

# MICRO-435

## Quantum and Nanocomputing

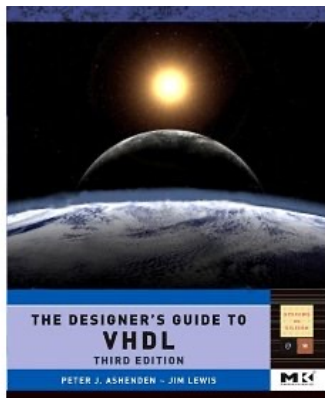
Edoardo Charbon  
Mariagrazia Graziano



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Peter J. Ashenden, *The Designer's Guide to VHDL*, Morgan Kaufmann Publishers,  
1<sup>st</sup> Edition (1995)

# John M. Martinis

## Facts



Ill. Niklas Elmehed © Nobel Prize Outreach

John M. Martinis  
Nobel Prize in Physics 2025

Born: 1958

Affiliation at the time of the award: University of California, Santa Barbara, CA, USA

Prize motivation: “for the discovery of macroscopic quantum mechanical tunnelling and energy quantisation in an electric circuit”

Prize share: 1/3

To cite this section

MLA style: John M. Martinis – Facts – 2025. NobelPrize.org. Nobel Prize Outreach 2025. Tue, 7 Oct 2025. <<https://www.nobelprize.org/prizes/physics/2025/martinis/facts/>>



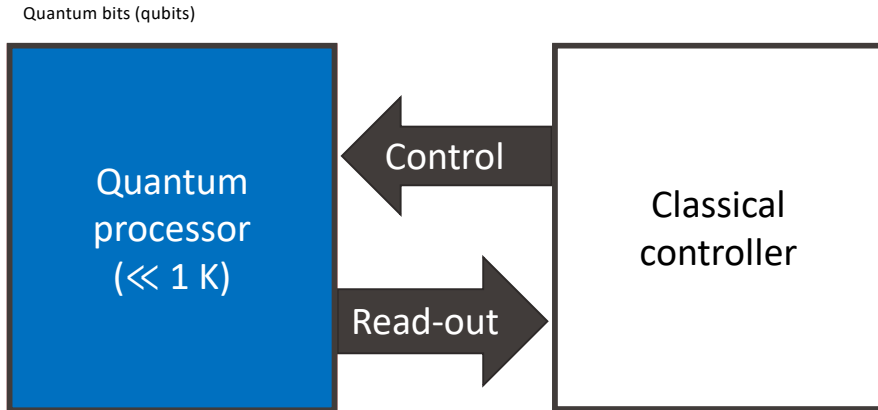
- Fundamentals of quantum computing
- Qubit realization & control
- **Cryo-CMOS components**
- Scalable quantum computers
- Quantum communication, sensing, and metrology

- Choosing a technology
- Cryo-CMOS modeling
- LNAs
- ADCs

Acknowledgements: Fabio Sebastiano, Marcel Pelgrom, Akira Matsuzawa

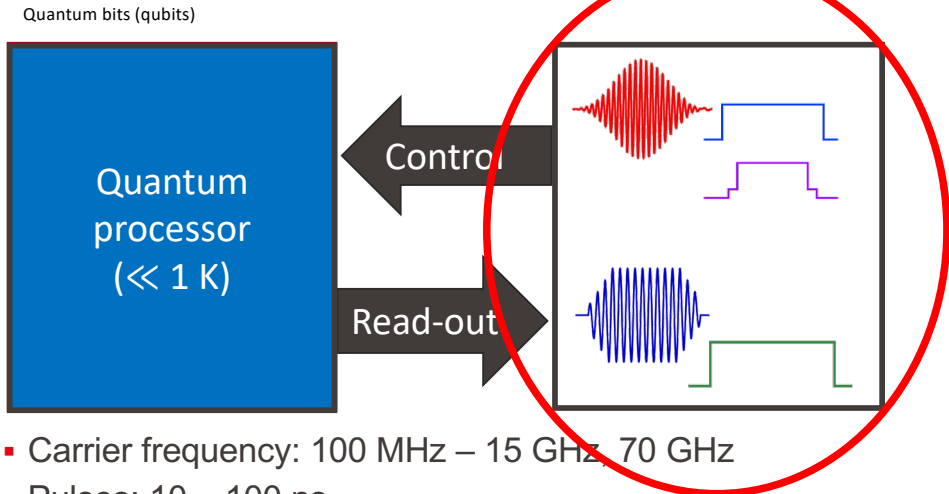
# Choosing a Technology

# Interfacing Qubits with Classical World



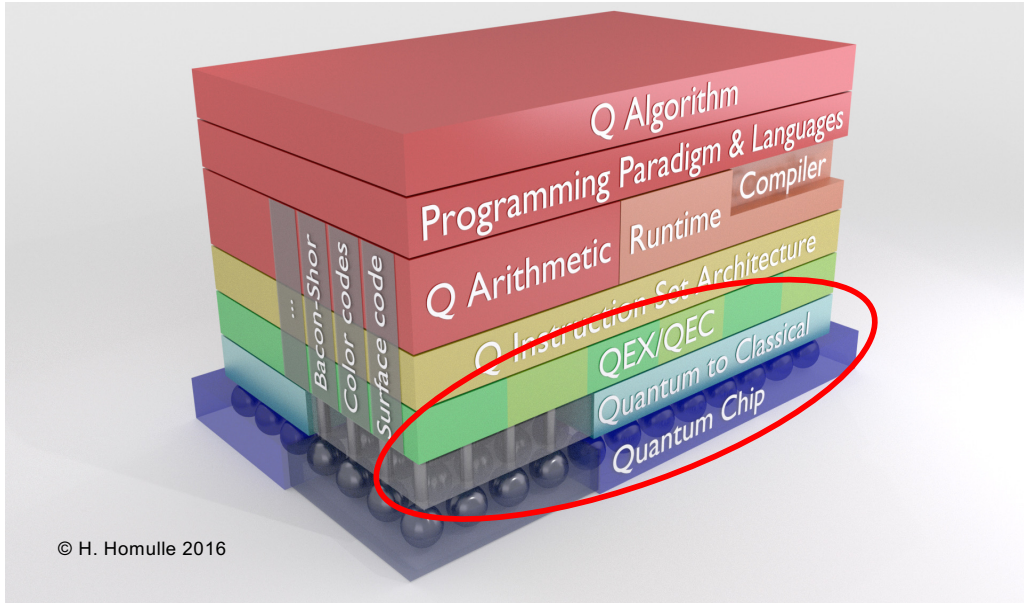
- Carrier frequency: 100 MHz – 15 GHz, 70 GHz
- Pulses: 10 – 100 ns

# Interfacing Qubits with Classical World

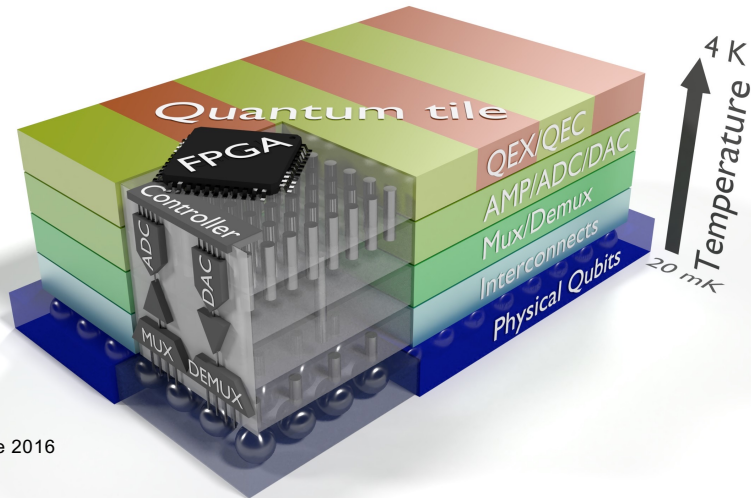


- Carrier frequency: 100 MHz – 15 GHz, 70 GHz
- Pulses: 10 – 100 ns
- Readout techniques for spin qubits: **ESR, EDSR**

