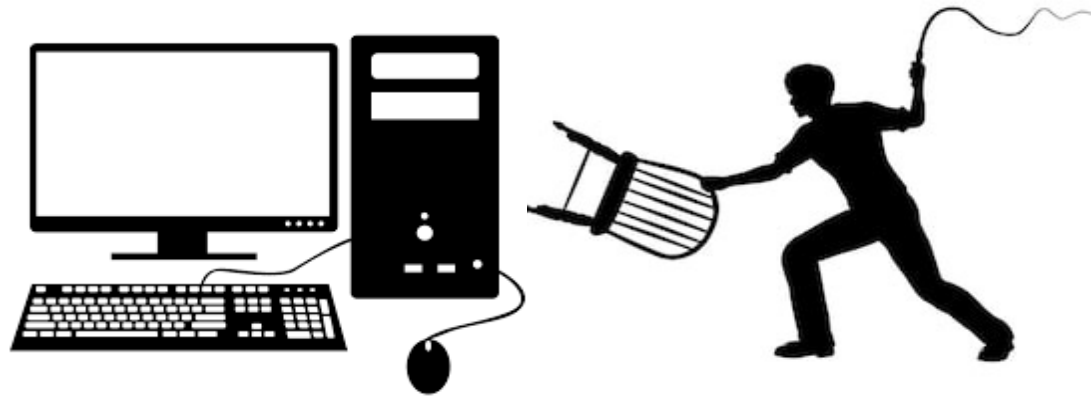
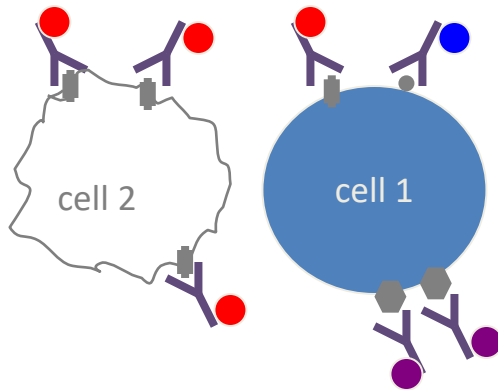


Bioinformatics: taming computers to make sense out of big data in biology and medicine



Maxime Jan, Julien Dorier, Christian Iseli & Nicolas Guex

Flow Cytometry



	FSC	SSC	color1	color2	color3
cell 1	100	100	100	100	200
cell 2	100	500	300	0	0
cell 3	110	100	100	90	220
cell 4	100	510	290	5	0

Curved arrows indicate the relationship between the cell diagrams and the table data.

Calculation for cell 1:

$$\sqrt{10^2 + 0^2 + 0^2 + 10^2 + 20^2} = 24.5$$

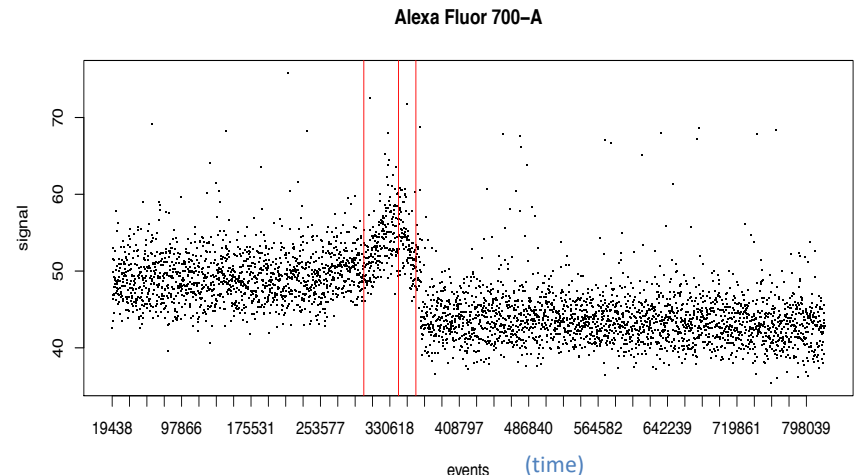
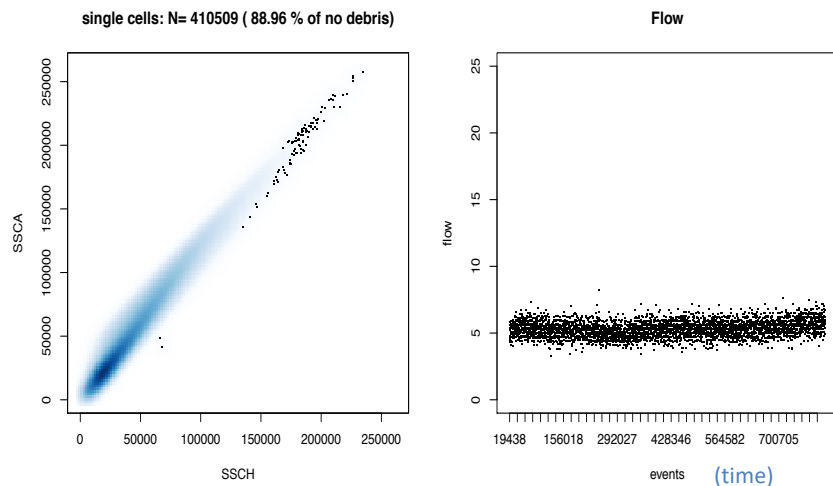
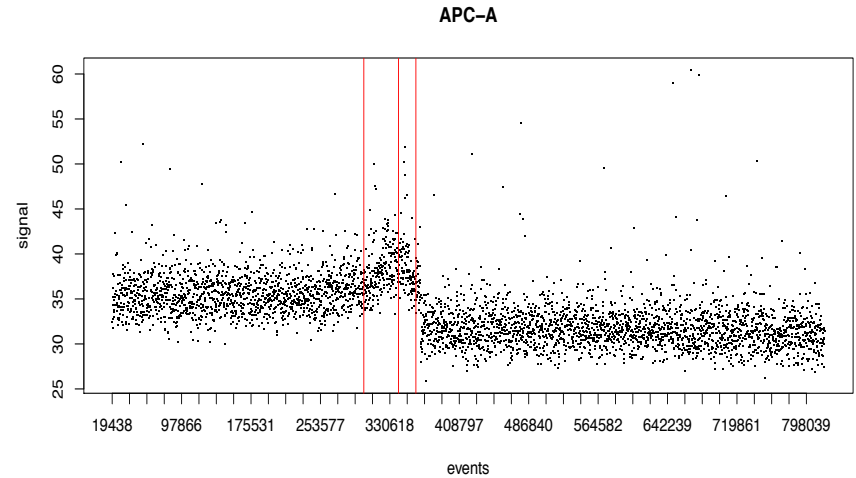
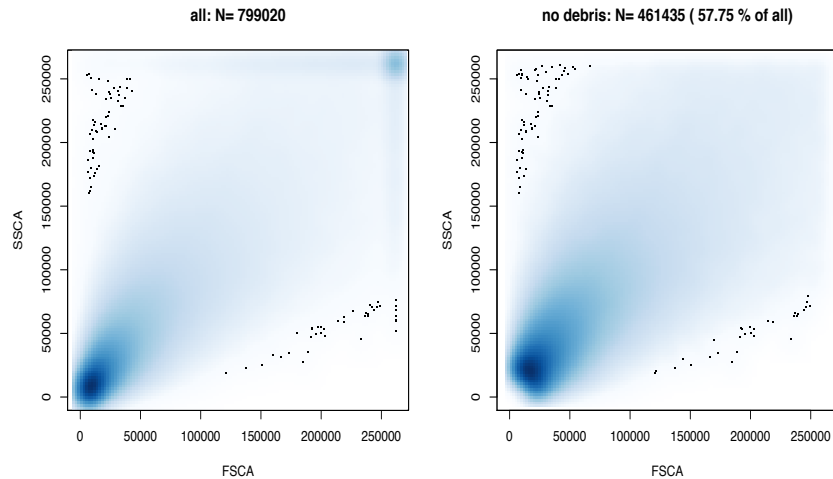
Calculation for cell 4:

$$\sqrt{10^2 + 410^2 + 190^2 + 95^2 + 200^2} = 494.3$$

Acquisition QC and filtering

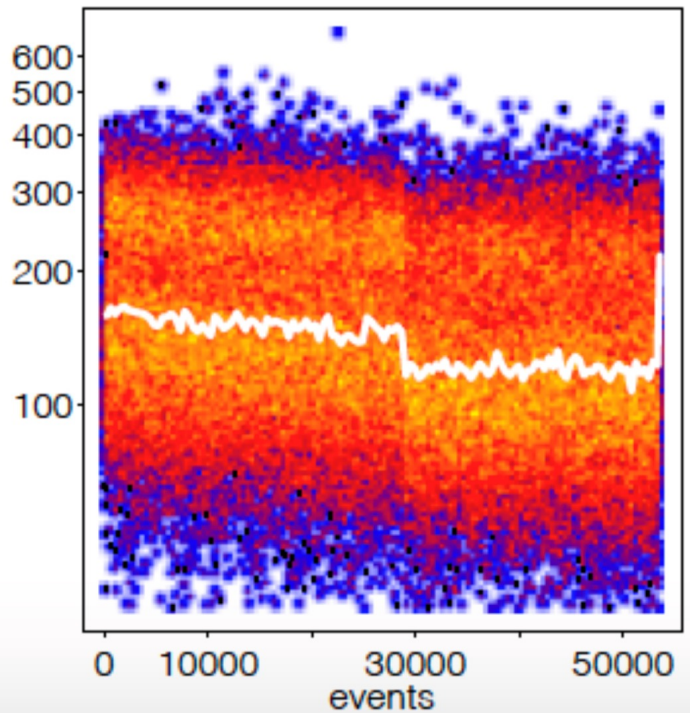
Debris, doublets, flow

... However, drop in intensity for few channels

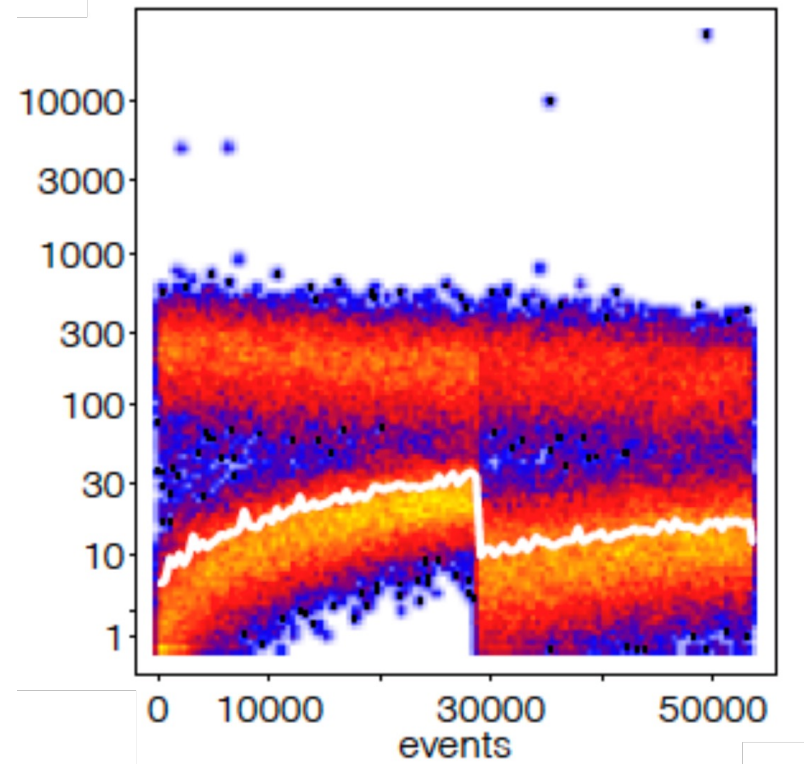


Cytof Drift

channel 1



channel 2

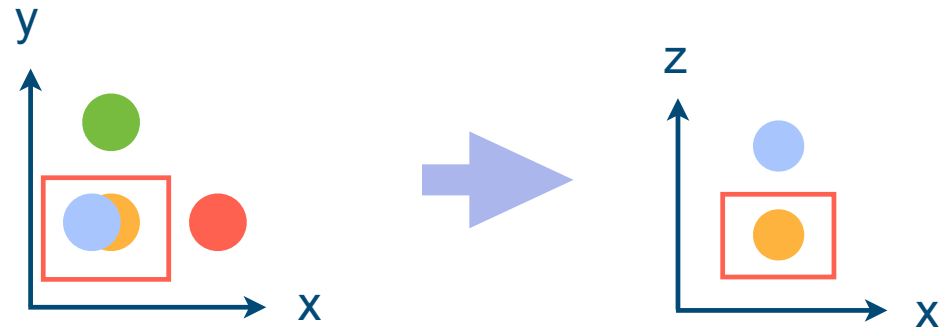
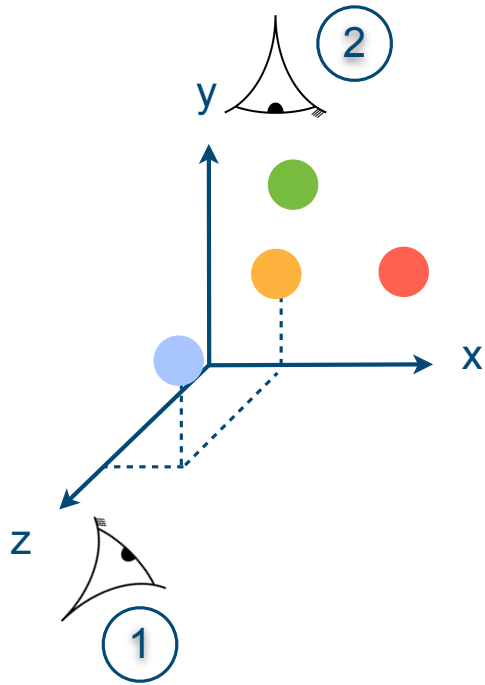


Large scale Data Analysis

Clustering

- applied to flow cytometry
- characteristics of various algorithms

Manual gating uses a sequential approach to address the multidimensionality of the data



