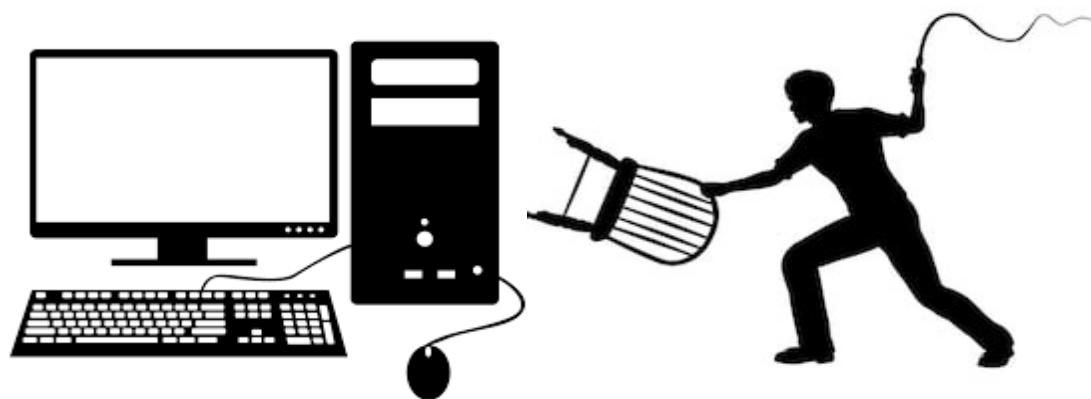


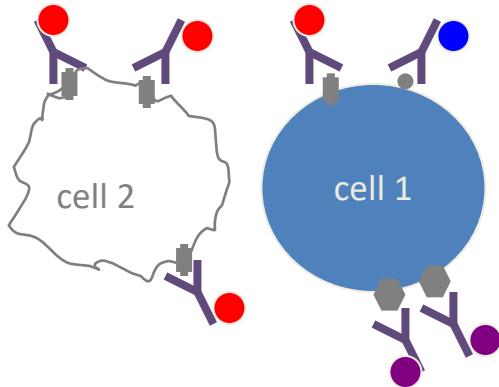
# *Bioinformatics:*

## *taming computers to make sense out of big data in biology and medicine*



Maxime Jan, Julien Dorier, Christian Iseli & Nicolas Guex

# Flow Cytometry



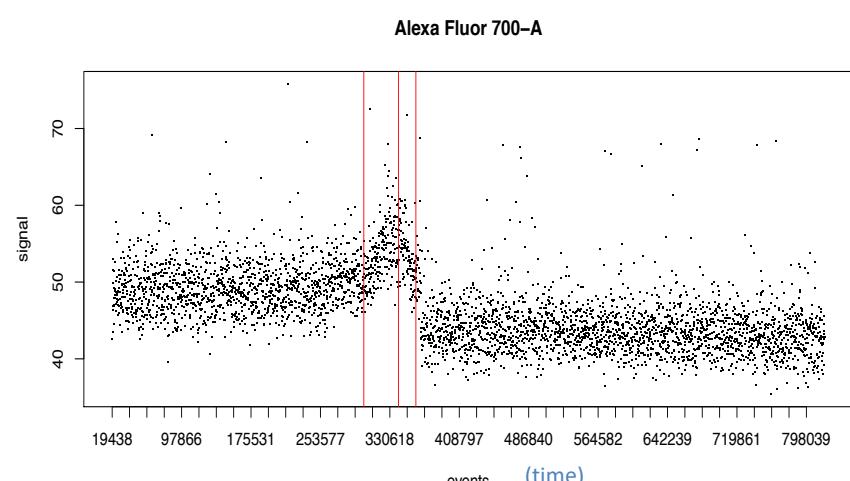
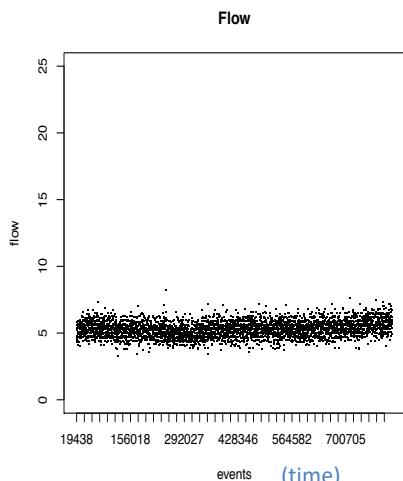
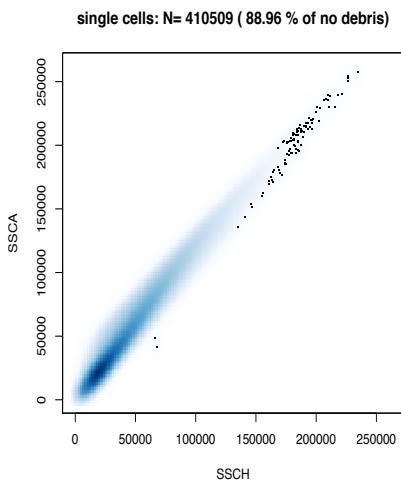
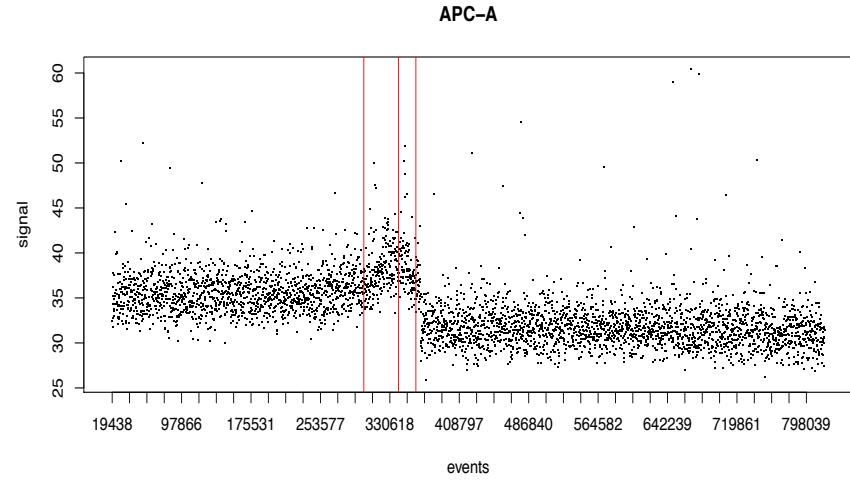
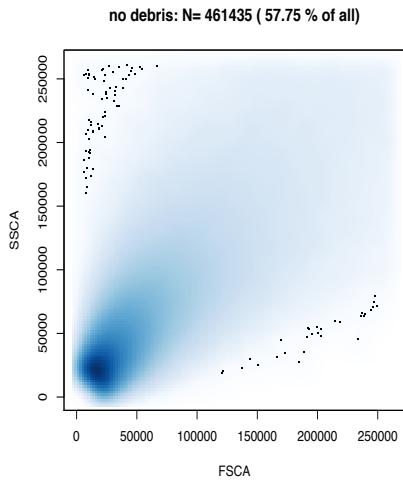
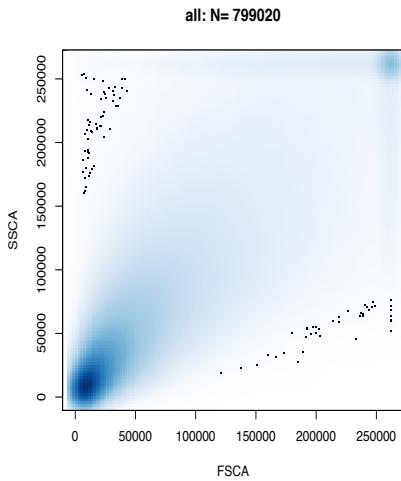
	FSC	SSC	color1	color2	color3
cell 1	100	100	100	100	200
cell 2	100	500	300	0	0
cell 3	110	100	100	90	220
cell 4	100	510	290	5	0

$$\sqrt{10^2+0^2+0^2+10^2+20^2} = 24.5$$
$$\sqrt{10^2+410^2+190^2+95^2+200^2} = 494.3$$

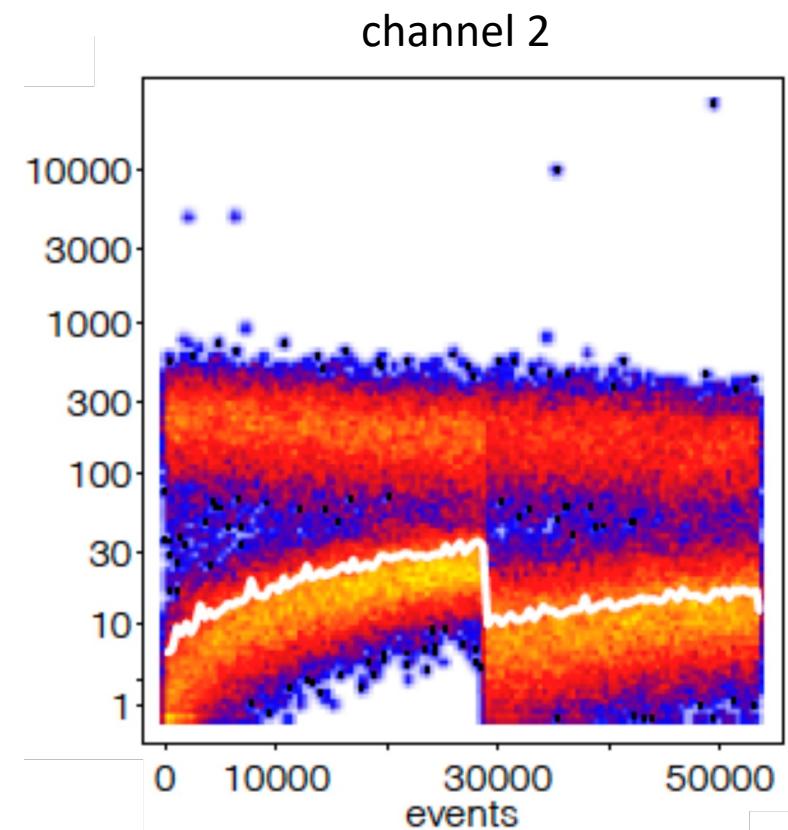
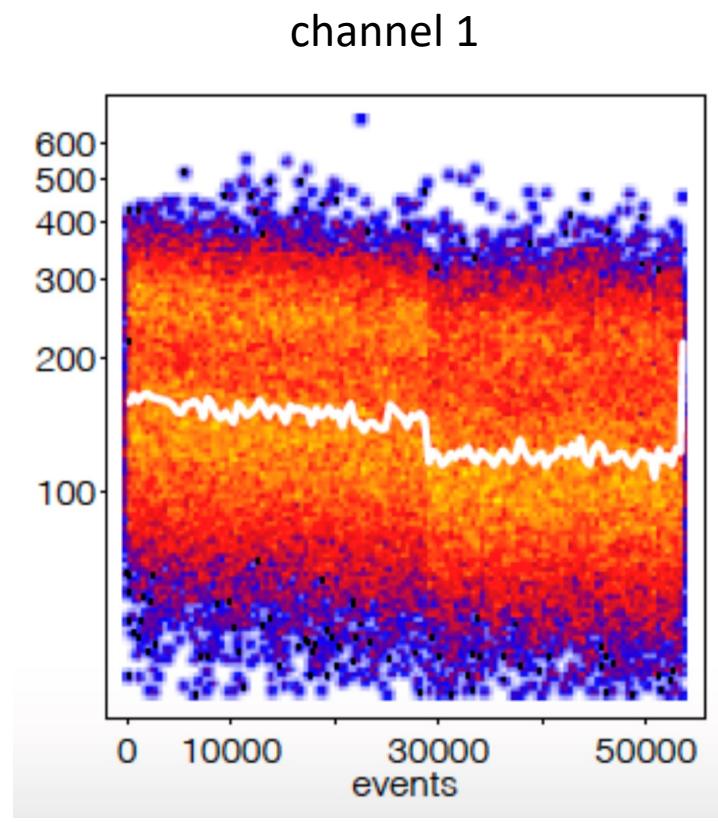
# Acquisition QC and filtering

