

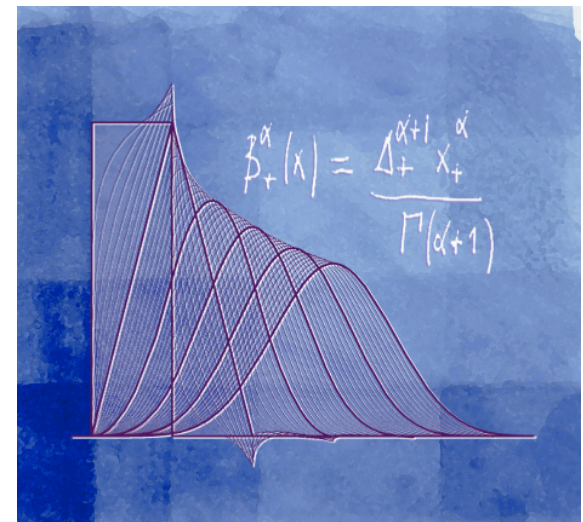
Image Processing

Chapter 4

Morphological Processing

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OUTLINE

- Morphology: introduction
- Basic definitions
- Erosion and dilation
- Opening and closing
- Distance map and watershed
- Graylevel morphology
- Morphological filtering

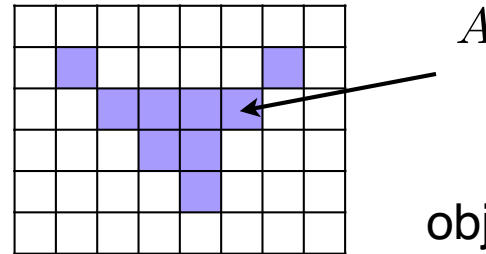
Morphology: introduction

Deals with shape and structure

[Serra, Matheron]

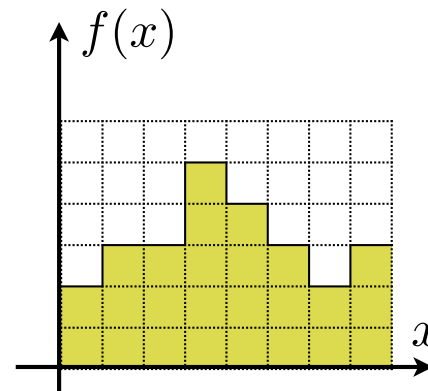
■ Language: set theory

- Binary images (bitmap)
Sets of points in 2D space (\mathbb{Z}^2)



object vs. background

- Quantized graylevel images
Sets of points in \mathbb{Z}^3



■ Type of transformations

- Set-theoretic: union, intersection, etc.
- With structuring element: dilation, erosion

Morphology: application areas

Classification of objects or image features based on shape.

■ Examples

- Extraction of objects with a specific shape
- With a size smaller or greater than a limit
- Contour detection

■ Typical image processing tasks where it can be useful

- Preprocessing: noise reduction, simplification
- Feature detection
- Segmentation: contour extraction
- Post-processing: shape cleaning and simplification

■ Main application area

- Material sciences, mineralogy, granulometry
- Medicine and biology: cell counting, cytology, gel electrophoresis, micro-arrays
- Machine vision

Basic definitions

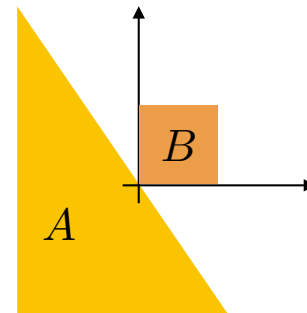
■ Universal set

\mathbb{E} is the set of every possible element (e.g., $\mathbb{E} = \mathbb{Z}^2$ or $\mathbb{E} = \mathbb{R}^2$)

■ Sets and subsets

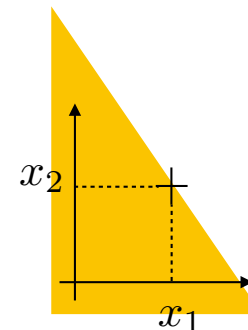
Sets: $A, B \subset \mathbb{E}$

Elements: $a = (a_1, a_2) \in A$, $b = (b_1, b_2) \in B$



■ Translation by $x = (x_1, x_2)$

$$(A)_x = \{c \mid c = a + x, \text{ for } a \in A\}$$



Basic definitions (Cont'd)