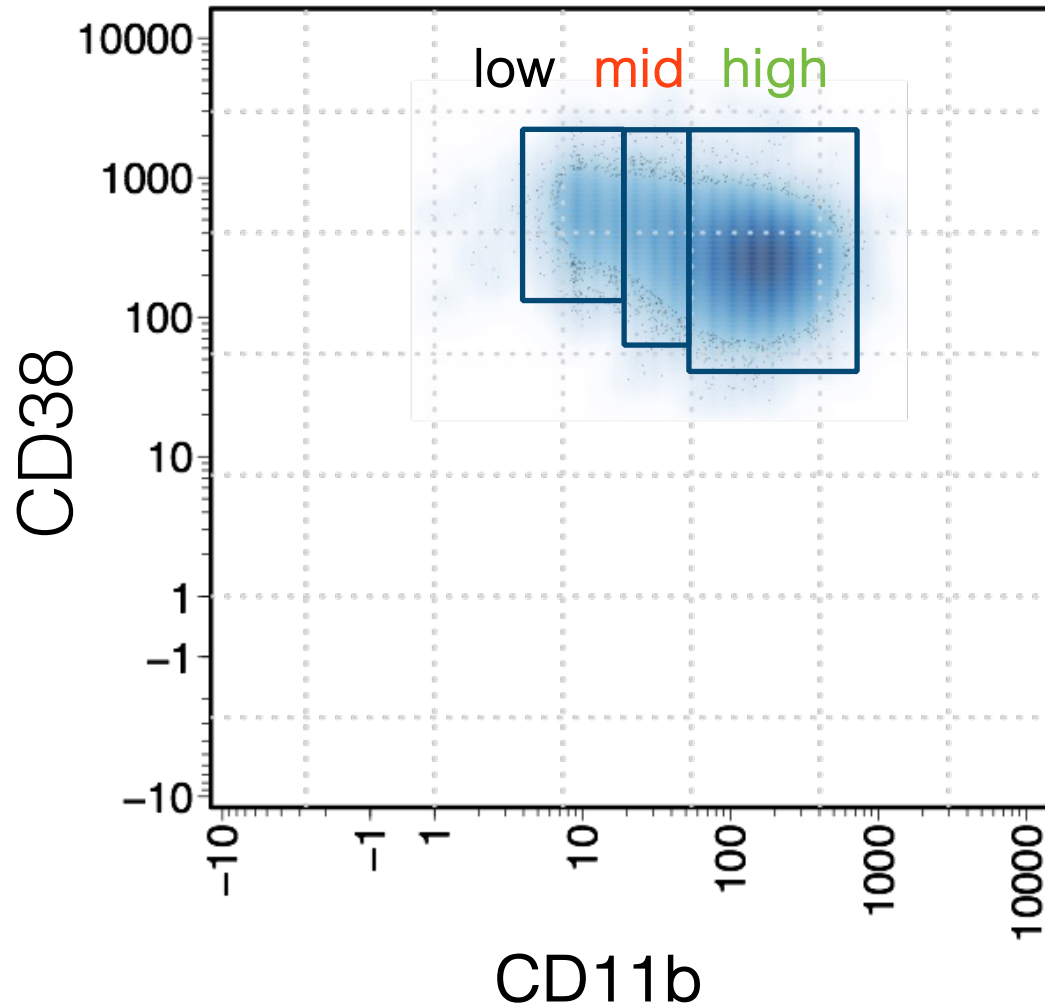
Does not scale well on large data sets
(i.e. samples and markers)

- Sequential → inaccuracies propagate and amplify in the downstream steps

Practical advantages of looking at all dimensions (1)

CD11b low/mid/high monocyte (sub)populations at resting state

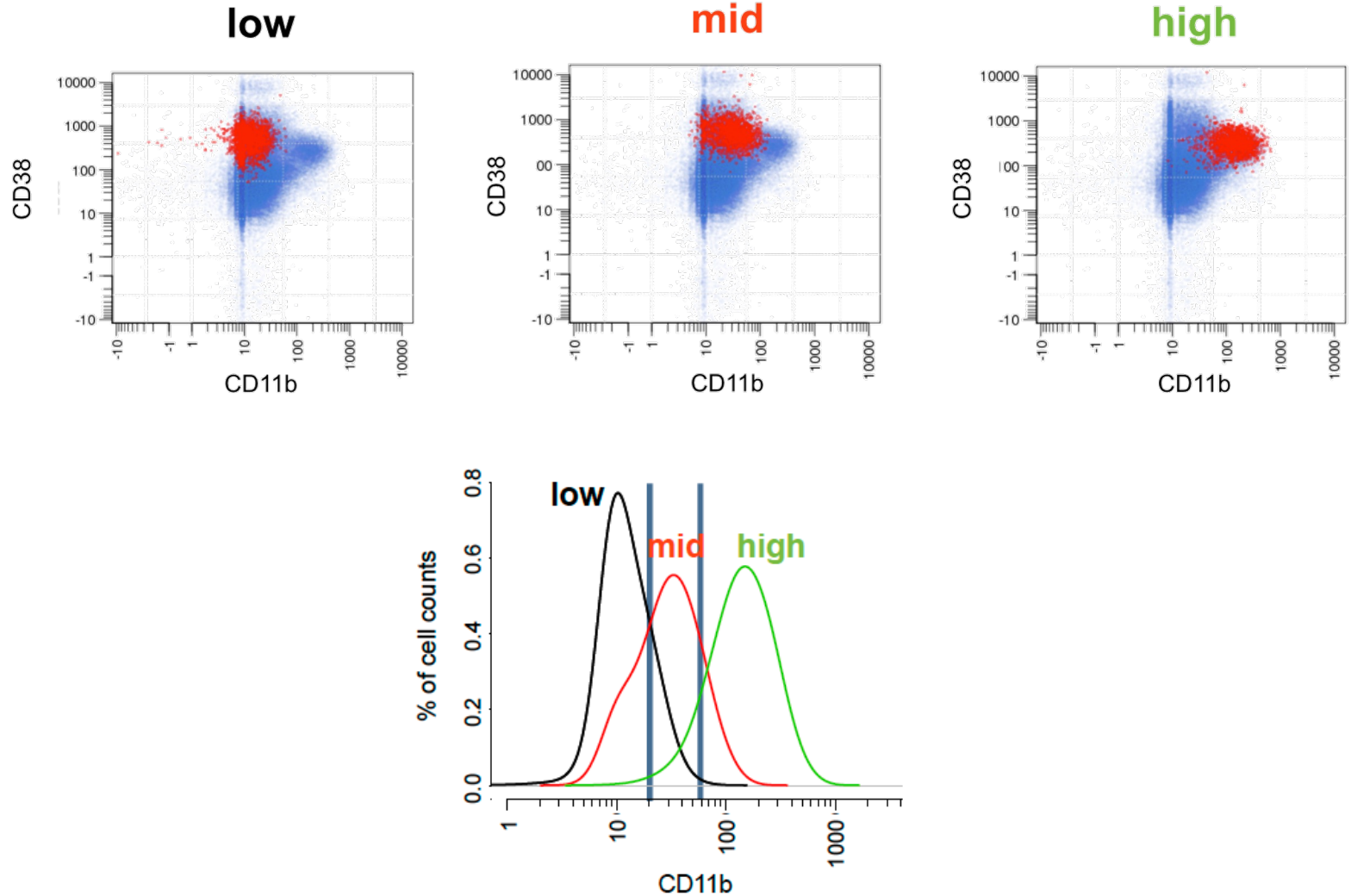
2D gating



Practical advantages of looking at all dimensions (2)

CD11b low/mid/high monocyte (sub)populations at resting state

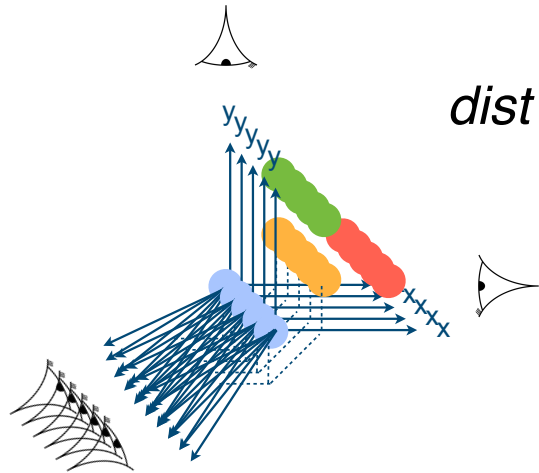
Multi-dimensional



B

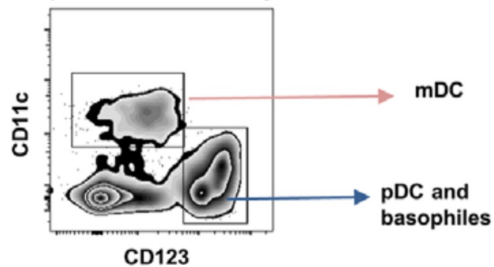


Clustering can consider all data at the same time

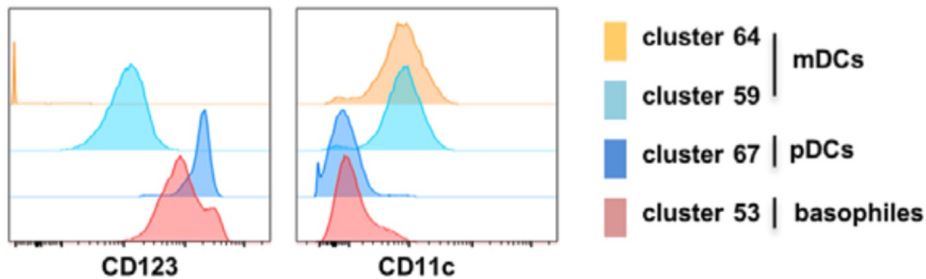


$$\text{dist}(\vec{A}, \vec{B}) = \sqrt{\sum_{i=1}^n (A_i - B_i)^2}$$

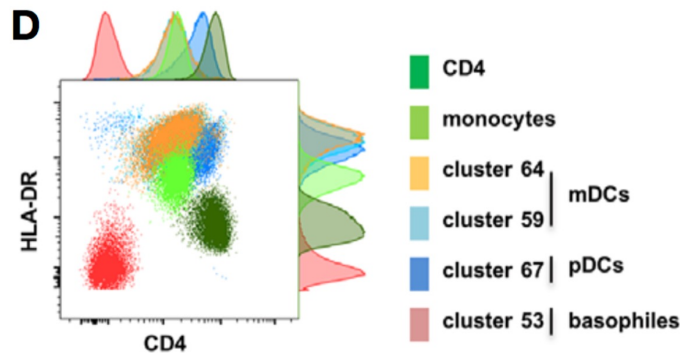
E Supervised re-analysis



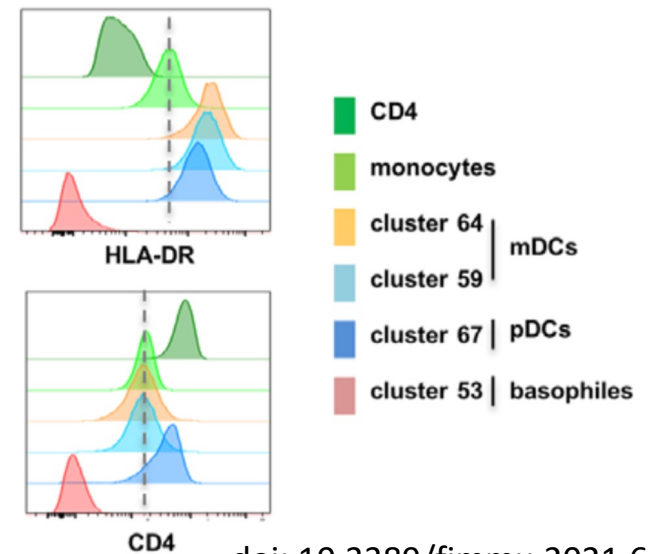
B



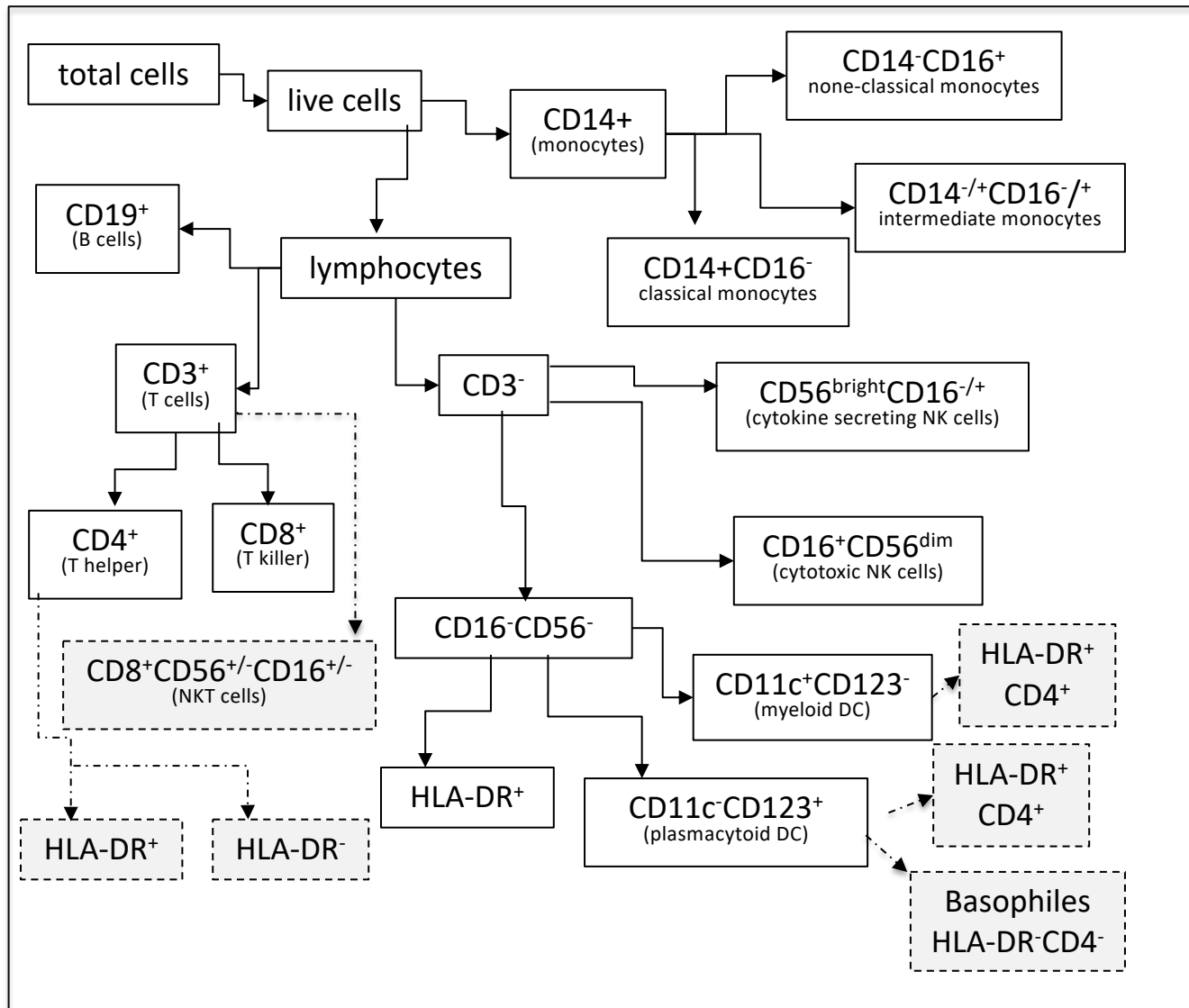
D



C



Revised gating strategy, considering new populations



Clustering Algorithms

Algorithm	Complexity	Robust to outliers	Order independence	User input	Mixed datatypes	Arbitrary-shaped cluster
Partitioning (k-means)						
k-Means [76]	$O(kN)$	No	No	1, 10	No	No
Farth. First Trav. [77]	$O(Nk)$	No	No	1	Yes	No
k-Medoids (PAM) [78]	$O(kN)$	Yes	No	1	No	No
CLARA [79]	$O(k^2 + k(N-k))$	Yes	Yes	1	No	Yes
CLARANS [80]	$O(N^2)$	Yes	Yes	1	No	Yes
Fuzzy k-means [43, 81]	$O(kN)$	No	No	1	No	Yes
k-Modes [82]	$O(kN)$	No	No	1	No	—
Fuzzy k-modes [83]	$O(kN)$	No	No	1	No	—
Squeezer [84]	$O(kN)$	No	No	13	Yes	No
k-Prototypes [85]	$O(kN)$	No	No	1	Yes	No
COOLCAT [86]	$O(N^2)$	No	No	1	No	No
CLICK (gene expr.) [36]	'Fast'	—	Yes	—	No	No
Hierarchical						
Agglomerative single, average, complete-linkage [145, 147]	$O(N^2)$ single, $O(N^2 \log N)$ average & complete	No	Yes	5, 15	Yes	Yes
Eisen gene expr. [15, 87]	$O(N^2)$ single, $O(N^2 \log N)$ average & complete	No	Yes	5	Yes	Yes
Spectral [88, 89]	$O(N)$ (roughly)	No	Yes	5	Yes	No
BIRCH [90]	$O(N)$	Yes	Yes	—	No	No
CURE [91]	$O(N)$	Yes	Yes	—	No	Yes
ROCK [92]	$O(kN^2)$	No	Yes	1, 13	Yes	—
Chameleon [93]	$O(N^2)$	Yes	Yes	13	No	Yes
LIMBO [94]	$O(N \log N)$	Yes	Yes	14	No	—
hMETIS [95]	'Fast'	No	Yes	5, 10	No	No
Power graphs [96]	$O(Nd^2)$	Yes	Yes	5, 10, 12, 13	Yes	—

