

Homework 2

28/09/2017

An “Almost” Freely Jointed Chain

The *freely jointed chain model* consists in a sequence of n bond vectors joining $n + 1$ monomers in the space. Each bond \vec{r}_i has a fixed length l and there is no correlation between the directions of different vectors.

1. Evaluate the average gyration radius in the case of the *freely jointed chain model*

$$\langle R_{gyr}^2 \rangle = \left\langle \frac{1}{n+1} \sum_{i=0}^n (\vec{R}_i - \vec{R}_{cm})^2 \right\rangle = \left\langle \frac{1}{(n+1)^2} \sum_{i=0}^n \sum_{j=i}^n (\vec{R}_i - \vec{R}_j)^2 \right\rangle \quad (1)$$

where the centre of mass position is $\vec{R}_{cm} = \frac{1}{n+1} \sum_{j=0}^n \vec{R}_j$.
Consider in particular the limit $n \gg 1$.

In the rest of this exercise we will consider a slightly modified version of this model. Consider a chain in which the angle between two successive bonds assumes a value $\theta \in [0, \frac{\pi}{2}]$ with probability

$$p_+ = \frac{1}{2} + \epsilon \quad \left(|\epsilon| \leq \frac{1}{2} \right).$$

Remember that the direction of a vector in the space is stated by the angle $\theta \in [0, \pi]$ and a torsion angle $\phi \in [0, 2\pi]$ (see figure 1).

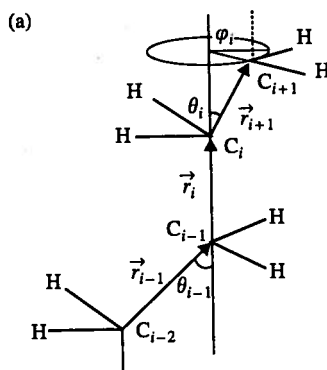


Figure 1: Freely jointed chain model (from *Polymer Physics*, M. Rubinstein and R.H. Colby).

2. Calculate the correlations $\langle \vec{r}_{i-1} \cdot \vec{r}_i \rangle$, $\langle \vec{r}_{i-1} \cdot \vec{r}_{i+1} \rangle$, and $\langle \vec{r}_i \cdot \vec{r}_j \rangle$.

3. Use the former results to evaluate the average end-to-end distance

$$R_{end}^2 = (\vec{R}_n - \vec{R}_0) \cdot (\vec{R}_n - \vec{R}_0),$$

and the gyration radius (eq. 1). Consider in particular the limit $n \gg 1$.

Useful formulas:

$$\begin{aligned}\sum_{k=1}^{m-1} \epsilon^k &= \epsilon \frac{1 - \epsilon^{m-1}}{1 - \epsilon} \\ \sum_{k=1}^{m-1} k \epsilon^k &= \epsilon \frac{d}{d\epsilon} \sum_{k=1}^{m-1} \epsilon^k \\ \sum_{m=1}^{n-i} m &= \frac{(n-i)(n-i+1)}{2} \\ \sum_{k=0}^n k(k+1) &= \frac{n(n+1)(2n+4)}{6}.\end{aligned}$$