# Quantum Computing Stack



# Quantum Computing Stack Detail

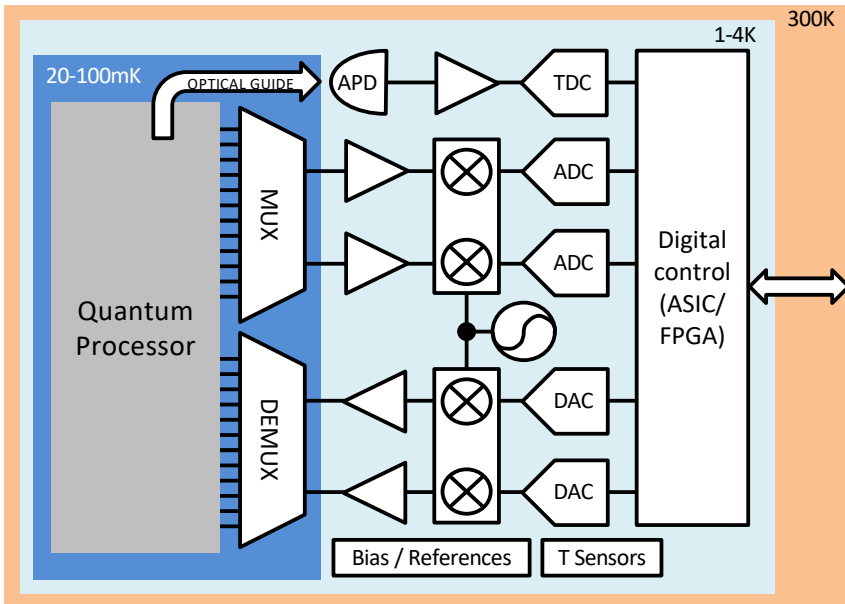


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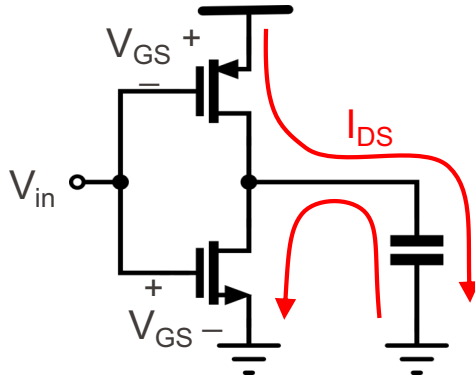
# Which Technology?

- Single-electron Transistors (SET)
- Superconducting devices (RSFQ, RQL, SQUID)
- Low-temperature semiconductors:

	Device	Lowest useable temperature	Limit
	Si BJT	100 K	Low gain
	Ge BJT	20 K	Carrier freeze-out
	SiGe HBT	4 K (or lower?)	?
Most used	Si JFET	40 K	Carrier freeze-out
	III-V MESFET	4K (or lower?)	Lower freeze-out?
VLSI integration →	CMOS	4 K (30 mK ?)	?



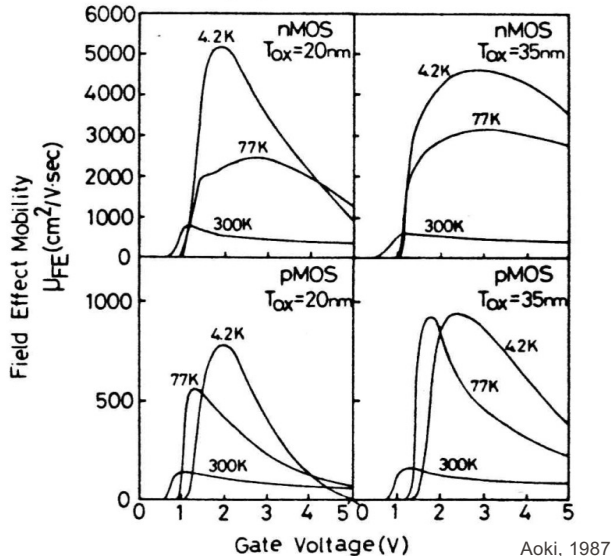
# Cryo-CMOS Modeling



$$I_{DS} = \mu \cdot C_{OX} \frac{W}{2L} (V_{GS} - V_T)^2$$

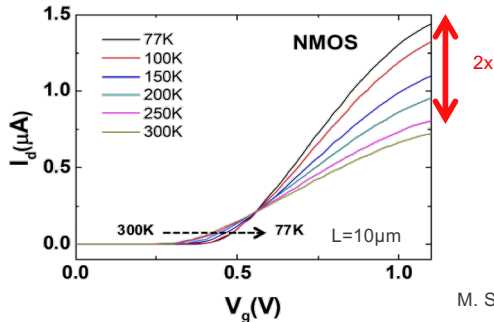
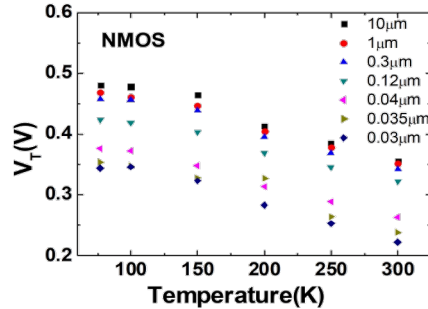
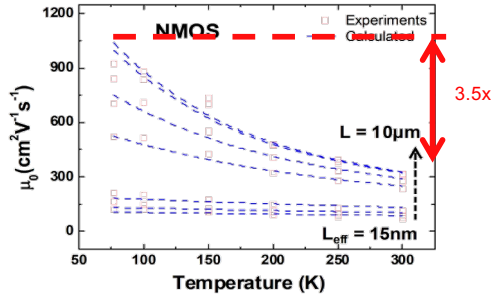
- Speed depends on
  - Mobility
  - Threshold voltage
  - Parasitic resistance/capacitance

# Mobility over Temperature



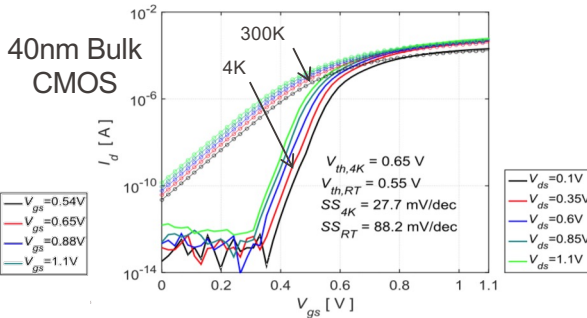
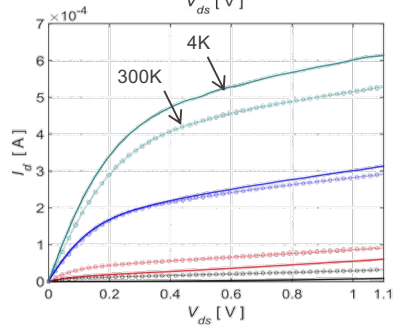
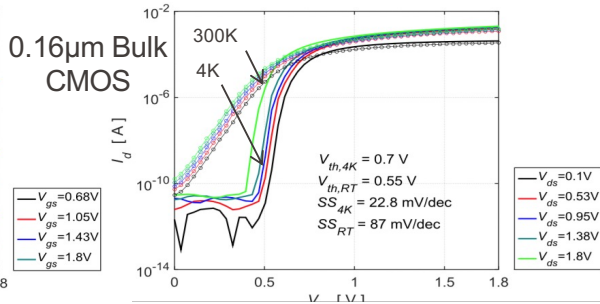
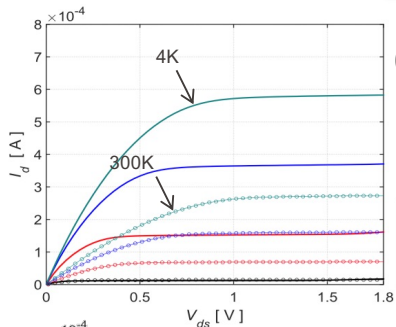
- Mobility increases at low temperature
- It depends on the materials used in the substrate