Algorithm	Complexity	Robust to outliers	Order independence	User input	Mixed datatypes	Arbitrary-shaped cluster
Density-based						
HIERDENC [97]	$O(N)$	Yes	Yes	—	Yes	—
MULIC [14, 97]	$O(N^2)$	Yes	No	—	Yes	—
DBSCAN [98]	$O(N \log N)$	Yes	Yes	3, 7	No	Yes
OPTICS [99]	$O(N \log N)$	Yes	Yes	3, 7	No	Yes
DENCLUE [100]	$O(N^2)$	Yes	No	7	No	Yes
CACTUS [101]	'Scalable'	No	Yes	1, 4	No	No
STIRR [102]	'Scalable'	No	No	12	No	No
CLICK (categ.) [103]	'Scalable'	No	Yes	—	No	—
CLOPE [104]	$O(kdN)$	No	Yes	—	No	No
WaveCluster [105]	$O(N)$	Yes	Yes	8, 9	No	Yes
STING [106]	$O(N)$	Yes	Yes	—	No	No
CLIQUE [107]	$O(N)$	Yes	Yes	3, 8	Yes	Yes
Model-based						
SOMs (NeuralNet) [23]	$O(N^2)$	No	No	1, 2, 5	No	Yes
COBWEB [108]	$O(Nd^2)$	Yes	No	—	No	—
BILCOM [109]	$O(N^2)$	Yes	No	5	Yes	—
AutoClass (ExpMax) [110]	$O(kd^2Nt)$	Yes	Yes	—	Yes	Yes
SVM clustering [111]	$O(N^{1.8})$	No	No	—	Yes	Yes
Graph-based						
MCODE [19]	$O(Nd^3)$	No	Yes	6	No	—
RNSC [112]	$O(N^3)$	No	Yes	1	No	—
SPC [65, 70]	$O(N^2)$	Yes	Yes	1	No	Yes
MCL [113]	$O(N^3)$	Yes	Yes	11	No	—

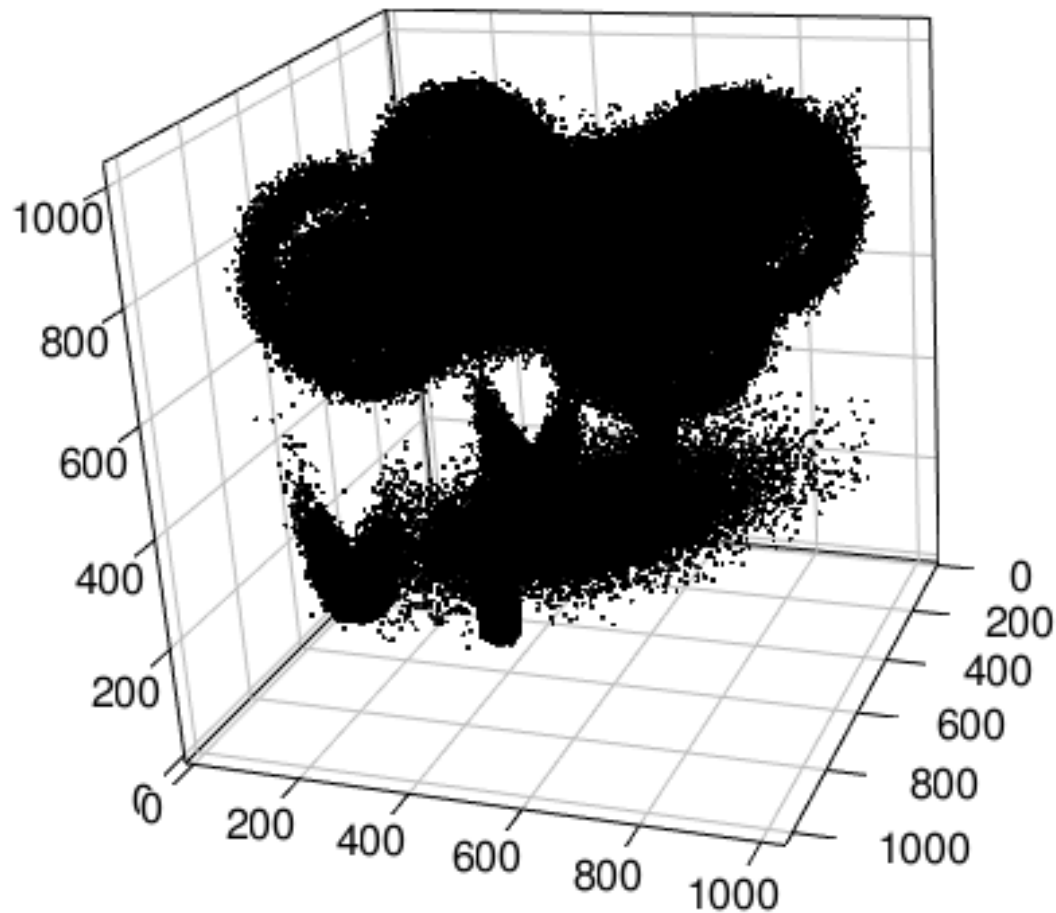
Source: A roadmap of clustering algorithms: finding a match for a biomedical application
B.Andreopoulos et al; Briefings in Bioinformatics (2009) VOL 10. NO 3. 297-314

Clustering Wishlist

- Unaffected by the order in which the data are presented
- Not assume any specific cluster shape
- Proper separation of overlapping distributions
- Automatically discover the “ideal” number of clusters
- Resistant to noise (e.g. not assign outliers in clusters)
- Capable of clustering millions of observations

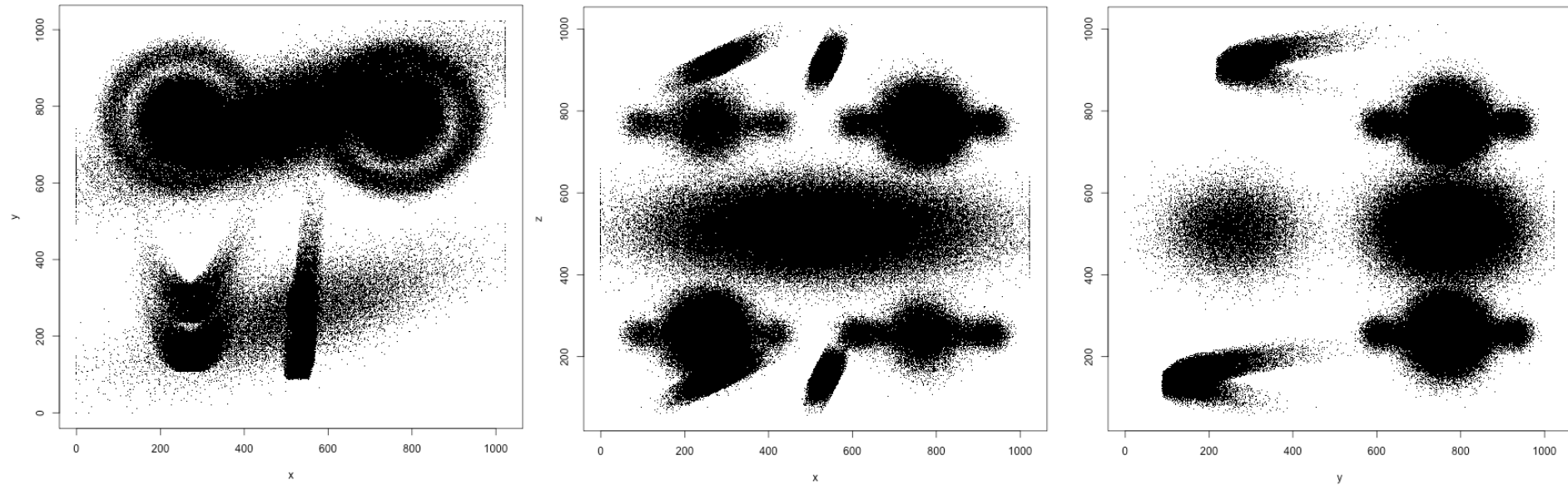
Tests with synthetic data

comprising a total of 799,956 points



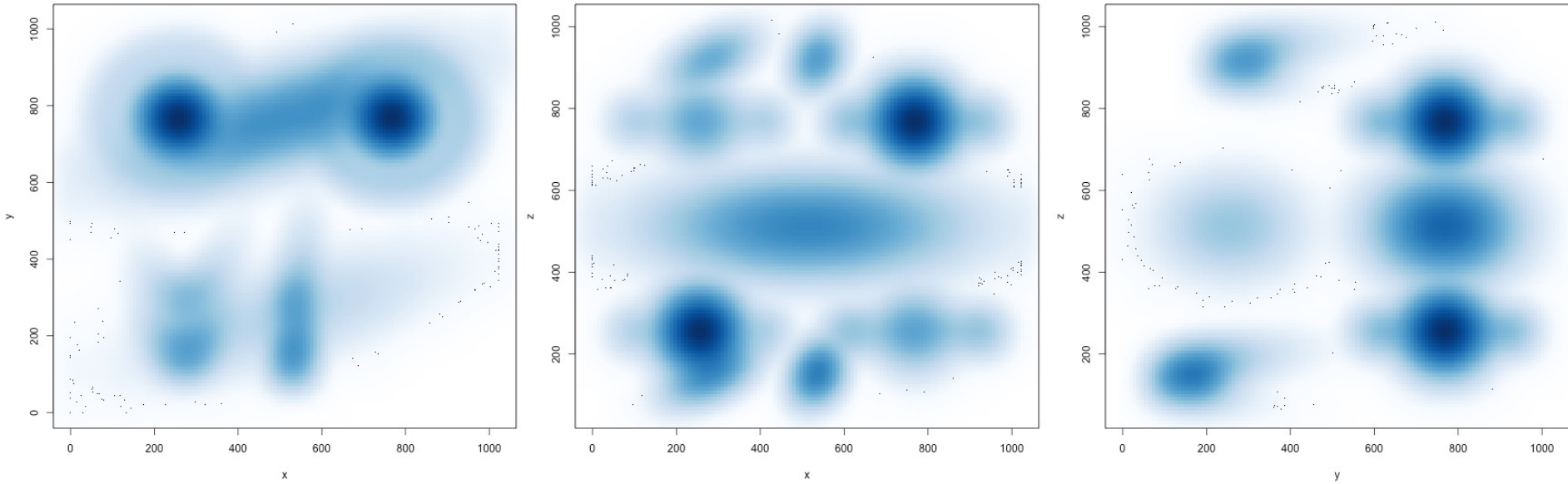
Tests with synthetic data

comprising a total of 799,956 points



Tests with synthetic data

comprising a total of 799,956 points



Tests with synthetic data

INPUT: 14 shapes, comprising a total of 799,956 points

Spheres 1 (blue) and 4 (dark blue) and ellipse 1 (yellow) have 200,000 points

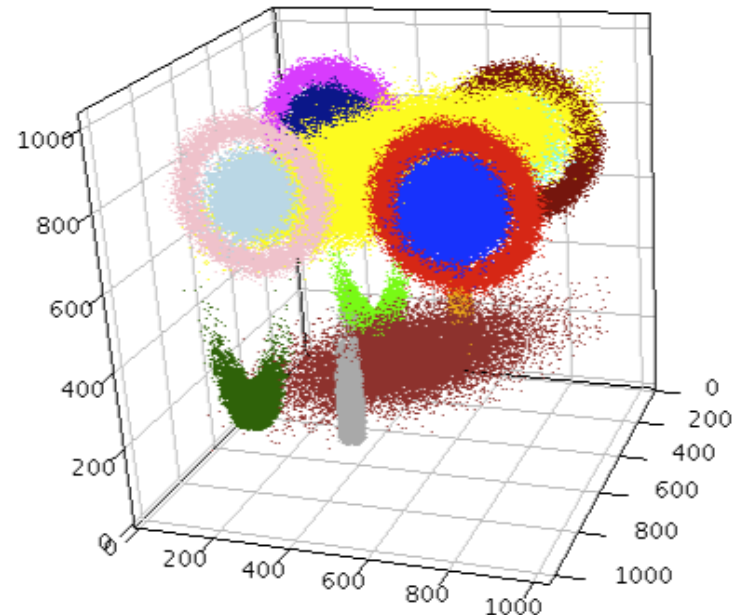
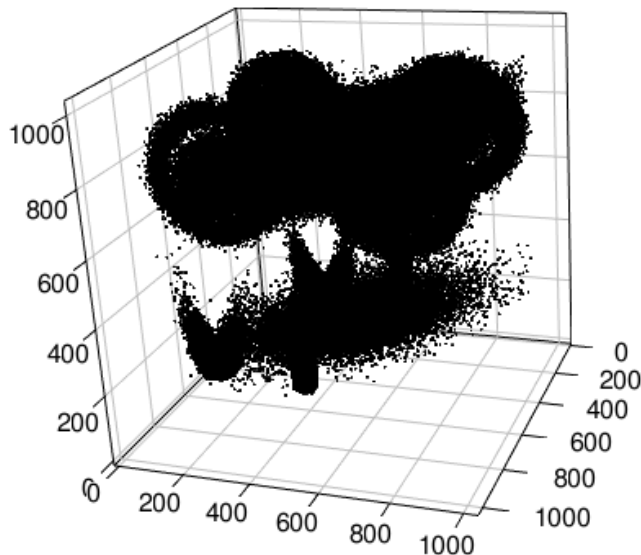
Spheres 2 (cyan) and 3 (light blue) and ellipse 2 (brown) have 20,000 points

Tores 1 (red) and 2 (dark red) have 16,652 points

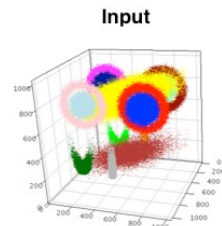
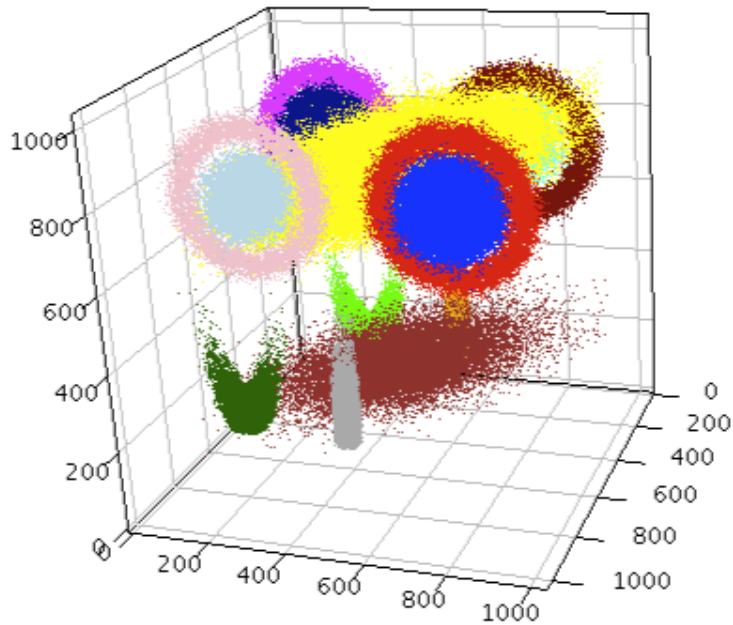
Tores 3 (pink) and 4 (magenta) have 8,326 points