## Debris, doublets, flow

... However, drop in intensity for few channels



# Cytof Drift

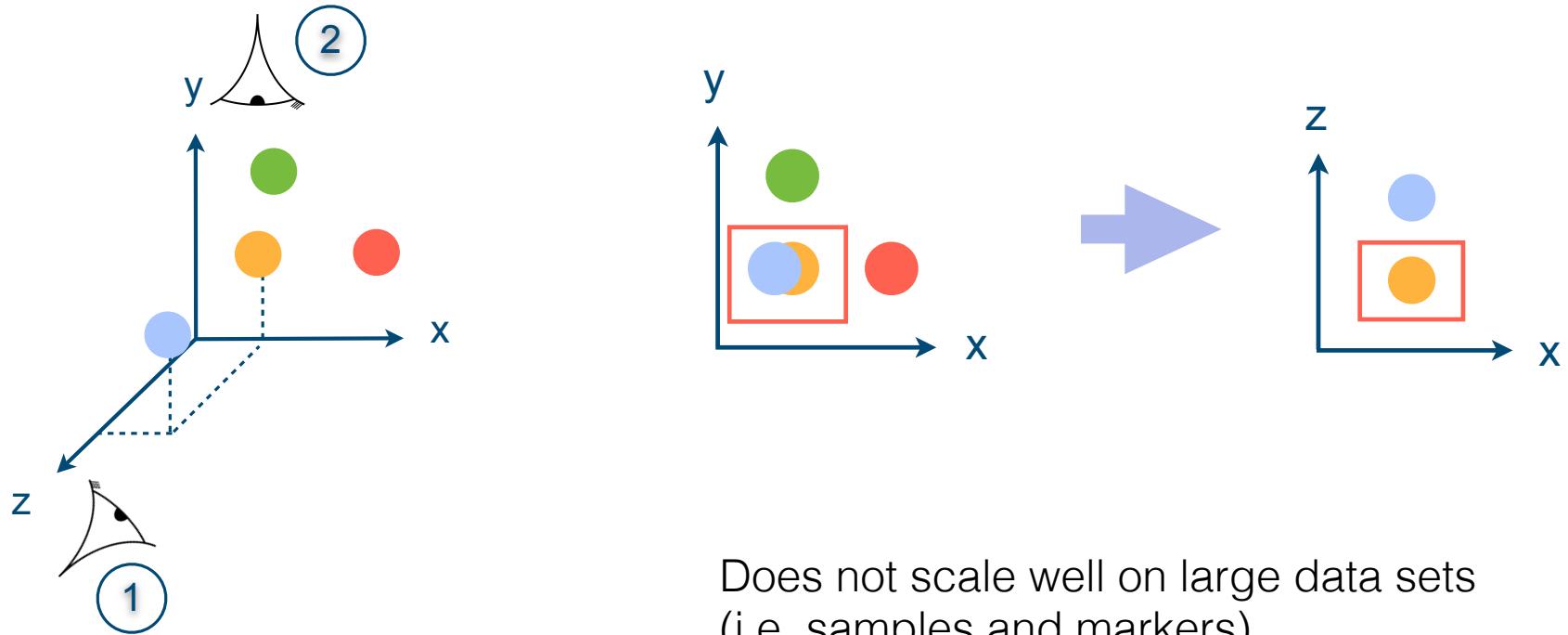


# Large scale Data Analysis

## Clustering

- applied to flow cytometry
- characteristics of various algorithms

# Manual gating uses a sequential approach to address the multidimensionality of the data



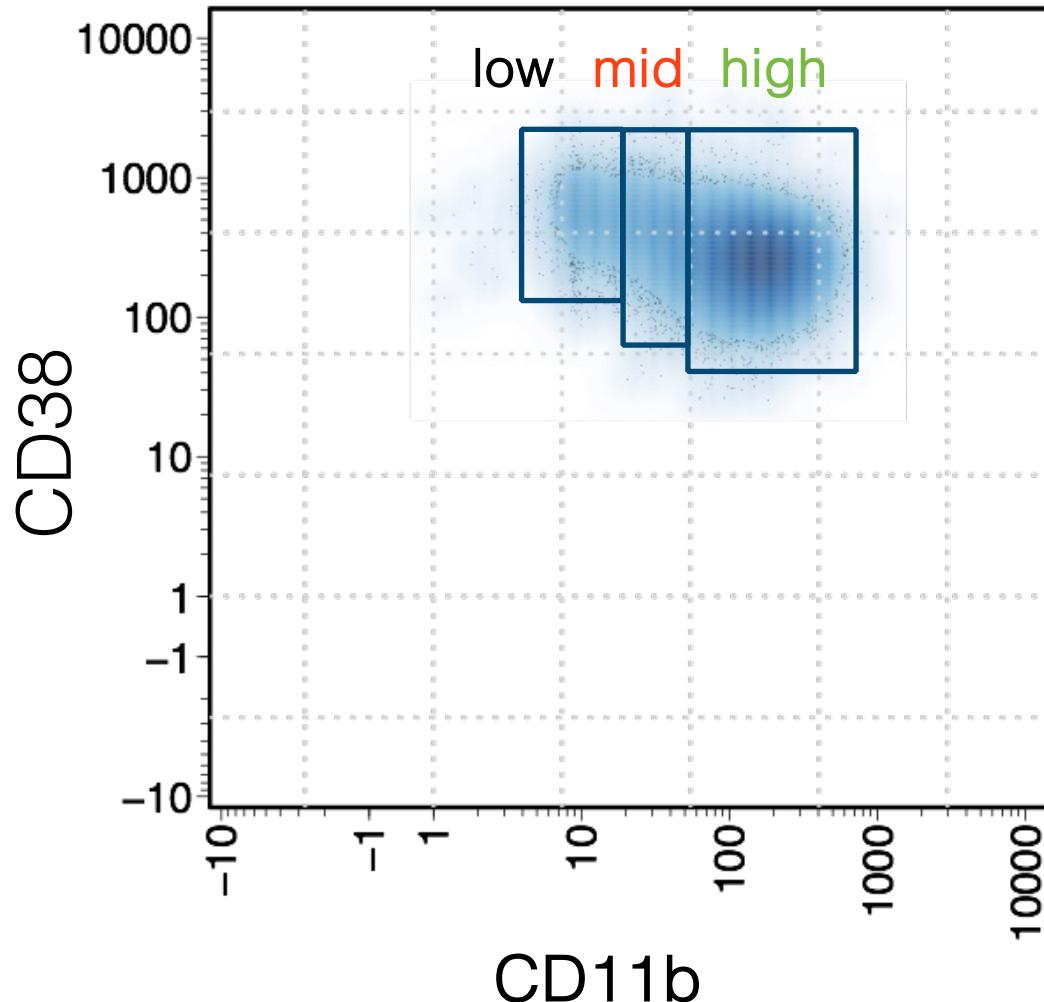
Does not scale well on large data sets  
(i.e. samples and markers)

- Sequential → inaccuracies propagate and amplify in the downstream steps

# Practical advantages of looking at all dimensions (1)

CD11b low/mid/high monocyte (sub)populations at resting state

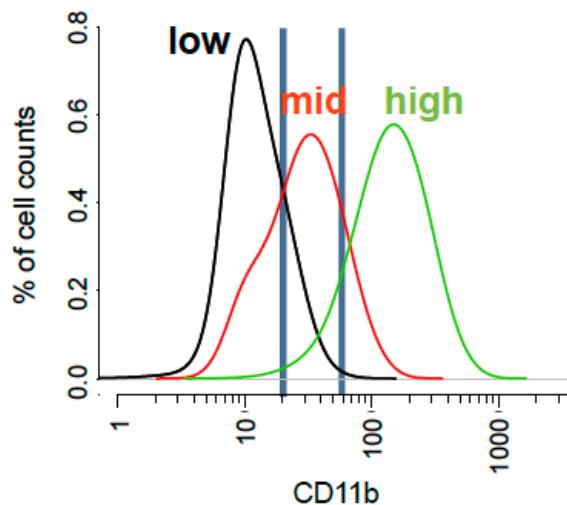
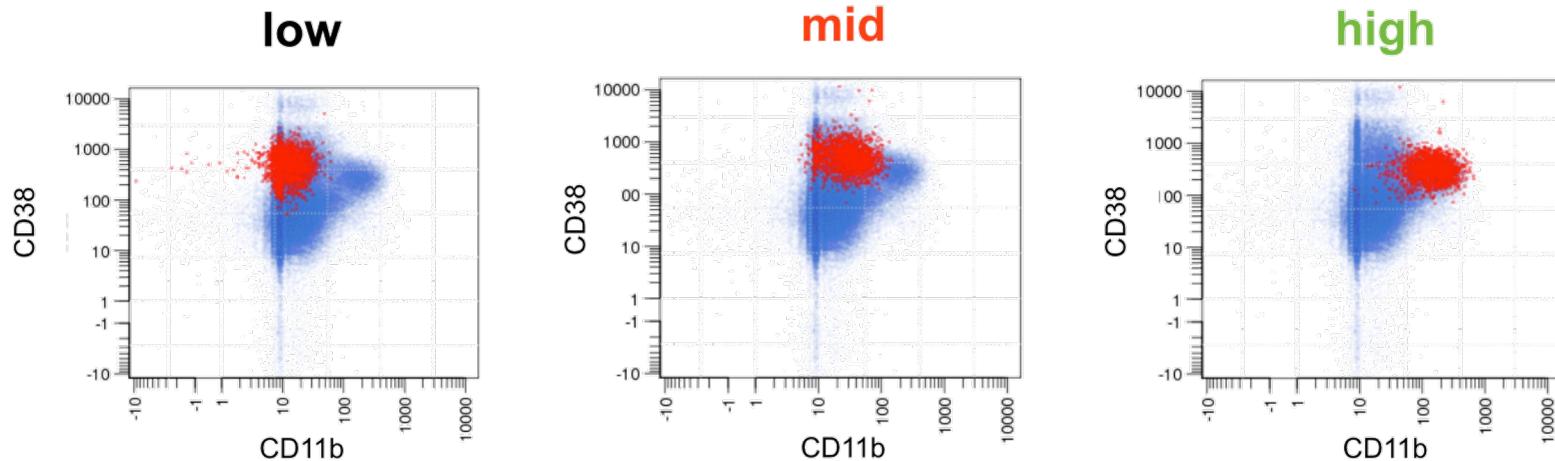
2D gating



# Practical advantages of looking at all dimensions (2)

CD11b low/mid/high monocyte (sub)populations at resting state

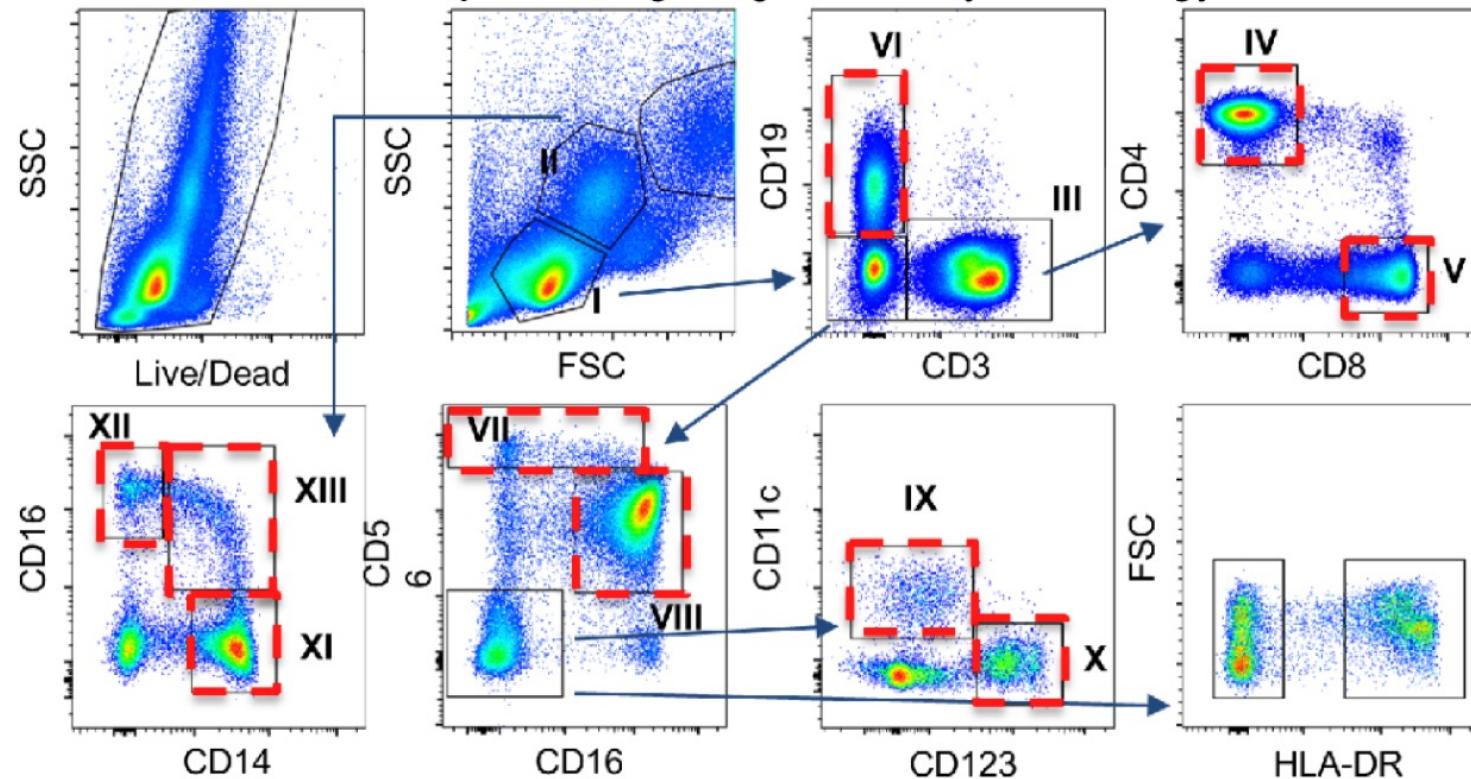
## Multi-dimensional



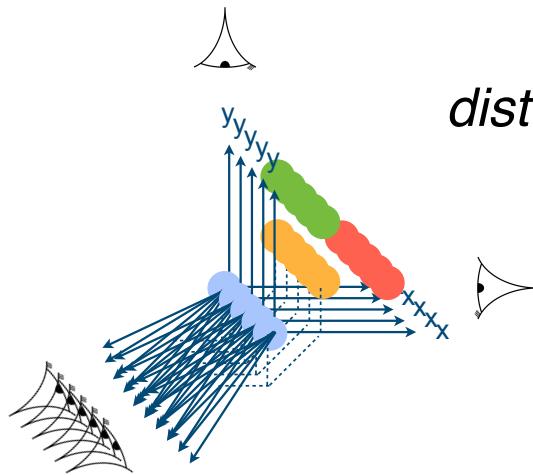
# Manual Gating Strategy

**B**

Supervised gating and analysis strategy

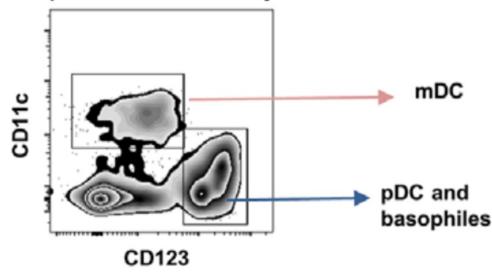


# Clustering can consider all data at the same time

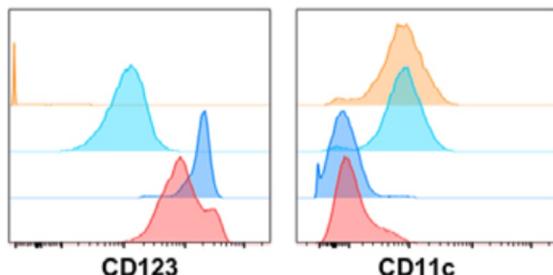


$$dist(\vec{A}, \vec{B}) = \sqrt{\sum_{i=1}^n (A_i - B_i)^2}$$

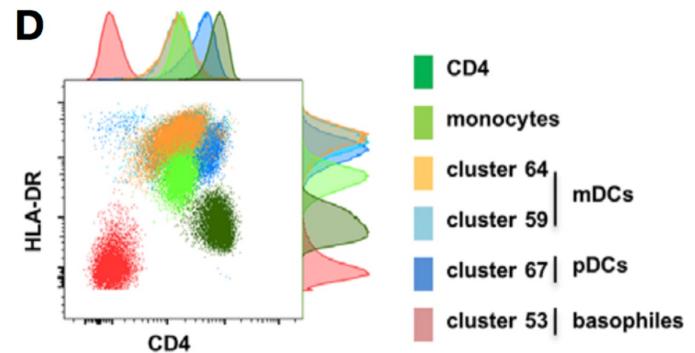
## E Supervised re-analysis



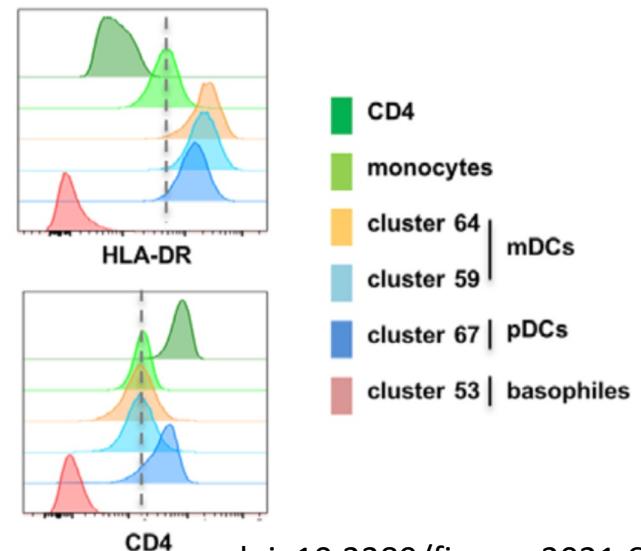
## B



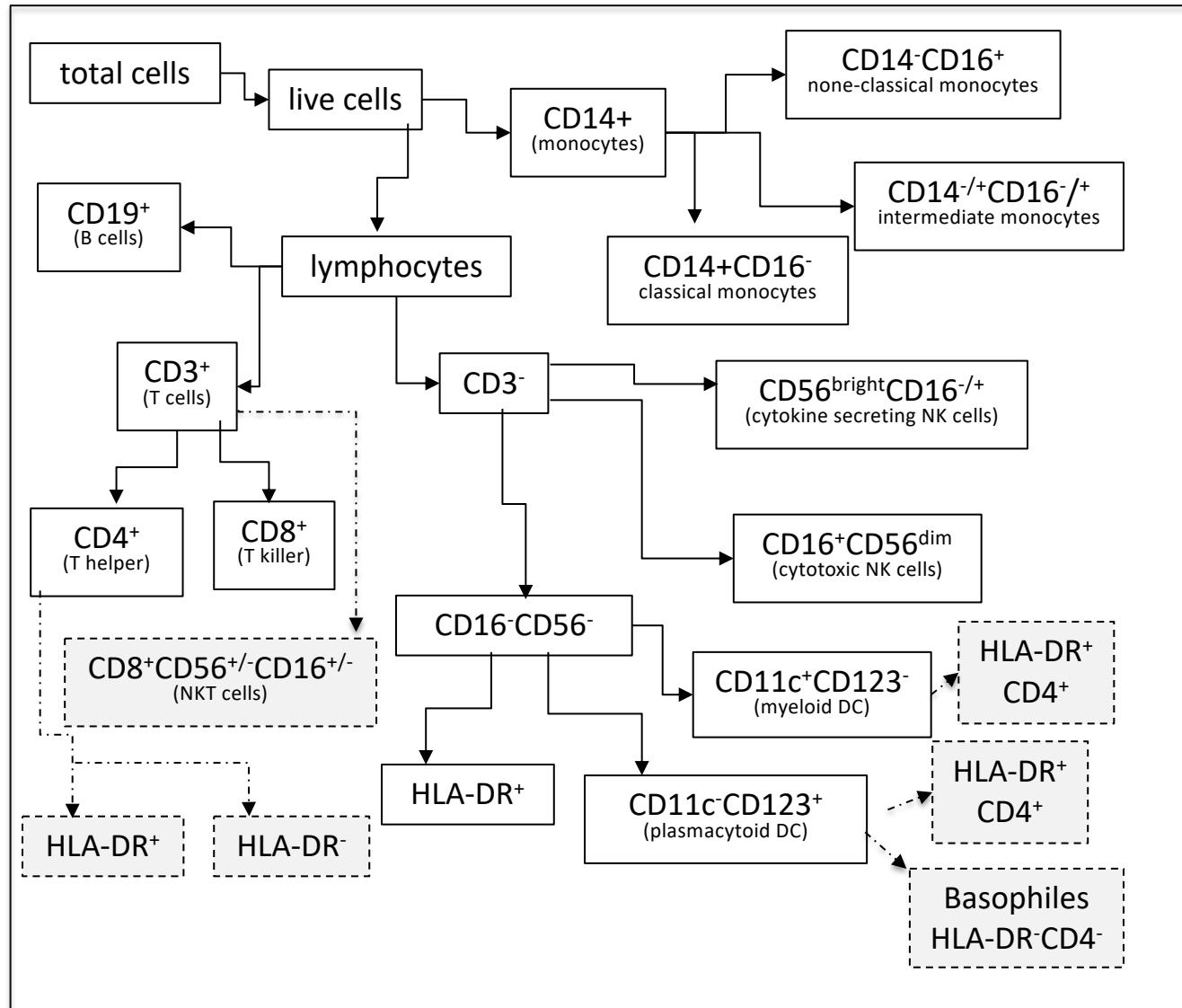
cluster 64 | mDCs  
cluster 59  
cluster 67 | pDCs  
cluster 53 | basophiles