# Mobility in Modern Process (14 nm)



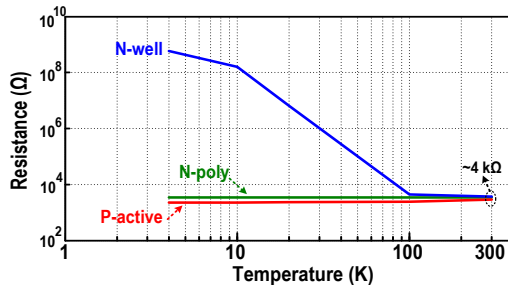
In general:

- More current, less parasitics
- Higher speed
- Lower thermal noise



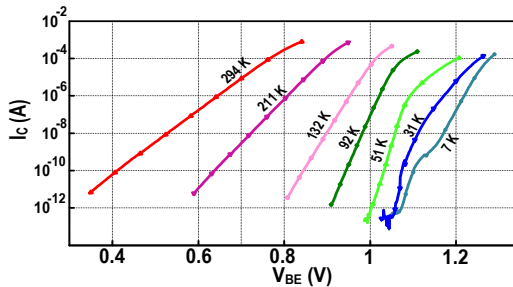
# Cryo-CMOS characterization: passives

Integrated resistor



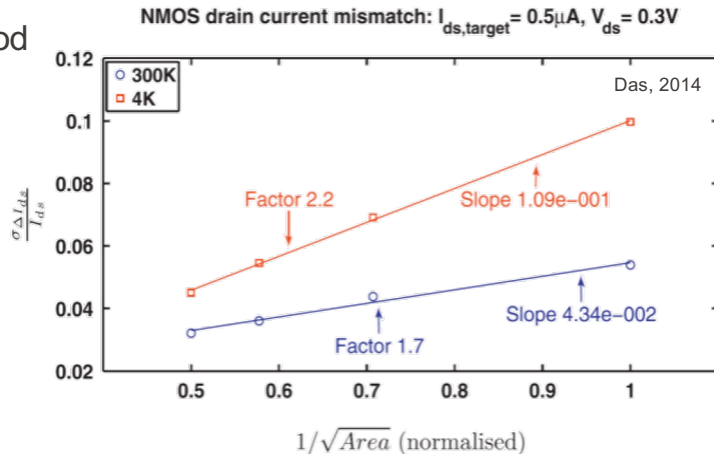
0.16  $\mu\text{m}$  bulk CMOS

Integrated BJT

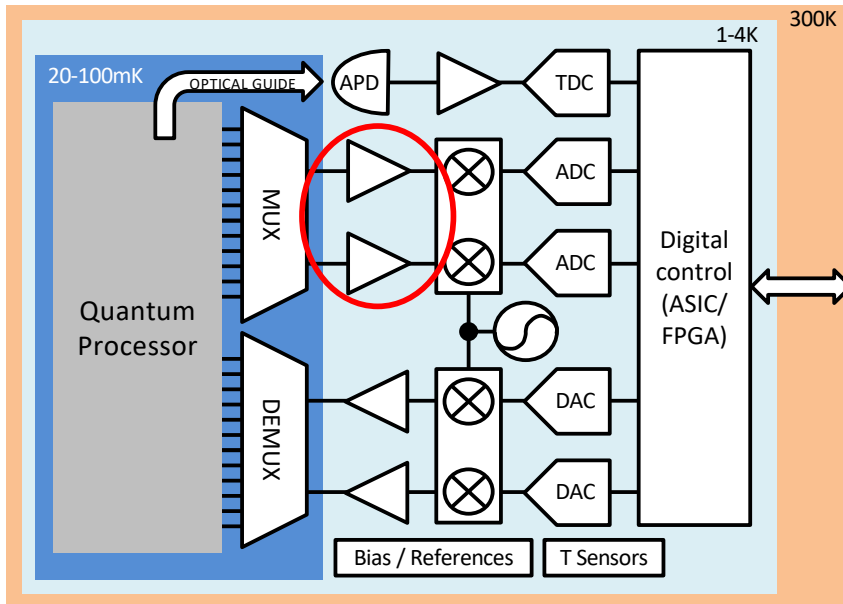


L. Song et al. IEEE Sensors 2016

- Mismatch: difference between nominally equal devices
- Fundamental for ADC/DAC design
- Degradation up to 2x
- Root cause not yet understood



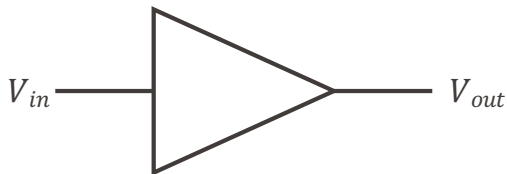
# Low-Noise Amplifiers (LNAs)



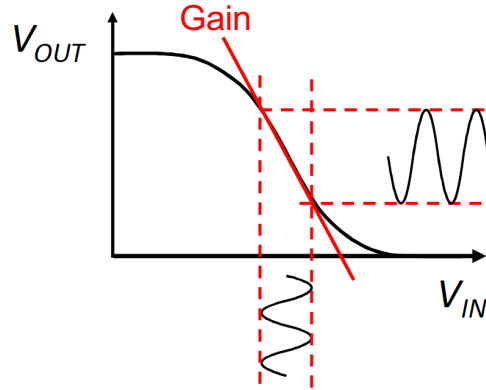
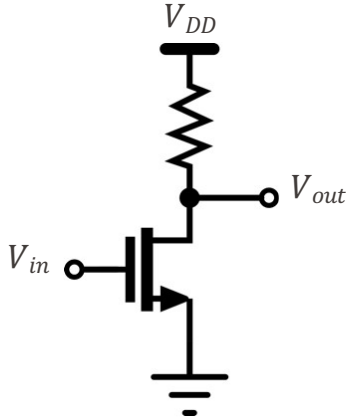
- Signal amplifiers
  - Deliver small signals
- Power amplifiers
  - Deliver large signal
  - Classified based of efficiency (A, B, AB, C, D, E, ...)

Input	Output	Amplifier type	Ideal input impedance	Ideal output impedance
I	I	Current	0	$\infty$
I	V	Transimpedance	0	0
V	I	Transadmittance	$\infty$	$\infty$
V	V	Voltage	$\infty$	0

- Gain
- Linearity
- Bandwidth
- Noise
- Immunity to interference
- Impedance matching
- Power dissipation

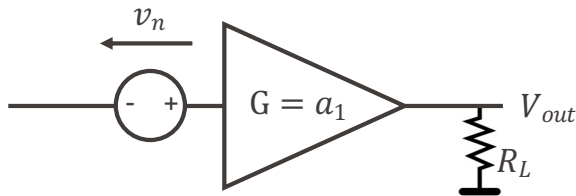


# Common-source Amplifier Example



# Noise in Amplifiers

- Input-referred noise (voltage) source  $v_n$  is a random process with mean  $\overline{v_n} = 0$  and variance  $\overline{v_n^2}$ .
- This source accounts for all sources of noise in the amplifier.