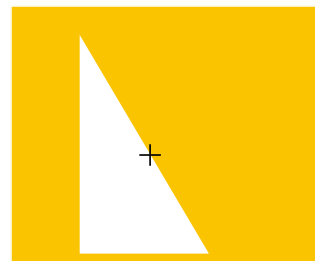
■ Reflection or symmetry



$$A^s = \{x \in \mathbb{E} \mid x = -a, \text{ for } a \in A\}$$

■ Complement

$$A^c = \{x \in \mathbb{E} \mid x \in \mathbb{E} \setminus A\}$$



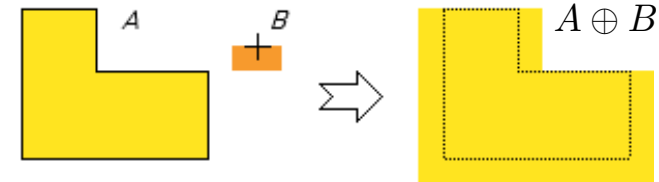
Dilation and erosion in \mathbb{R}^2

■ Structuring element



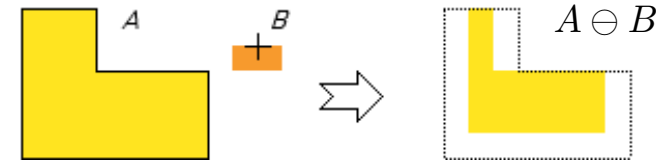
■ Dilation

$$A \oplus B = \{x \in \mathbb{E} \mid (B^s)_x \cap A \neq \emptyset\} = \bigcup_{x \in A} (B)_x$$

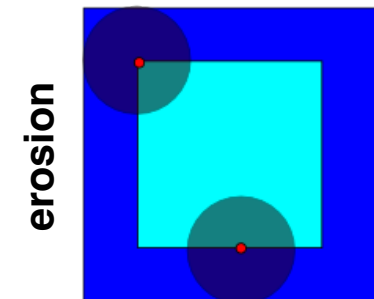
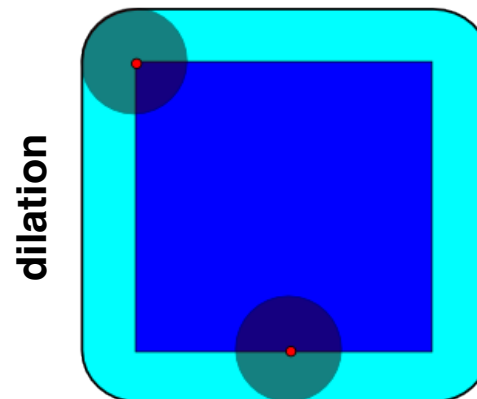
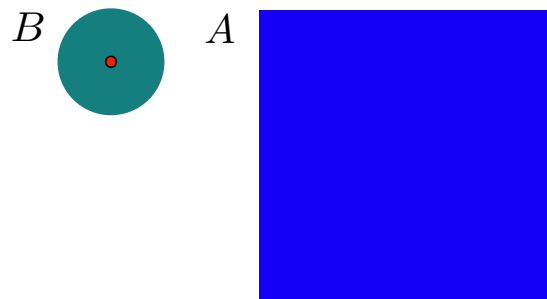


■ Erosion

$$A \ominus B = \{x \in \mathbb{E} \mid (B)_x \subseteq A\} = \bigcap_{x \in B^s} (A)_x$$

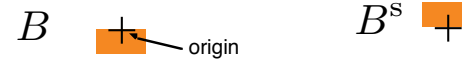


■ Complementary example



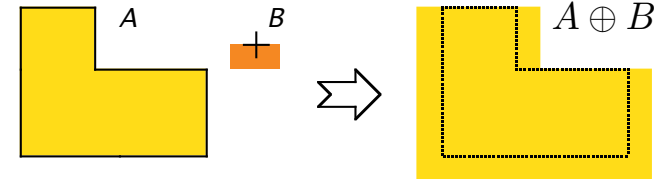
Dilation and erosion in \mathbb{R}^2

■ Structuring element



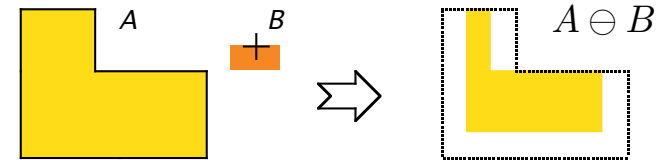
■ Dilation

$$A \oplus B = \{x \in \mathbb{E} \mid (B^s)_x \cap A \neq \emptyset\} = \bigcup_{x \in A} (B)_x$$



■ Erosion

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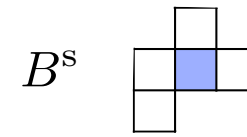
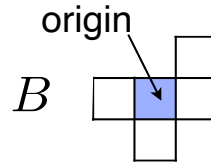
■ Duality relations

$$A \ominus B = (A^c \oplus B^s)^c \quad (\text{Erosion} = \text{“Dilation” of complement})$$

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Dilation and erosion in \mathbb{Z}^2

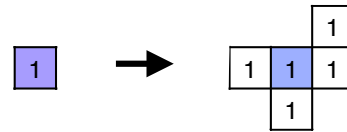
■ Structuring element



■ Dilation

$$A \oplus B = \{x \in \mathbb{E} \mid (B^s)_x \cap A \neq \emptyset\} \quad \Leftrightarrow \quad A \oplus B = \bigcup_{x \in A} (B)_x$$

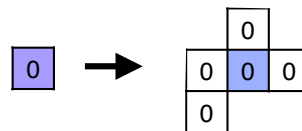
Parallel implementation:
(once 1, remains 1)



