

Principles of Digital Communication

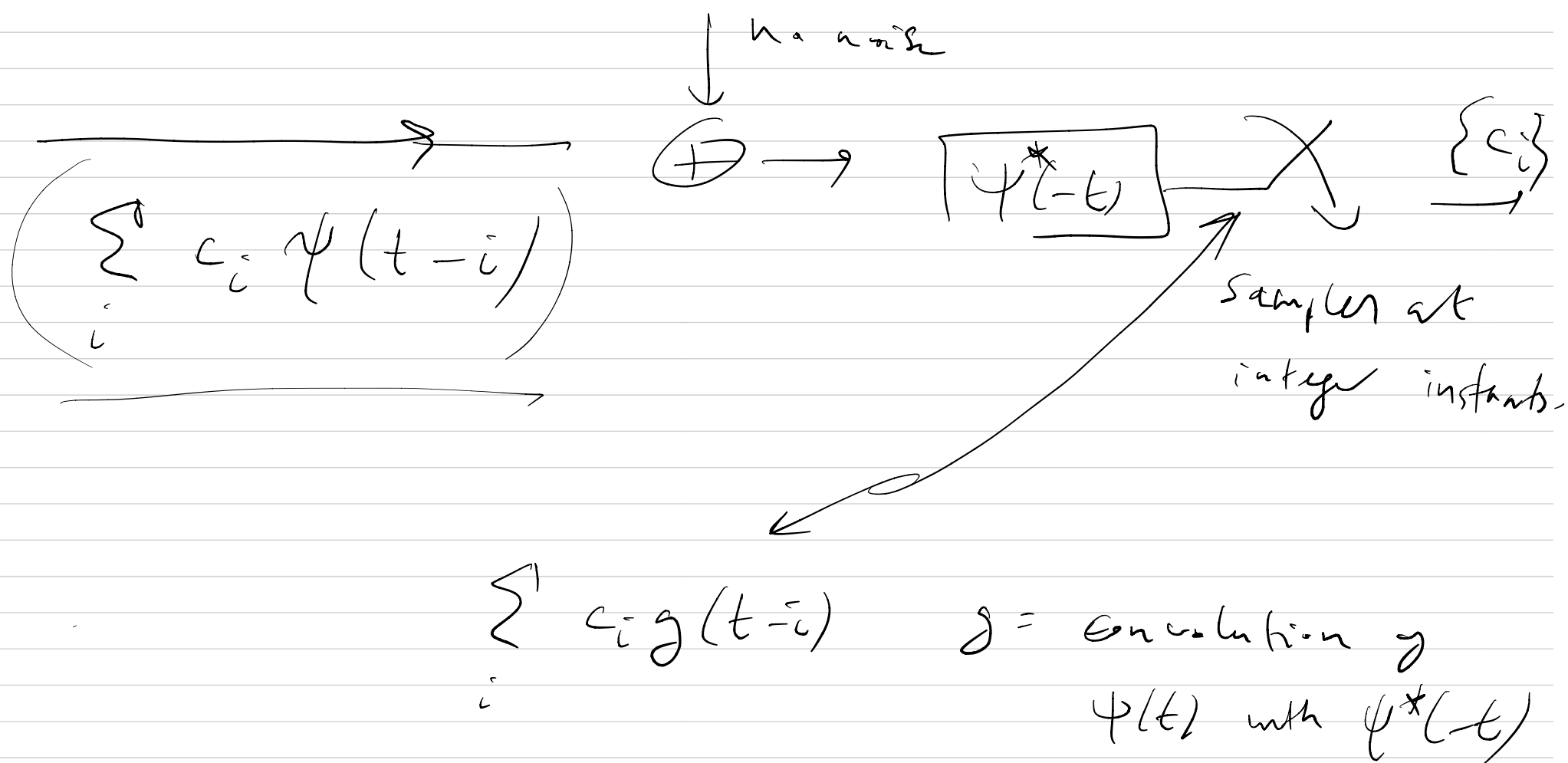
May 5, 2021



Reading was

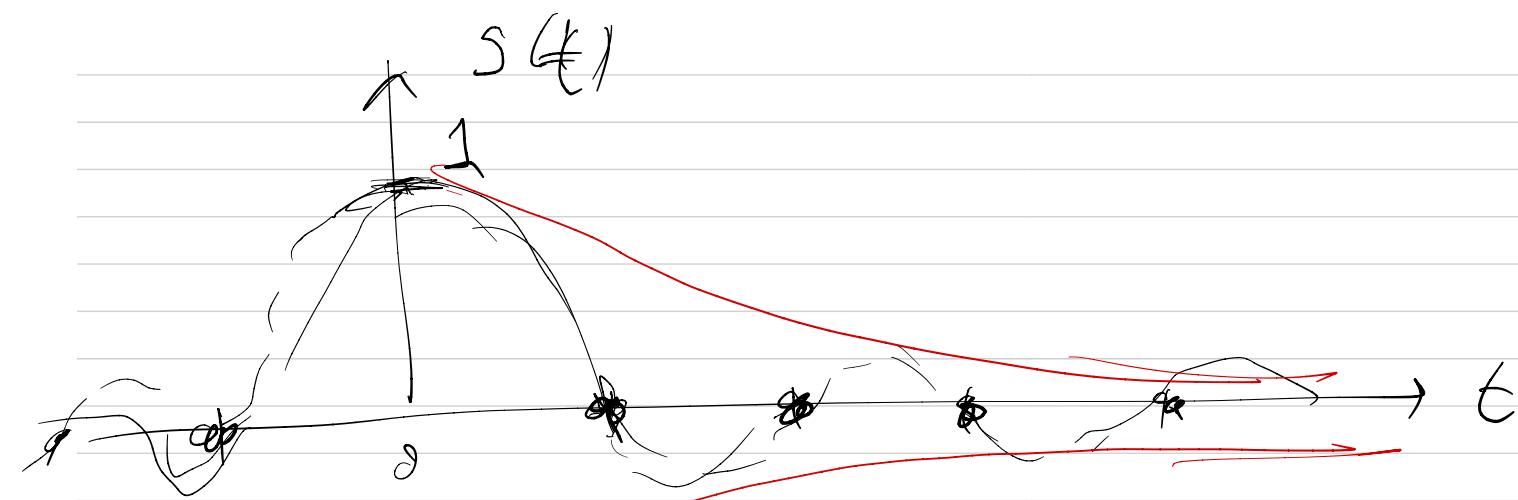
- Root-raised cosine pulses
 - Eye diagrams
 - Convolutional codes
- } ch 5
- } ch 6 (1, 2, 3).