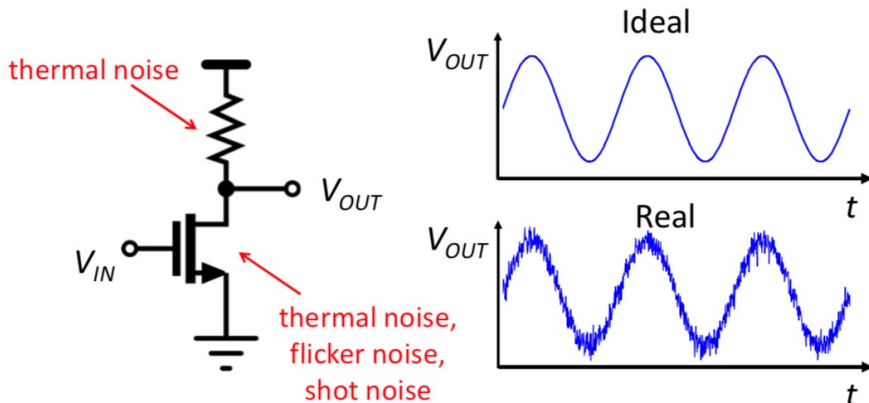


- The output noise is computed as:

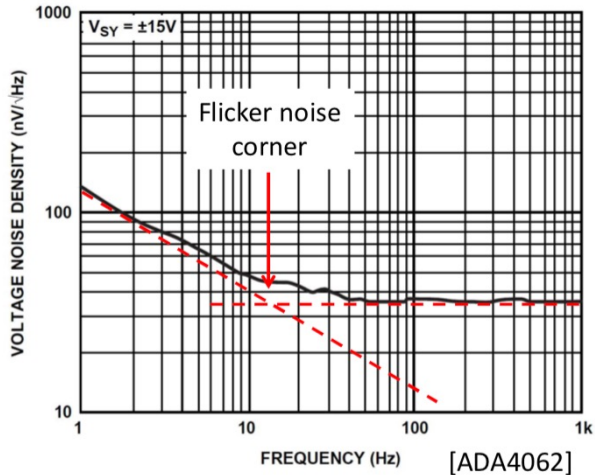
$$\overline{v_{out\_n}^2} = |a_1|^2 \overline{v_n^2}.$$

- If referred to output impedance  $R_L$ , then the noise power  $P_n = \frac{|a_1|^2 \overline{v_n^2}}{R_L}$ .

- Noise sources: thermal noise, shot noise,  $1/f$  or flicker noise, RTS.



- White noise:
  - Thermal noise (resistors, transistors)
  - Shot noise (diodes, transistors)
- Flicker or  $1/f$  noise (non-idealities of fabrication).
- Random telegraph signal (traps and fabrication non-idealities).



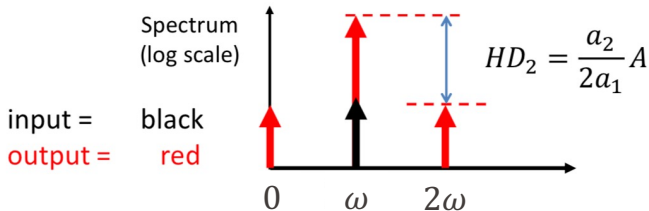
# Linearity – Harmonic Distortion

- Gain may not be linear, thus output voltage is represented as:

$$V_{out} = a_0 + a_1 \cdot V_{in} + a_2 \cdot V_{in}^2 + a_3 \cdot V_{in}^3 + a_4 \cdot V_{in}^4 + \dots$$

- Thus, if  $V_{in} = A \cdot \cos\omega t$ , then

$$\begin{aligned} V_{out} &= a_0 + a_1 \cdot A \cdot \cos\omega t + a_2 \cdot A^2 \cdot \cos^2\omega t + a_3 \cdot A^3 \cdot \cos^3\omega t + \dots \\ &= a_0 + a_1 \cdot A \cdot \cos\omega t + \frac{1}{2} a_2 A^2 + \frac{1}{2} a_2 A^2 \cdot \cos 2\omega t + \dots \end{aligned}$$



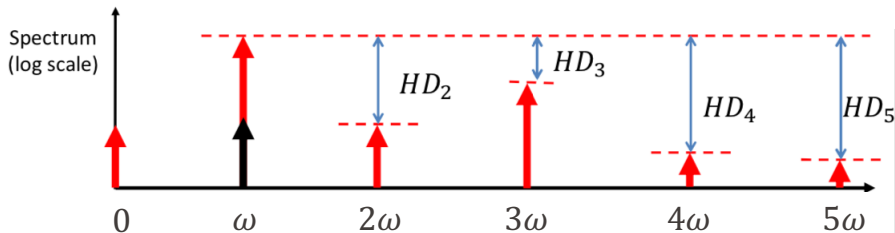
# Linearity – Harmonic Distortion (2)

- Higher order distortions can be similarly computed:

$$HD_3 = \frac{a_3}{4a_1} A^2, \quad HD_4, \dots$$

- Total harmonic distortion:

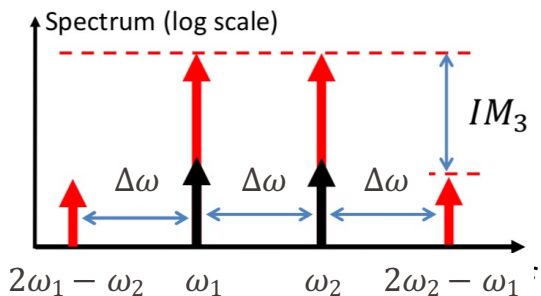
$$THD = \sqrt{\sum_i HD_i^2}$$



- Let  $V_{in} = A \cdot (\cos\omega_1 t + \cos\omega_2 t)$ , then:

$$IM_3 = \frac{3a_3}{4a_1} A^2 = 3HD_3.$$

- Intermodulation creates harmonics at distances  $\Delta\omega = \omega_2 - \omega_1$ .

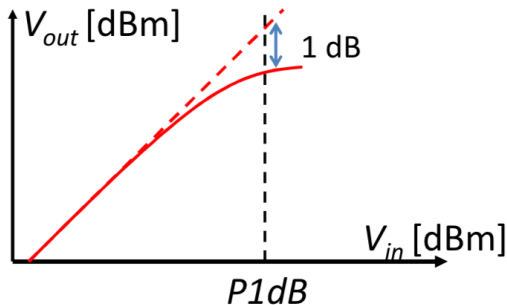


# 1-dB Compression Point

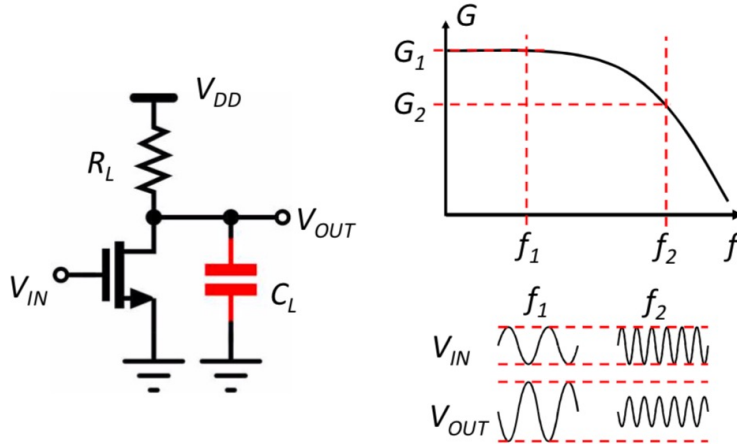
- Let  $V_{in} = A \cdot \cos\omega_1 t$

then:

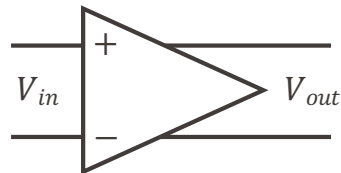
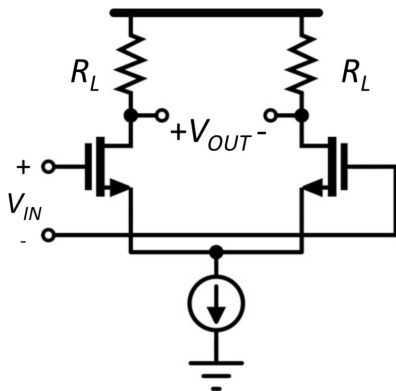
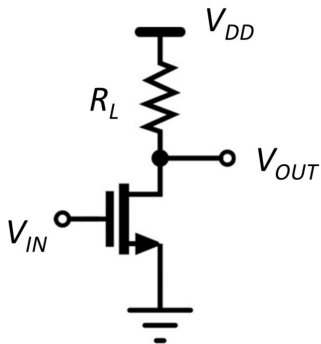
$$\begin{aligned} V_{out} &= a_1 V_{in} + a_3 V_{in}^3 \\ &= \left( a_1 + \frac{3}{4} a_3 A^2 \right) \cdot A \cdot \cos\omega t + \frac{a_3}{4} A^3 \cdot \cos 3\omega t \end{aligned}$$



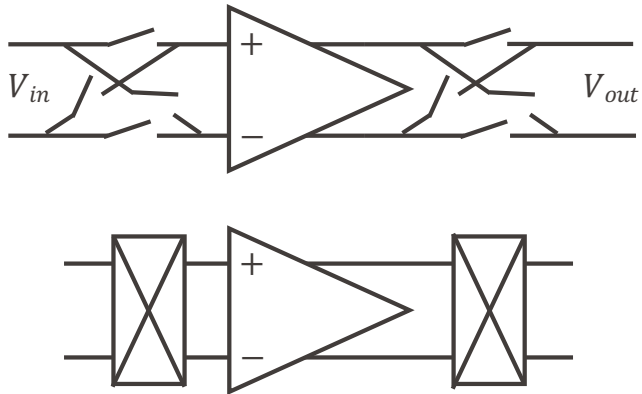
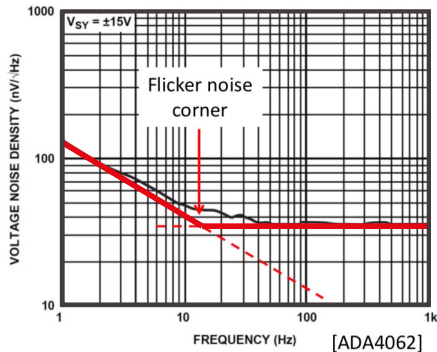
- Amplifier has frequency limits due to internal passive components.



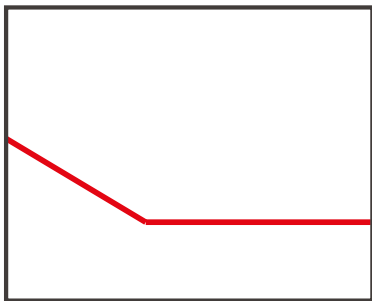
- Input/output characteristic = odd function
- No offset ( $a_0 = 0$ ), no even-order distortions ( $a_i = 0, HD_i = 0, i = 2, 4, 6, \dots$ )
- Mismatch destroys, in part, this property.



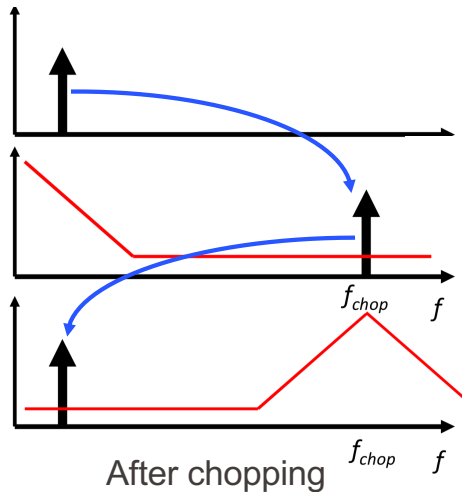
- Reduce  $1/f$  noise
- Cancel mismatch effects (to a first approximation)



# Chopper Amplifiers (2)



Before chopping

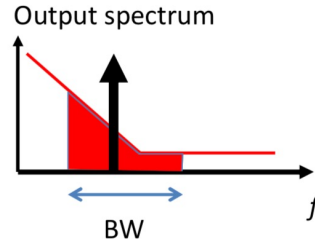


After chopping

# Noise Specifications

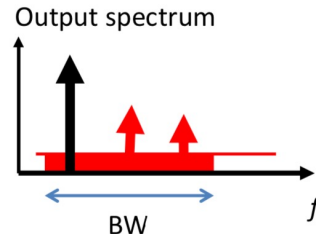
- $S_{out}$  = signal power
- $N_{out}$  = noise power
- Signal-to-Noise Ratio

$$SNR = \frac{S_{out}}{N_{out}}$$



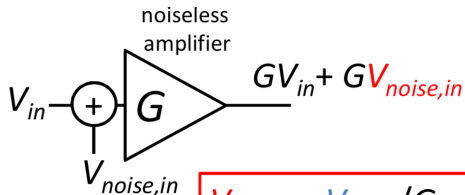
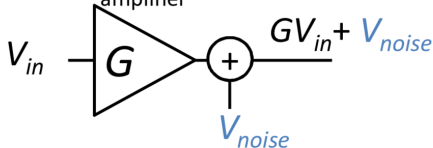
- Must be defined for a certain bandwidth BW
- If also distortion are taken into account:
  - Signal-to-Noise-and-Distortion-Ratio

$$\begin{aligned}
 \text{– } SNDR &= \frac{S_{out}}{\sqrt{N_{out}^2 + S_{out}^2 THD^2}} \\
 &= \sqrt{\frac{1}{\frac{1}{SNR^2} + THD^2}}
 \end{aligned}$$

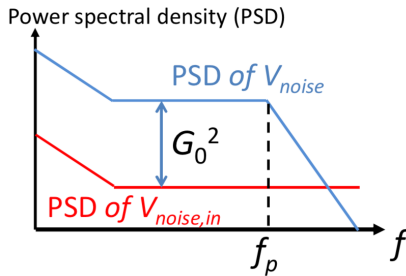
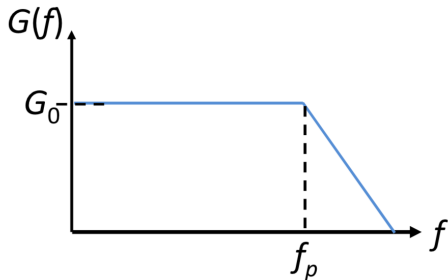


# Noise Specifications (2)

- noiseless amplifier

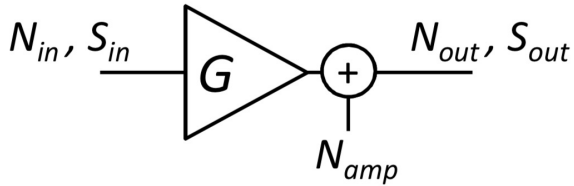


$$V_{noise,in} = V_{noise}/G$$



- Input-referred noise ( $V_{noise,in}$ ) is an useful tool for calculation
- But it is not really there!