## C



# Revised gating strategy, considering new populations



# Clustering Algorithms

Algorithm	Complexity	Robust to outliers	Order independence	User input	Mixed datatypes	Arbitrary-shaped cluster	Algorithm	Complexity	Robust to outliers	Order independence	User input	Mixed datatypes	Arbitrary-shaped cluster
<b>Partitioning (k-means)</b>													
k-Means [76]	$O(kN)$	No	No	I, I0	No	No	HIERDENC [97]	$O(N)$	Yes	Yes	—	Yes	—
Farth. First Trav. [77]	$O(Nk)$	No	No	I	Yes	No	MULIC [I4, 97]	$O(N^2)$	Yes	No	—	Yes	—
k-Medoids (PAM) [78]	$O(kN)$	Yes	No	I	No	No	DBSCAN [98]	$O(N \log N)$	Yes	Yes	3, 7	No	Yes
CLARA [79]	$O(k^2 + k(N-k))$	Yes	Yes	I	No	Yes	OPTICS [99]	$O(N \log N)$	Yes	Yes	3, 7	No	Yes
CLARANS [80]	$O(N^2)$	Yes	Yes	I	No	Yes	DENCLUE [I00]	$O(N^2)$	Yes	No	7	No	Yes
Fuzzy k-means [43, 81]	$O(kN)$	No	No	I	No	Yes	CACTUS [I01]	'Scalable'	No	Yes	I, 4	No	No
k-Modes [82]	$O(kN)$	No	No	I	No	—	STIRR [I02]	'Scalable'	No	No	I2	No	No
Fuzzy k-modes [83]	$O(kN)$	No	No	I	No	—	CLICK (categ.) [I03]	'Scalable'	No	Yes	—	No	—
Squeezer [84]	$O(kN)$	No	No	I3	Yes	No	CLOPE [I04]	$O(kdN)$	No	Yes	—	No	No
k-Prototypes [85]	$O(kN)$	No	No	I	Yes	No	WaveCluster [I05]	$O(N)$	Yes	Yes	8, 9	No	Yes
COOLCAT [86]	$O(N^2)$	No	No	I	No	No	STING [I06]	$O(N)$	Yes	Yes	—	No	No
CLICK (gene expr.) [36]	'Fast'	—	Yes	—	No	No	CLIQUE [I07]	$O(N)$	Yes	Yes	3, 8	Yes	Yes
<b>Hierarchical</b>													
Agglomerative single, average, complete-linkage [I45, I47]	$O(N^2)$ single, $O(N^2 \log N)$ average & complete	No	Yes	5, I5	Yes	Yes	SOMs (NeuralNet) [23]	$O(N^2)$	No	No	I, 2, 5	No	Yes
Eisen gene expr. [I5, 87]	$O(N^2)$ single, $O(N^2 \log N)$ average & complete	No	Yes	5	Yes	Yes	COBWEB [I08]	$O(Nd^2)$	Yes	No	—	No	—
Spectral [88, 89]	$O(N)$ (roughly)	No	Yes	5	Yes	No	BILCOM [I09]	$O(N^2)$	Yes	No	5	Yes	—
BIRCH [90]	$O(N)$	Yes	Yes	—	No	No	AutoClass (ExpMax) [I10]	$O(kd^2 Nt)$	Yes	Yes	—	Yes	Yes
CURE [91]	$O(N)$	Yes	Yes	—	No	Yes	SVM clustering [III]	$O(N^{1.8})$	No	No	—	Yes	Yes
ROCK [92]	$O(kN^2)$	No	Yes	I, I3	Yes	—	Graph-based						
Chameleon [93]	$O(N^2)$	Yes	Yes	I3	No	Yes	MCODE [I9]	$O(Nd^3)$	No	Yes	6	No	—
LIMBO [94]	$O(N \log N)$	Yes	Yes	I4	No	—	RNSC [I12]	$O(N^2)$	No	Yes	I	No	—
hMETIS [95]	'Fast'	No	Yes	5, I0	No	No	SPC [65, 70]	$O(N^2)$	Yes	Yes	I	No	Yes
Power graphs [96]	$O(Nd^2)$	Yes	Yes	5, I0, I2, I3	Yes	—	MCL [I13]	$O(N^3)$	Yes	Yes	II	No	—

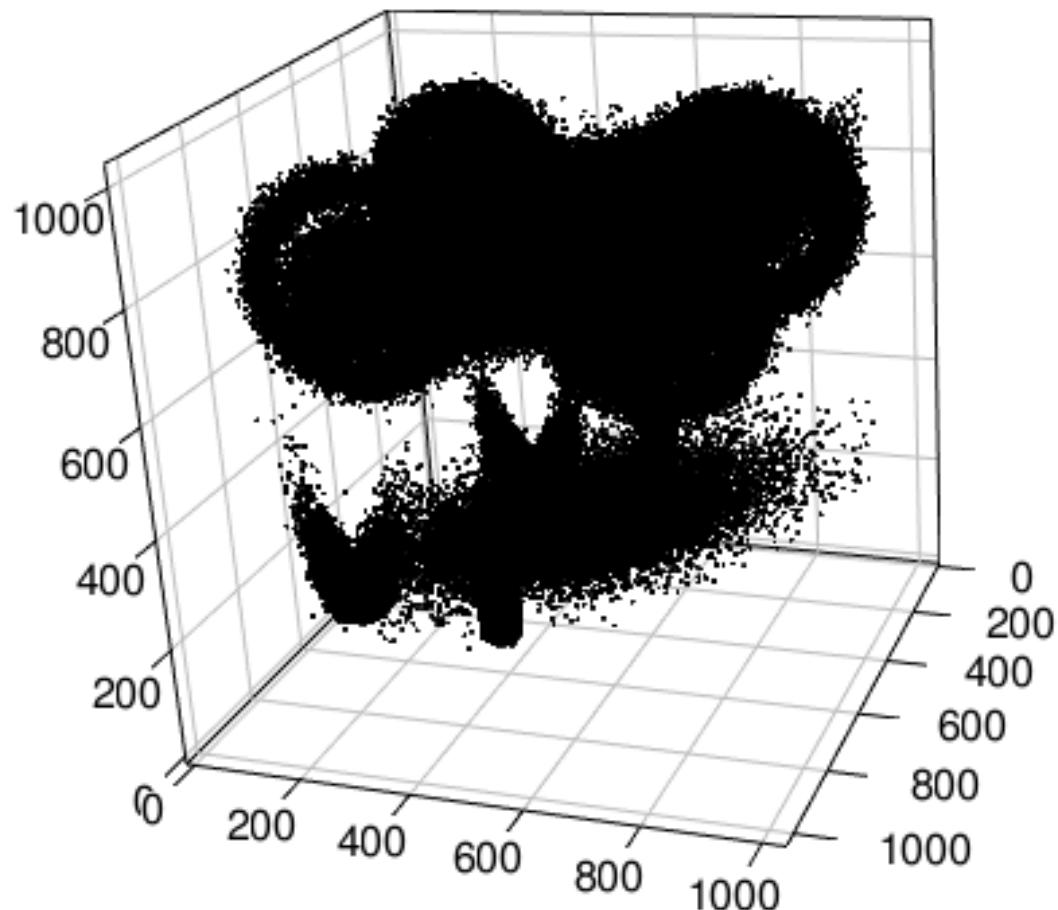
Source: A roadmap of clustering algorithms: finding a match for a biomedical application  
 B.Andreopoulos et al; Briefings in Bioinformatics (2009) VOL 10. NO 3. 297-314

# Clustering Wishlist

- Unaffected by the order in which the data are presented
- Not assume any specific cluster shape
- Proper separation of overlapping distributions
- Automatically discover the “ideal” number of clusters
- Resistant to noise (e.g. not assign outliers in clusters)
- Capable of clustering millions of observations

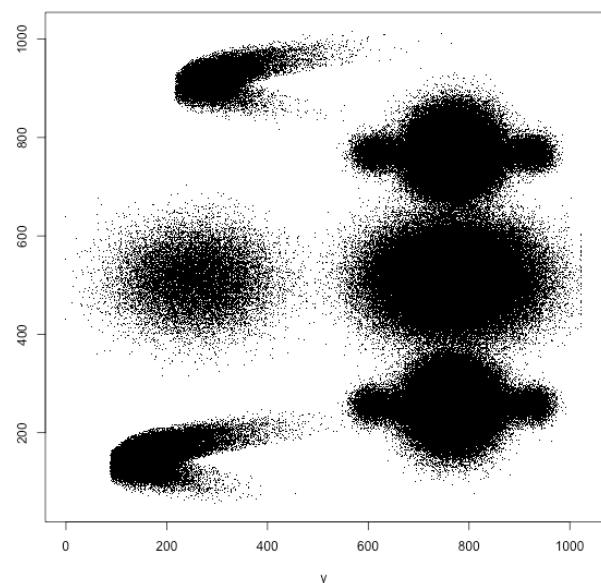
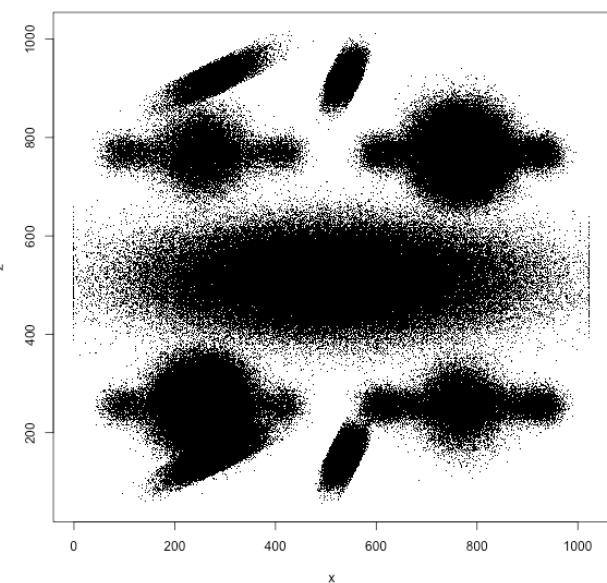
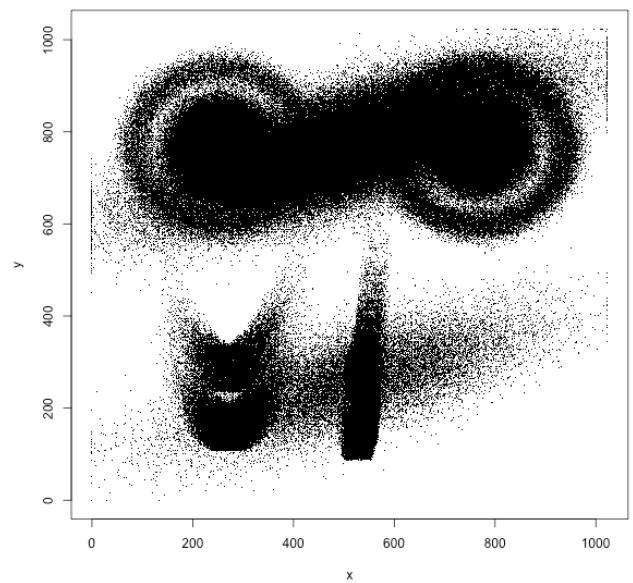
# Tests with synthetic data

comprising a total of 799,956 points



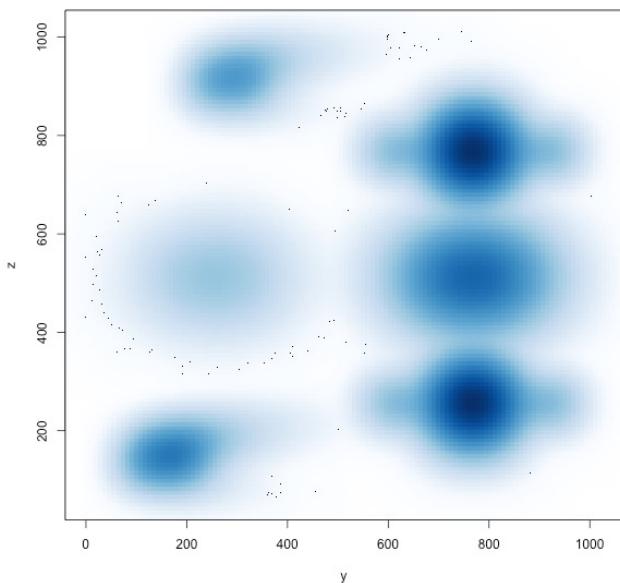
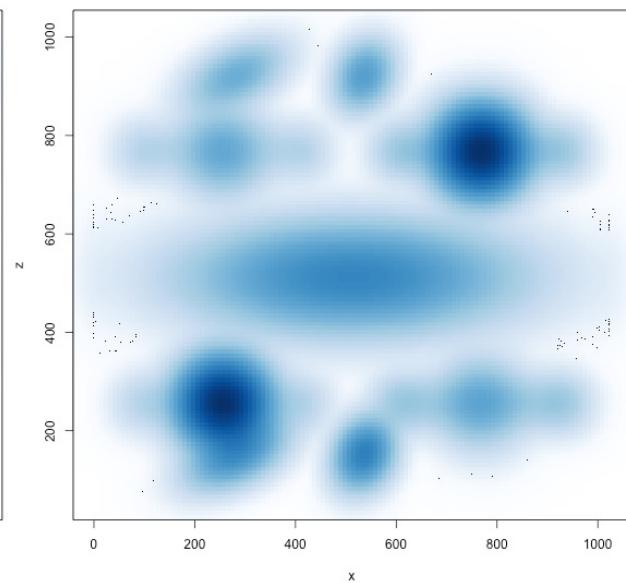
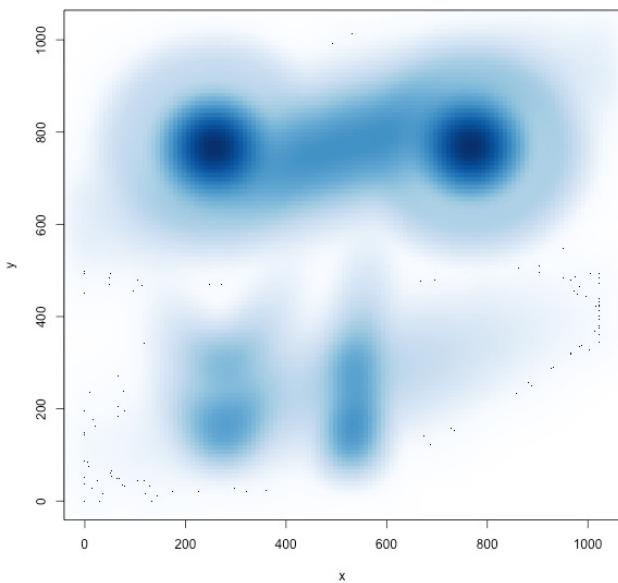
# Tests with synthetic data