■ Erosion

$$A \ominus B = \{x \in \mathbb{E} \mid (B)_x \subseteq A\} \quad \Leftrightarrow \quad A \ominus B = \left(\bigcup_{x \in A^c} (B^s)_x \right)^c$$

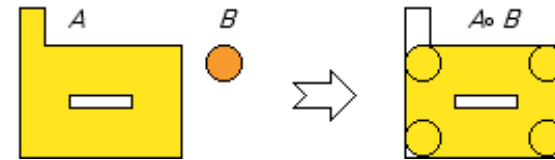
Parallel implementation:
(once 0, remains 0)



Opening

■ Opening operator

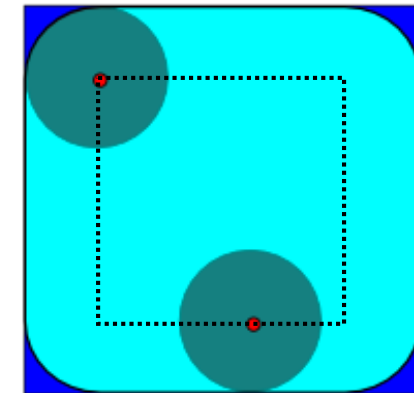
$$A \circ B = (A \ominus B) \oplus B$$



- Interpretation 1: smallest set that has a given erosion $A \ominus B$

- Interpretation 2: Union all B 's included in A

$$A \circ B = \bigcup_{x \in \mathbb{E}} \{(B)_x \mid (B)_x \subseteq A\}$$



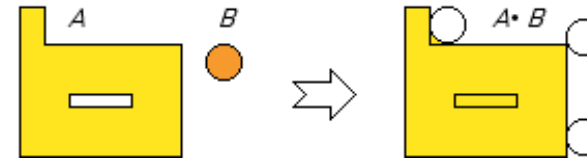
■ Properties

- Subset $A \circ B \subseteq A$
- Invariance to origin $\forall x, A \circ (B)_x = A \circ B$
- Idempotence $(A \circ B) \circ B = (A \circ B)$
- Order preservation $C \subseteq D \Rightarrow (C \circ B) \subseteq (D \circ B)$

Closing

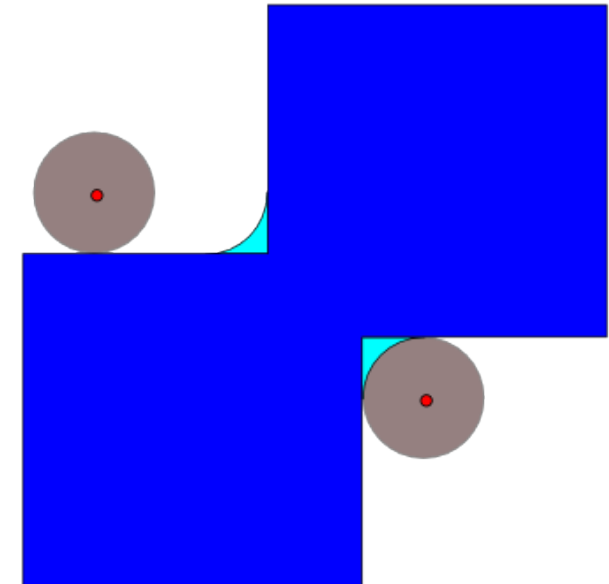
■ Closing operator

$$A \bullet B = (A \oplus B) \ominus B$$



- Interpretation 1: : largest set that has a given dilation $A \oplus B$
- Interpretation 2: : Complement of union all B^s included in A^c

$$A \bullet B = \left(\bigcup_{x \in \mathbb{E}} \{(B^s)_x \mid (B^s)_x \subseteq A^c\} \right)^c$$



■ Properties

- Superset $A \subseteq A \bullet B$
- Invariance to origin $\forall x, A \bullet (B)_x = A \bullet B$
- Idempotence $(A \bullet B) \bullet B = (A \bullet B)$
- Order preservation $C \subseteq D \Rightarrow (C \bullet B) \subseteq (D \bullet B)$

Duality relations

■ Erosion and dilation

$$(A \ominus B)^c = A^c \oplus B^s$$

$$(A \oplus B)^c = A^c \ominus B^s$$

■ Opening and closing

$$A \circ B = (A^c \bullet B^s)^c$$

$$A \bullet B = (A^c \circ B^s)^c$$

Distance Map and Watershed

$$A_0[\mathbf{k}] = \begin{cases} 1, & \mathbf{k} \in \text{object} \\ 0, & \mathbf{k} \in \text{background} \end{cases}$$

