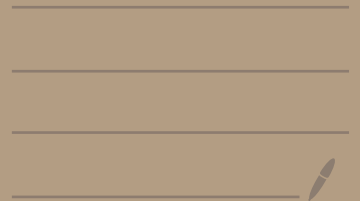


Information Theory & Coding

Nov 10th, 2020



Yesterday

$$x \rightarrow x + Z \quad Z \sim N(0, \sigma^2)$$

$$h(x) = x^2, \text{ we saw}$$

$$C(P) = \frac{1}{2} \log(1 + P/\sigma^2)$$

To day : "Additive Gaussian Noise Waveform Channel"

$$\begin{array}{ccc} x(t) & \longrightarrow & y(t) = x(t) + Z(t). \\ \text{input} & & \text{output} \end{array} \quad t \in \mathbb{R}$$

the process $(Z(t) : t \in \mathbb{R})$ has statistics independent of $(x(t) : t \in \mathbb{R})$

What is $Z(t)$, the noise?

when we measure Z at time t_0 , we in fact

mean a measurement of the form

$$\int_{t_0 - \Delta/2}^{t_0 + \Delta/2} Z(t) dt$$

$$Z_1 = \int_a^{a+\Delta} Z(t) dt \quad Z_2 = \int_b^{b+\Delta} Z(t) dt$$

if a & b are far apart: then we expect Z_1 & Z_2 to be independent.

An idealized version will say if

$$(a, a+\Delta) \cap (b, b+\Delta) = \emptyset \Rightarrow Z_1, Z_2 \text{ indep. \& identically distrib.}$$

I will also assume that Z_1 & Z_2 have zero-mean.

$$Z_3 = \int_a^{a+2\Delta} Z(t) dt = \underbrace{\int_a^{a+\Delta} Z(t) dt}_{\substack{\text{0-mean} \\ \text{same variance } f(\Delta)}} + \underbrace{\int_{a+\Delta}^{a+2\Delta} Z(t) dt}_{\substack{\text{0-mean} \\ \text{variance } f(\Delta)}}$$

0-mean variance $2f(\Delta)$

$$\Rightarrow f(\Delta) = \sigma^2 \Delta$$

$$Z_b = \int g(t) Z(t) dt \approx \sum_n \int_{n\Delta}^{(n+1)\Delta} g(t) Z(t) dt$$

$$\approx \sum_n \int_{n\Delta}^{(n+1)\Delta} g(n\Delta) Z(t) dt$$

$$\int_{n\Delta}^{(n+1)\Delta} \underbrace{g(n\Delta)}_{\substack{\text{0-mean variance } \sigma^2 \Delta}} z(t) dt = \underbrace{g(n\Delta)}_{\substack{\text{0-mean variance } \sigma^2 \Delta}} \int_{n\Delta}^{(n+1)\Delta} z(t) dt$$

0-mean variance $g(n\Delta)^2 \sigma^2 \Delta$

$\int z(t) \underbrace{g(t)}_{\substack{\text{0-mean variance}}} dt$

$$\sigma^2 \sum_n g(n\Delta)^2 \Delta \approx \int g(t)^2 dt$$

$$Z_1 = \int g_1(t) Z(t) dt$$

$$\approx \sum_n g_1(n\Delta) \int_{n\Delta}^{(n+1)\Delta} Z(t) dt$$

$$Z_2 = \int g_2(t) Z(t) dt$$

$$\approx \sum_m g_2(m\Delta) \int_{m\Delta}^{(m+1)\Delta} Z(t) dt$$

$$E(Z_1 Z_2) = \sum_{n,m} g_1(n\Delta) g_2(m\Delta) E\left(\int_{n\Delta}^{(n+1)\Delta} Z(t) dt \int_{m\Delta}^{(m+1)\Delta} Z(t) dt \right)$$

$$= \begin{cases} 0 & \text{if } n \neq m \\ \sigma^2 \Delta & \text{if } n = m \end{cases}$$

$$= \sum_n g_1(n\Delta) g_2(n\Delta) \sigma^2 \Delta$$

$$\approx \sigma^2 \int g_1(t) g_2(t) dt$$

Z is an aggregation of microscopic phenomena.

$$X = \frac{1}{\sqrt{n}} \sum_{i=1}^n (X_i \sqrt{n})$$

X_i 0-mean, indep.

$$E(X_i^2) \approx O\left(\frac{1}{n}\right)$$

Central Limit Theorem will say X is Gaussian in the limit of large n .