comprising a total of 799,956 points



# Tests with synthetic data

comprising a total of 799,956 points



# Tests with synthetic data

**INPUT: 14 shapes, comprising a total of 799,956 points**

Spheres 1 (blue) and 4 (dark blue) and ellipse 1 (yellow) have 200,000 points

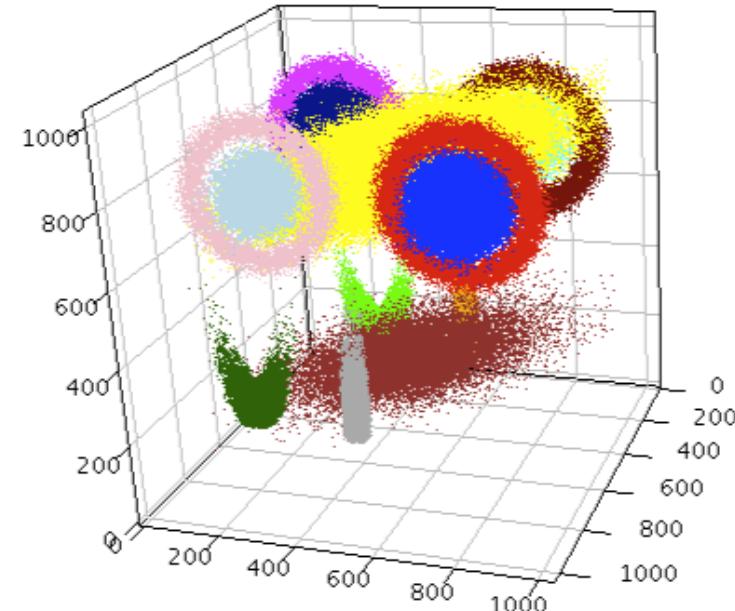
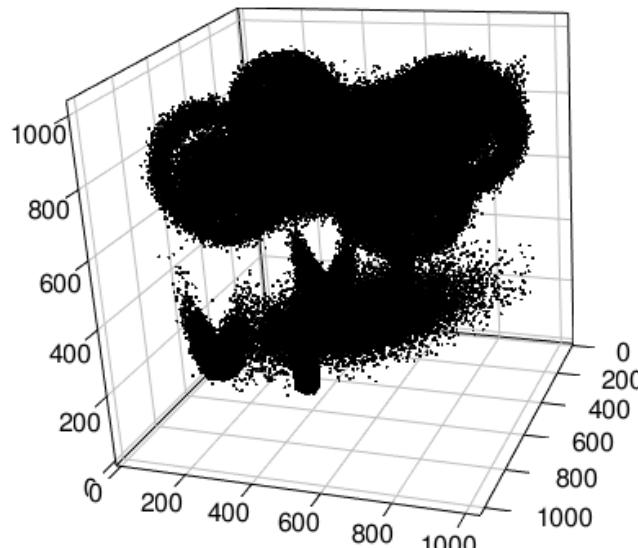
Spheres 2 (cyan) and 3 (light blue) and ellipse 2 (brown) have 20,000 points

Tores 1 (red) and 2 (dark red) have 16,652 points

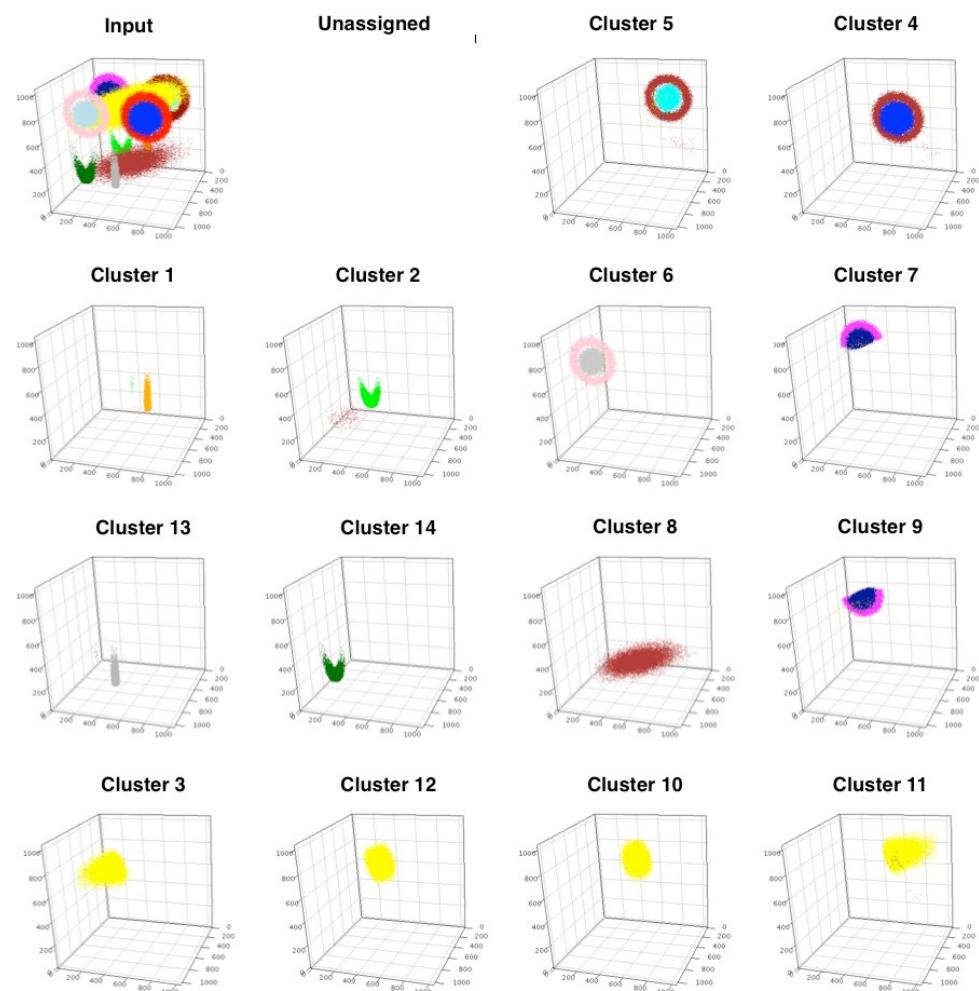
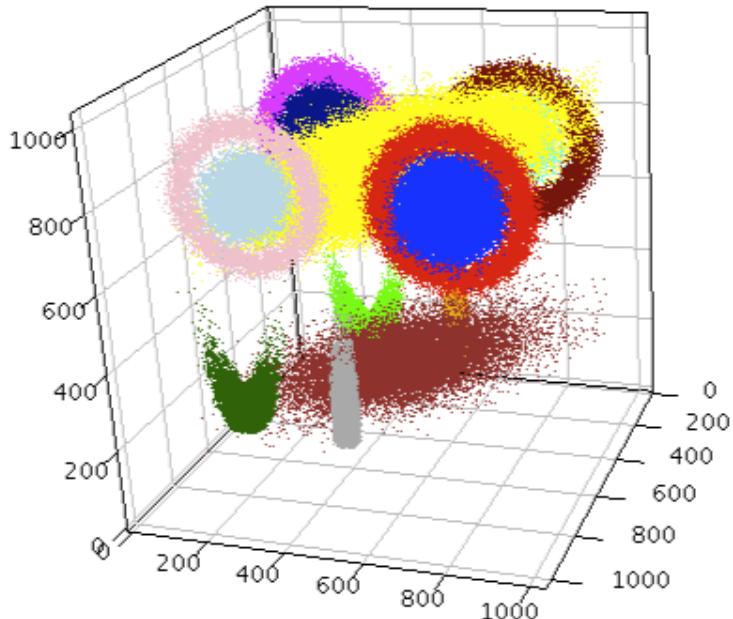
Tores 3 (pink) and 4 (magenta) have 8,326 points

Bananas 1 (green) and 2 (orange) have 30,000 points and different curvatures

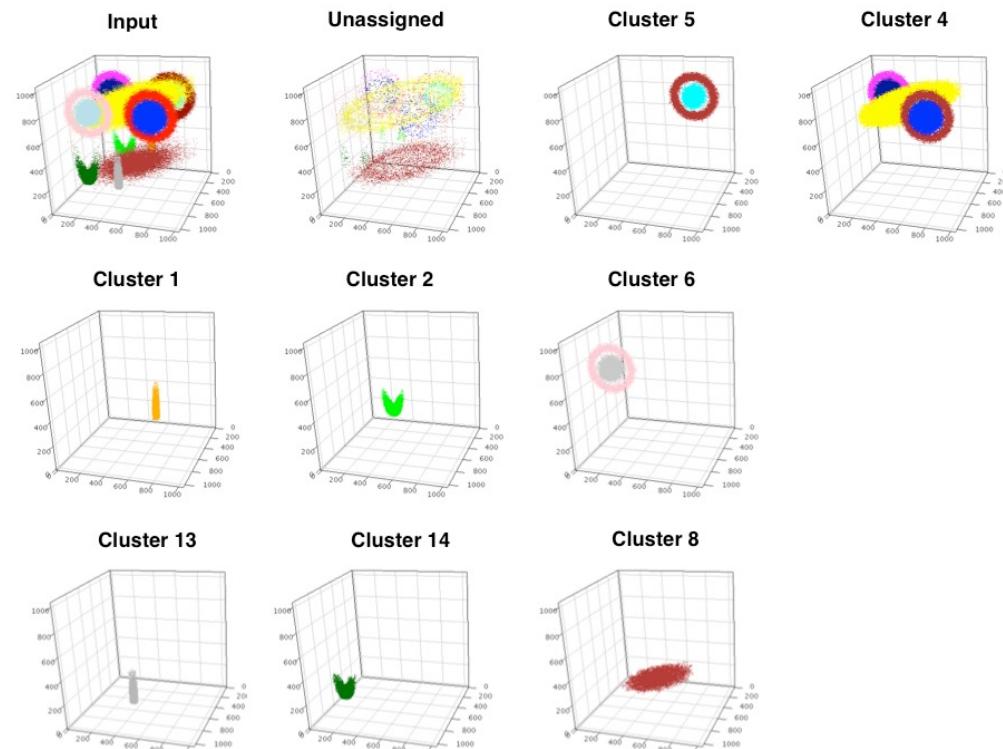
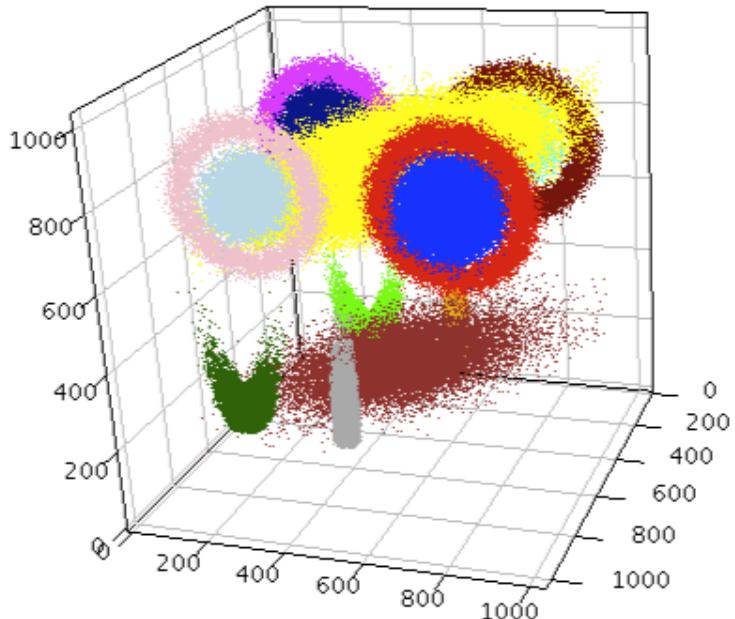
Bananas 3 (dark green) and 4 (dark grey) have 15,000 points and different curvatures



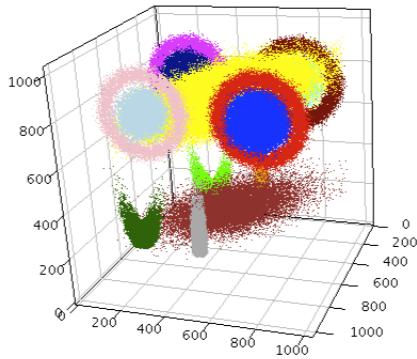
# K - mean



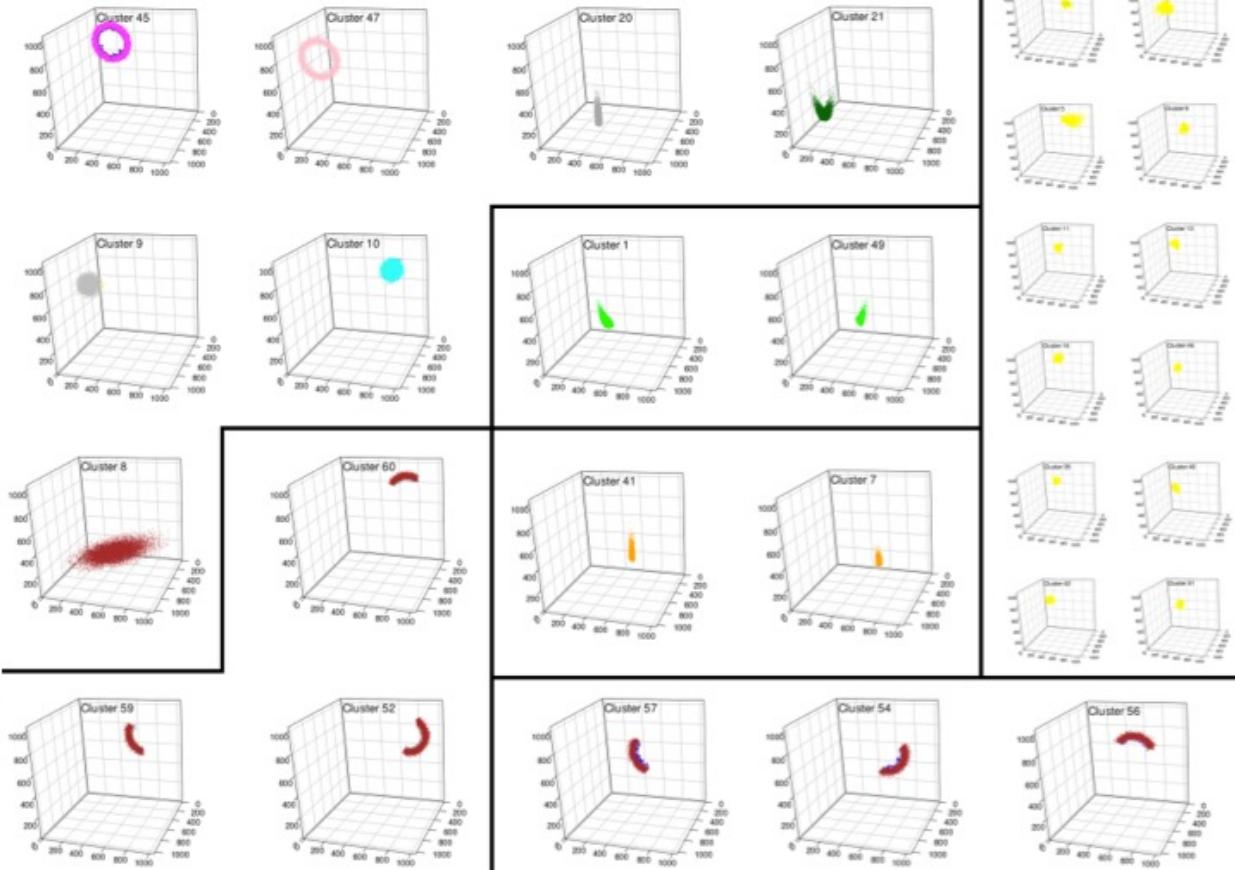
# DBscan



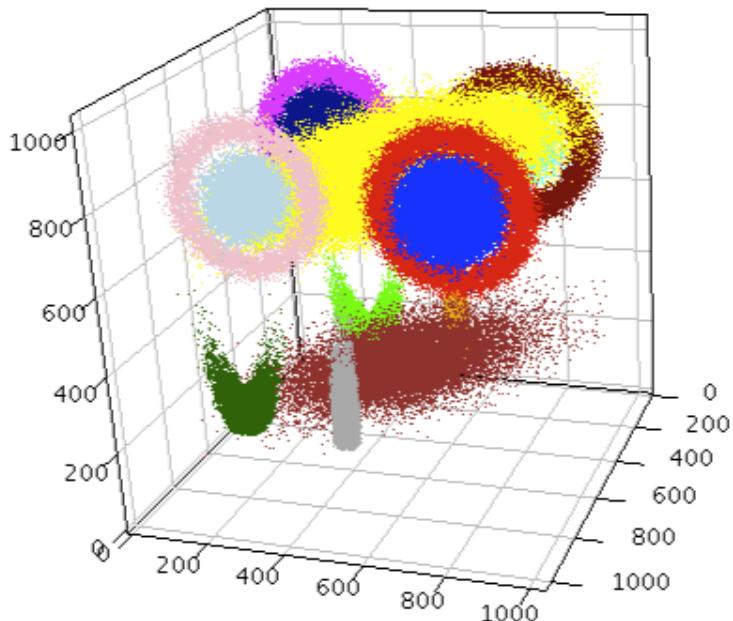
# Phenograph



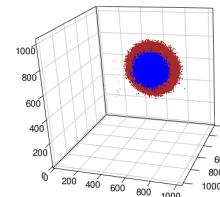
- Identified 61 clusters
- Correctly identified 7 out of 14 shapes
- Oversplit the others
- Dense spheres each split in 16 clusters



