

ÉCOLE POLYTECHNIQUE FÉDÉRALE DE LAUSANNE

School of Computer and Communication Sciences

**Handout 31**

Final exam

Principles of Digital Communications

July 3, 2023

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4 problems, 43 points, 180 minutes

2 sheets (4 pages) of notes allowed.

Good Luck!

PLEASE WRITE YOUR NAME ON EACH SHEET OF YOUR ANSWERS.

PLEASE WRITE THE SOLUTION OF EACH PROBLEM ON A SEPARATE SHEET.

PROBLEM 1. In a hypothesis testing problem with hypothesis  $H \in \{0, 1, 2\}$ , observation  $Y \in \mathcal{Y}$ , decision  $\hat{H} \in \{0, 1, 2\}$ , the penalty for deciding  $j$  when the true hypothesis is  $i$  is  $\text{pen}(i, j) = |i - j|$ .

(a) (3 pts) Suppose  $D_0$ ,  $D_1$  and  $D_2$  are the decision regions for a decision rule  $\hat{H} : \mathcal{Y} \rightarrow \{0, 1, 2\}$ . Find  $b_0(y)$ ,  $b_1(y)$  and  $b_2(y)$  — expressed in terms of  $p_{Y|H}(y|i)$  and  $p_H(i)$  — so that the expected penalty of the rule is given by

$$\mathbb{E}[\text{pen}(H, \hat{H}(Y))] = \sum_{y \in D_0} b_0(y) + \sum_{y \in D_1} b_1(y) + \sum_{y \in D_2} b_2(y).$$

(b) (2 pts) Show that for any decision rule,  $\mathbb{E}[\text{pen}(H, \hat{H})] \geq \sum_{y \in \mathcal{Y}} b(y)$ , where

$$\begin{aligned} b(y) = \min \{ & p_{Y|H}(y|1)p_H(1) + 2p_{Y|H}(y|2)p_H(2), \\ & p_{Y|H}(y|0)p_H(0) + p_{Y|H}(y|2)p_H(2), \\ & 2p_{Y|H}(y|0)p_H(0) + p_{Y|H}(y|1)p_H(1) \}. \end{aligned}$$

(c) (2 pts) What is the decision rule that minimizes the expected penalty (in terms of  $b(y)$  and/or  $b_i(y)$ )?

(d) (3 pts) Suppose all hypotheses are equally likely,  $\mathcal{Y} = \{0, 1, 2\}$ , and

$$p_{Y|H}(y|i) = \begin{cases} 0.4 & y = i, \\ 0.3 & \text{else.} \end{cases}$$

Then, what is the decision rule  $\hat{H}(y)$  as an explicit function from  $\mathcal{Y}$  to  $\{0, 1, 2\}$  that minimizes the expected penalty? What is the MAP rule for this case?

PROBLEM 2. Let  $w_i(t)$ ,  $i = 1, \dots, m$  be the waveforms of a communication system designed for an AWGN channel with noise power spectral density  $N_0/2$ , suppose that  $w_i(t) = 0$  whenever  $t \notin [0, T]$ . Let  $\pi(N_0)$  denote the error probability of this system (with its optimal receiver).

Consider now two new systems:

1. The first has waveforms  $\tilde{w}_i(t) = \alpha w_i(t)$ ,  $i = 1, \dots, m$  for a (real) scalar  $\alpha \neq 0$ .
2. The second has waveforms  $w'_i(t) = \sum_{j=0}^{r-1} w_i(t - jT)$ ,  $i = 1, \dots, m$ ; i.e.,  $w_i$  repeated  $r$  times, once every  $T$  units of time. (Here  $r$  is a positive integer.)

(a) (2 pts) How can we re-use the optimal receiver for the original system to design an optimal receiver for system 1?  
*Hint:* Think of some pre-processing of the received signal  $\tilde{R}(t)$  of system 1 before giving it as input to the optimal receiver of the original system.

(b) (2 pts) Express the error probability  $\tilde{\pi}(N_0)$  of system 1 (with its optimal receiver), in terms of  $\pi(N_0)$ .

(c) (3 pts) How can we re-use the optimal receiver for the original system to design an optimal receiver for system 2?  
*Hint:* Think of some pre-processing of the received signal  $R'(t)$  of system 2 before giving it as input to the optimal receiver of the original system.

(d) (2 pts) Express the error probability  $\pi'(N_0)$  of system 2 (with its optimal receiver), in terms of  $\pi(N_0)$ .

PROBLEM 3. A bandpass transmitter for four equally likely messages is designed for an AWGN channel as follows:

- The waveform  $\psi(t) = \text{sinc}(t)$  is chosen as the Nyquist pulse, upon observing that  $\psi(t), \psi(t-1), \psi(t-2), \dots$  form an orthonormal collection. (Note also that the Fourier transform of  $\psi$  is  $\text{rect}(f) = \mathbb{1}\{|f| < \frac{1}{2}\}$ .)
- Four codewords  $c_1 = (1, 0), c_2 = (0, 1), c_3 = -c_1, c_4 = -c_2$  are chosen as vectors in  $\mathbb{R}^2$ . (Note: they are *real*, not complex.)
- At the transmitter, the message  $i \in \{1, 2, 3, 4\}$  is first mapped to  $c_i$ , then to the baseband waveform  $w_{i,E}(t) = \sum_{j=1}^2 c_{ij} \psi(t-j)$ , and finally to the transmitted waveform as

$$\begin{aligned} w_i(t) &= \sqrt{2} \Re\{w_{i,E}(t) \exp(j2\pi f_c t)\} \\ &= \sqrt{2} w_{i,E}(t) \cos(2\pi f_c t) \quad \text{with } f_c > \frac{1}{2}. \end{aligned}$$