Bananas 1 (green) and 2 (orange) have 30,000 points and different curvatures

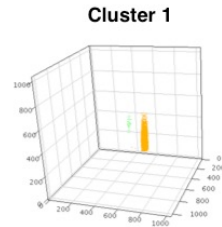
Bananas 3 (dark green) and 4 (dark grey) have 15,000 points and different curvatures



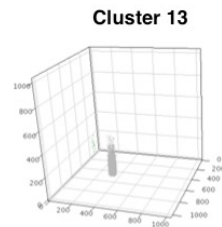
K - mean



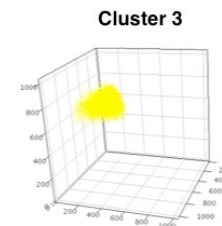
Unassigned



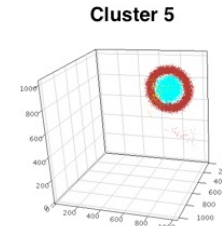
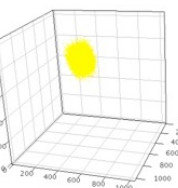
Cluster 2



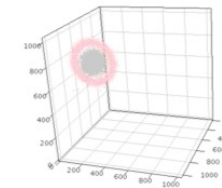
Cluster 14



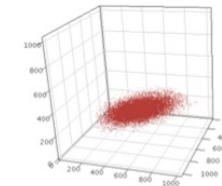
Cluster 12



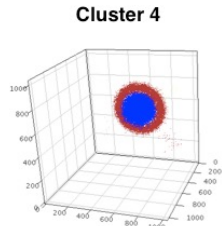
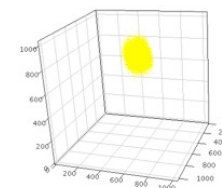
Cluster 6



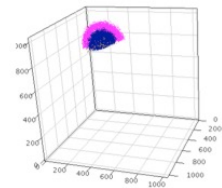
Cluster 8



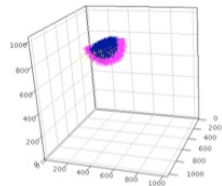
Cluster 10



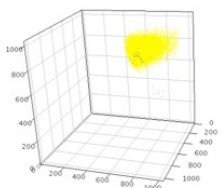
Cluster 7



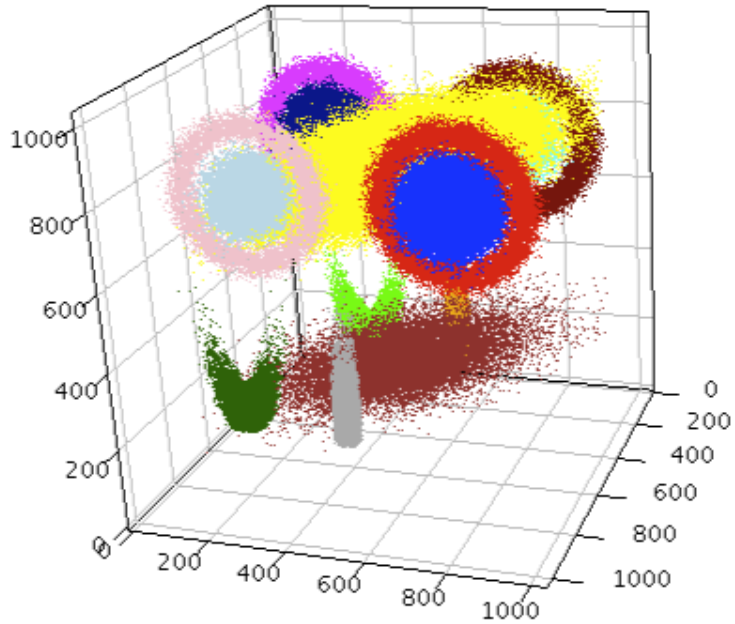
Cluster 9



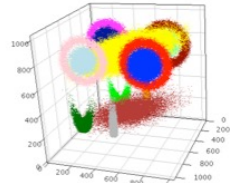
Cluster 11



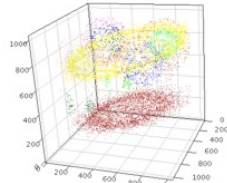
DBscan



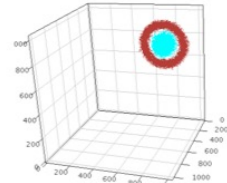
Input



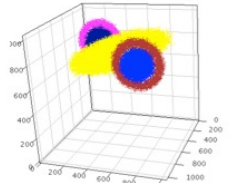
Unassigned



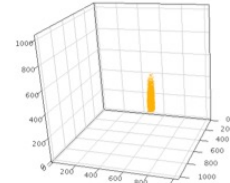
Cluster 5



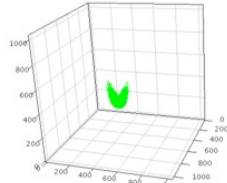
Cluster 4



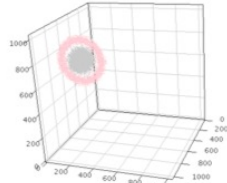
Cluster 1



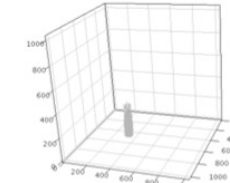
Cluster 2



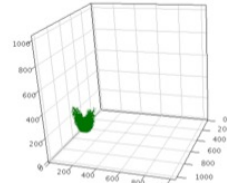
Cluster 6



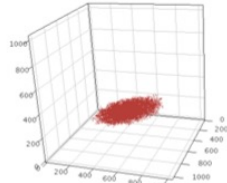
Cluster 13



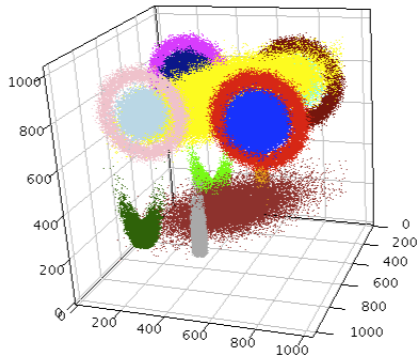
Cluster 14



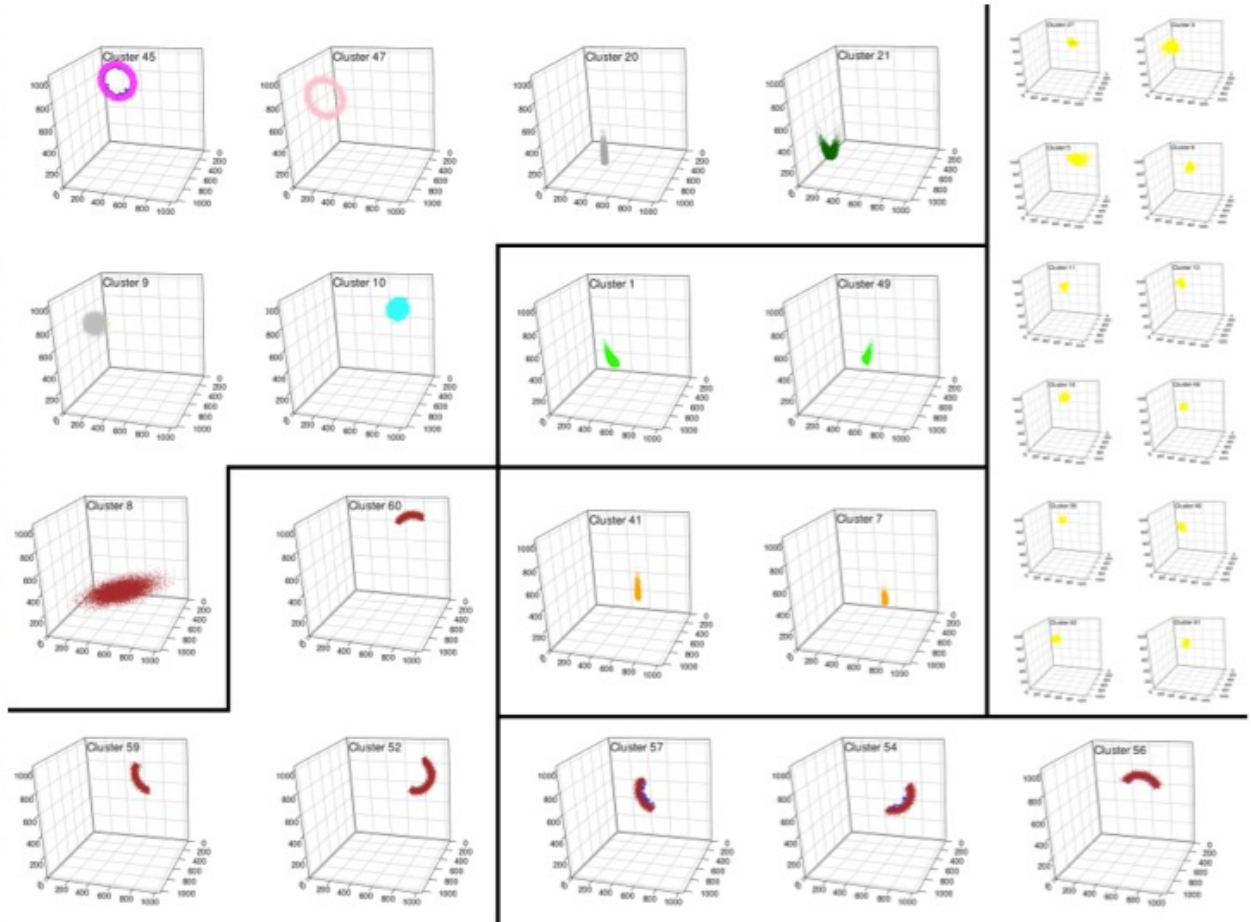
Cluster 8



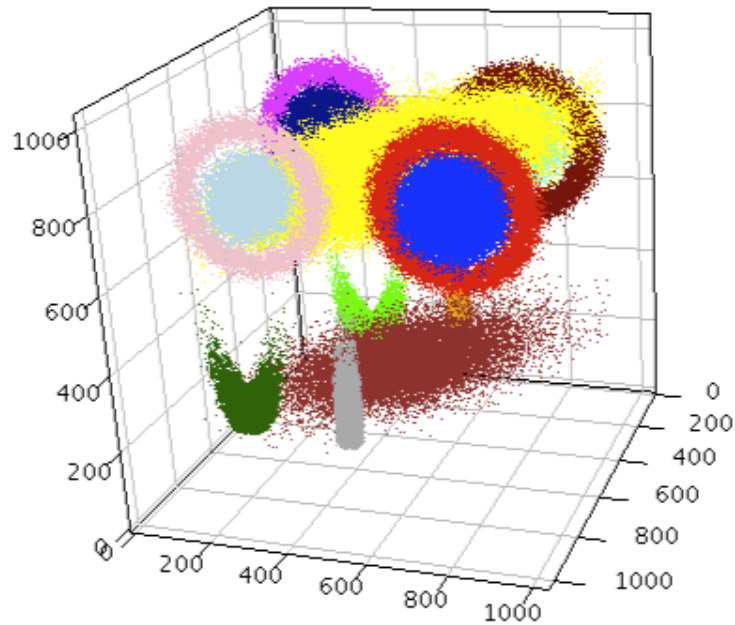
Phenograph



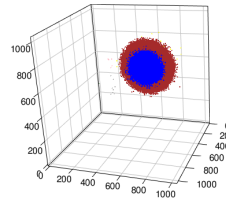
- Identified 61 clusters
- Correctly identified 7 out of 14 shapes
- Oversplit the others
- Dense spheres each split in 16 clusters



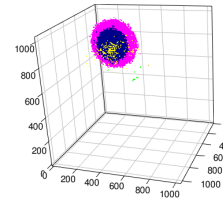
FlowSOM (run #1)



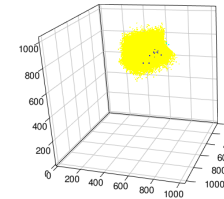
cluster 1



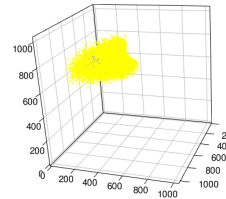
cluster 2



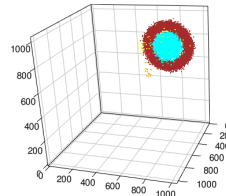
cluster 3



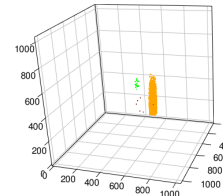
cluster 4



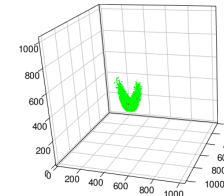
cluster 5



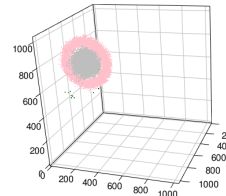
cluster 6



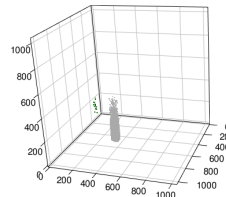
cluster 7



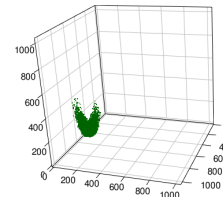
cluster 8



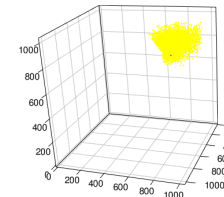
cluster 9



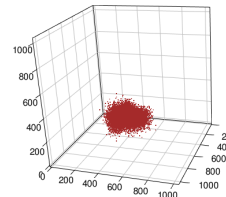
cluster 10



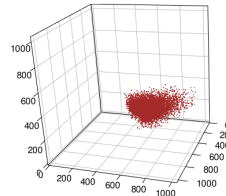
cluster 11



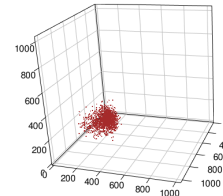
cluster 12



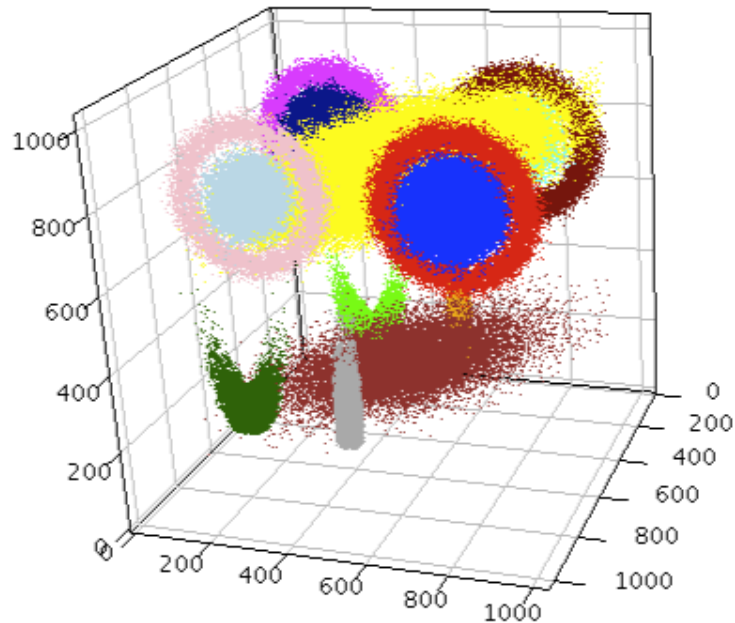
cluster 13



cluster 14

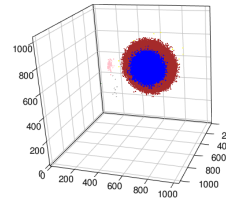


FlowSOM (run #2)