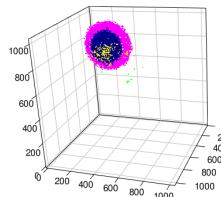
# FlowSOM (run #1)



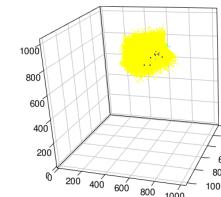
cluster 1



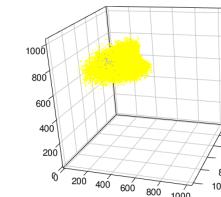
cluster 2



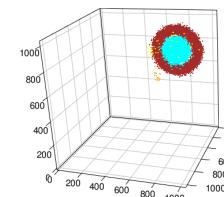
cluster 3



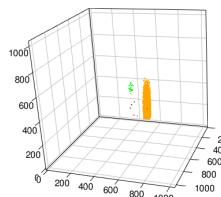
cluster 4



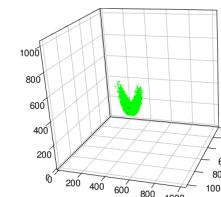
cluster 5



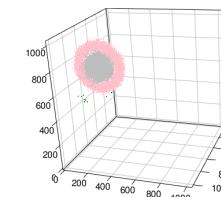
cluster 6



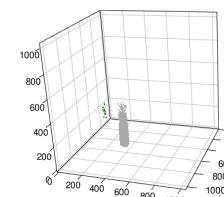
cluster 7



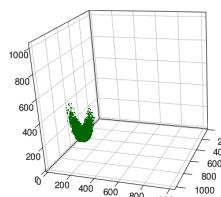
cluster 8



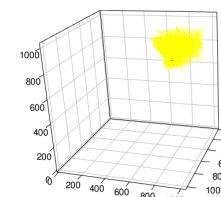
cluster 9



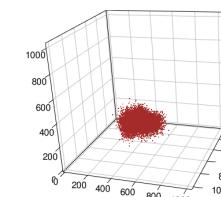
cluster 10



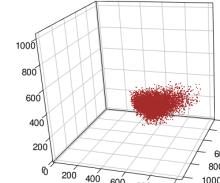
cluster 11



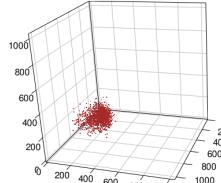
cluster 12



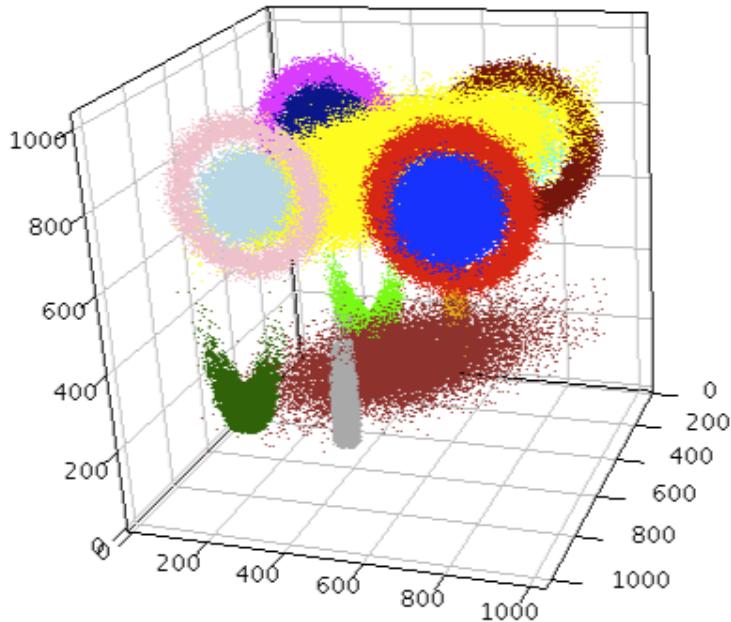
cluster 13



cluster 14

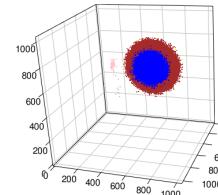


# FlowSOM (run #2)

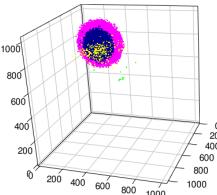


RUN #1	RUN #2
216882	216964
208557	208644
111741	130095
74487	54045
36688	36772
30008	29998
29967	29967
28328	28223
15014	16856
14968	15270
13325	15024
10927	14957
7428	1623
1635	1518

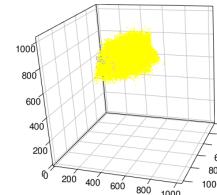
cluster 1



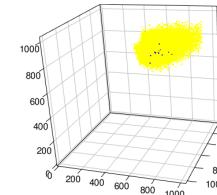
cluster 2



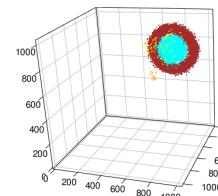
cluster 3



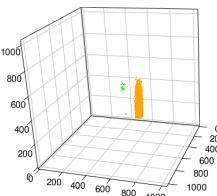
cluster 4



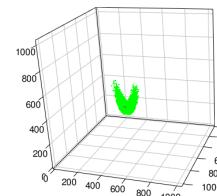
cluster 5



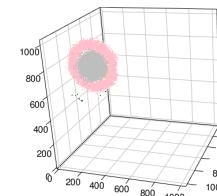
cluster 6



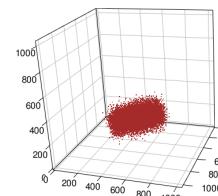
cluster 7



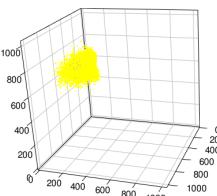
cluster 8



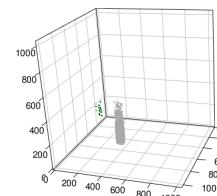
cluster 9



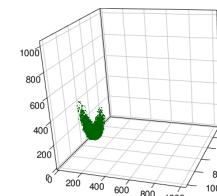
cluster 10



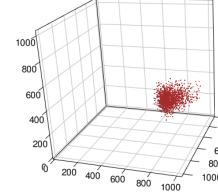
cluster 11



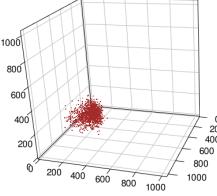
cluster 12



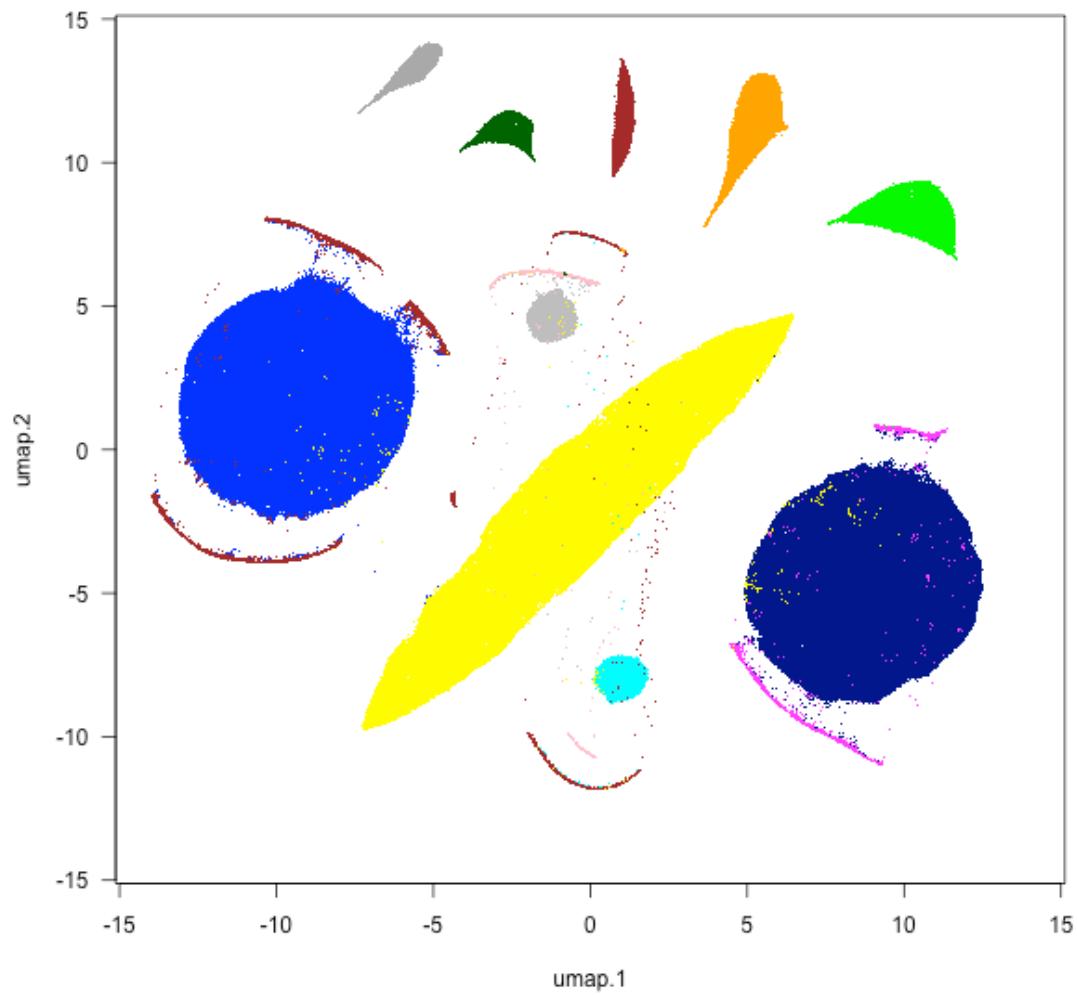
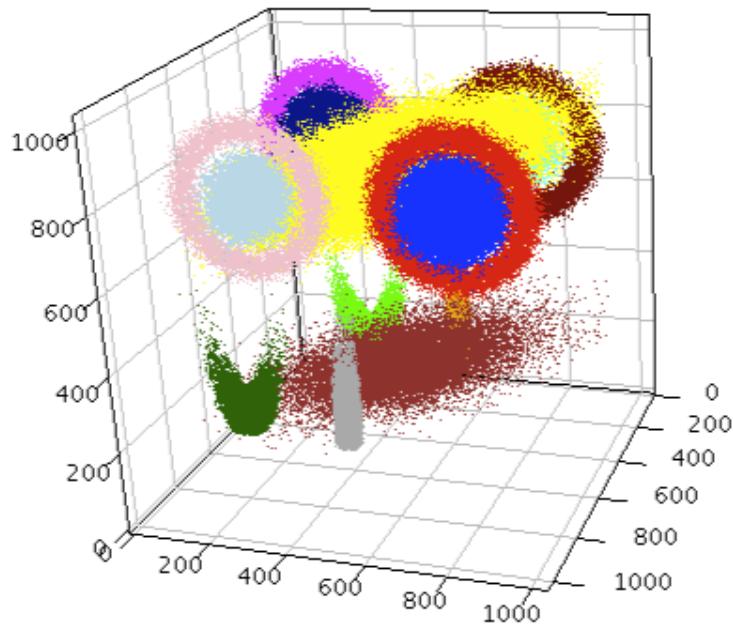
cluster 13