The "idealized" noise process $z(t)$ is characterized by the following property: whenever $g_1, g_2, \dots, g_n$ are functions of time and we form

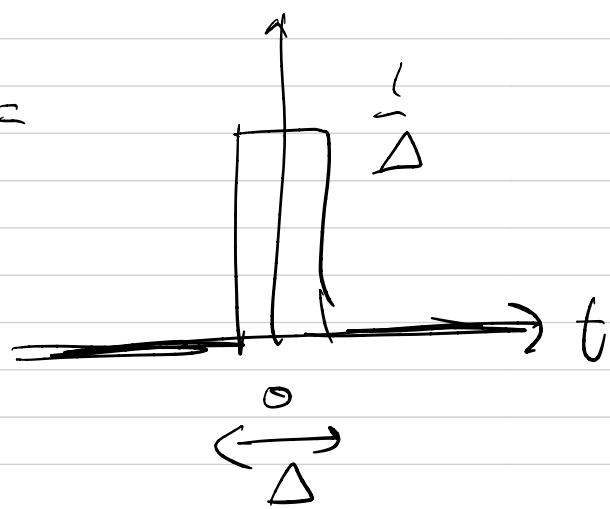
$$z_1 = \int g_1(t) z(t) dt, \dots, z_n = \int g_n(t) z(t) dt$$

then $\begin{bmatrix} z_1 \\ \vdots \\ z_n \end{bmatrix}$ is a Gaussian Random Vector with 0-mean & covariance matrix

$$K \text{ with } K_{ij} = \sigma^2 \int g_i(t) g_j(t) dt.$$

In the literature such a $(z(t) : t \in \mathbb{R})$ is called "white" gaussian noise of intensity σ^2 .

$$g_1(t) =$$



had $z(t)$ been a non-random, continuous then

$$\int g_1(t) z(t) dt$$

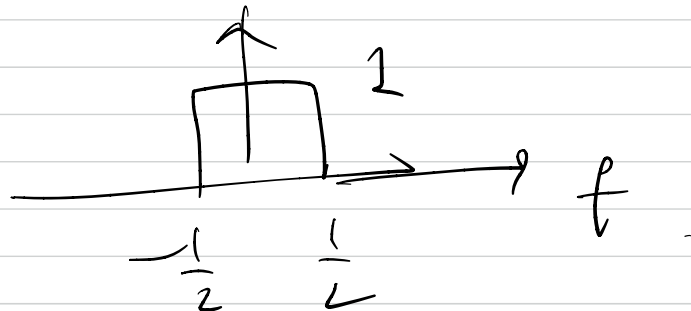
$$\lim_{\Delta \rightarrow 0} \int g_1(t) z(t) dt = z(0).$$

$$= \text{Gaussian} \left(0\text{-mean}, \text{variance} = \frac{\sigma^2}{\Delta} \right)$$

$$g_1(t) = \text{sinc}(t)$$

$$\text{sinc}(t) = \frac{\sin \pi t}{\pi t}$$

Fourier Transform



$$\int x(t) e^{-j2\pi ft} dt = X(f)$$

$$\int X(f) e^{j2\pi ft} df = x(t)$$

Parseval formula :

$$\int x(t) y^*(t) dt = \int X(f) Y^*(f) df$$

$$g_1(t) = \text{sinc}(t)$$

$$g_2(t) = \text{sinc}(t-1)$$

$$z_1 = \int z(t) g_1(t) dt$$

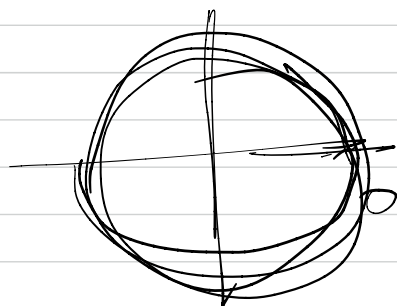
$$z_2 = \int z(t) g_2(t) dt$$

$$E(z_1^2) = \sigma^2 \int g_1(t)^2 dt = \sigma^2 \int_{-\frac{1}{2}}^{\frac{1}{2}} 1^2 df = \sigma^2$$

$$E(z_2^2) = \sigma^2$$

$$E(z_1 z_2) = \sigma^2 \int \text{sinc}(t) \text{sinc}(t-1) dt$$

$$= \sigma^2 \int_{-\frac{1}{2}}^{\frac{1}{2}} 1 \cdot \left(e^{-j2\pi f} \right) df = 0$$



so z_1, z_2 are i.i.d $N(0, \sigma^2)$.

$$g_i(t) = \text{sinc}(t-i) \quad i \in \mathbb{Z}$$

$$z_i = \int z(t) g_i(t) dt$$

we will find $(z_i : i \in \mathbb{Z})$ are i.i.d $N(0, \sigma^2)$.