# Noise Specifications (3)



$$N_{out} = G^2 N_{in} + N_{amp}$$

$$S_{out} = G^2 S_{in}$$

$$N_{amp, in-referred} = N_{amp} / G^2$$

- Noise Figure

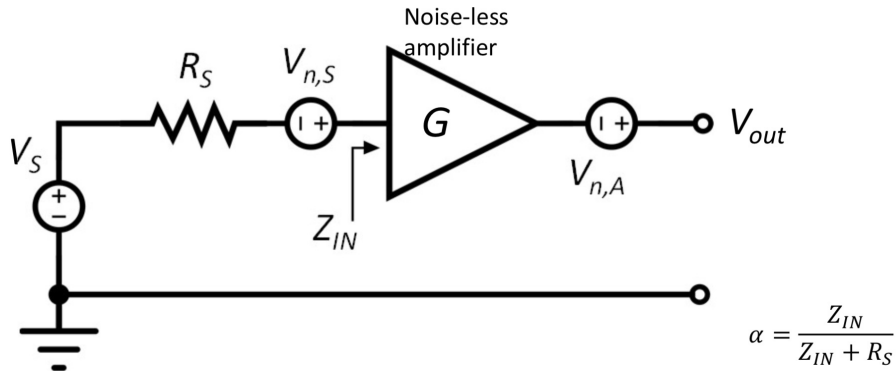
$$NF = \frac{S_{in}/N_{in}}{S_{out}/N_{out}} = \frac{S_{in} N_{out}}{S_{out} N_{in}} = \frac{1}{G} \cdot \frac{GN_{in} + N_{amp}}{N_{in}} = 1 + \frac{N_{amp}}{GN_{in}}$$

- By definition  $N_{in} = 4kTR_S$ ,  $R_S = 50 \Omega$ ,  $T = 290 \text{ K}$

$$- NF = 1 + \frac{N_{amp, in-referred}}{4kTR_S}$$

- $NF$  is expressed in dB
- $NF$  is frequency dependent

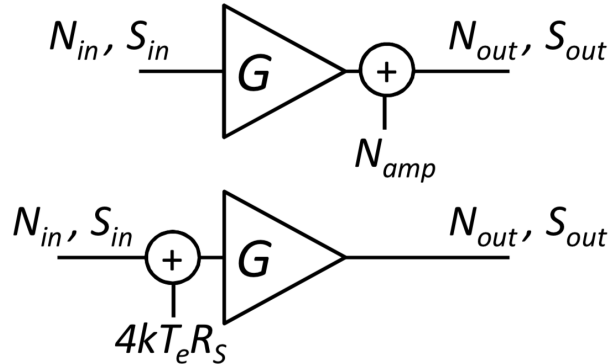
# Noise Figure



- $SNR_{in} = \frac{V_S^2 |\alpha|^2}{V_{n,S}^2 |\alpha|^2} = \frac{V_S^2}{V_{n,S}^2}, SNR_{out} = \frac{V_S^2 |\alpha|^2 |G|^2}{V_{n,S}^2 |\alpha|^2 |G|^2 + V_{n,A}^2}$
- $NF = \frac{SNR_{in}}{SN_{out}} = \frac{1}{\frac{|\alpha|^2 |G|^2}{V_{n,S}^2} + \frac{V_{n,A}^2}{V_{n,S}^2}}$ 

Noise at the output  
Noise at the output due only to input noise
- **Be aware:** NF depends on source and input impedance

# Noise Temperature



- $T_e$  is temperature of resistor  $R_S$  to generate same output noise
- $NF = 1 + \frac{N_{amp, in-referre}}{4kT_0 R_S} = 1 + \frac{4kT_e R_S}{4kT_0 R_S} = 1 + \frac{T_e}{T_0}$
- By definition  $T_0 = 290$  K
- Equivalent noise resistance is defined in analog way

# Example

- Amplifier noise is the same as a 50  $\Omega$  resistance (input referred):

$$\begin{aligned} - V_{in,rms} &= (4 kT R_S BW)^{0.5} \\ &= 0.9 \text{ nV}_{\text{rms}} \end{aligned}$$

@ 290 K,  $BW = 1$  Hz

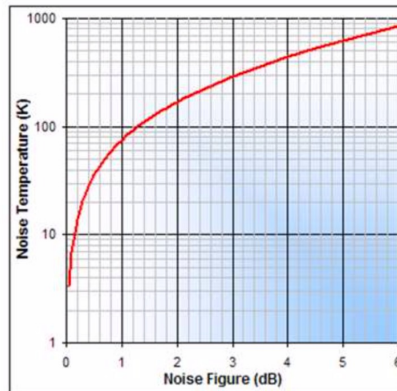
$$- NF = 3 \text{ dB}, T_e = 290 \text{ K}, R_e = 50 \Omega$$

- We cool down the amplifier to 4 K. Assuming the noise scale with T:

$$\begin{aligned} - V_{in,rms} &= (4 kT R_S BW)^{0.5} \\ &= 0.1 \text{ nV}_{\text{rms}} \end{aligned}$$

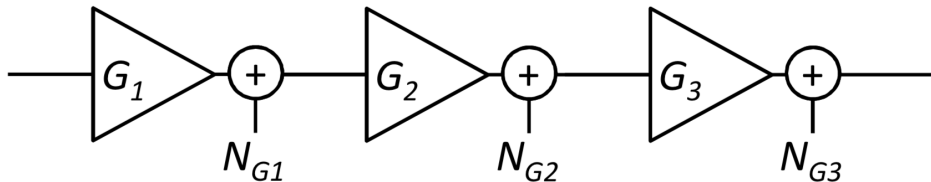
@ 4 K,  $BW = 1$  Hz

$$- NF = 0.06 \text{ dB}, T_e = 4 \text{ K}, R_e = 0.7 \Omega$$



[<http://www.rfcafe.com/references/calculators/noise-figure-temperature-calculator.htm>]

# Cascading Amplifiers



- Input-referred noise

$$- V_{noise,in} = \frac{N_{G1}}{G_1} + \frac{N_{G2}}{G_1 G_2} + \frac{N_{G3}}{G_1 G_2 G_3} + \dots$$