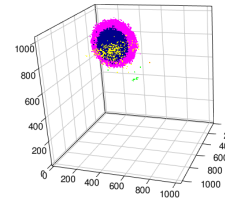


RUN #1		RUN #2
216882	—	216964
208557	—	208644
111741	—	130095
74487	—	54045
36688	—	36772
30008	—	29998
29967	—	29967
28328	—	28223
15014	—	16856
14968	—	15270
13325	—	15024
10927	—	14957
7428	—	1623
1635	—	1518

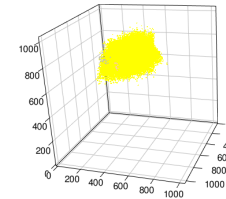
cluster 1



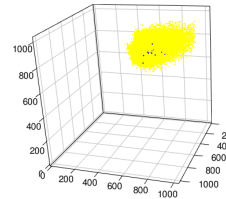
cluster 2



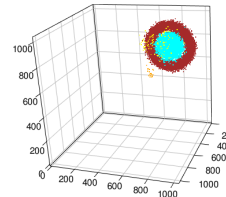
cluster 3



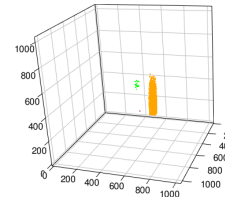
cluster 4



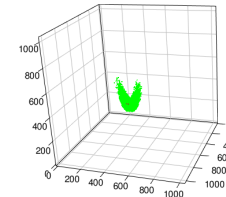
cluster 5



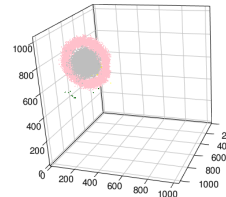
cluster 6



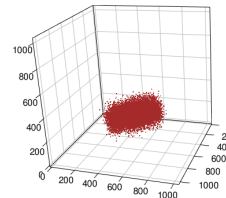
cluster 7



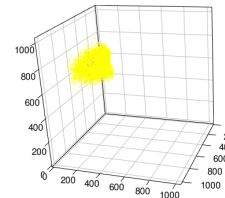
cluster 8



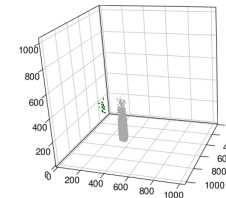
cluster 9



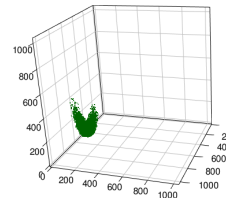
cluster 10



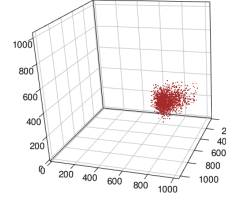
cluster 11



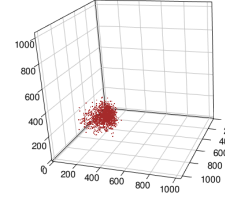
cluster 12



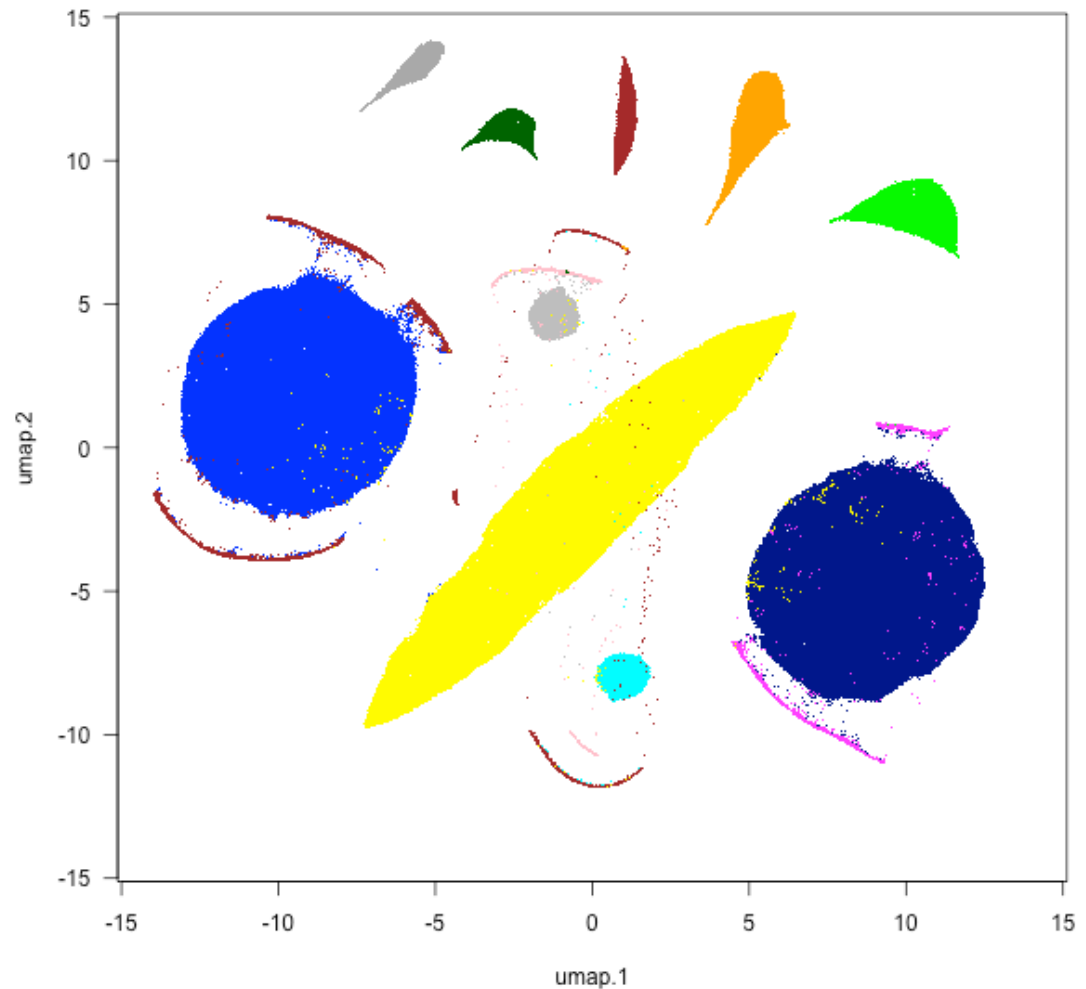
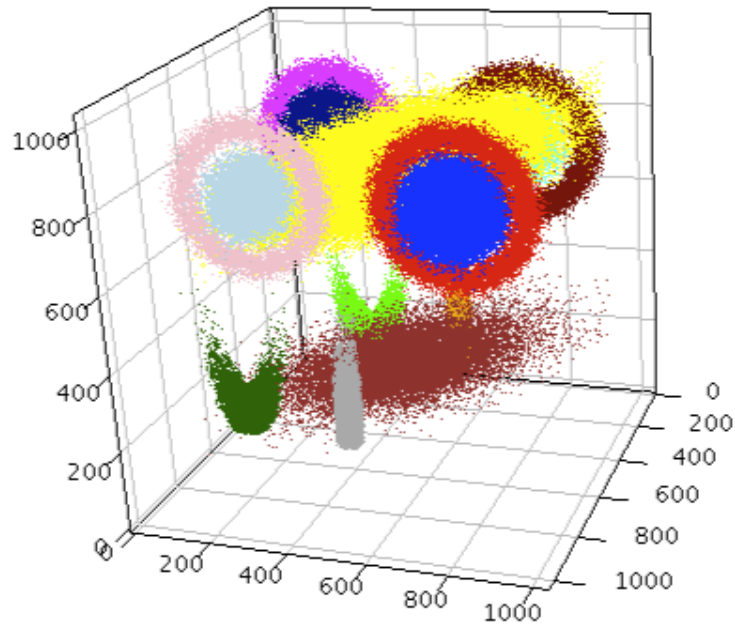
cluster 13



cluster 14

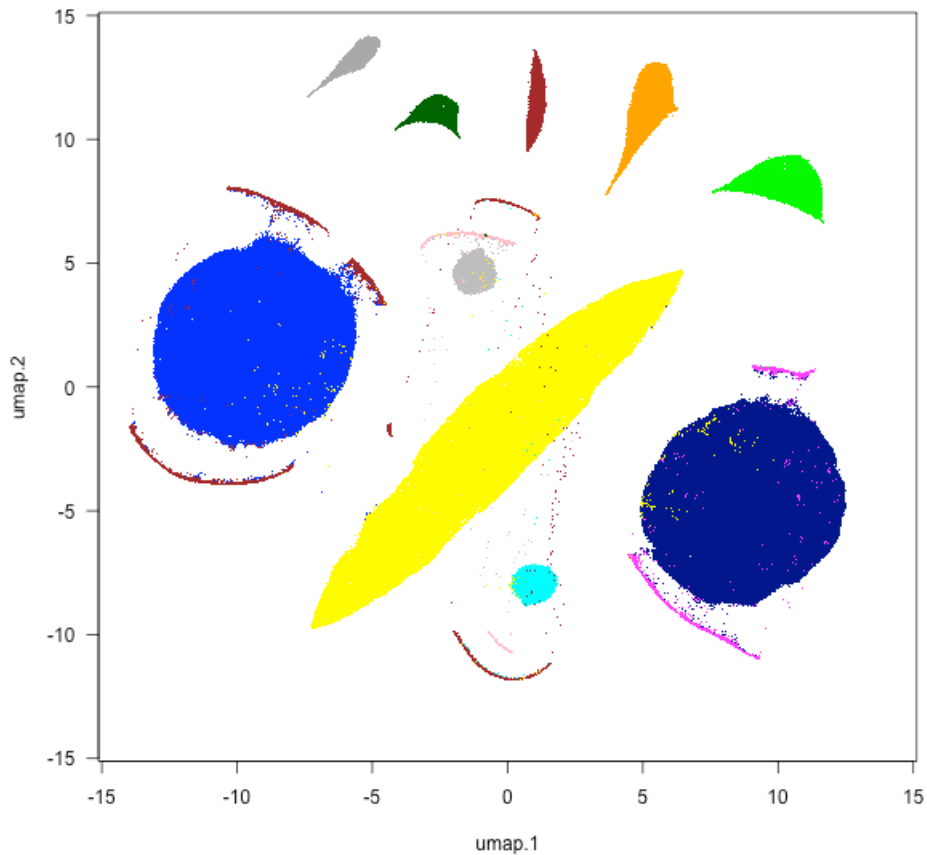


small parenthesis : UMAP

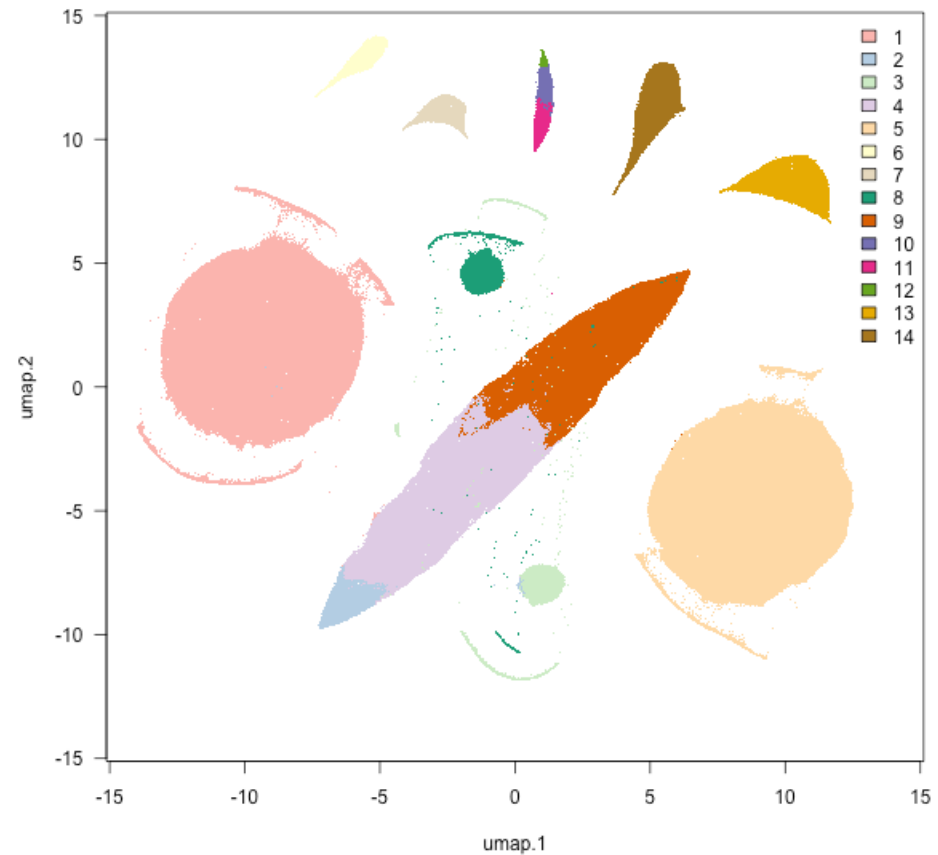


small parenthesis : UMAP

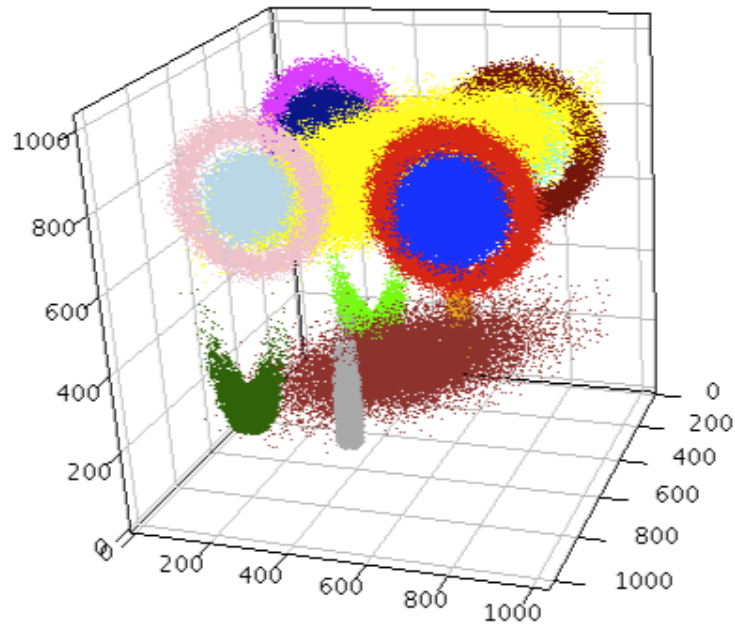
3D Gold Standard Projected in 2D



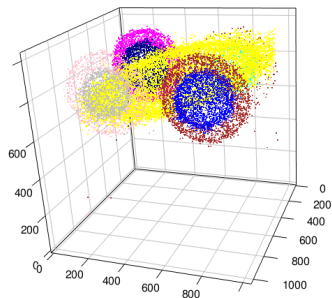
FlowSOM run #1 clusters



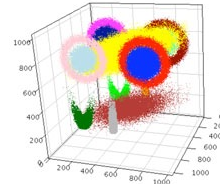
Megaclust / hdbscan



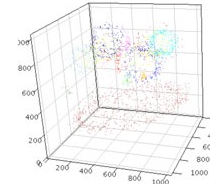
hdbscan unassigned (3%)