$n = 0$

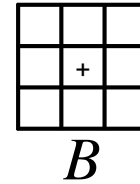
initialize D_{map}

while $\max(A_n) = 1$ do

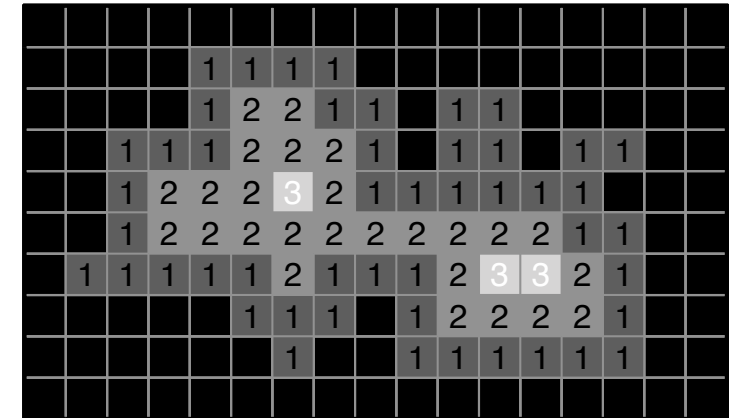
$$A_{n+1} = \text{erode}(A_n, B)$$

$$D_{\text{map}} = D_{\text{map}} + (n + 1)(A_n - A_{n+1})$$

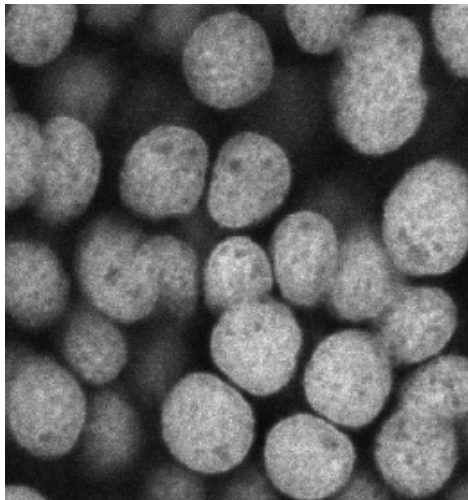
$n = n + 1$



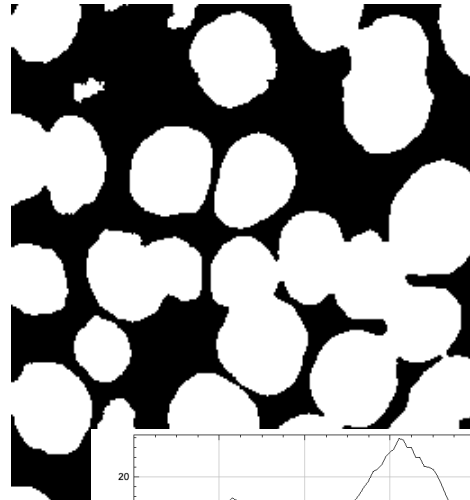
□ object
■ background



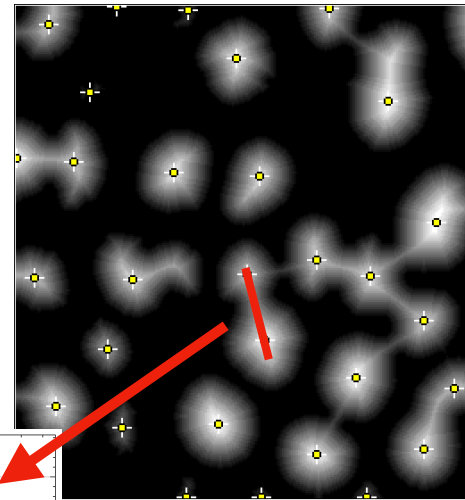
Original



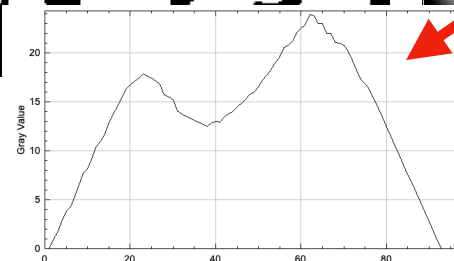
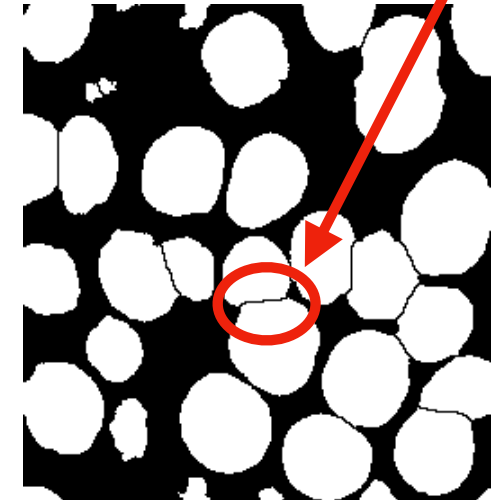
Thresholded image



Distance map

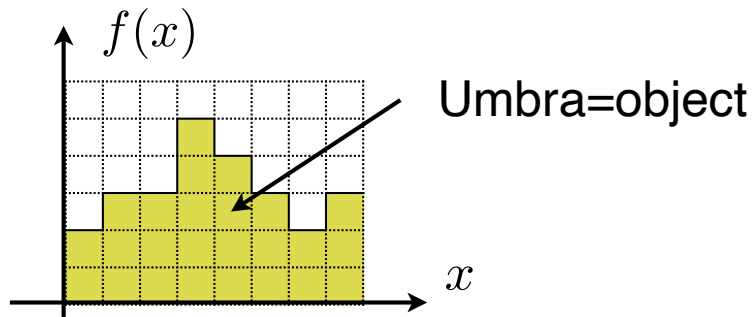


Watershed dam





local maxima → seeds of watershed

Graylevel morphology

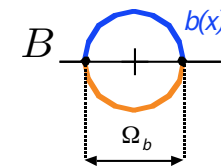


Common structural elements are symmetric

- Horizontal 2D: W -neighborhood (flat top) 
- Volumetric: approximation of a ball (rolling ball) 