RRC: motivation:



$$g(t) = \int \underbrace{\psi(\tau)}_{\psi^*(\tau-t)} \underbrace{g(t-\tau)}_{\psi^*(\tau-t)} d\tau = \int \psi(\tau) \psi^*(\tau-t) dt$$

$$\begin{aligned} \underline{g(t)} &\leq \sqrt{\int |\psi(t)|^2 dt} \sqrt{\int |\psi^*(t)|^2 dt} \\ &= \int |\psi(t)|^2 dt = g(0). \end{aligned}$$



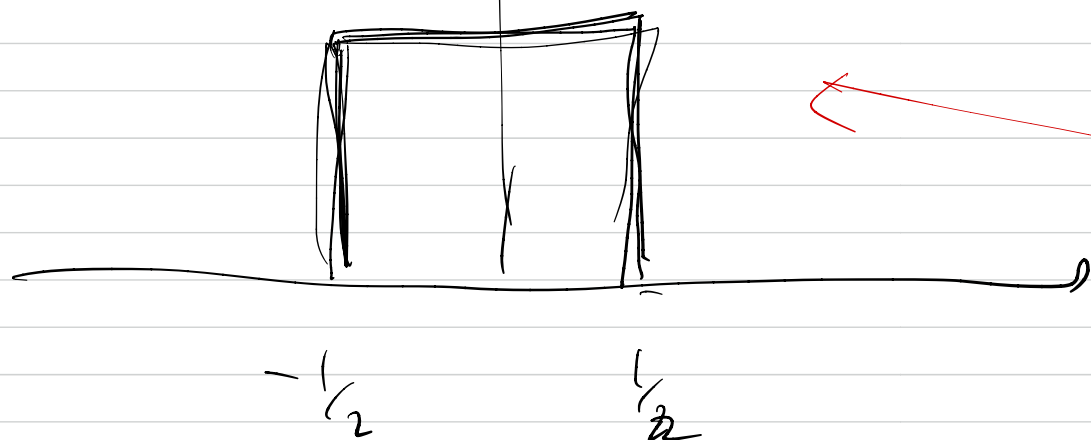
If the filter output is sampled not at integer times but at slightly wrong times, e.g. $i + \delta$ then the i th sample will be

$$\sum_j c_j g(t-j) \Big|_{t=i+\delta} = c_i g(\delta) + \sum_{j: j \neq i} c_j g(\underline{i-j} + \delta)$$

A fast decaying (in time) $g(\cdot)$ will ensure that δ is small, so we will have some protection against timing errors.

Our difficulty is:

$$g_F(f) = |\psi_F(f)|^2 \quad \text{should satisfy Nyquist.}$$



the minimal BW
 $g_F(\cdot)$

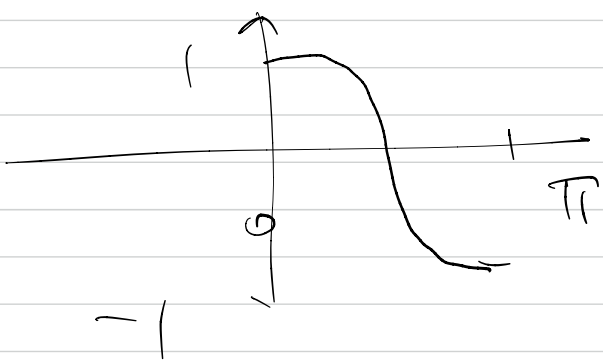
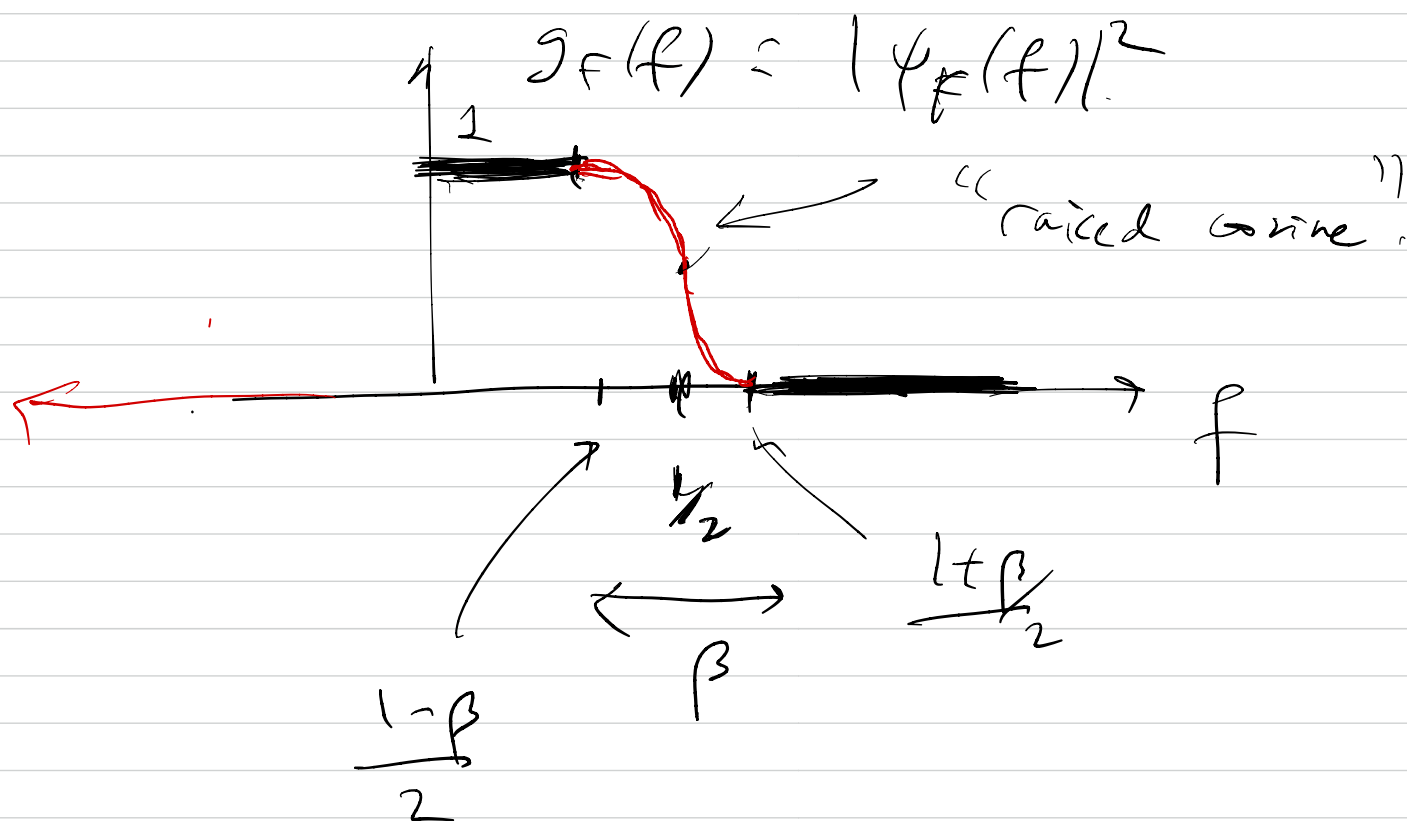
$$\rightarrow g(t) = \text{sinc}(t)$$