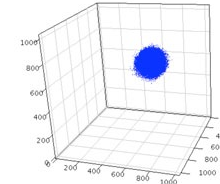
Input



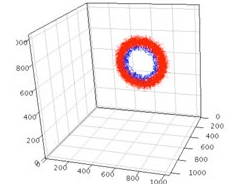
Unassigned (0.3%)



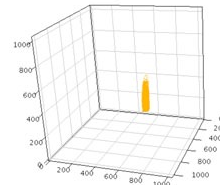
Cluster 5 (99.1%)



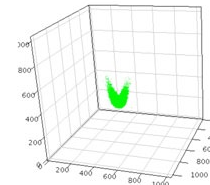
Cluster 4 (99.4%)



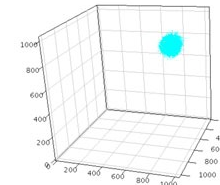
Cluster 1 (99.7%)



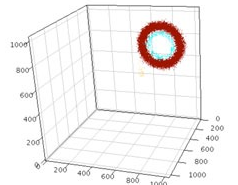
Cluster 2 (99.9%)



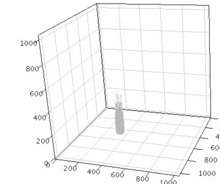
Cluster 6 (95.9%)



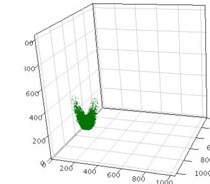
Cluster 7 (99.7%)



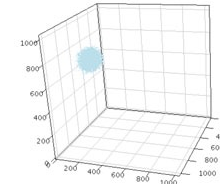
Cluster 13 (99.9%)



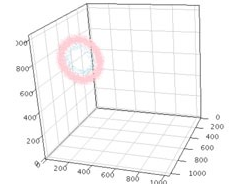
Cluster 14 (99.9%)



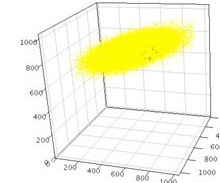
Cluster 8 (95.4%)



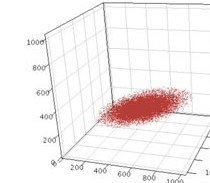
Cluster 9 (99.3%)



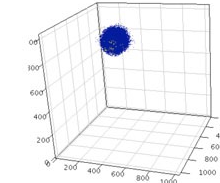
Cluster 3 (99.7%)



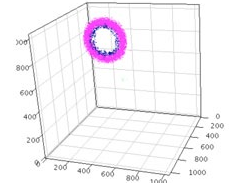
Cluster 12 (96.7%)



Cluster 10 (99.4%)



Cluster 11 (98.6%)



Hierarchical Clustering

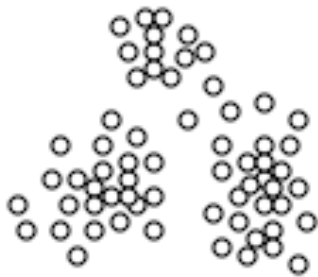
- Number of Computations

- Memory

$$1e6 * 1e6 * 4 = 4Tb$$

observations	computation	time
10	50	60 us
100	5000	6 ms
1000	500000	600 ms
10000	50000000	1 mn
100000	5000000000	1 h 40 mn
1000000	500000000000	7 days

- Parallelization

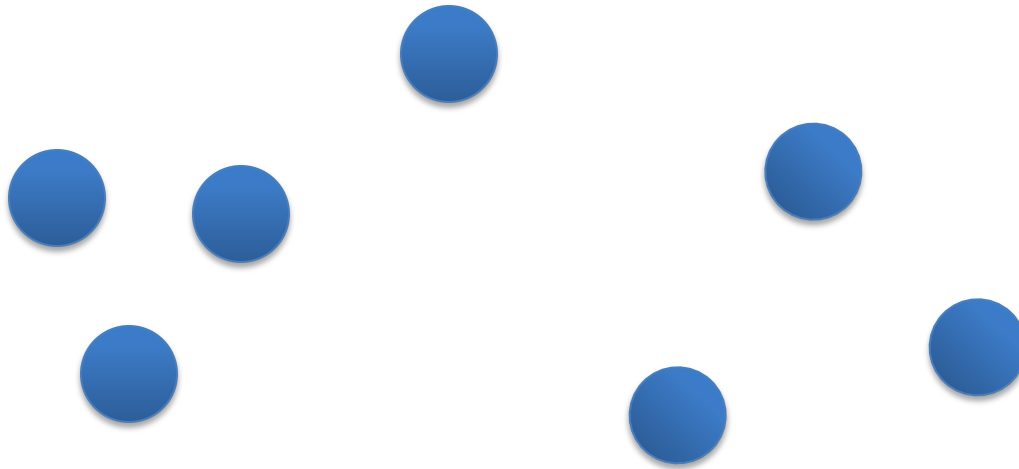


Density-based hierarchical clustering

- Compute all pairwise distances and retain only those that are equal or smaller than a given distance threshold T
- A cluster is formed by single linkage and retained if it contains at least N points. Clusters too small are ignored
- Hierarchical clustering is obtained by repeating the clustering for increasing distance thresholds