cluster 14

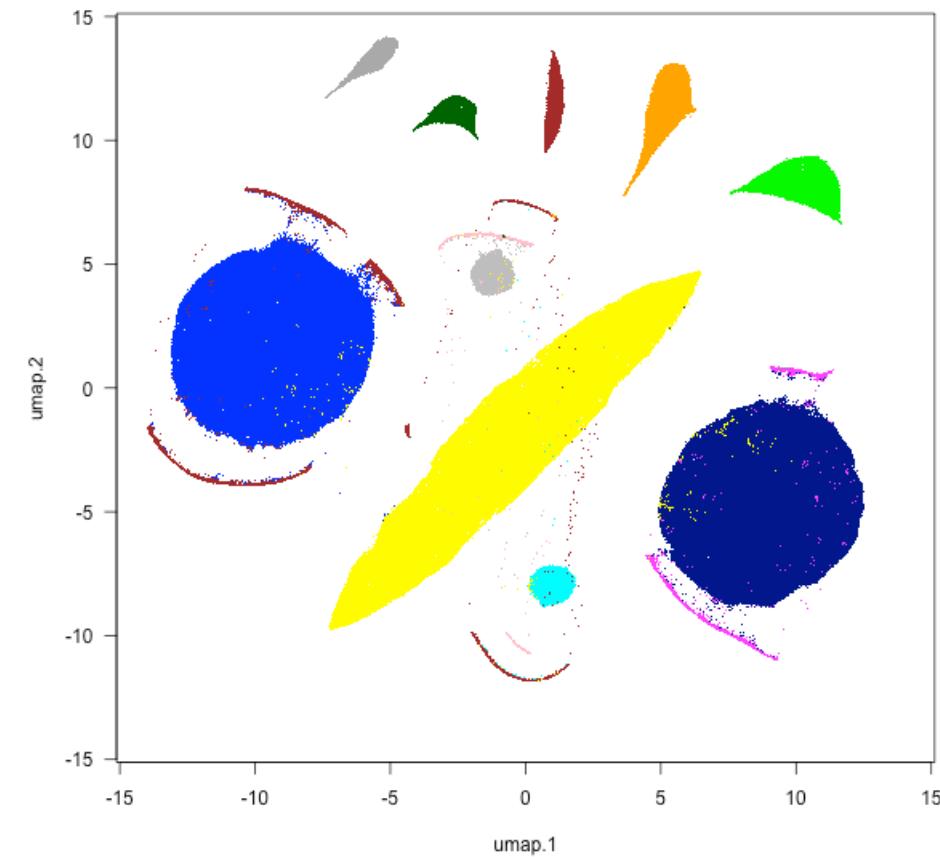


# small parenthesis : UMAP

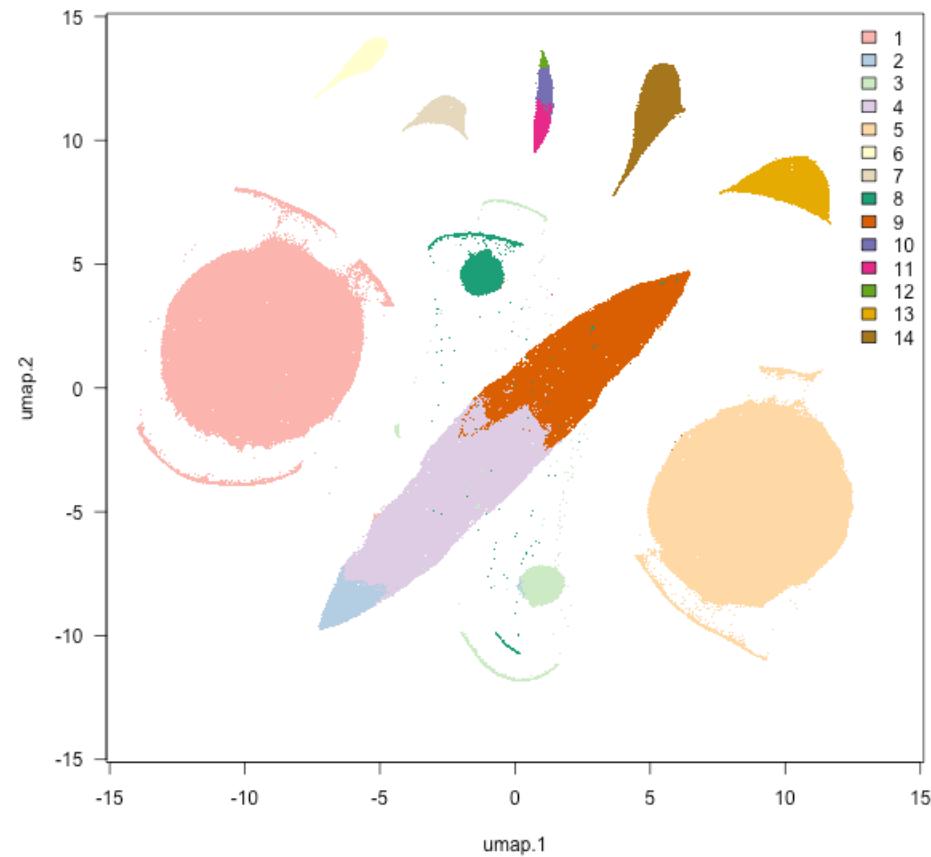


# small parenthesis : UMAP

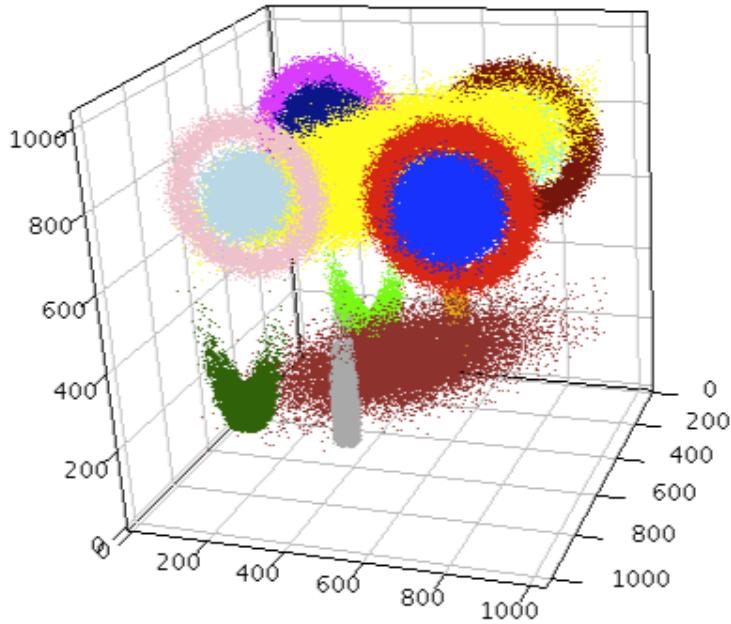
3D Gold Standard Projected in 2D



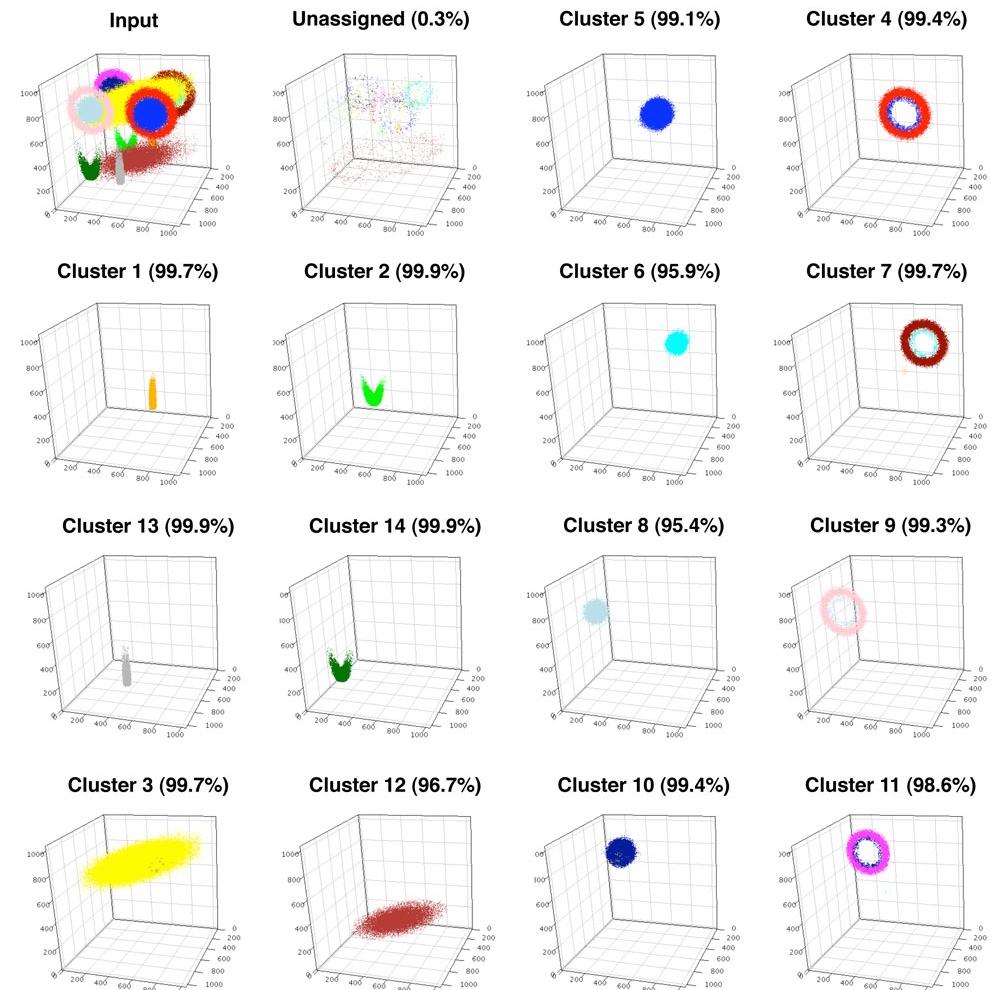
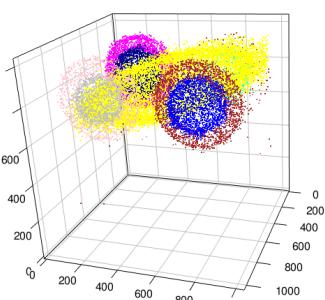
FlowSOM run #1 clusters



# Megaclust / hdbscan



hdbscan unassigned (3%)



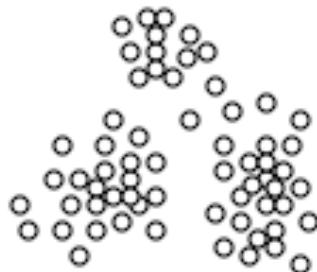
# Hierarchical Clustering

- Number of Computations
- Memory

$$1e6 * 1e6 * 4 = 4Tb$$

<b>observations</b>	<b>computation</b>	<b>time</b>
10	50	60 us
100	5000	6 ms
1000	500000	600 ms
10000	50000000	1 mn
100000	5000000000	1 h 40 mn
1000000	500000000000	7 days

- Parallelization

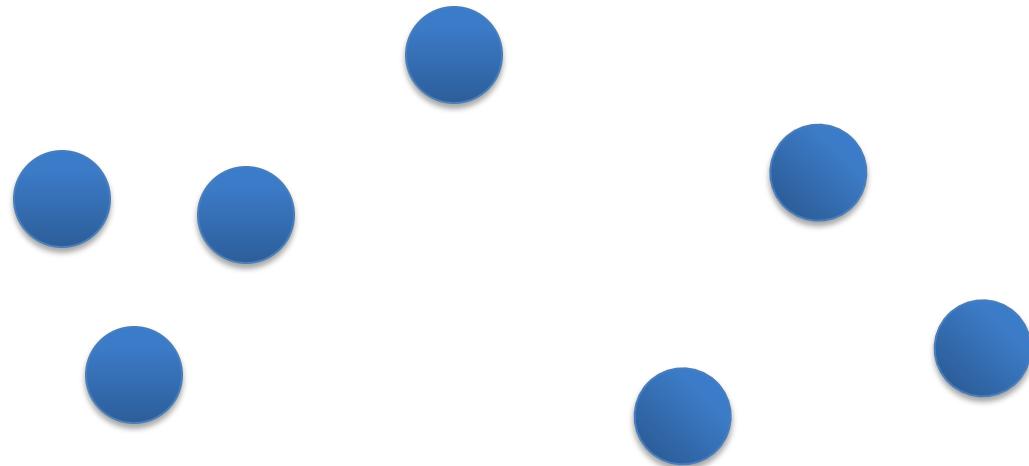


# Density-based hierarchical clustering

- Compute all pairwise distances and retain only those that are equal or smaller than a given distance threshold  $T$
- A cluster is formed by single linkage and retained if it contains at least  $N$  points. Clusters too small are ignored
- Hierarchical clustering is obtained by repeating the clustering for increasing distance thresholds

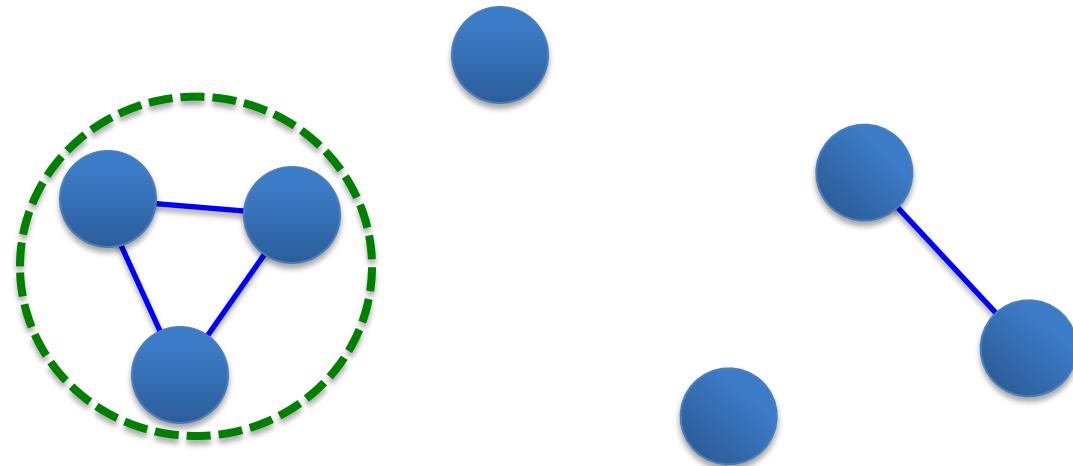
$T$  from  $T_{min}$  to  $T_{max}$  in  $s$  steps