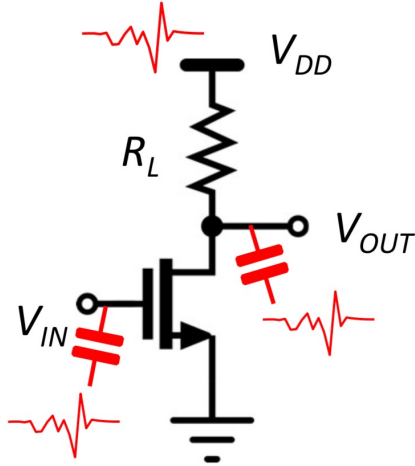
- Noise Figure

$$- NF = NF_1 + \frac{NF_2 - 1}{G_1} + \frac{NF_3 - 1}{G_1} + \dots$$

– “Friis” formula

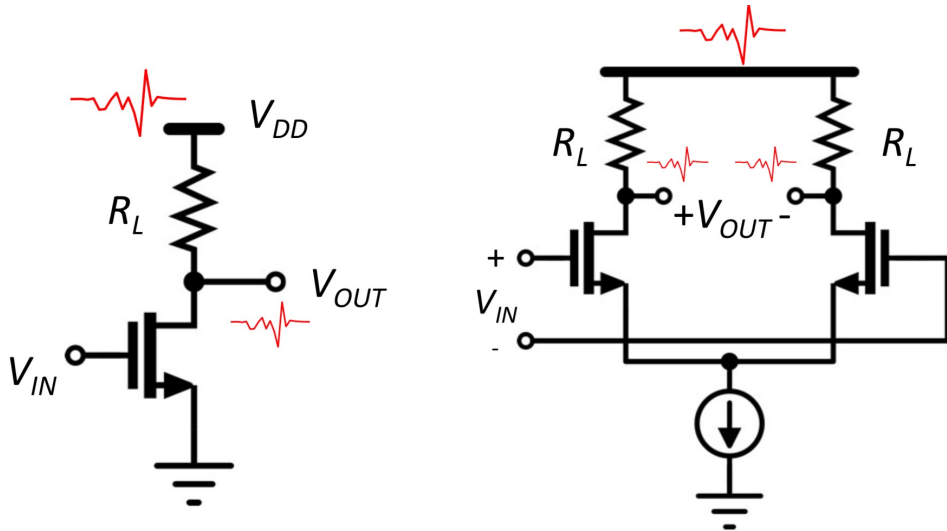
– Note:  $G_i$  is the available power gain

# Immunity to External Interference



- Interference coupling through signal lines
  - Inductive coupling
  - Capacitive coupling
- Interference coupling through supplies

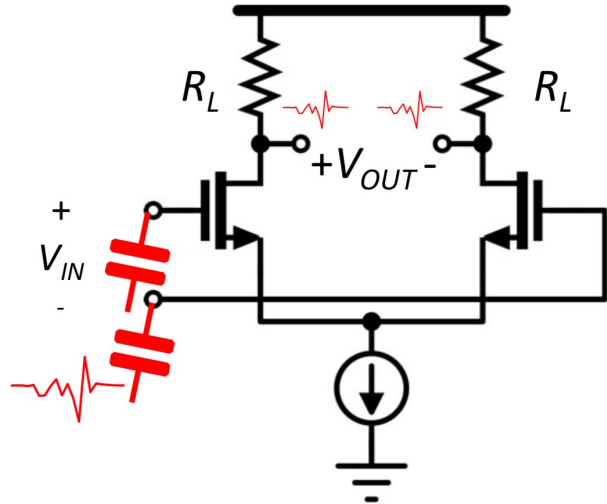
## Immunity to External Interference (2)

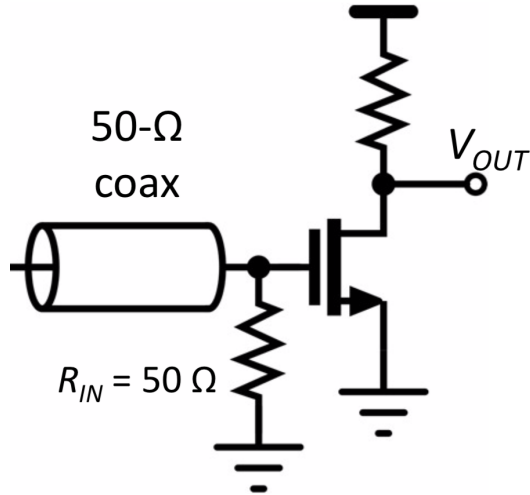


- Differential structure cancels supply noise (when perfect matching)
- Power Supply Rejection Ratio (PSRR) =  $20 \log_{10}(V_{\text{noise,out}}/V_{\text{noise,supply}})$

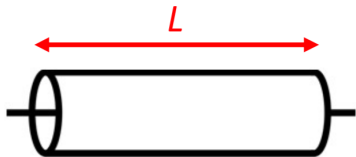
# Immunity to External Interference (3)

- Differential structure cancels common-mode noise
  - (when perfect matching)
- Common-Mode Rejection Ratio
$$\text{CMRR} = V_{\text{noise,out}} / V_{\text{noise,CM}}$$
- Always try to route signals differentially
  - Ex. Twisted pairs



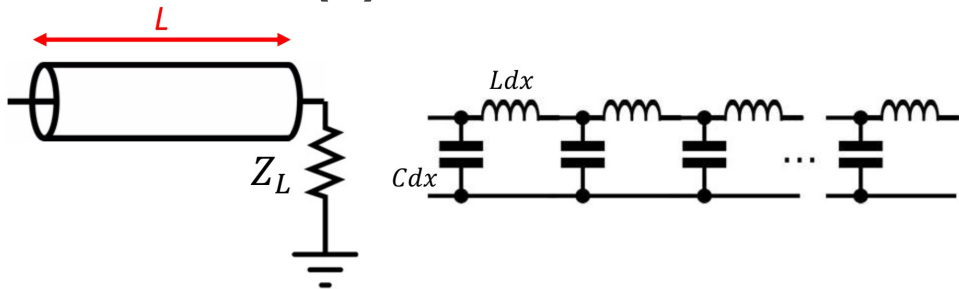


- Coaxial lines to propagate high frequency signals
  - Controlled impedance
  - Typically  $R_o = 50 \Omega$
- If no input matching  $R_{IN} \neq 50 \Omega$ 
  - Previous stage output load depends on line length
  - Previous stage load is different than expected  $\Rightarrow$  malfunctioning
  - Multiple reflections  $\Rightarrow$  signal distortion
- Similar requirements for output impedance



- Signal propagation time is finite
  - $v = \frac{c}{\sqrt{\epsilon_r \mu_r}}$
  - $L = 1 \text{ m} \Rightarrow$  typically  $\Delta t = 4 \text{ ns}$
- Propagation effect can be ignored if  $L < \frac{\lambda}{10}$ 
  - $L = 1 \text{ m} \Rightarrow \lambda = \frac{v}{f} > 0.1 \text{ m} \Rightarrow f < 2.25 \text{ GHz}$
- **Propagation effects are important at high frequency**

## Coaxial Cables (2)



- Modelled as sequence of distributed LC filters
- Electrical waves can propagate in both direction
- **Characteristic impedance:**  $Z_0 = \sqrt{L/C}$  , typ. 50  $\Omega$  or 75  $\Omega$
- Standing waves can form due to reflections
  - Destructive interference with reflected wave
  - If unlucky, no voltage at the receiving end
- **Reflection coefficient:**  $\Gamma = \frac{Z_L - Z_0}{Z_L + Z_0}$

# Impedance Matching

- Input matching measured by  $S_{11}$

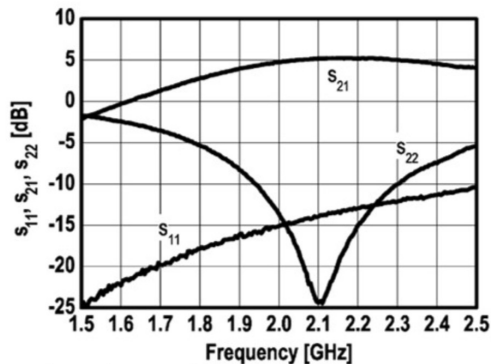
$$S_{11} = \frac{Z_{in} - R_0}{Z_{in} + R_0}$$