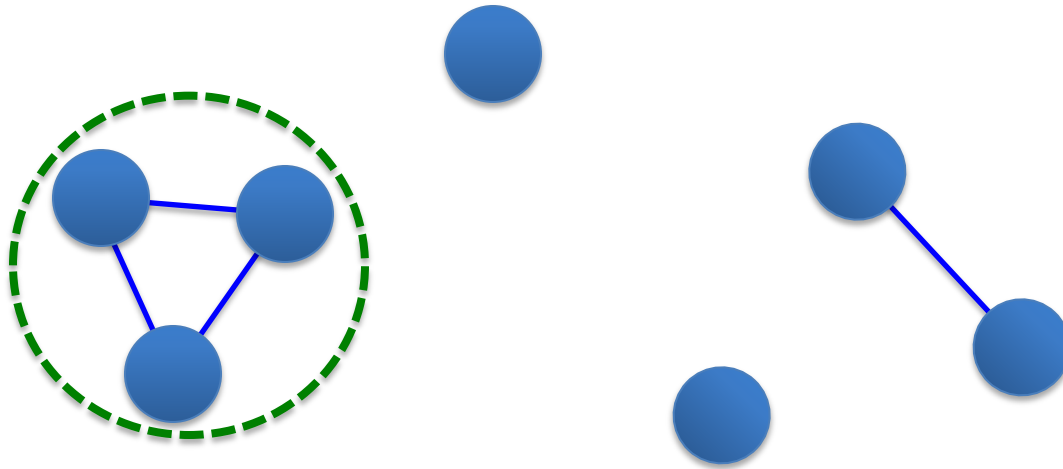
T from T_{min} to T_{max} in s steps

Density-based hierarchical clustering



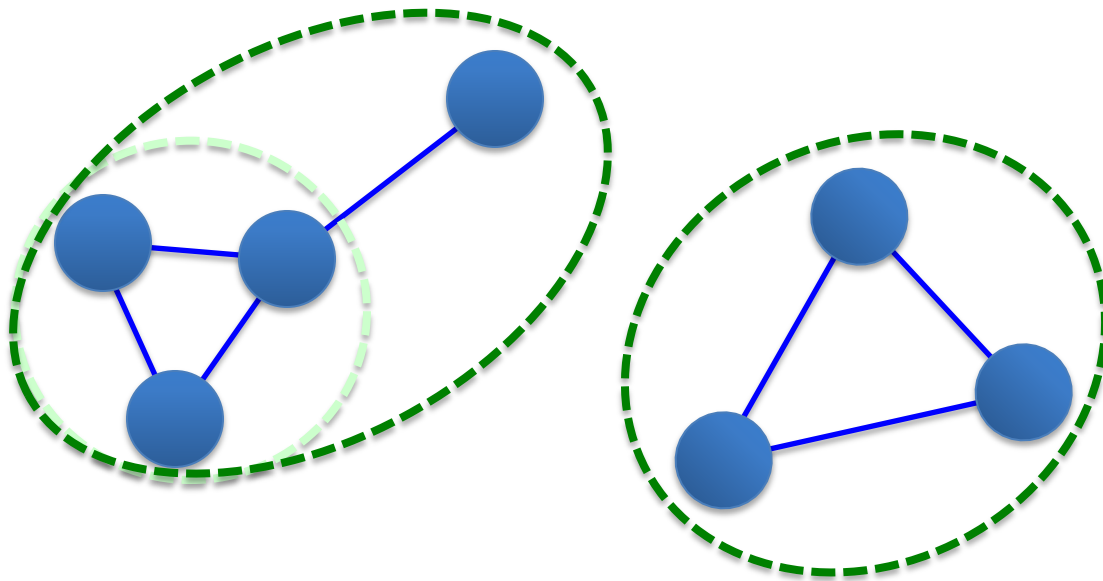
Density-based hierarchical clustering

- $D \leq 1$ and $N \geq 3$



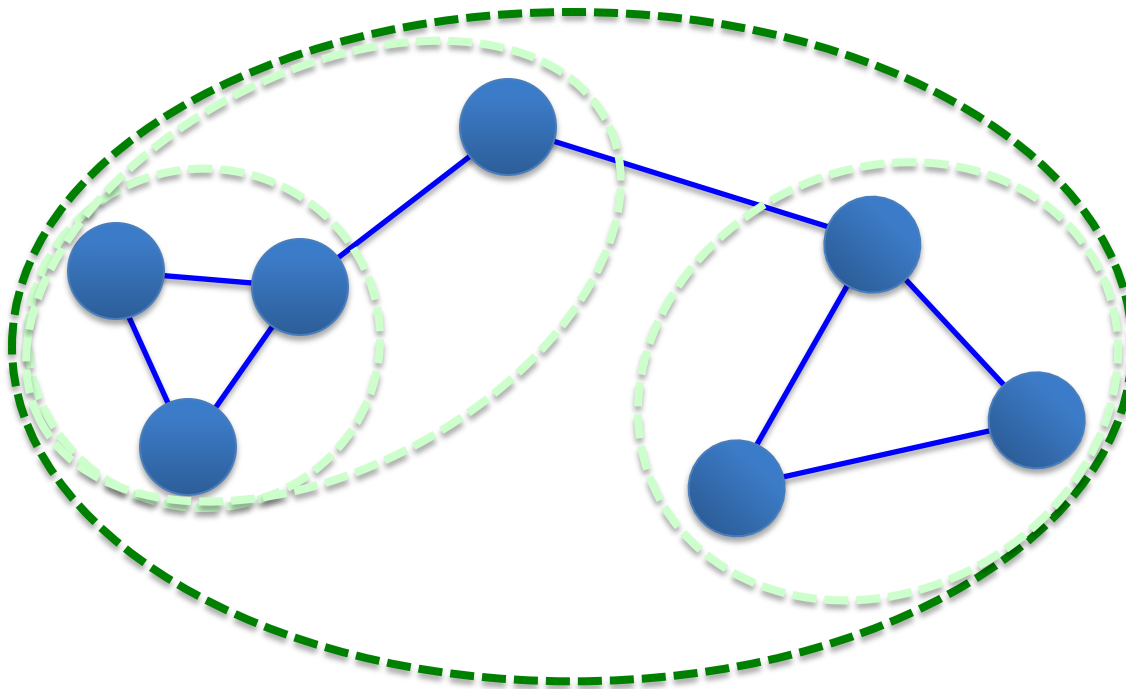
Density-based hierarchical clustering

- $D \leq 2$ and $N \geq 3$

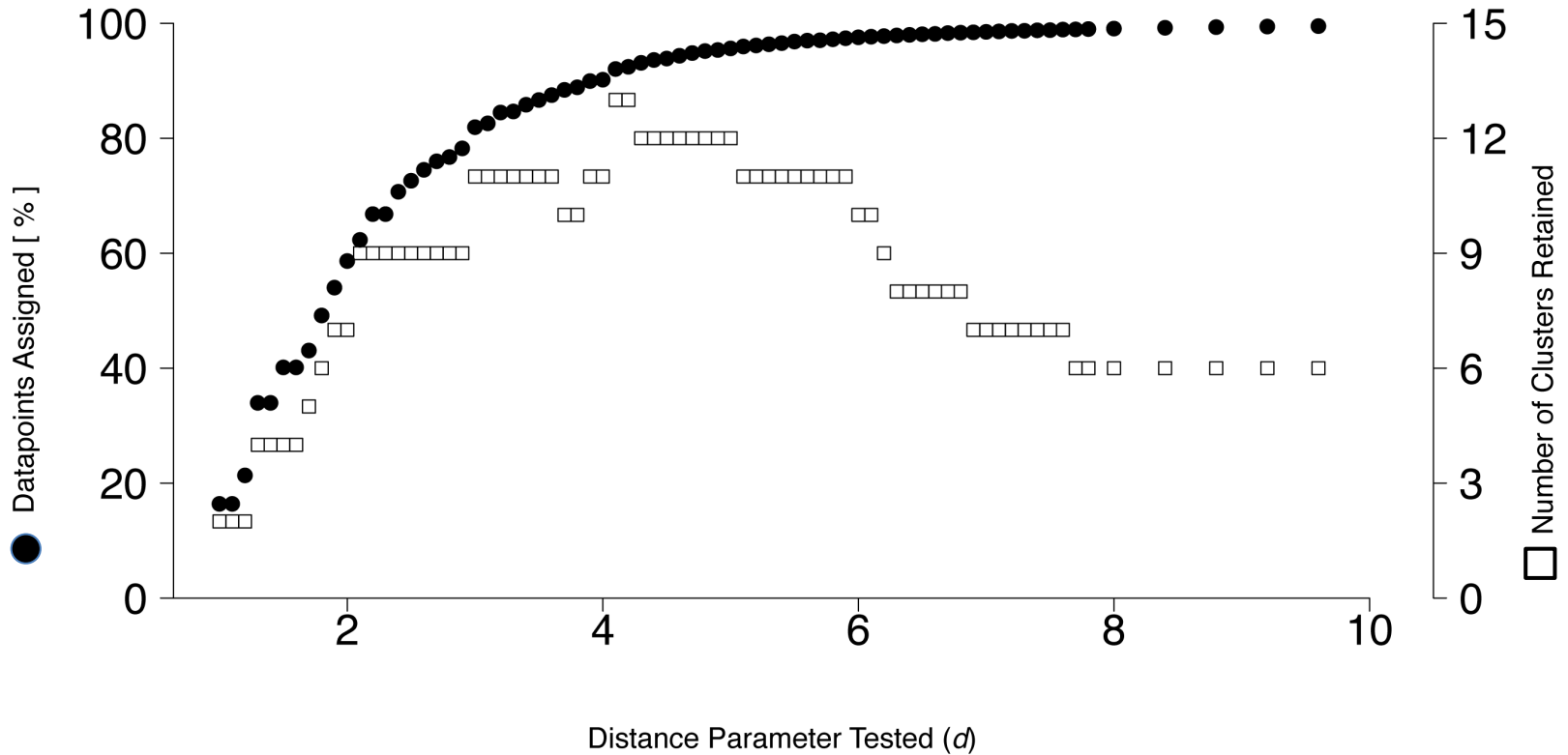


Density-based hierarchical clustering

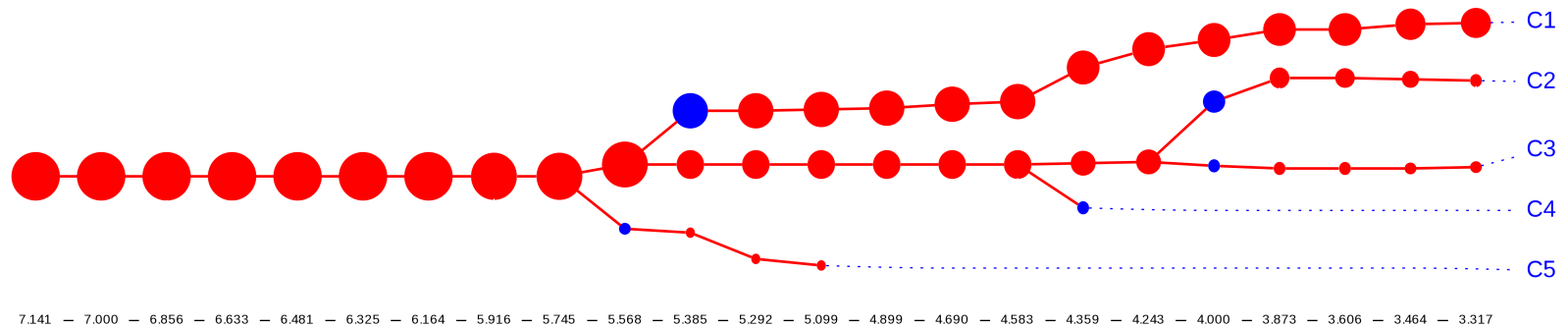
- $D \leq 3$ and $N \geq 3$



Density-based hierarchical clustering

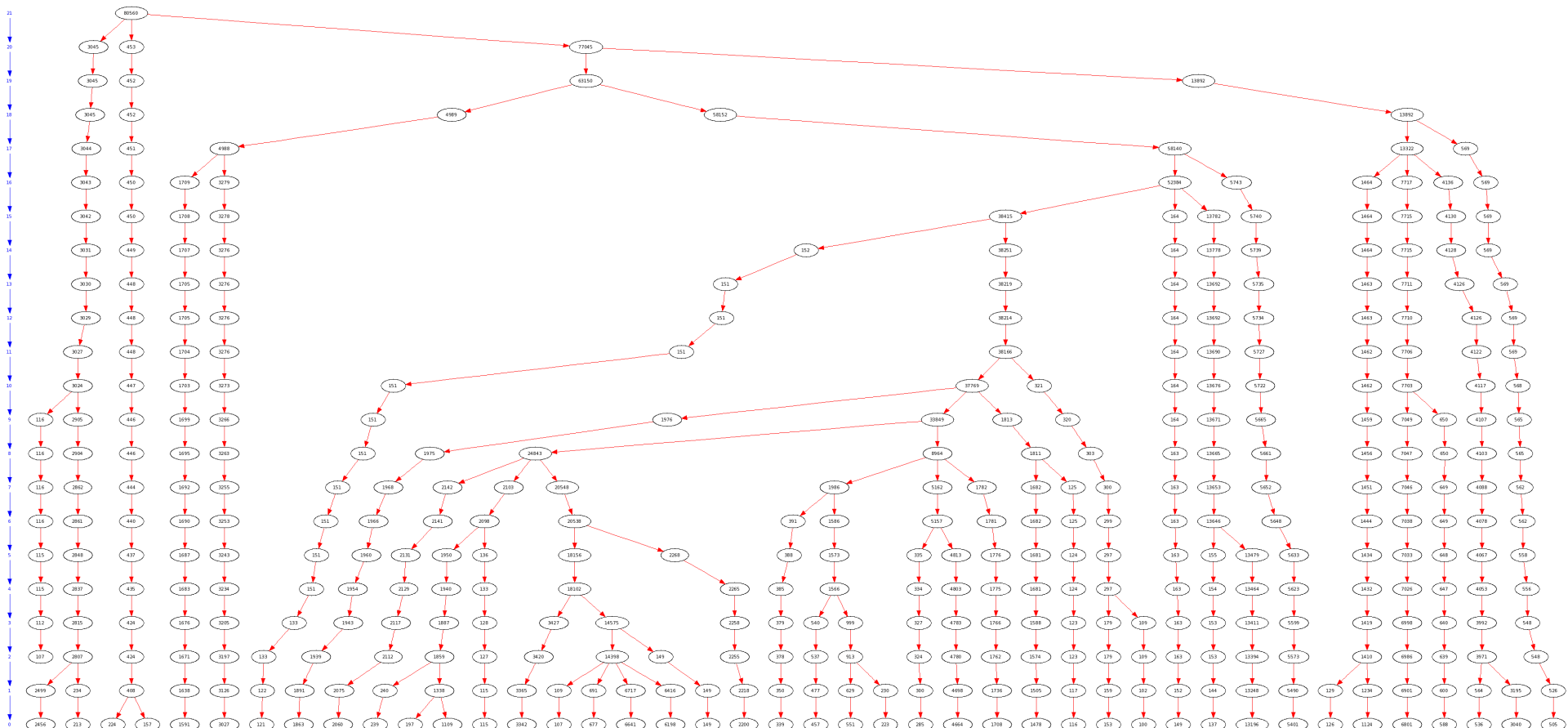


Assignment to the final partition

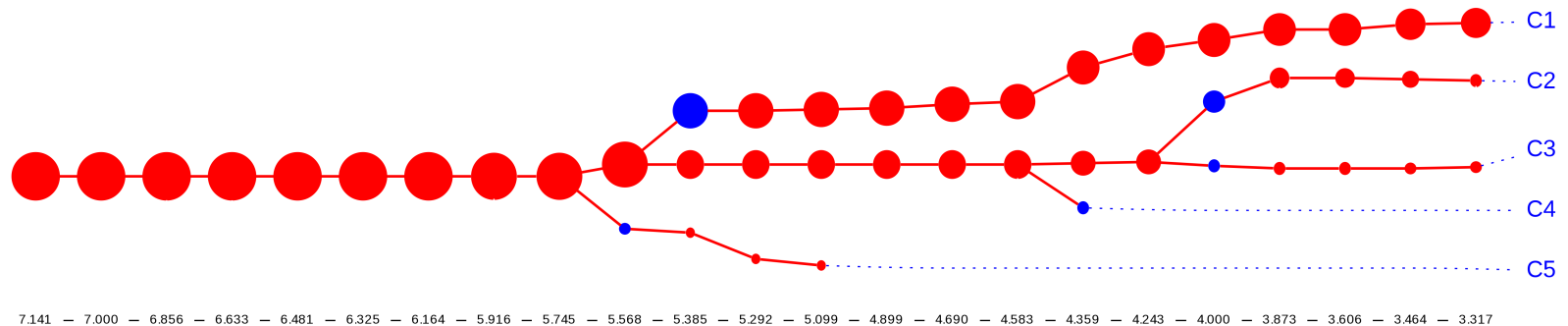


- At the end of the hierarchical clustering, **seed clusters** are determined and the points are re-attributed to the closest seed

A more realistic output

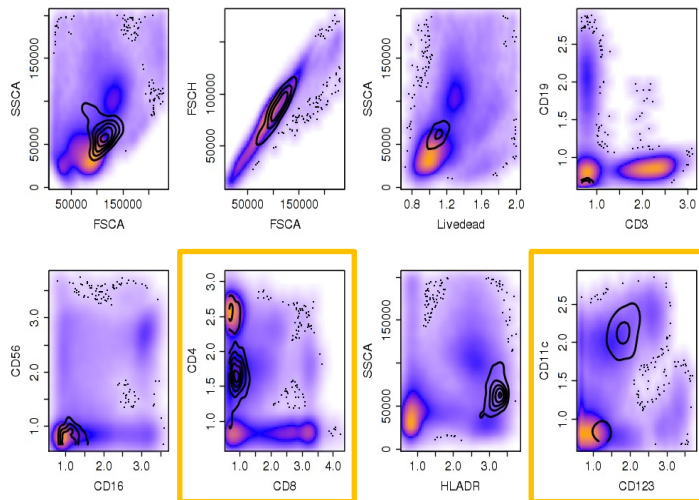


Parameters affecting results

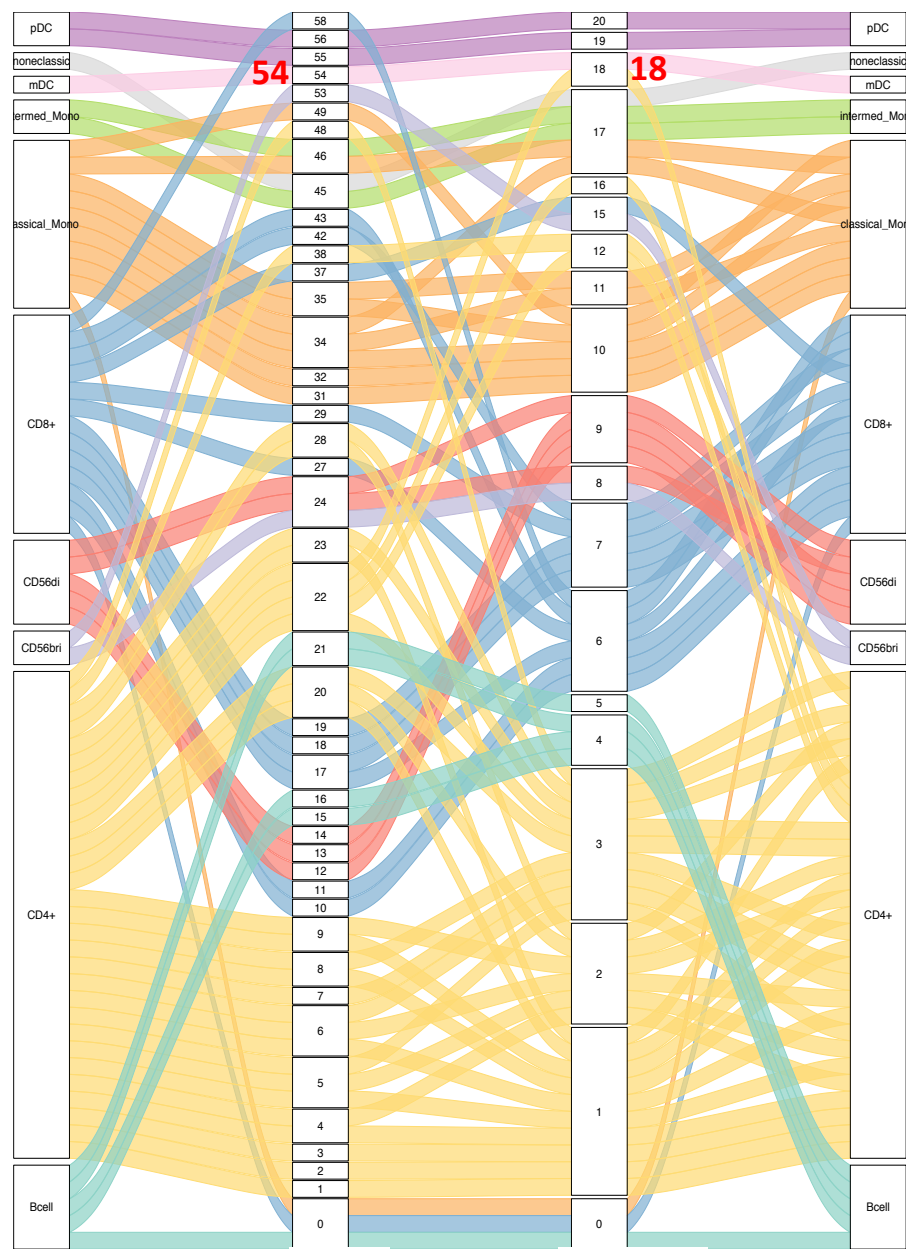
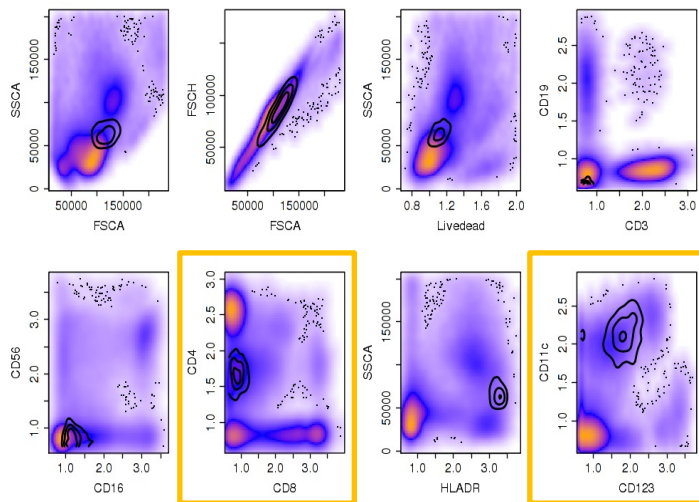


- -f first distance to test
- -l last distance to be tested
- -s step increment for the distance test
- -k minimum percent of events needed to retain a cluster
- -n minimum number of events needed to retain a cluster
- -p pctAssigned (Stop sampling as soon as pctAssigned events have been assigned)

@n120, Cluster 18 (1197 events, 0.005% live cells)



@n40, Cluster 54 (890 events, 0.003% live cells)



Manual
Gating

n=40

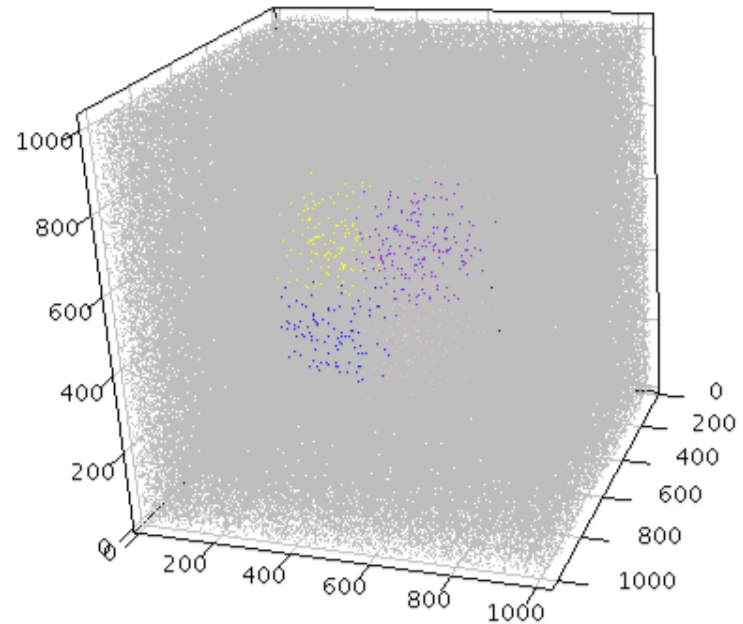
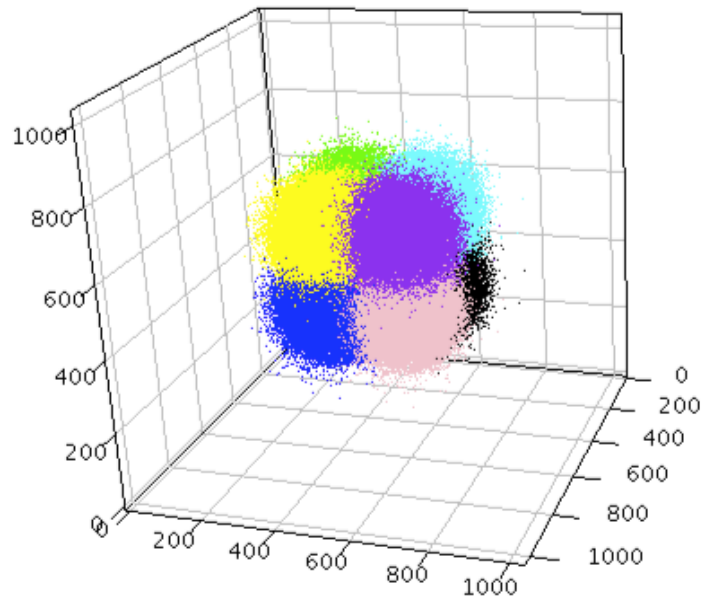
n=120

