

# Problem Set 3

## CIVIL-425: Continuum Mechanics and Applications

14 March 2024

### Exercise 1, compatibility conditions

Consider a cylindrical solid referred to an orthonormal Cartesian reference frame  $\{X_1, X_2, X_3\}$ . Let the axis of the solid be aligned with the  $X_3$ -direction and let its normal cross-section occupy a region  $\Omega$  in the  $X_1 - X_2$  plane of boundary  $\partial\Omega$ . Consider deformations which result in the deformation gradients of the form:

$$[\mathbf{F}] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \gamma_1 & \gamma_2 & 1 \end{pmatrix}, \quad (1)$$

where  $\gamma_1$  and  $\gamma_2$  are functions of  $(X_1, X_2)$ .

1. What condition do  $(\gamma_1, \gamma_2)$  need to satisfy to verify compatibility?
2. Assuming that the compatibility conditions derived in the previous are satisfied, express the deformation mapping in terms of  $(\gamma_1, \gamma_2)$  and show that it is of the same form as of 1 for some  $w(X_1, X_2)$ .
3. Consider the deformation defined by:

$$\gamma_1 = -\frac{\sin \theta}{r}, \gamma_2 = \frac{\cos \theta}{r} \quad (2)$$

where  $(r, \theta)$  are polar coordinates centered at the origin, with  $\theta$  measured from  $X_1$ , so that:

$$X_1 = r \cos \theta, X_2 = r \sin \theta. \quad (3)$$

Verify that the deformation field in eq. 2 satisfies the compatibility condition derived in the first point everywhere in the  $X_1 - X_2$  plane excluding the origin.

4. Compute the displacement field  $w(X_1, X_2)$  which gives rise to the deformation 2, assuming that  $w = 0$  on the positive half-line  $X_2 = 0, X_1 > 0$ . Sketch the deformed shape of an initially circular region centered at the origin and contained in the  $X_1 - X_2$  plane.
5. Consider the Burgers circuit  $r = \text{const}, 0 < \theta < 2\pi$  centered at the origin. Does the same circuit close in the deformed configuration? Interpret the results in terms of dislocations.

### Exercise 2, Orthogonal cutting

A rigid tool cuts a layer from a metal workpiece with its edge perpendicular to the direction of motion (orthogonal machining). The feed is  $h$ , the rake angle is  $\alpha$  and the angle of the primary shear zone to the surface of the workpiece is  $\beta$ . The thickness of the resulting chip is  $d$ . The material is assumed to be incompressible and undeformed prior to cutting.

1. Calculate the thickness of the chip as a function of  $h$ ,  $\alpha$  and  $\beta$ , by considering conservation of mass at the primary shear zone.
2. Calculate the deformation  $\mathbf{F}$  in the chip as a function of  $\alpha$  and  $\beta$ . In particular, calculate the shear  $\gamma = \mathbf{s} \cdot (\mathbf{F}\mathbf{N})$  through the primary shear zone, where  $\mathbf{s}$  and  $\mathbf{N}$  are the unit vectors tangent and normal to the primary shear zone, respectively. *Hint: consider there is a discontinuous jump in the deformation field normal to the primary shear zone*

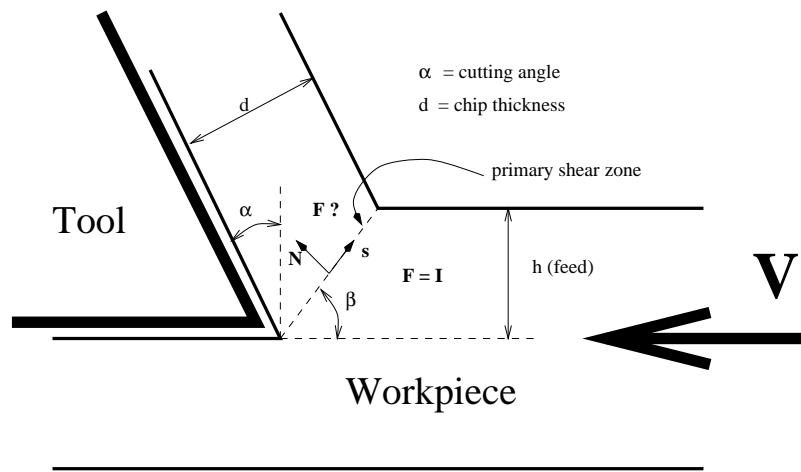


Figure 1: Geometry of orthogonal cutting.

3. Suppose that the material deforms so as to minimize the shear deformation  $\gamma$ . Compute  $\beta$  from this condition. Calculate the corresponding  $\gamma$  and chip thickness.