decays slowly. We saw last week

that how fast $g(t)$ decays

$\iff$ how smooth $g_F(f)$ is.

This leads to an ad-hoc choice (raised cosine)

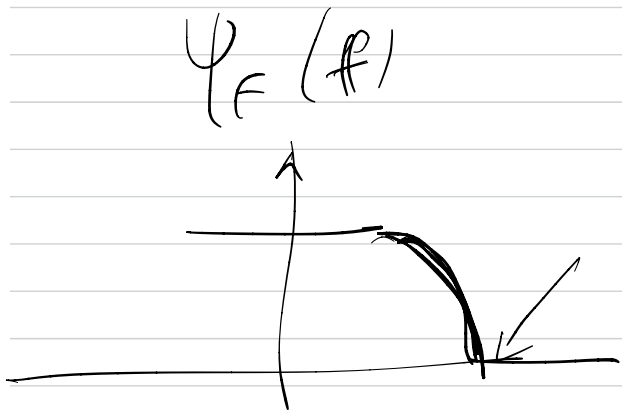


Since $\frac{1+\cos x}{2} = \cos^2 \frac{x}{2}$

So we have a simple expression for $\psi_F(f)$

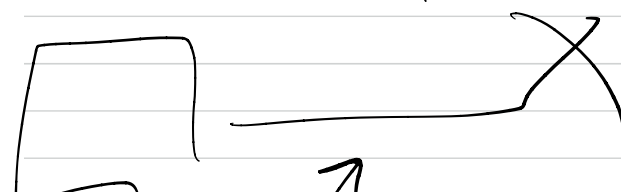
So we expect

$g(t)$ to decay like $\left(\frac{1}{t^3}\right)$

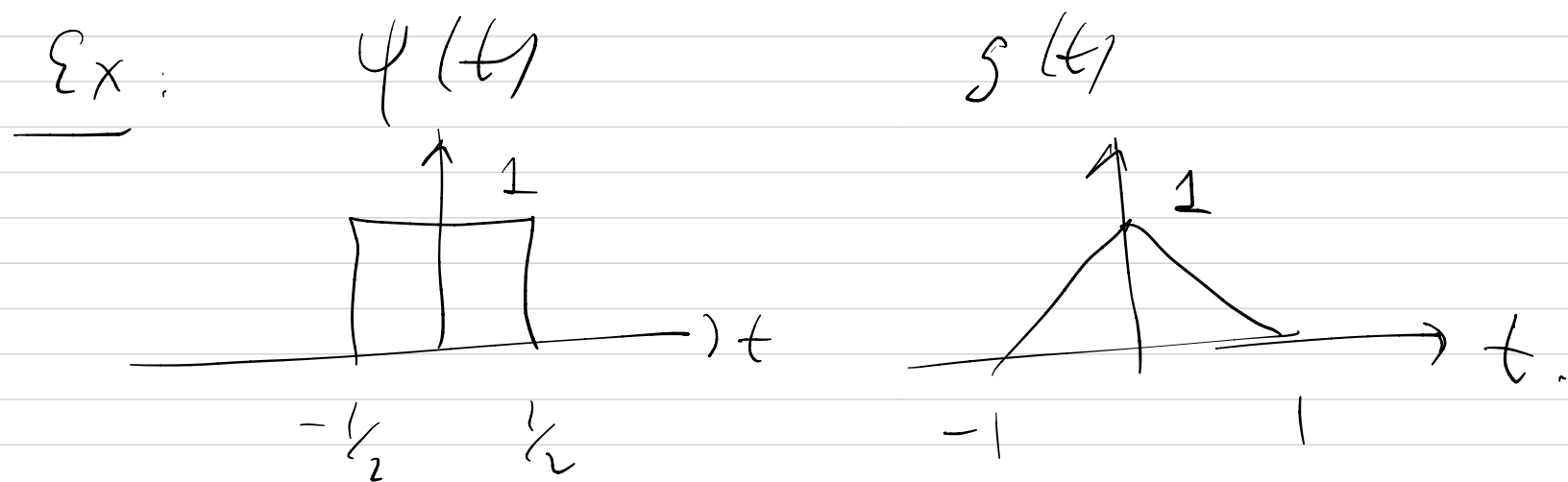


so $\psi(t)$ decays like $\frac{1}{t^2}$.