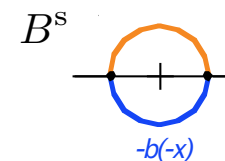
■ Dilation

$$(f \oplus b)[\mathbf{k}] = \max_{\mathbf{k}_0 \in \Omega_b} \{f[\mathbf{k} - \mathbf{k}_0] + b[\mathbf{k}_0] \mid (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$



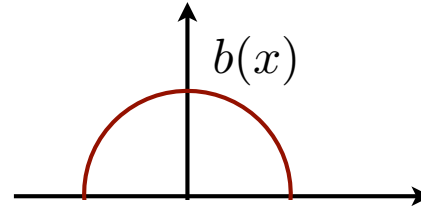
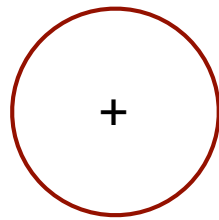
■ Erosion

$$(f \ominus b)[\mathbf{k}] = \min_{-\mathbf{k}_0 \in \Omega_b} \{f[\mathbf{k} - \mathbf{k}_0] - b[-\mathbf{k}_0] \mid (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$



Graylevel dilation and erosion

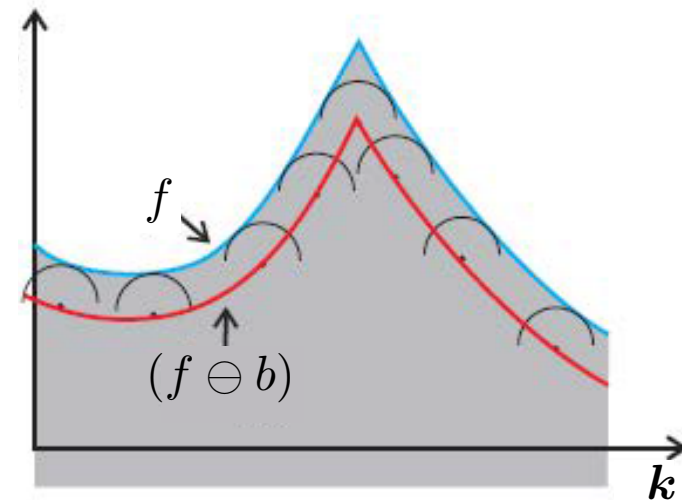
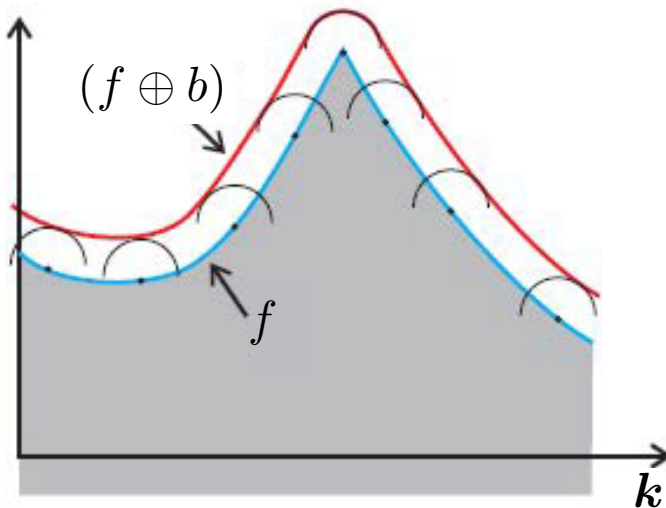
Structuring element:



« **Graylevel formula** » (*gray = function value*)

$$\max_{\mathbf{k}_0 \in \Omega_b} \{f[\mathbf{k} - \mathbf{k}_0] + b[\mathbf{k}_0] \mid (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$

$$\min_{-\mathbf{k}_0 \in \Omega_b} \{f[\mathbf{k} - \mathbf{k}_0] - b[-\mathbf{k}_0] \mid (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$



« **Binary formula** » (*gray = extra dimension*)