# Density-based hierarchical clustering



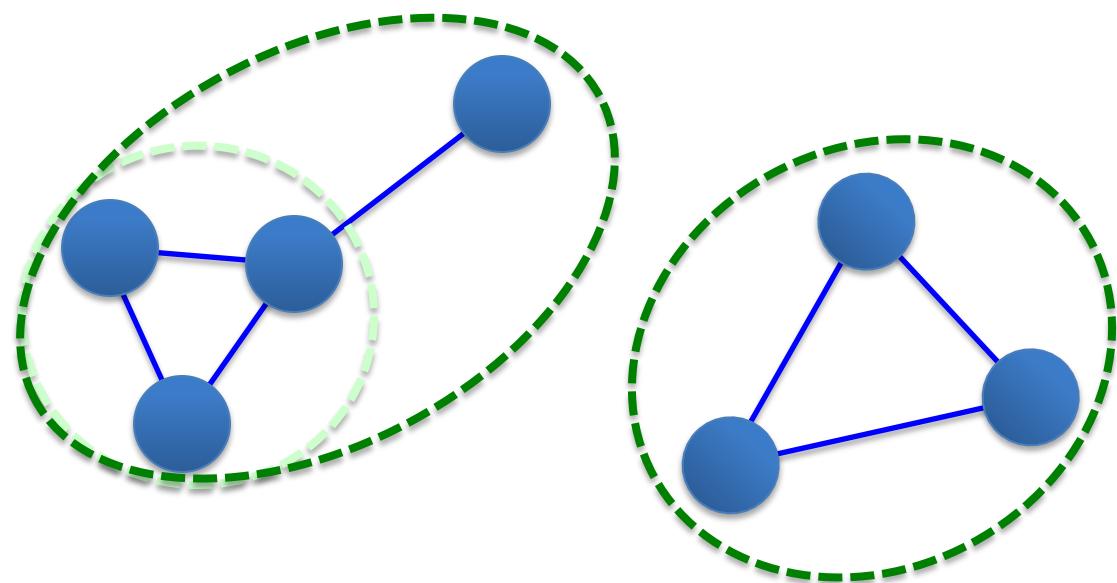
# Density-based hierarchical clustering

- $D \leq 1$  and  $N \geq 3$



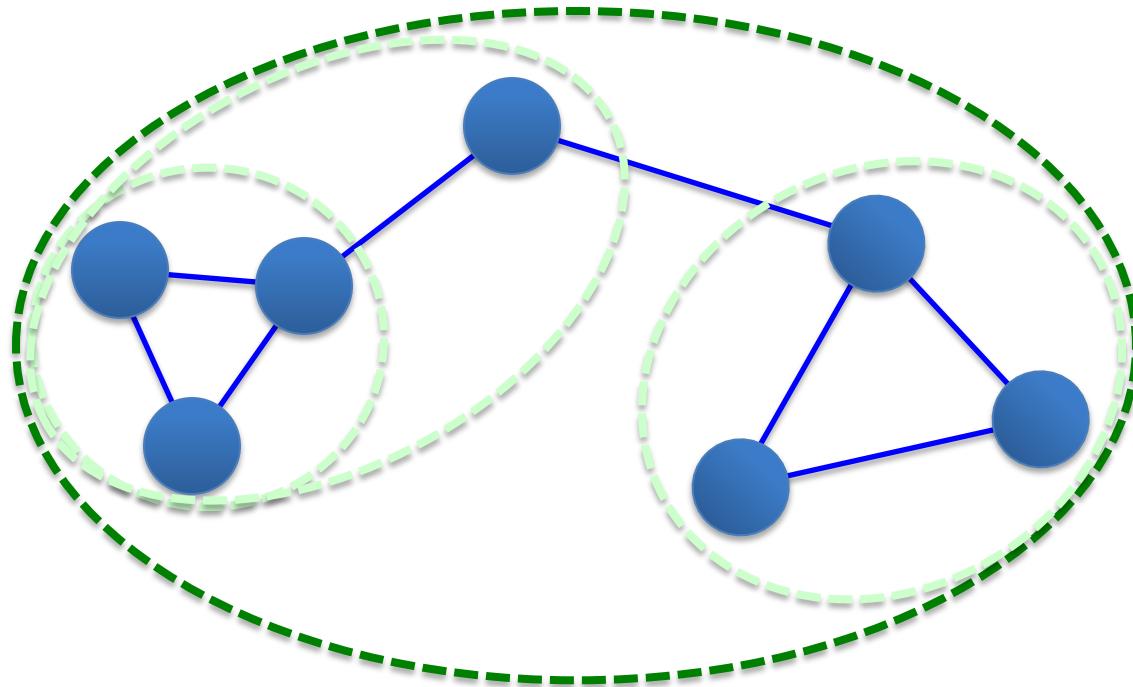
# Density-based hierarchical clustering

- $D \leq 2$  and  $N \geq 3$

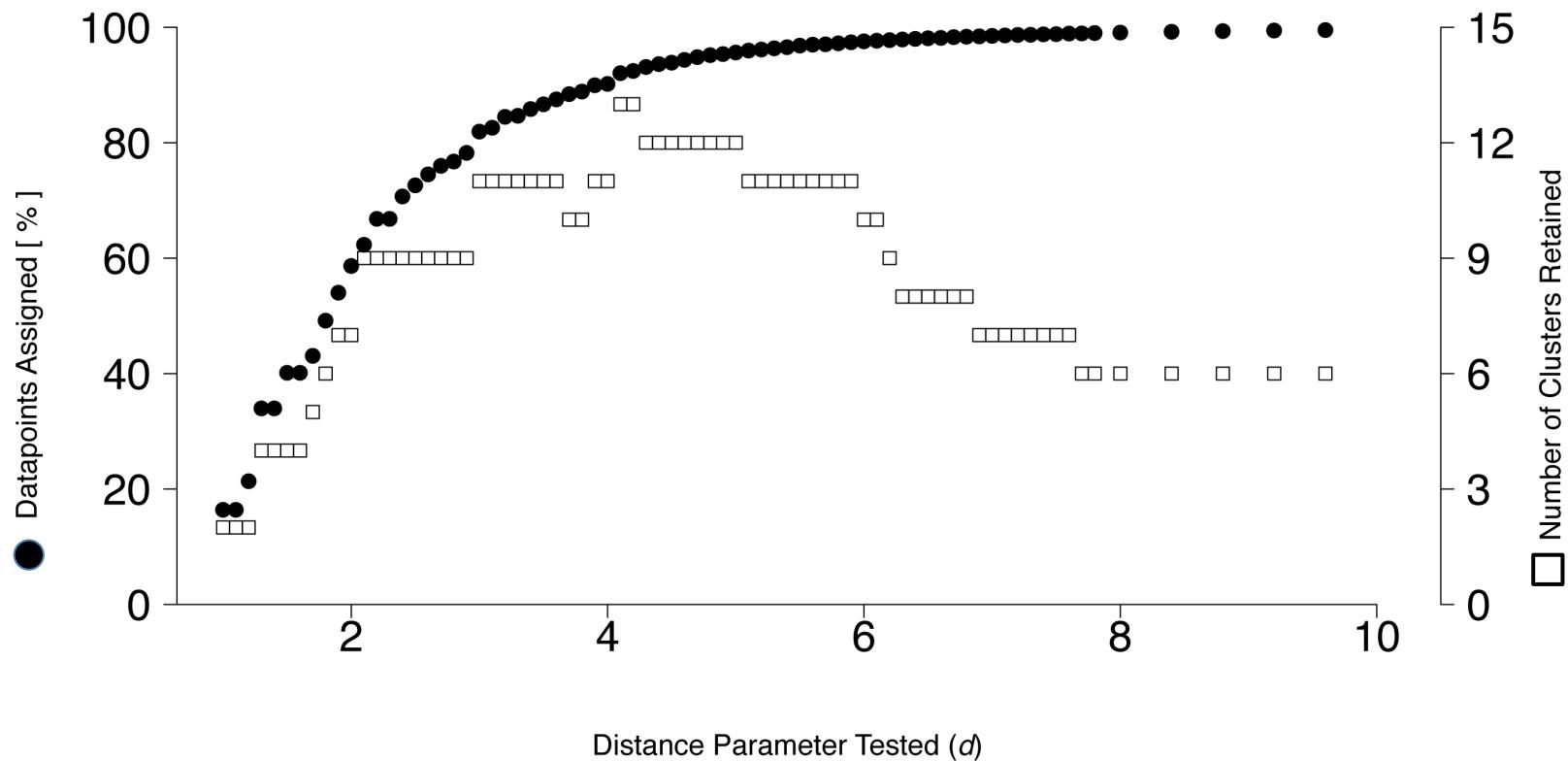


# Density-based hierarchical clustering

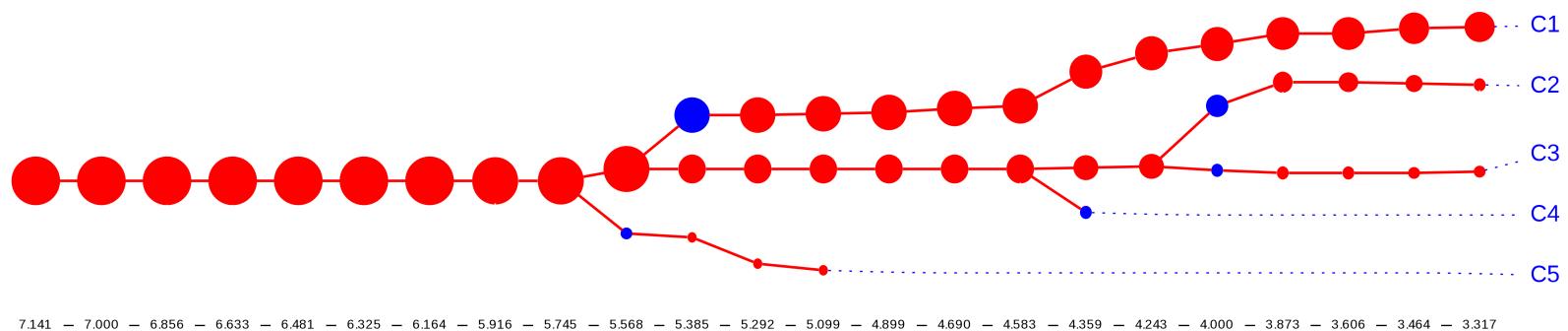
- $D \leq 3$  and  $N \geq 3$



# Density-based hierarchical clustering

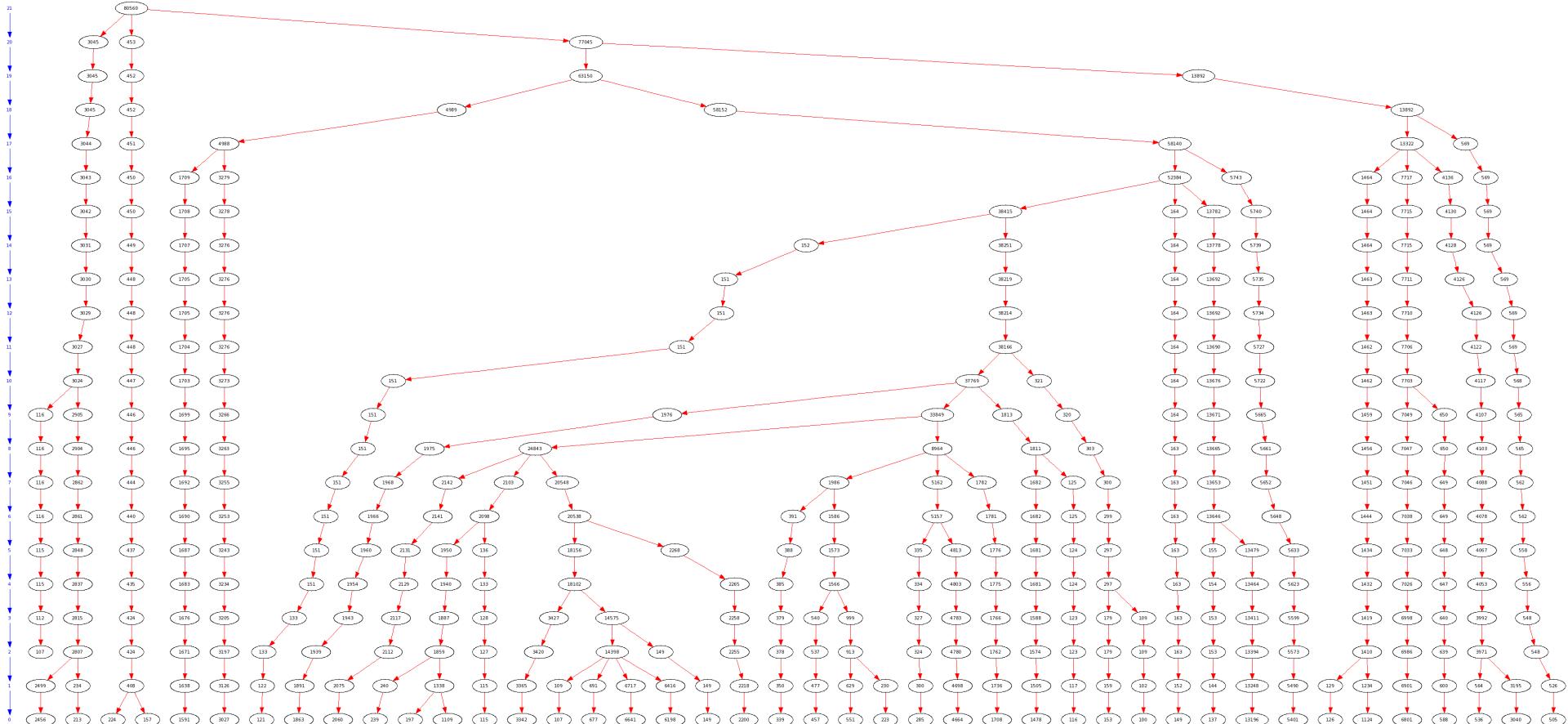


# Assignment to the final partition

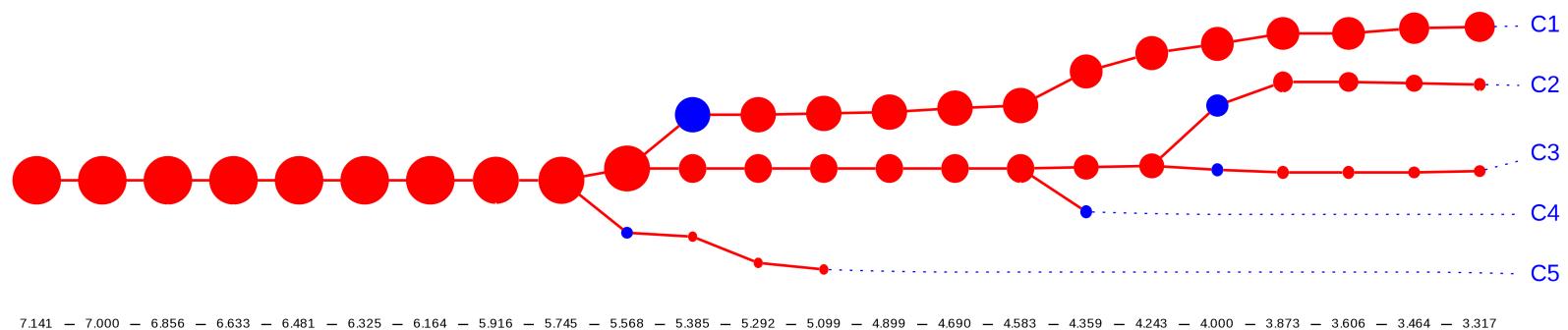


- At the end of the hierarchical clustering, **seed clusters** are determined and the points are re-attributed to the closest seed

# A more realistic output

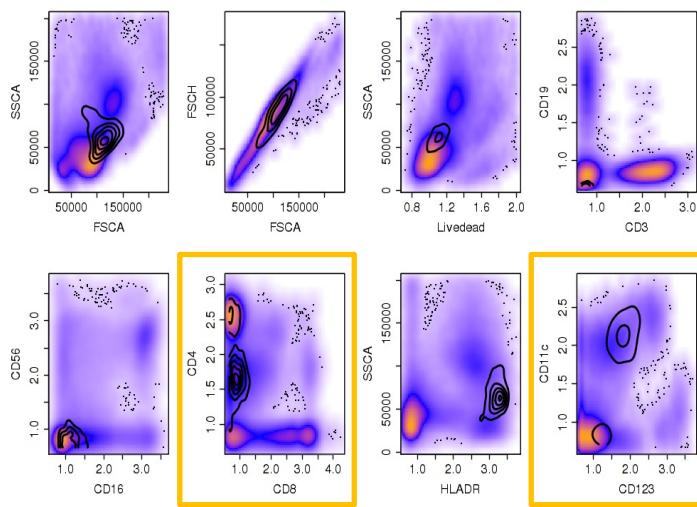


# Parameters affecting results

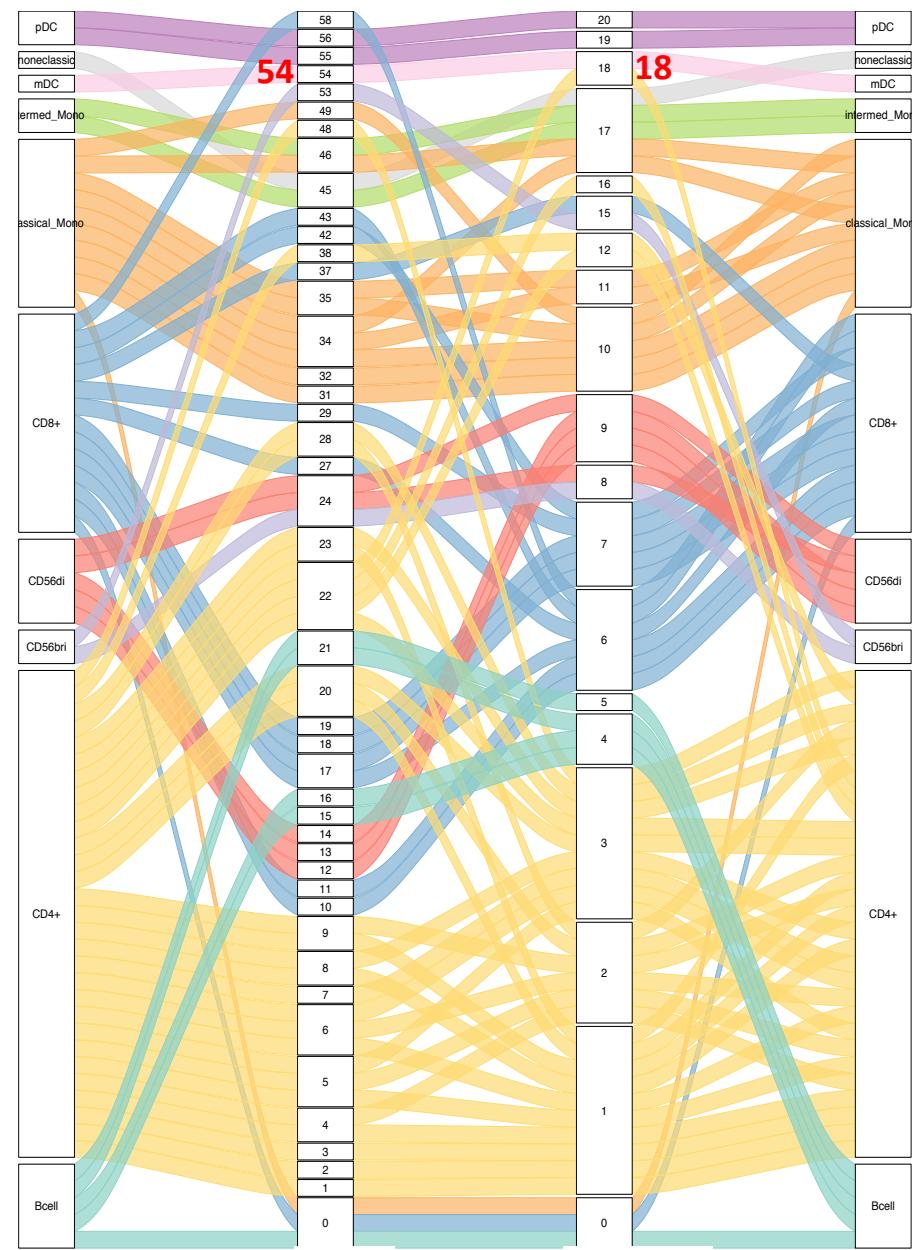
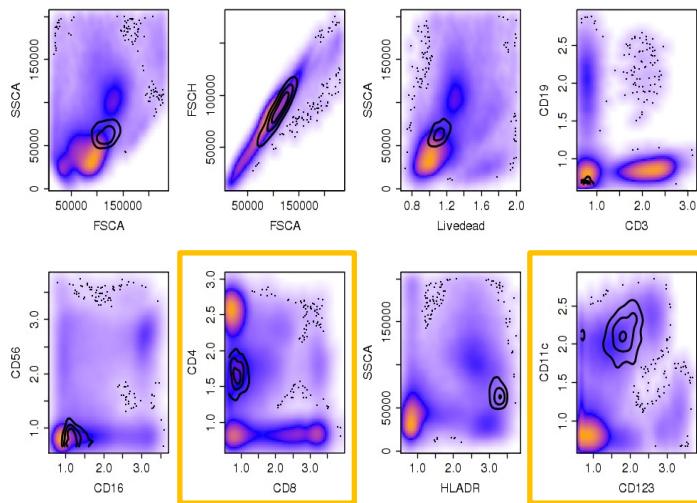


- **-f** first distance to test
- **-l** last distance to be tested
- **-s** step increment for the distance test
- **-k** minimum percent of events needed to retain a cluster
- **-n** minimum number of events needed to retain a cluster
- **-p** pctAssigned (Stop sampling as soon as pctAssigned events have been assigned)