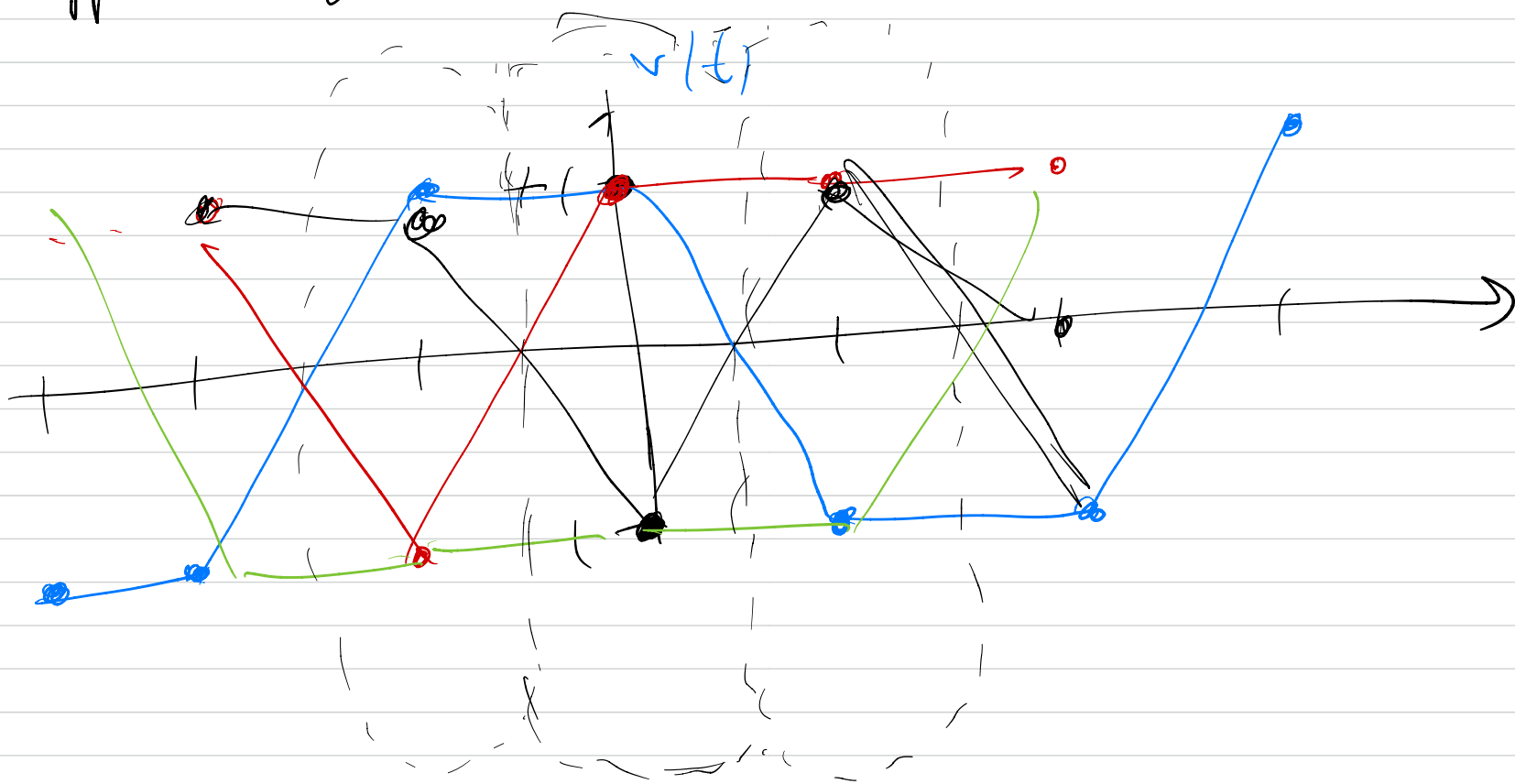
Eye diagrams: A way to judge how immune a system with a given $\psi(t)$ is against timing errors (samples taken not exactly at integers) & noise.

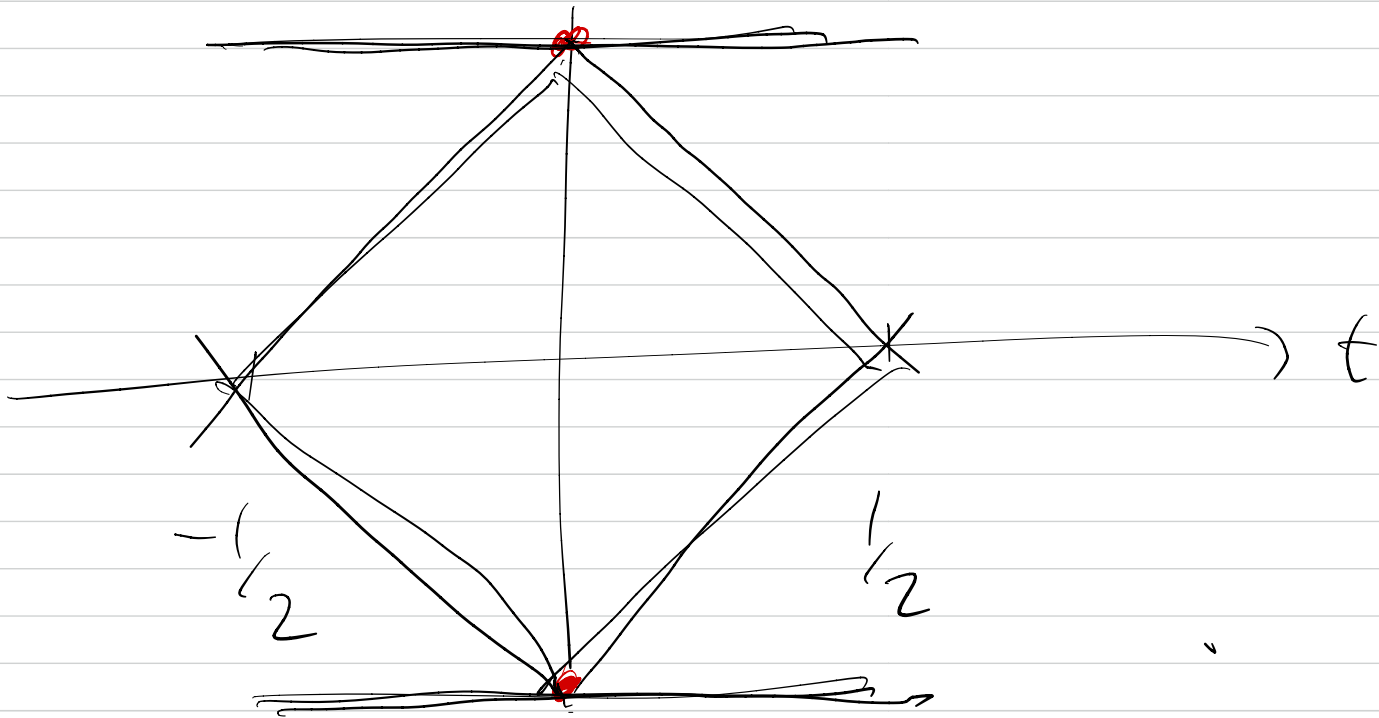
matched filter  should the samples at integer times.