At the receiver, the received signal  $R(t)$  is multiplied by  $\sqrt{2} \cos(2\pi f_c t)$ , to form  $R_E(t)$ .  $R_E$  is passed through a filter with impulse response  $\text{sinc}(t)$ , and the output of the filter is sampled at times  $t_1 = 1$  and  $t_2 = 2$ . With  $Y_1$  and  $Y_2$  denoting the samples respectively, the vector  $Y = (Y_1, Y_2)$  is formed. The  $i$  for which  $c_i$  is closest to  $Y$  (in the Euclidean norm) is the receiver's guess of the transmitted message.

- (a) (3 pts) Is the receiver described in the above paragraph optimal? (Note: the procedure in the book would have formed the *complex* waveform  $R(t)\sqrt{2} \exp(-j2\pi f_c t)$  instead of the above  $R_E$ . If you claim optimality, you should explain why  $R_E$  above leads to the same decision.)
- (b) (2 pts) What is the probability of error (in terms of  $N_0$ )?

Due to an inaccuracy in circuit design, the frequency of the cosine at the receiver is not  $f_c$  but  $f'_c$  instead, i.e.,  $R(t)$  is multiplied by  $\sqrt{2} \cos(2\pi f'_c t)$  to form  $R_E(t)$ . The rest of the receiver is unchanged.

- (c) (3 pts) For  $x(t) = \text{sinc}(t) \cos(2\pi f_0 t)$  and  $y(t) = \text{sinc}(t - t_0)$ , show that their inner product satisfies

$$\langle x, y \rangle = \begin{cases} 0 & |f_0| \geq 1, \\ \frac{1}{2} [\text{sinc}(t_0) + (1 - 2|f_0|) \text{sinc}((2|f_0| - 1)t_0)] & \text{else.} \end{cases}$$

*Hint:* Use Parseval's relationship.

- (d) (2 pts) Suppose  $|f'_c - f_c| > 1$ . What is the error probability?

*Hint:* Use (c) to show that  $Y$  is independent of the transmitted message.

- (e) (2 pts) Suppose  $f'_c = f_c + \frac{1}{2}$ . What is the error probability?

PROBLEM 4. Consider a 3-state encoding device (with states 0, 1, 2) that accepts a sequence of data bits  $b_1, b_2, \dots$ , with  $b_i \in \{+1, -1\}$ , and produces encoded bits  $x_1, x_2, \dots$  as follows:

Current state	Input bit $b_i$	Next state	Output $x_{2i-1}, x_{2i}$
0	+1	0	+1, +1
	-1	1	-1, -1
1	+1	1	-1, +1
	-1	2	+1, -1
2	+1	1	+1, -1
	-1	0	-1, +1

The machine initially starts at state 0.

(a) (2 pts) After encoding  $k$  data bits  $b_1, \dots, b_k$ , we would like to ensure that the machine returns to the initial state 0 by appending  $L$  termination bits  $b_{k+1}, \dots, b_{k+L}$  to the data sequence. What is the value of  $L$  needed to ensure this? (Note that  $(b_{k+1}, \dots, b_{k+L})$  can depend on  $(b_1, \dots, b_k)$ , but  $L$  can not.)

This encoding device, with the termination scheme in (a), is used as a transmitter for an AWGN channel. The channel output  $y_1, y_2, \dots$  is given by  $y_i = \sqrt{\mathcal{E}_s}x_i + Z_i$ , where  $Z_1, Z_2, \dots$  are i.i.d.  $\mathcal{N}(0, \sigma^2)$ .

(b) (2 pts) Draw a trellis diagram and explain how the receiver can implement the ML rule to produce  $\hat{b}_1, \dots, \hat{b}_k$  from  $y_1, \dots, y_n$ .

(c) (3 pts) For  $k = 3$ , and  $y_1, y_2, \dots$  given by

$$+0.3, -1.1, +0.6, +0.9, -0.7, +1.0, +1.2, -1.1, -0.6, +0.7, +0.4, -1.2, +0.5, -0.5, \dots$$

determine the maximally likely  $(\hat{b}_1, \hat{b}_2, \hat{b}_3)$ . (You may not need the last few  $y_i$ 's to do this.)

(d) (3 pts) For the all +1 reference path sketch the detour flow graph labeled with  $I^i D^d$ 's. Construct a system of equations of the form

$$\begin{aligned} A_1(I, D) &= ?? + ?? A_1(I, D) + ?? A_2(I, D) \\ A_2(I, D) &= ?? + ?? A_1(I, D) + ?? A_2(I, D) \\ A(I, D) &= ?? A_2(I, D), \end{aligned}$$

where  $A_1$  and  $A_2$  denote the transfer functions until states 1 and 2, and verify that  $A(I, D) = I^3 D^4 / (1 - D - ID^2)$ .

(e) (2 pts) Differentiate  $A(I, D)$  with respect to  $I$ , and use it to find an upper bound to the bit error probability on sending the all +1 sequence, as a function of  $\mathcal{E}_s/\sigma^2$ .