Reminder: $A \oplus B = \bigcup_{x \in A} (B)_x$

$$A \ominus B = \{x \in \mathbb{E} \mid (B)_x \subseteq A\}$$

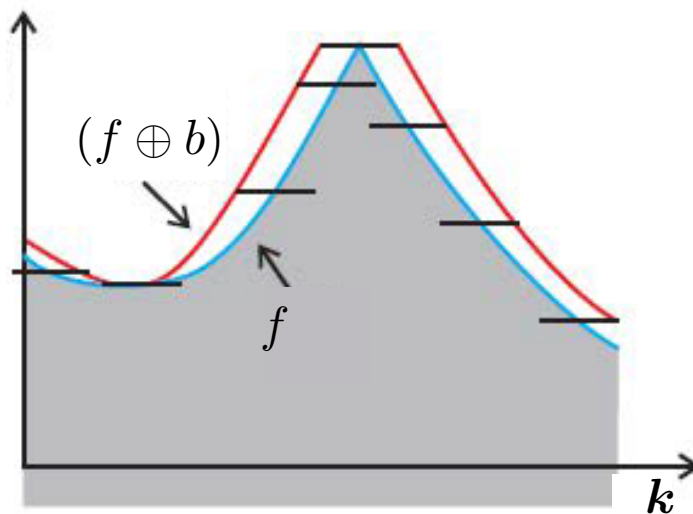
Graylevel dilation and erosion

Structuring element: $b(x) = 0$
 $\Omega_b = W$

« *Graylevel formula* » (*gray = function value*)

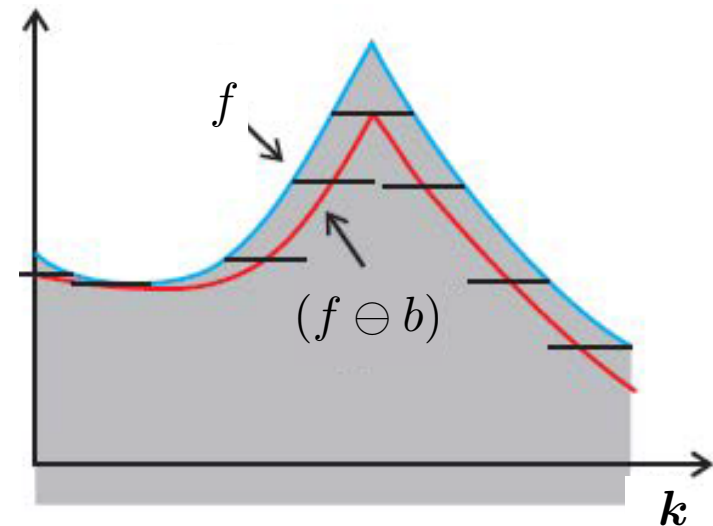
$$\max_{\mathbf{k}_0 \in W} \{f[\mathbf{k} - \mathbf{k}_0] \mid (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$$

max-filter



$$\min_{\mathbf{k}_0 \in W} \{f[\mathbf{k} + \mathbf{k}_0] \mid (\mathbf{k} + \mathbf{k}_0) \in \Omega_f\}$$

min-filter



« *Binary formula* » (*gray = extra dimension*)

Reminder: $A \oplus B = \bigcup_{x \in A} (B)_x$

$$A \ominus B = \{x \in \mathbb{E} \mid (B)_x \subseteq A\}$$

Morphological filtering

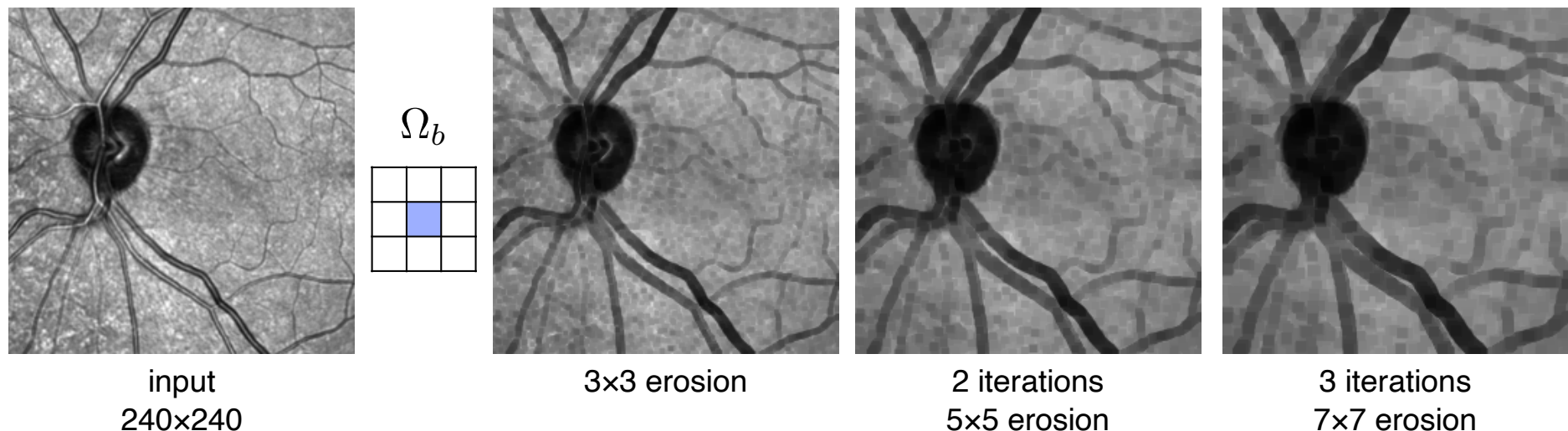
- Special case: $b_0[\mathbf{y}] = 0$ and $\Omega_b = W$