without noise = $\sum_j c_j g(t-j)$ $\equiv v(t)$



suppose c_i 's are ± 1 's.





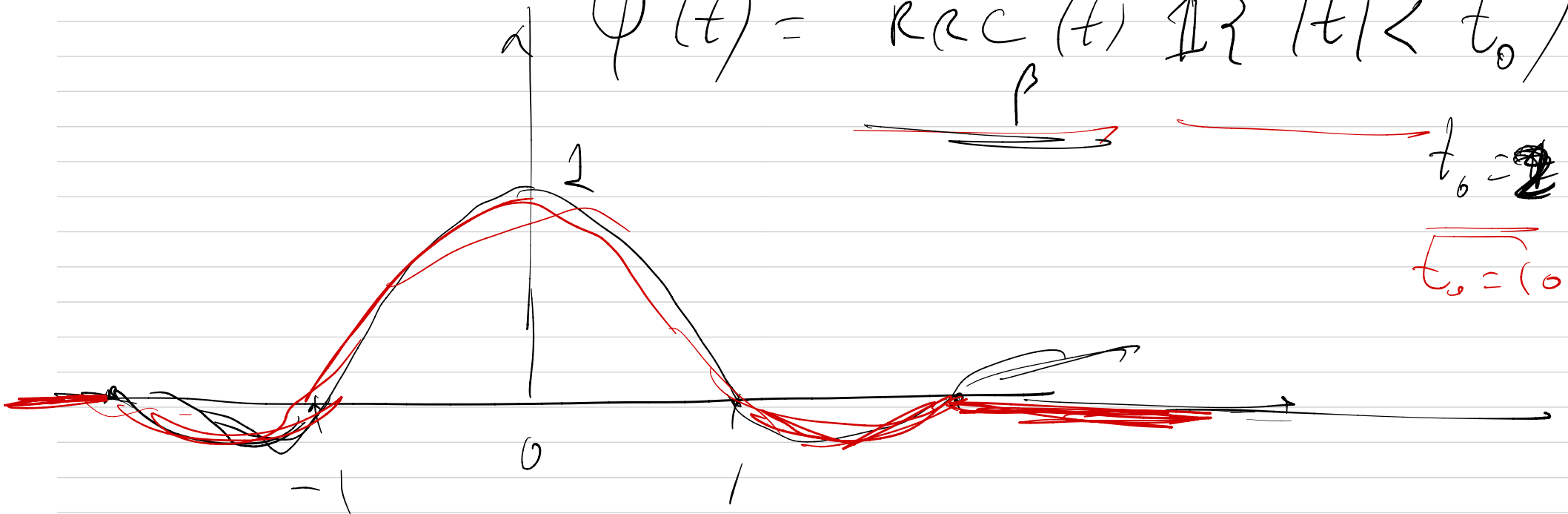
The book consider

$$\psi(t) = \underbrace{\text{RAC}(t)}_{\beta} \mathbb{1}_{\{|t| < t_0\}}$$

β

$t_0 = 2$

$t_0 = 10$



And plot the Eye-diagrams in 174.

β large $\rightarrow$ "more open eye"

small $\rightarrow$ "more closed eye"

t_0 small $\rightarrow$

t_0 large $\rightarrow$



Graded HW = already on Moodle

Due: 16th

"Group solutions"

Chapt 6

recall that we saw

k = # of bits in our message $k = \log_2 m$

n : # of dimensions (Duration $\times$ BW)

k/n : bit rate (bits/sec/Hz)

efficiency per dimension

ξ_b = energy/bit $\|c\|^2/k$

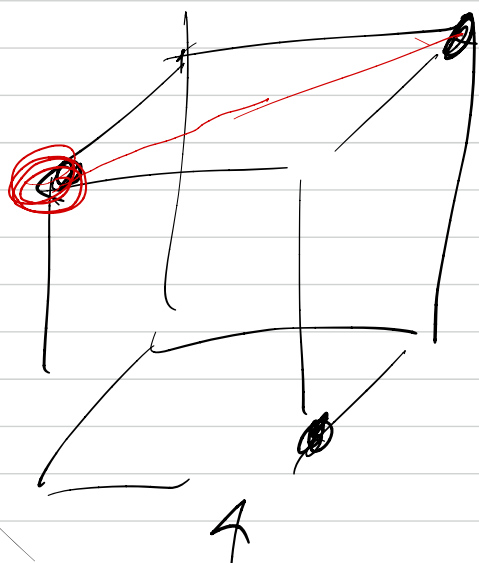
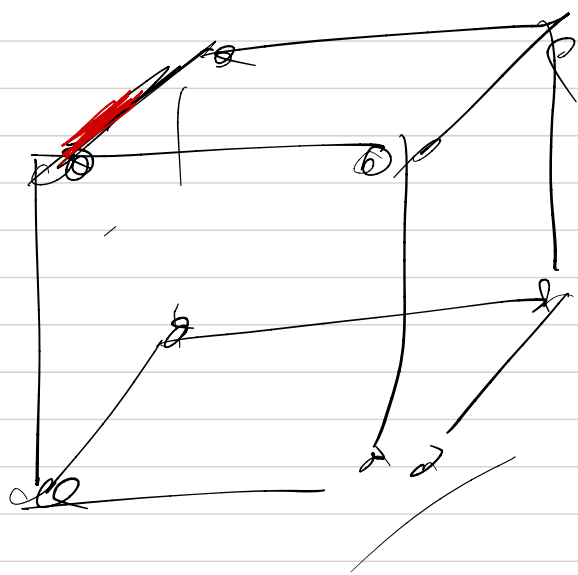
$b_1 \dots b_k$ to be sent ($\{+1, -1\}$ each of them).