Manual
Gating

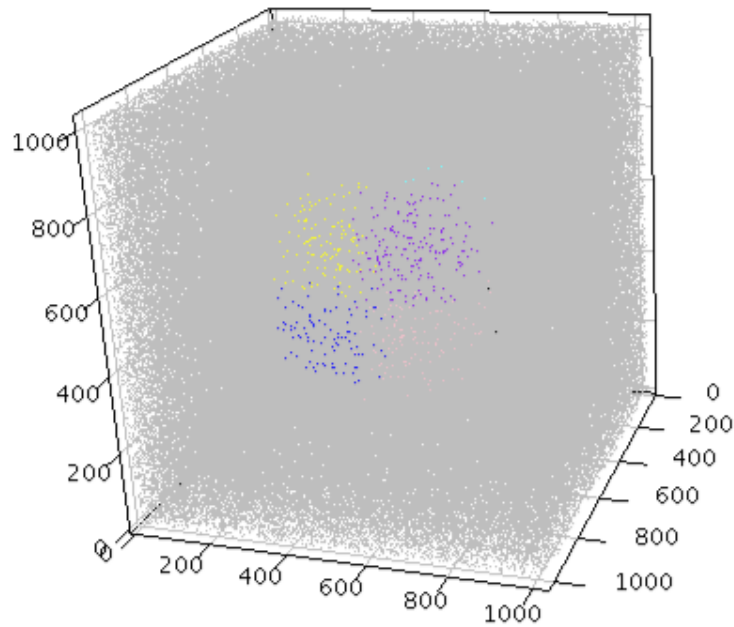
Tests with noise

INPUT:

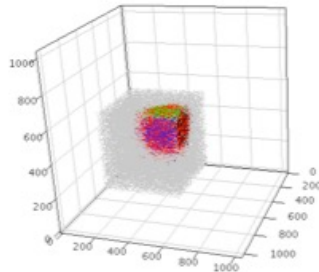
- 8 overlapping spheres with 125,000 points, comprising a total of 1e6 points
- random noise 500,000 points



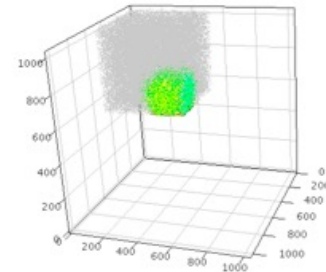
K - means



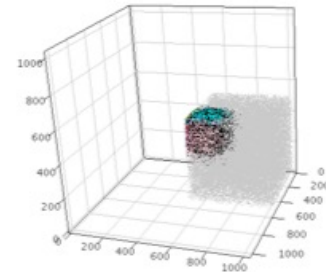
Cluster 1



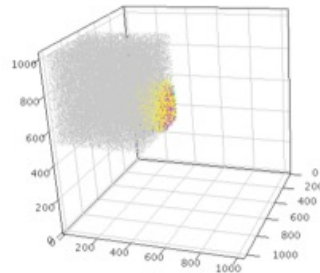
Cluster 2



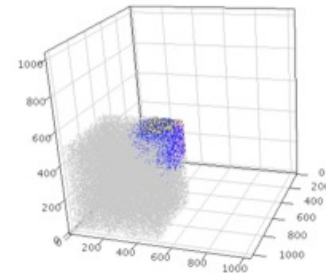
Cluster 3



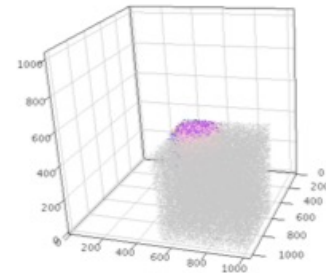
Cluster 4



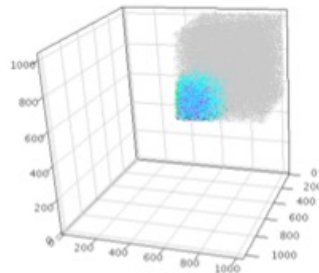
Cluster 5



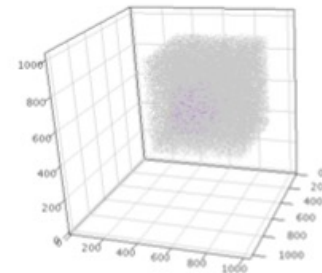
Cluster 6



Cluster 7

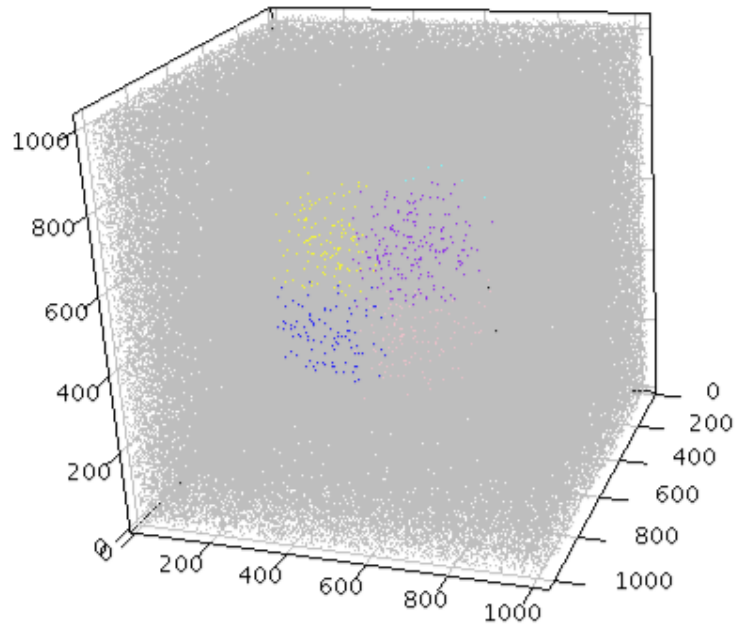


Cluster 8

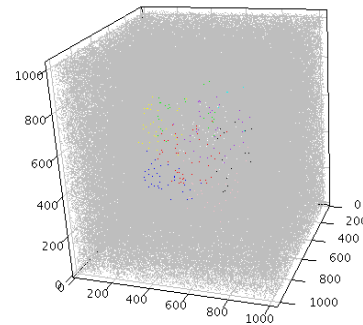


Unassigned

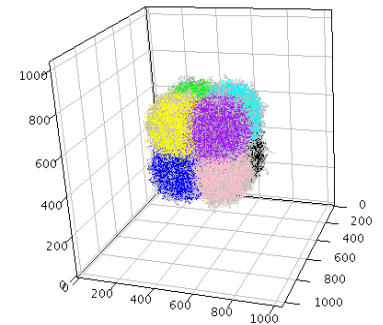
DBscan



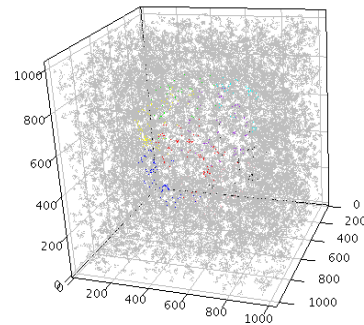
Unassigned
367' 162 points



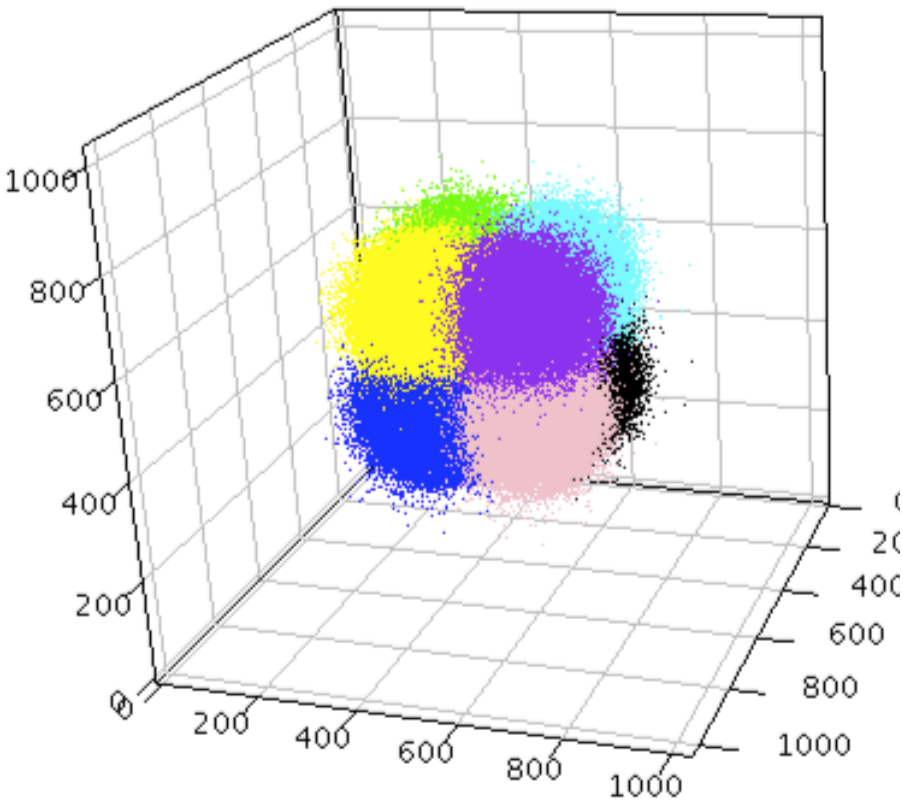
Cluster 1
1' 051' 091 points



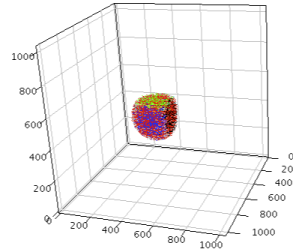
pool of 5' 346 other clusters:
81' 747 points



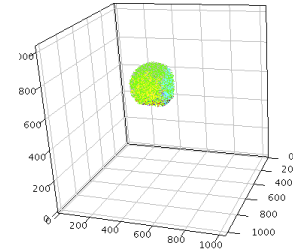
Megaclust



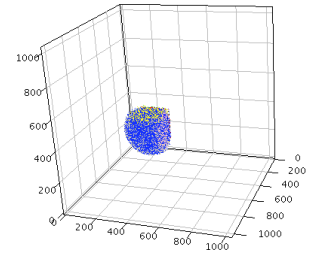
Cluster 1



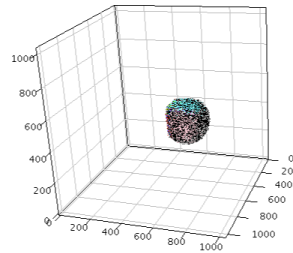
Cluster 2



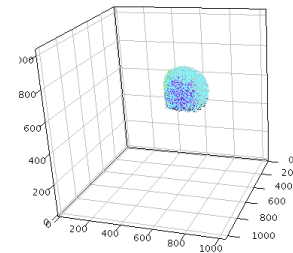
Cluster 7



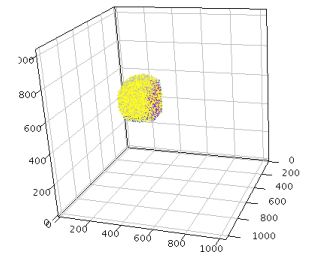
Cluster 3



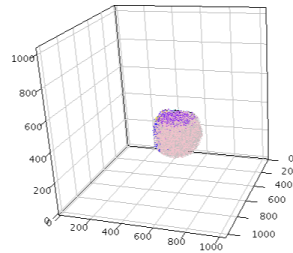
Cluster 4



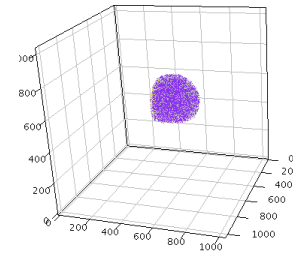
Cluster 8



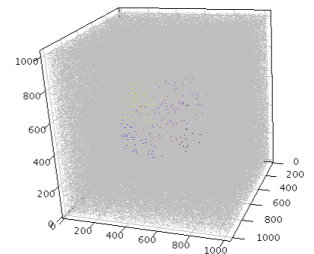
Cluster 5



Cluster 6

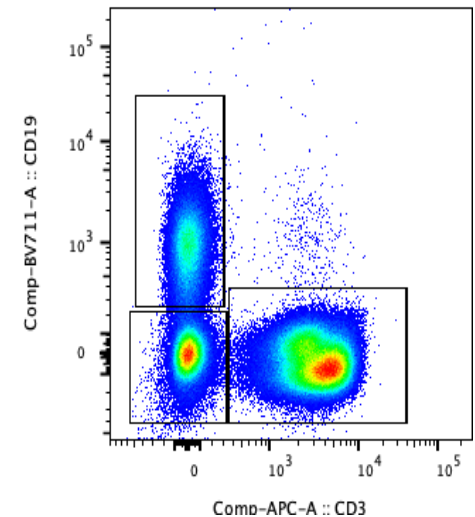


Unassigned

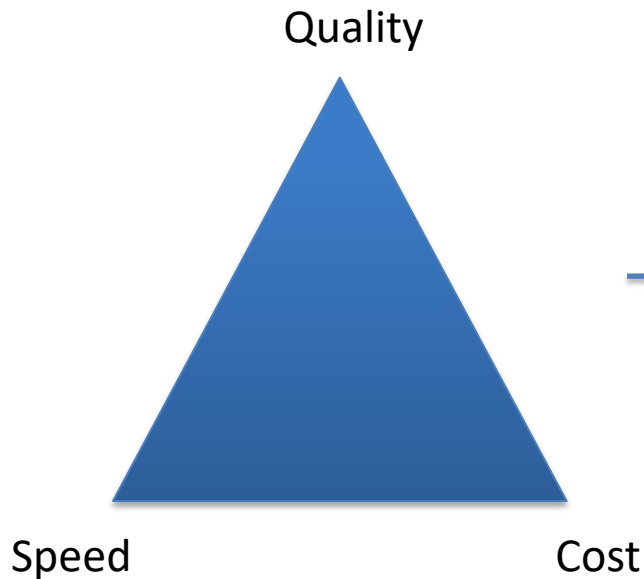


Input and parameters affecting results

- numerical range of markers
 - will each marker contribute equally to the distance metric ?
- data sampling
 - will each sample contribute equally to the cluster discovery ?
- data acquisition calibration
 - can samples be mixed in a single run ?
- input quality
 - are acquisitions stable ?



Data Analysis Tradeoffs



Practical considerations

- consider computer time
- consider human time (to code or operate)
- consider delivery time
- consider desired outcome
- consider quality *really* necessary