Dilation = Max-filter: $(f \oplus b_0)[\mathbf{k}] = \max_{\mathbf{k}_0 \in W} \{f[\mathbf{k} - \mathbf{k}_0] \mid (\mathbf{k} - \mathbf{k}_0) \in \Omega_f\}$

Erosion = Min-filter: $(f \ominus b_0)[\mathbf{k}] = \min_{\mathbf{k}_0 \in W} \{f[\mathbf{k} + \mathbf{k}_0] \mid (\mathbf{k} + \mathbf{k}_0) \in \Omega_f\}$

- Benefit of iteration

Dilation/erosion can be iterated to construct larger equivalent structuring elements



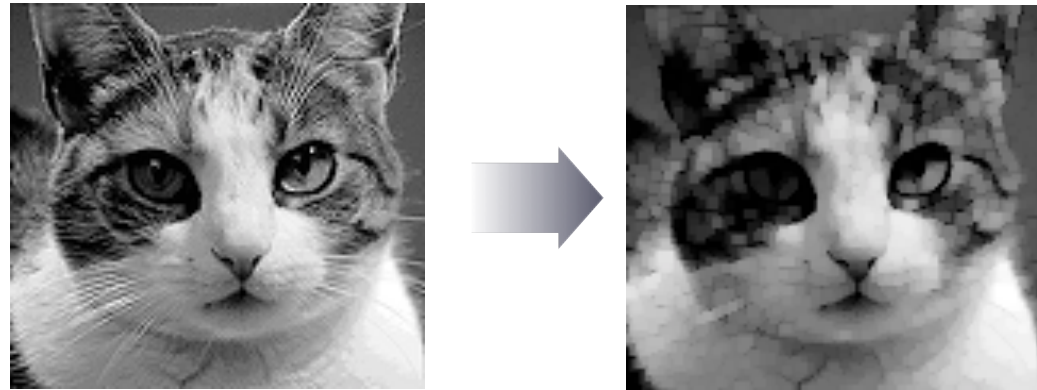
Morphological filtering (Cont'd)

■ Morphological smoothing

- Opening (*i.e.*, min then max)

$$f \circ b = (f \ominus b) \oplus b$$

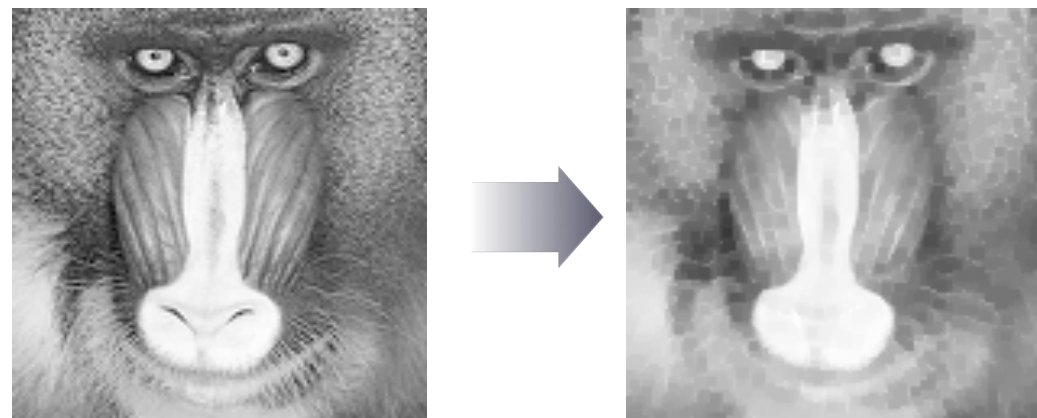
Smoothing by suppression of small bright features



- Closing (*i.e.*, max then min)

$$f \bullet b = (f \oplus b) \ominus b$$

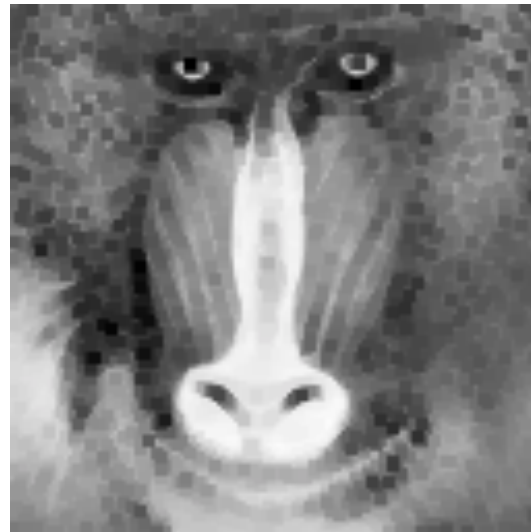
Smoothing by suppression of small black features