4.4.3 $w(t; b_1 \dots b_k) = \sum_i b_i \psi(t - i)$

has $k/n = 1$

for large k this has high $P(\text{message error})$.

To rectify this:



bit-by-bit
method

use all 2^k corners
of the hypercube
as signal points.

use a fraction
of the vertices

2^k corners of a
($2h$) dim cube
 $\binom{2h}{2^k}$ corners

We hope to gain reliability by reducing bit-rate.

How to do this:

Crazy idea: pick 2^k points among $2^n = 2^{2k}$

"at random": If we do so, there is an
excellent chance that we end up with a
"good" selection. ($P(\text{error})$ will not be very
different than the "best" choice of the 2^k points.)

Ex: $k=20$ we have $2^{20} \approx 10^6$ points.

Recr: $\arg \min \|y - c_i\|$
 $1 \leq i \leq 2^{20}$

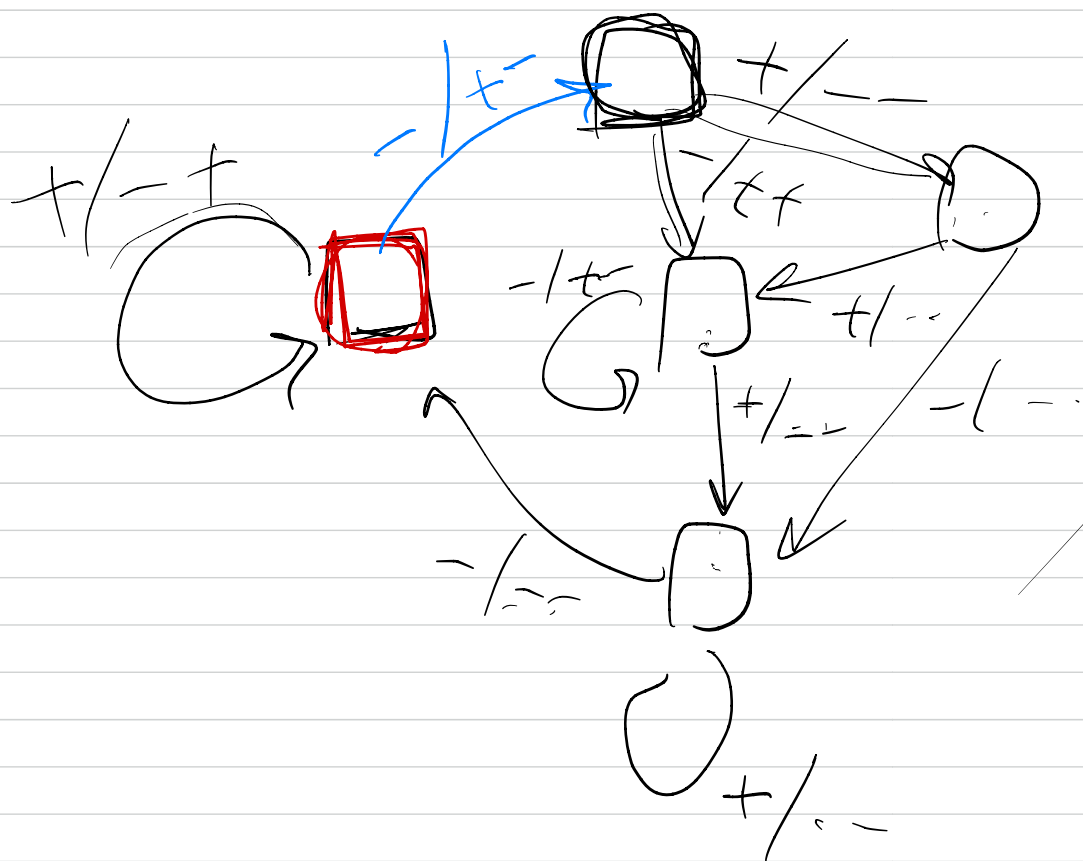
10^6 operations to decode 20 bits.

If $k=100 \Rightarrow$ deep trouble.

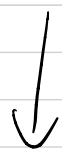
Now what?

Encoding by Finite state Machines.

Ex:



$b_1 b_2 b_3 b_4 = - - + -$

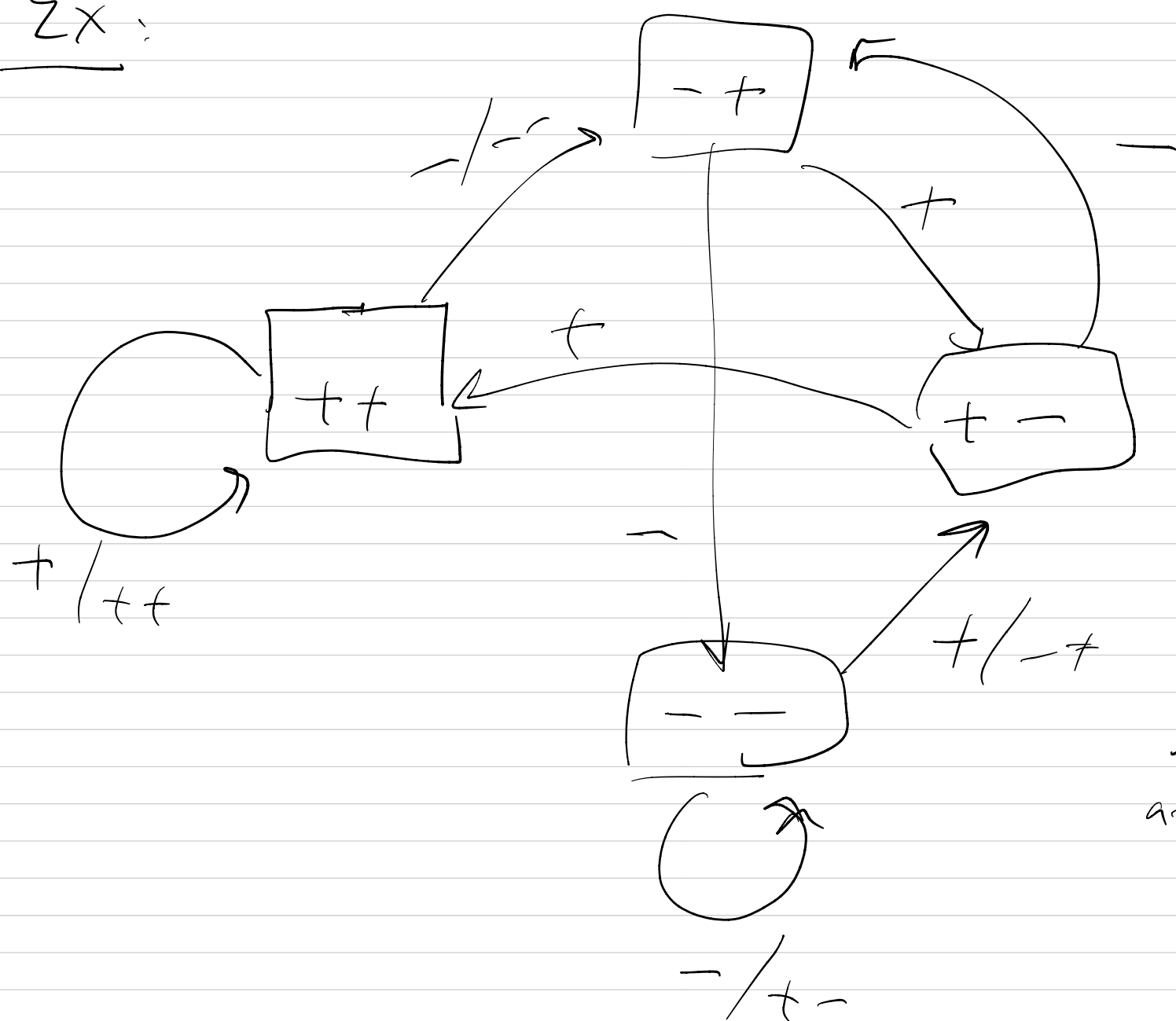


$+ - + + - - - -$

Such a machine maps k bit sequences to

$n = 2k$ words

Ex:



state: $b_{j-1} b_{j-2}$
 at time j
 input = b_j

$$\text{output} = \begin{pmatrix} b_j b_{j-2} \\ b_j b_{j-1} b_{j-2} \end{pmatrix}$$

- The description complexity of the encoder does not change with k (compare with "crazy-methods" encoder description = 2^k)

- The encoding complexity is $\sim k$

How about the receiver?

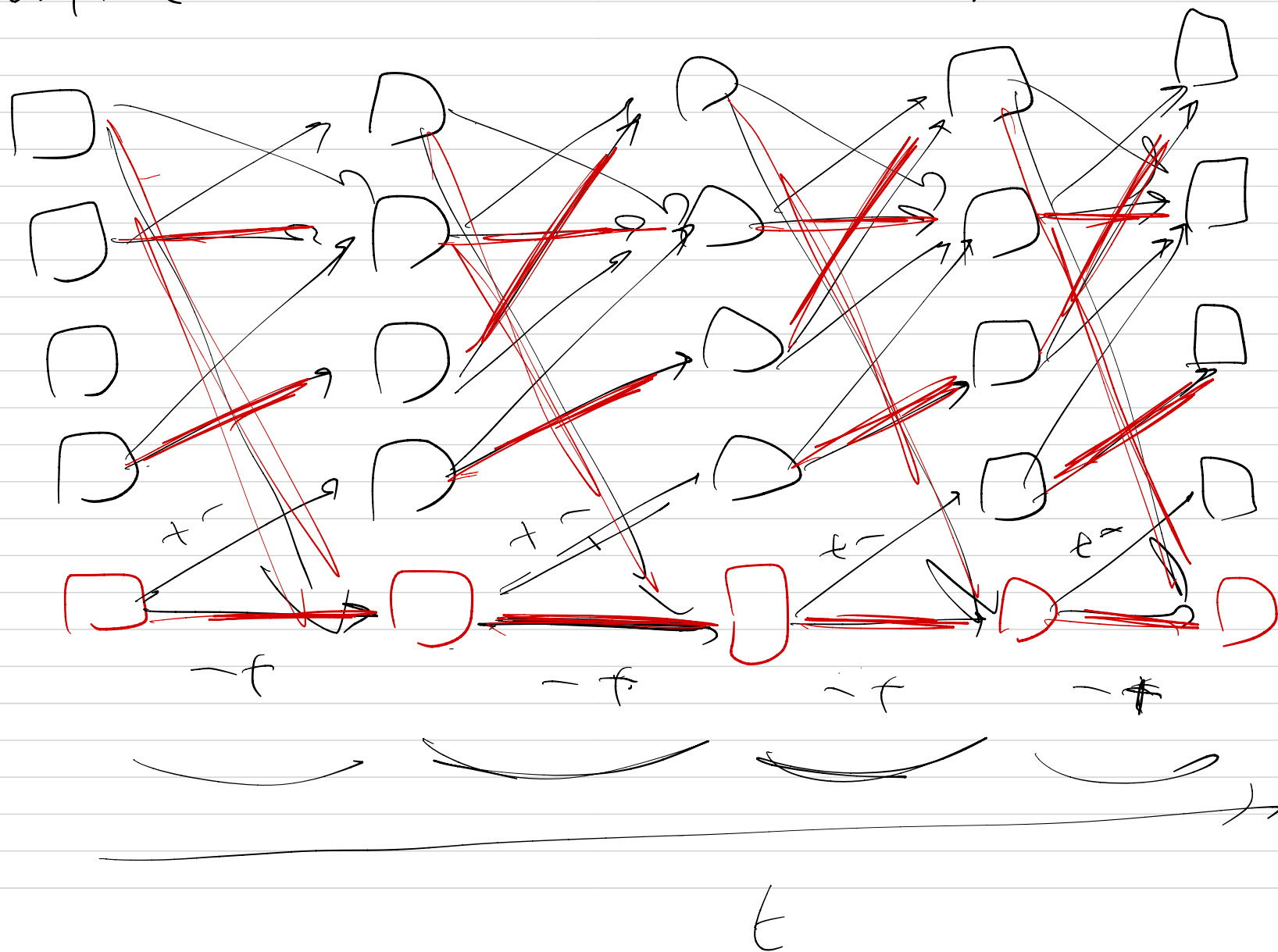
we need to find

$$\underset{b_1 \dots b_k}{\operatorname{argmin}} \| (y_1 \dots y_n) - \mathcal{E}(b_1 \dots b_k) \|$$

the encoder
output when
 $b_1 \dots b_k$ is
the input.