@n120, Cluster 18 (1197 events, 0.005% live cells)



@n40, Cluster 54 (890 events, 0.003% live cells)



Manual  
Gating

n=40

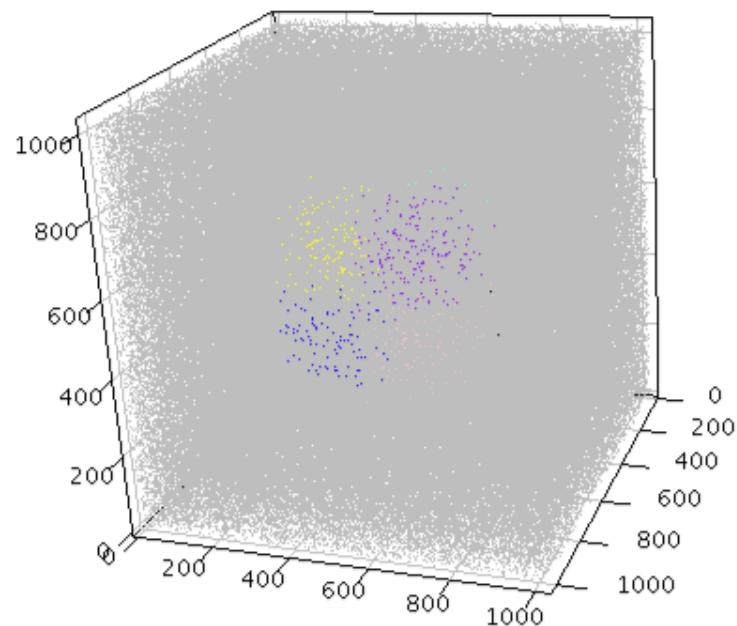
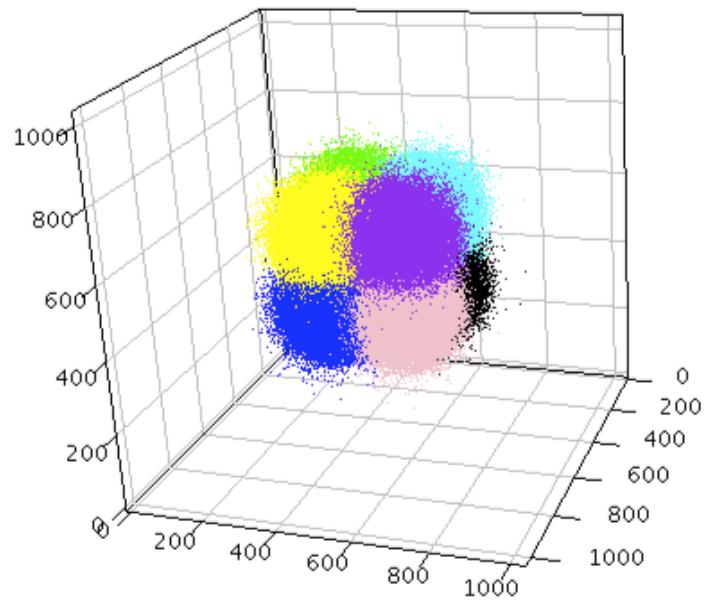
n=120

Manual  
Gating

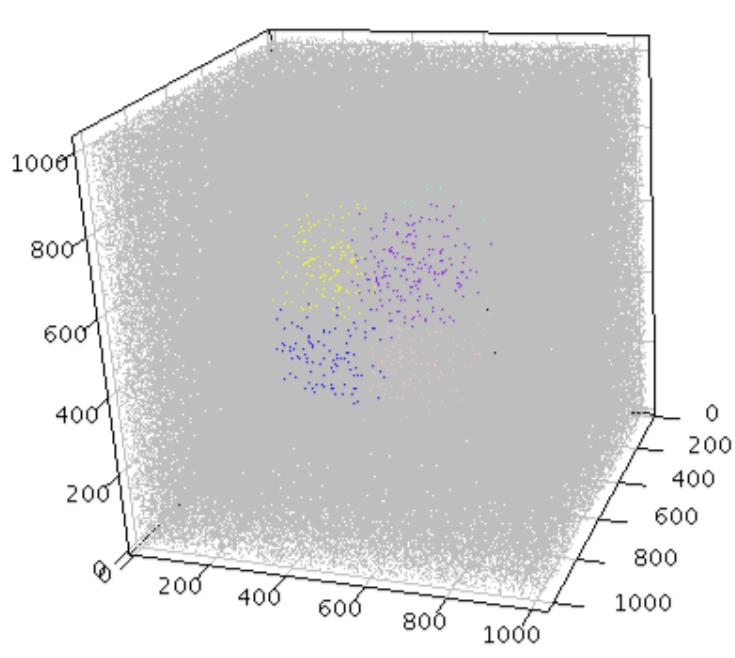
# Tests with noise

## INPUT:

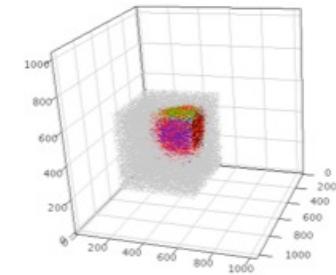
- 8 overlapping spheres with 125,000 points, comprising a total of 1e6 points
- random noise 500,000 points



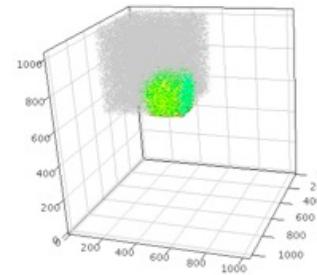
# K - means



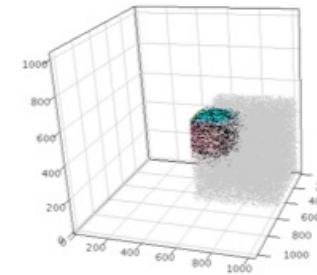
**Cluster 1**



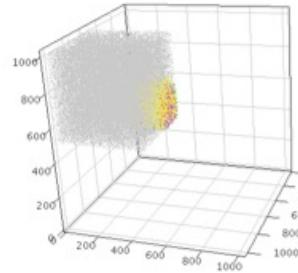
**Cluster 2**



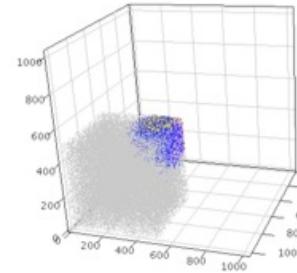
**Cluster 3**



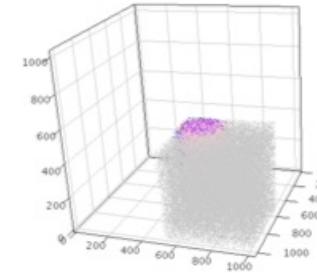
**Cluster 4**



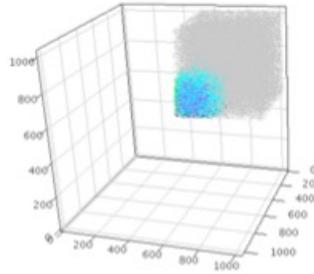
**Cluster 5**



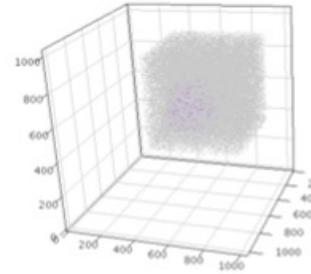
**Cluster 6**



**Cluster 7**

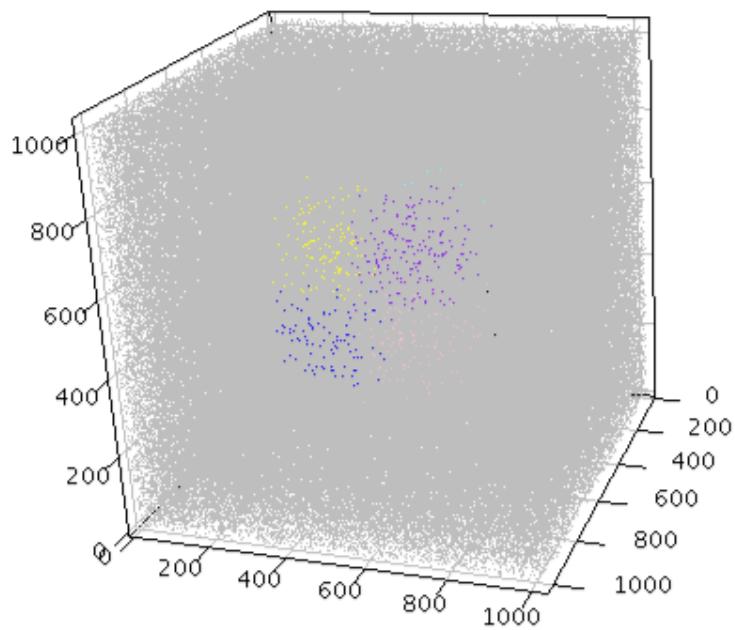


**Cluster 8**

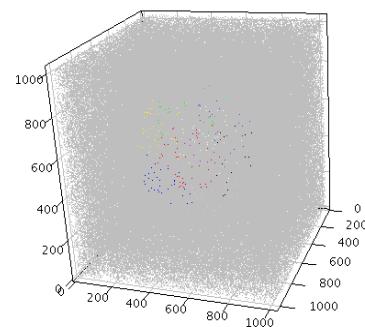


**Unassigned**

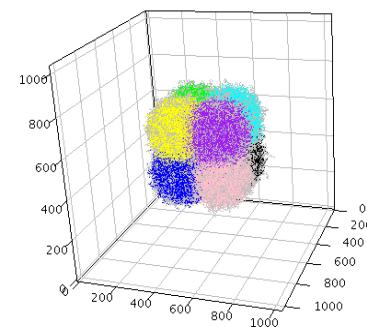
# DBscan



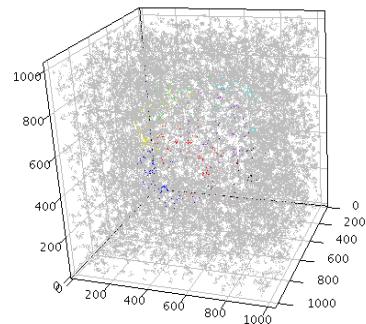
Unassigned  
367' 162 points



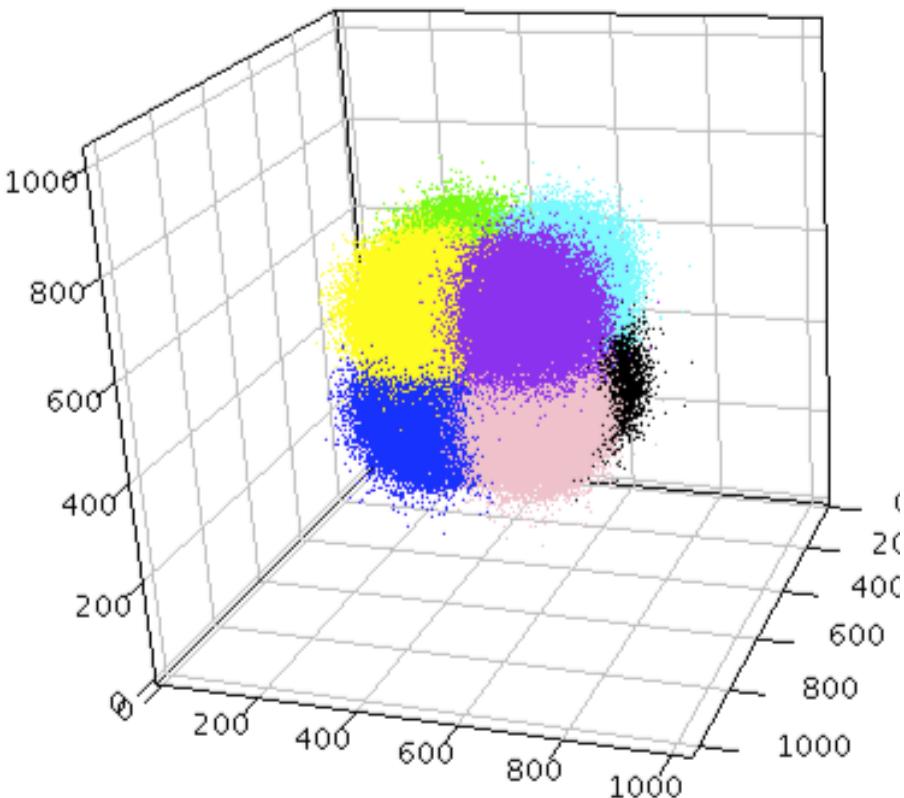
Cluster 1  
1' 051' 091 points



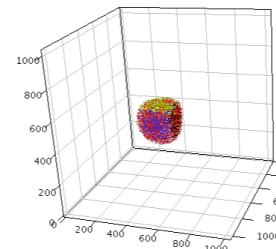
pool of 5' 346 other clusters:  
81' 747 points



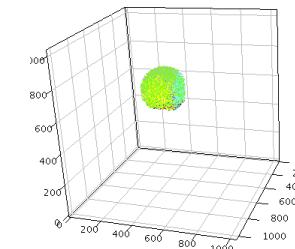
# Megaclust



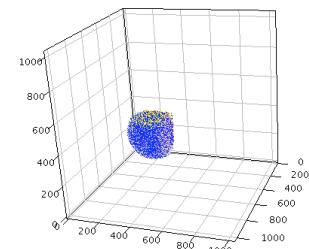
Cluster 1



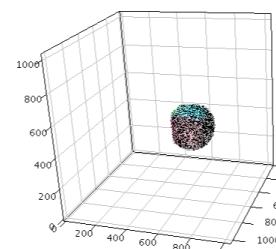
Cluster 2



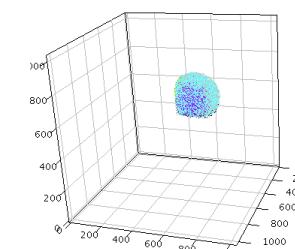
Cluster 7



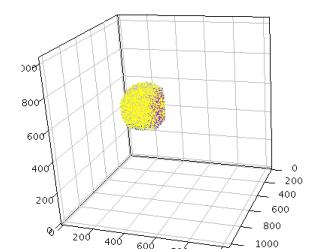
Cluster 3



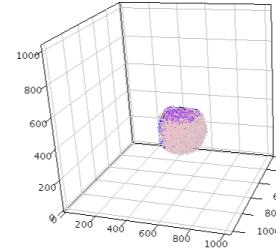
Cluster 4



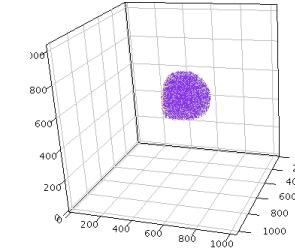
Cluster 8



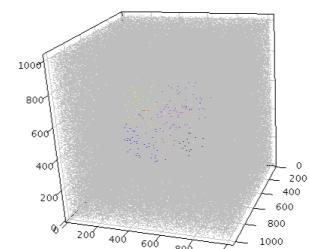
Cluster 5



Cluster 6

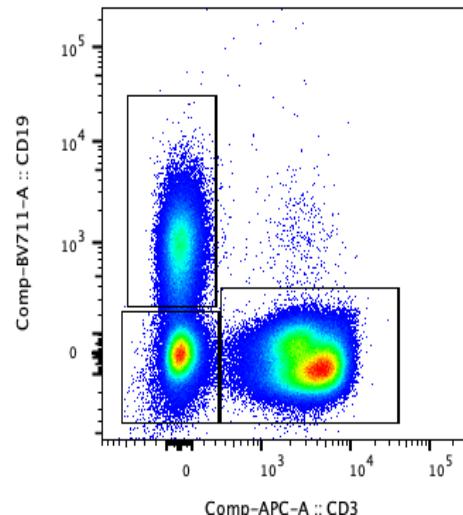


Unassigned



# Input and parameters affecting results

- numerical range of markers
  - will each marker contribute equally to the distance metric ?
- data sampling
  - will each sample contribute equally to the cluster discovery ?
- data acquisition calibration
  - can samples be mixed in a single run ?
- input quality
  - are acquisitions stable ?



# Data Analysis Tradeoffs