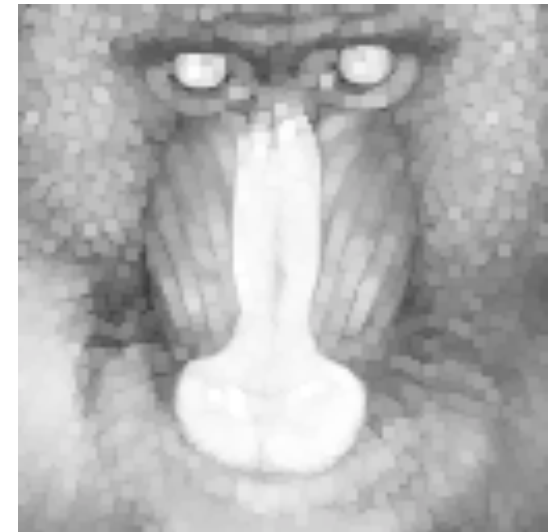
Example of morphological filtering



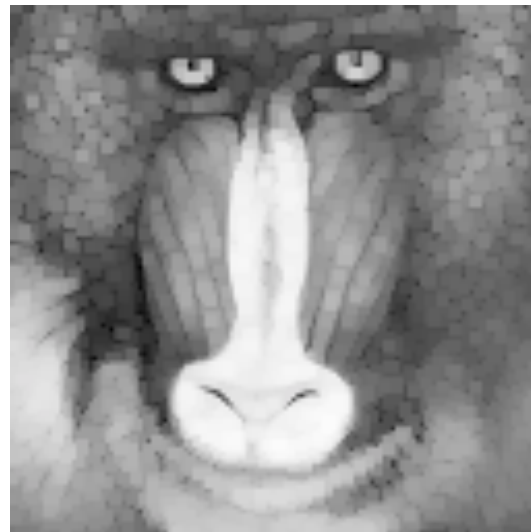
Original (reduced): 128x128



A: 3x3 min



B: 3x3 max



C: 3x3 max of A

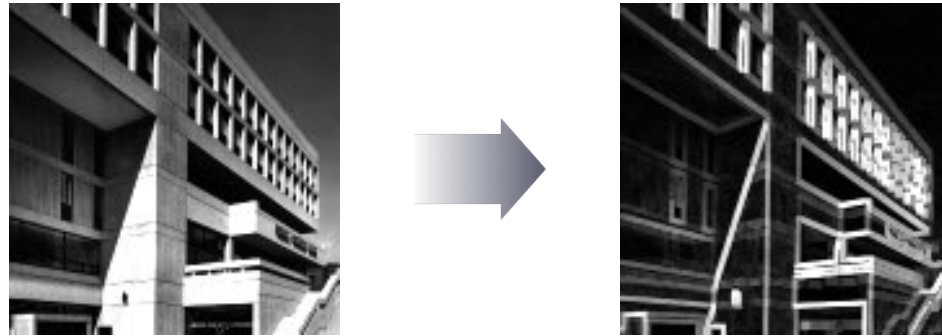


D: 3x3 min of B

Morphological filtering (Cont'd)

- Morphological gradient

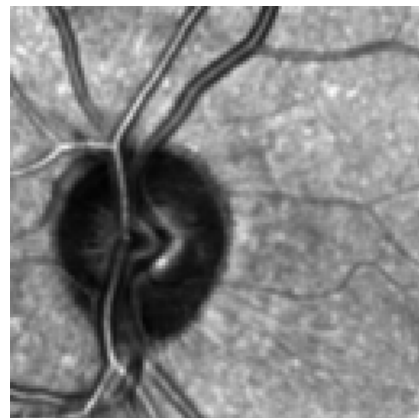
$$g = (f \oplus b) - (f \ominus b)$$



Property: not sensitive to edge direction when using symmetric b

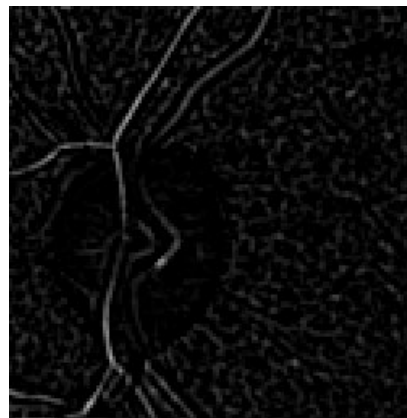
- Top hat

Analog of linear Laplacian



For bright-feature detection

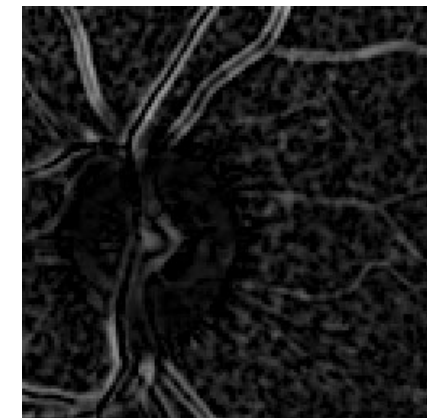
$$g = f - (f \circ b)$$



disk, $r=1$

For dark-feature detection

$$g = (f \bullet b) - f$$



disk, $r=3$

References

A.K. Jain, *Fundamentals of Digital Image Processing*. Englewood Cliffs, NJ: Prentice-Hall, 1989.

W.K. Pratt, *Digital Image Processing*. New York: Wiley, 1991.

J. Serra, *Image Analysis and Mathematical Morphology*. Academic Press, 1982.