This still looks impractical: there are
 2^k things to compare.

Continue with the 1st example?



reception task:

$$\arg \min_{b_1 \dots b_k} \underbrace{\|y - c(b_1 \dots b_k)\|^2}_{\text{does not depend on } b_1 \dots b_k}$$

$$= \|y\|^2 + \|c(b_1 \dots b_k)\|^2 - 2 \langle y, c(b_1 \dots b_k) \rangle$$

does not depend on
 $b_1 \dots b_k$

$$= \arg \max_{b_1 \dots b_k} \underbrace{\langle y, c(b_1 \dots b_k) \rangle}$$

$$\sum_{j=1}^n y_j c(b_1 \dots b_k)_j$$

□

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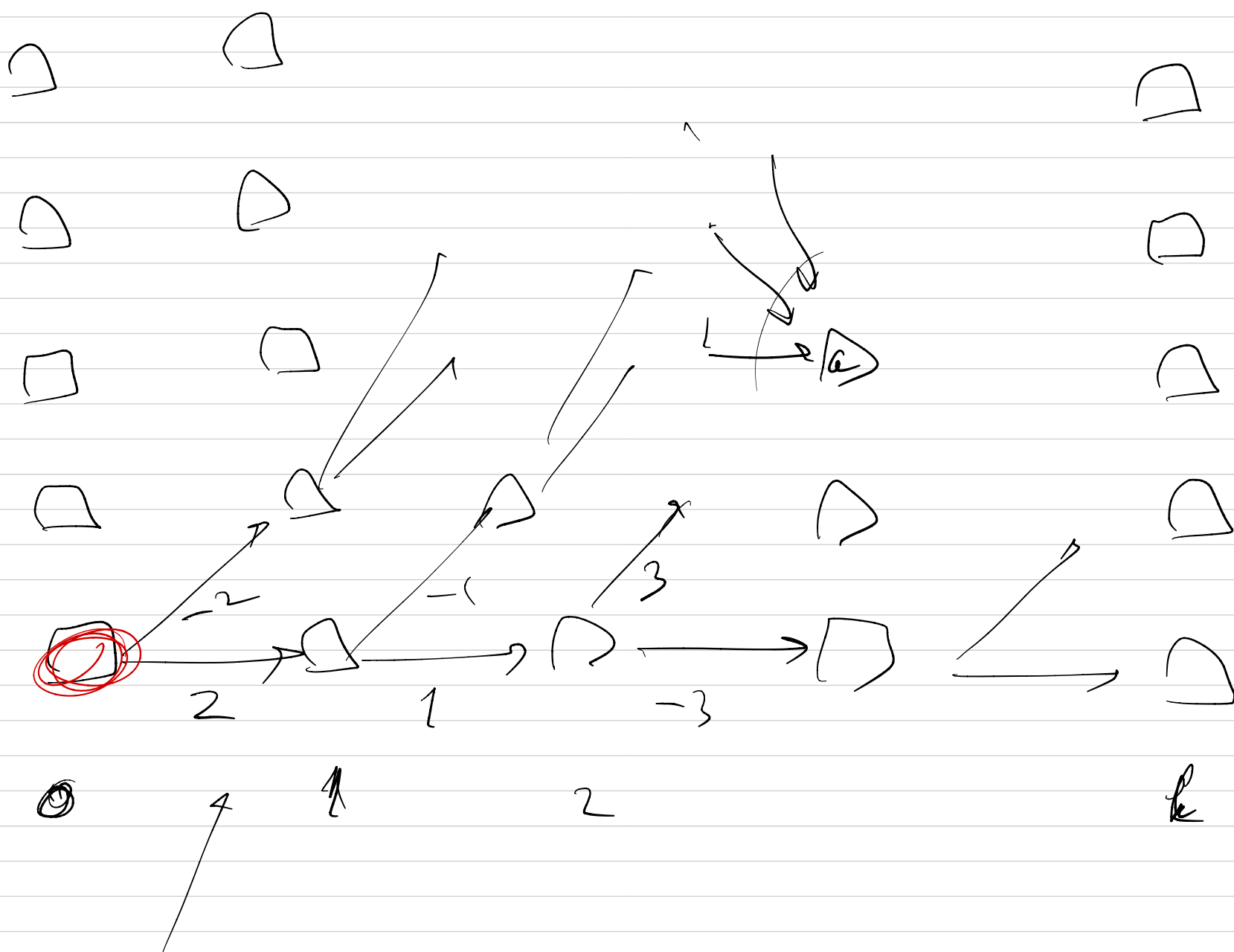
$t+1$

$$(+y_{2t+1} - y_{2t+2})$$

$$(-y_{2t+1} + y_{2t+2})$$

$$j = 2t+1, 2t+2$$

contribution
to the
 $\langle, \rangle$
if we
traverse
that
branch.



labeled by the control to the inner product

We try to find which path from  to the right edge has the largest reward?

Algorithm: go from left to right:

for node a at stage i ,

$$\text{reward}(a) = \left(\max_{b: \text{the nodes at stage } i-1 \text{ that can lead to } a} (\text{reward}(b) + \text{reward}(b \rightarrow a)) \right)$$

when this terminates at the right edge nodes.

The path found by the algorithm from the starting node to the most valuable right edge node identifies the MAP decision.

of operations prop to $(states) \times k$,

$\Rightarrow$ the decoding effort is bounded/bits

See figure 6.4 on p. 210 for a fully worked out example.