific uses
 - ▶ Bad at search