Suppose we have such a $z(t)$ and we have a channel

$$x(t) \longrightarrow \underline{y(t)} = x(t) + \underline{z(t)},$$

Suppose $x(t)$ belongs to a finite dimensional linear space, i.e., $\exists$ basis functions

~~$x(t)$~~ $\varphi_1(t), \dots, \varphi_n(t)$ s.t.

$$x(t) = \sum_{i=1}^n x_i \varphi_i(t). \quad \text{we might assume}$$

that φ_i 's are orthonormal.

$$\int \varphi_i(t) \varphi_j(t) dt = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

Example: suppose $x(t) \in \{x_1(t), \dots, x_M(t)\}$

in this case $x(t)$ belongs to the space spanned

by $x_1(t), \dots, x_M(t)$

$$= \{ \bar{x}(t) : \bar{x}(t) = \sum_{i=1}^M \alpha_i x_i(t) \quad \alpha_i \in \mathbb{R} \}$$

$(x(t))$ is specified by specifying $(x_1, \dots, x_n)$

$$\Rightarrow x(t) = \sum_i \alpha_i \psi_i(t)$$

$$\alpha_i \equiv \int x(t) \psi_i(t) dt$$

So the input $x(t)$ to the channel is

in fact $\equiv$ to $(x_1, \dots, x_n)$.

Let us now consider the output $(y(t) : t \in \mathbb{R})$.

$$= (x(t) * z(t) : t \in \mathbb{R}).$$

Let us form the "measurements"

$$Y_i = \int Y(t) \psi_i(t) dt \quad i=1, \dots, n.$$

$$= \underbrace{\int x(t) \psi_i(t) dt}_{x_i} + \underbrace{\int z(t) \psi_i(t) dt}_{z_i}$$

$$z_1, z_2, \dots \text{ iid } N(0, \sigma^2)$$

Any additional measurements we can do will be

$$\tilde{Y}_i = \int Y(t) \tilde{g}_i(t) dt \quad i=1, \dots, m$$

$$\text{let } \tilde{g}_i(t) = \sum_j \alpha_{ij} \psi_j(t) + \tilde{\tilde{g}}_i(t)$$

with

$$\alpha_{ij} = \int \tilde{g}_i(t) \psi_j(t) dt$$

$$\Rightarrow \int \tilde{\tilde{g}}_i(t) \psi_j(t) dt = 0 \quad \forall j=1, \dots, n.$$

$$\tilde{Y}_i = \sum_j \alpha_{ij} Y_j + \int (z(t) + x(t)) \tilde{\tilde{g}}_i(t) dt$$

$$= \sum_j \alpha_{ij} Y_j + \underbrace{\int z(t) \tilde{\tilde{g}}_i(t) dt}_{\tilde{z}_i}$$

S_{10} the combined measurements

$$y_1 \dots y_n, \tilde{y}_1 \dots \tilde{y}_m$$

$$\equiv (y_1 \dots y_n, \tilde{z}_1 \dots \tilde{z}_m)$$

$$= (x_1 + z_1 \dots x_n + z_n, \tilde{z}_1 \dots \tilde{z}_m)$$

with $(\tilde{z})$ independent of $(z_1 \dots z_n)$.

$$\Rightarrow I(X_1 \dots X_n; y_1 \dots y_n, \tilde{y}_1 \dots \tilde{y}_m)$$

$$= I(X^n; X^n + z^n, \tilde{z}^m)$$

with $X^n, z^n, \tilde{z}^m$ independent

$$= I(X^n; X^n + z^n) + I(X^n; \tilde{z}^m | X^n + z^n)$$

$$\downarrow$$

$$h(\tilde{z}^m | X^n + z^n) - h(\tilde{z}^m | X^n, X^n + z^n)$$

$$= h(\tilde{z}^m) - h(\tilde{z}^m)$$

$$= I(X^n; X^n)$$

Conclusion y^n is sufficient. The additional measurements $\tilde{y}^m$ are unnecessary.

So the channel between

$$\begin{aligned} \underline{x(t)} & \text{ \& } \underline{y(t)} = x(t) + z(t) \\ \equiv \underline{(x_1 \dots x_n)} & \rightsquigarrow \underline{(y_1 \dots y_n)} = \\ & \underline{(x_1 \dots x_n) + (z_1 \dots z_n)} \\ & \text{ i.i.d } N(0, \sigma^2) \\ (y_i = x_i + z_i) \end{aligned}$$

Suppose now we have the waveform channel

$$\begin{aligned} & x(t) \rightsquigarrow x(t) + z(t). \\ & x(t) \text{ is bandlimited.} \\ & X(f) \\ & \frac{1}{2T} \int_{-T}^T x(t)^2 dt \leq P \\ & \text{Diagram: A plot of } X(f) \text{ vs } f \text{ showing a bandpass signal centered at } f=0 \text{ with bandwidth } 2W. \text{ The signal is zero for } |f| > W. \end{aligned}$$

Recall the sampling theorem.

$$\begin{aligned} (x(t) : t \in \mathbb{R}) & \longleftrightarrow (x_n : n \in \mathbb{Z}) \\ & x_n = x\left(\frac{n}{2W}\right) \end{aligned}$$

$$x(t) = \sum_n \left(\frac{x_n}{\sqrt{2\omega}} \right) \text{sinc}(2\omega t - n) \sqrt{2\omega} \quad \perp$$

$$x_n = x\left(\frac{n}{2\omega}\right) = \sqrt{2\omega} \int x(t) \text{sinc}(2\omega t - n) \sqrt{2\omega} dt$$

Equivalently

$$x(t) = \sum_n x_n \psi_n(t)$$

$$x_n = x\left(\frac{n}{2\omega}\right) \sqrt{2\omega} = \int x(t) \psi_n(t) dt$$

$$\psi_n(t) = \sqrt{2\omega} \cdot \text{sinc}(2\omega t - n)$$

$$\int \psi_i(t) \psi_j(t) dt = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

see the channel between $(x(t) : t \in \mathbb{R})$
 $(y(t) : t \in \mathbb{R})$

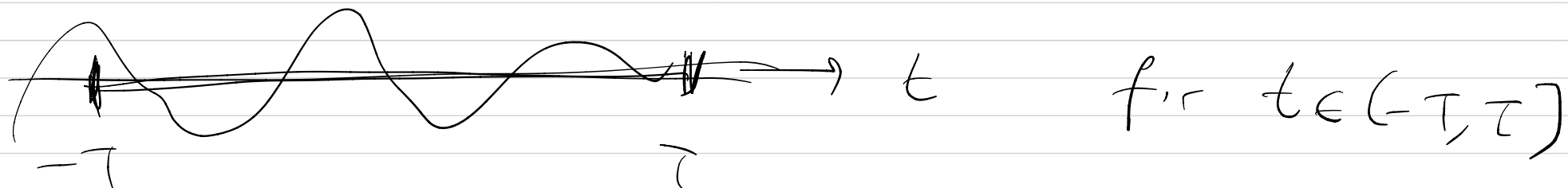
$\equiv$ ^{between} $(x_i : i \in \mathbb{Z})$ and $(y_i : i \in \mathbb{Z})$.

$$y_i = x_i + z_i \quad z_i \sim N(0, \sigma^2)$$

$$= \int y(t) \psi_i(t) dt$$

$$\underline{x(t)} = \sum_i x_i \psi_i(t)$$

$$= \sum_i x_i \operatorname{sinc}(\underline{2\omega t - i}) \sqrt{2\omega}$$



$$\approx \sum_{i=-2\omega T}^{+2\omega T} x_i \psi_i(t)$$

$$\Rightarrow \frac{1}{2T} \int_{-T}^T x^2(t) dt$$

$$\approx \frac{1}{2T} \sum_{i=-2\omega T}^{+2\omega T} x_i^2 \approx \frac{2\omega}{4\omega T} \sum_{i=-2\omega T}^{+2\omega T} x_i^2$$

$$\frac{1}{4\omega T} \sum_{i=-2\omega T}^{+2\omega T} x_i^2$$

to satisfy the power constraint

$$\frac{1}{2T} \int_{-T}^T x^2(t) dt \leq P \quad \text{we need the}$$

$(x_i : i \in \mathbb{Z})$ to satisfy

$$\frac{1}{2N} \sum_{i=-N}^N x_i^2 \leq \frac{P}{2\omega}$$

So need to consider the capacity of the discrete time channel

$$x_i \rightarrow y_i = x_i + z_i$$

$$\nearrow \nwarrow N(0, \sigma^2)$$

obeys the power constraint

$$E(x_i^2) \leq P/2W$$

$$\Rightarrow C(P) = \frac{1}{2} \log_2 \left(1 + \frac{P}{2W\sigma^2} \right) \quad \begin{array}{l} \text{bits/sample} \\ \text{(in discrete time)} \end{array}$$

in each second we use the channel $2W$ times,
so

$$C = W \log_2 \left(1 + \frac{P}{\underline{2W\sigma^2}} \right) \quad \text{bits/sec}$$

with $\sigma^2 = \frac{N_0}{2}$ the intensity of the white Gaussian n.v.

we get

$$C = \underline{W} \log_2 \left(1 + \frac{P}{\underline{N_0 W}} \right) \quad \text{bits/sec.}$$

is the capacity of the AWGN channel with
white-noise intensity $N_0/2$, input power $= P$
& input bandwidth W .