- Output matching measured by  $S_{22}$

$$S_{22} = \frac{Z_{out} - R_0}{Z_{out} + R_0}$$

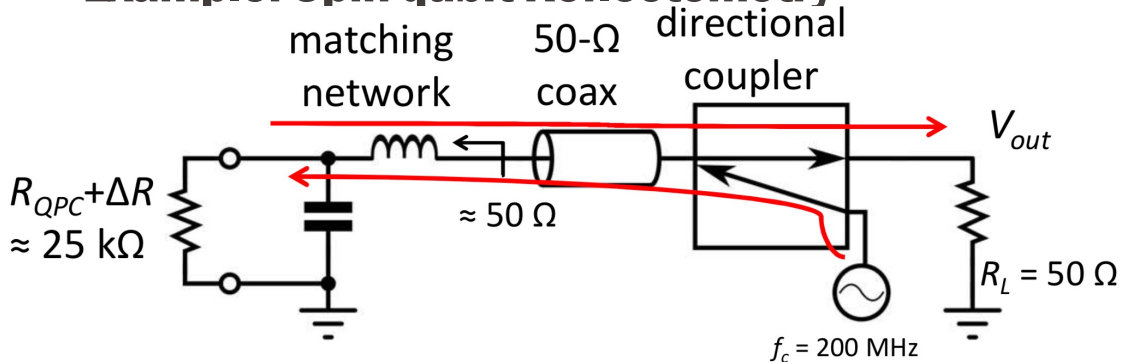
- Typical requirement

$$S_{11}, S_{22} < -10 \text{ dB}$$



[Jussila 2008]

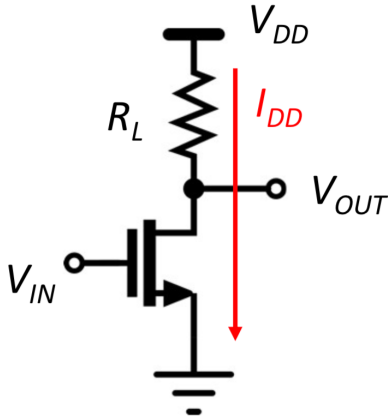
# Example: Spin qubit Reflectometry



- Reflection of power also follows the same equation:

$$S_{11} = \frac{Z_{in} - R_0}{Z_{in} + R_0}$$

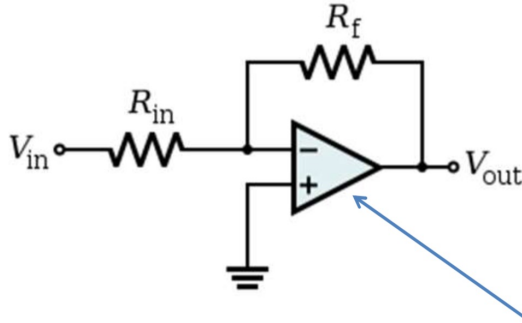
- Matching network adapt impedance from  $R_{QPC}$  to  $50 \Omega$
- $\Delta R = 0 \Rightarrow$  impedance matching  $\Rightarrow$  no reflected power



- $P = V_{DD} \cdot I_{DD}$
- Typical trade-offs:
  - Gain:  $G = -gm \cdot R_L \propto I_{DD}$
  - Noise:  $v_{in,rms} \propto 1/I_{DD}$
  - Linearity

- For cryo electronics, power dissipated by cooling
- **Limiting factor for large scale quantum computers**

# Feedback Amplifier (Inverting OpAmp)

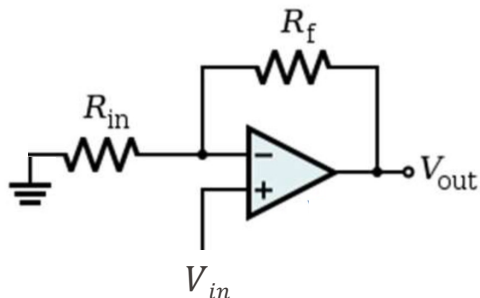


$$\frac{V_{out}}{V_{in}} = -\frac{R_f}{R_{in}}$$

Opamp = amplifier with very large DC gain  
and low output impedance

- Use feedback to improve
  - Well-controlled gain
  - High linearity
- But limited bandwidth

# Feedback Amplifier (Non-inverting OpAmp)



$$\frac{V_{out}}{V_{in}} = 1 + \frac{R_f}{R_{in}}$$

Special case:  $R_{in} \rightarrow \infty$  (open circuit) and  $R_f \rightarrow 0$  (short),  
then gain = 1 (buffer)

# **Analog-to-Digital Converters (ADCs)**

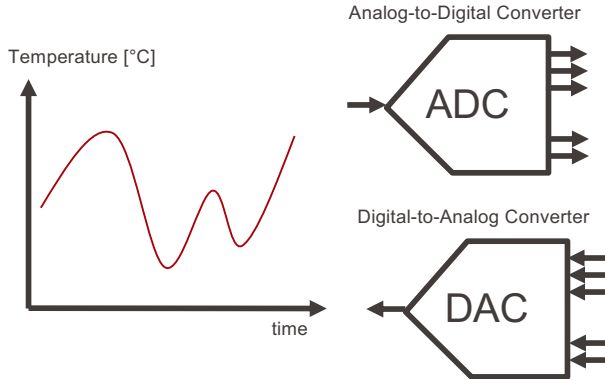
# **Digital-to-Analog Converters (DACs)**

# Analog-to-Digital Converters (ADCs) Part I

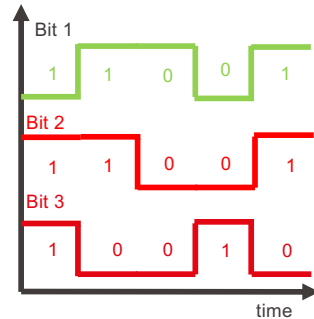


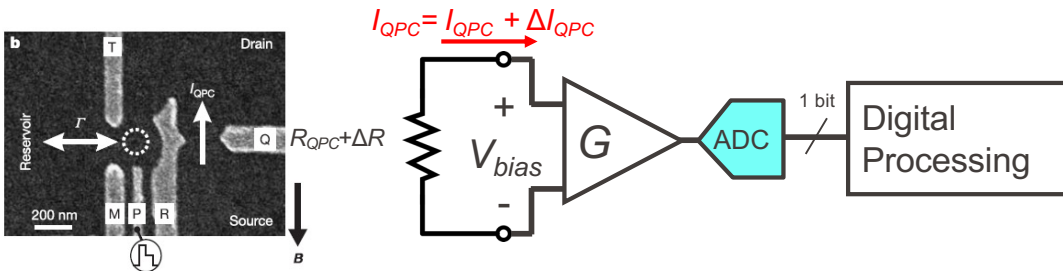
# Analog vs. Digital

- The world is analog
  - Temperature, humidity, speed, light,... are analog!



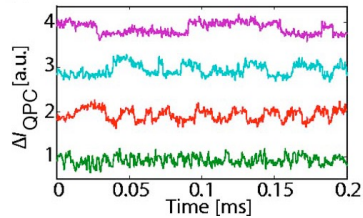
- Computing is digital



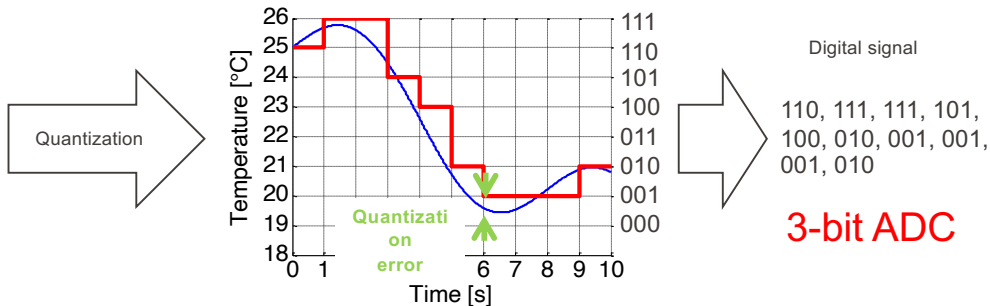
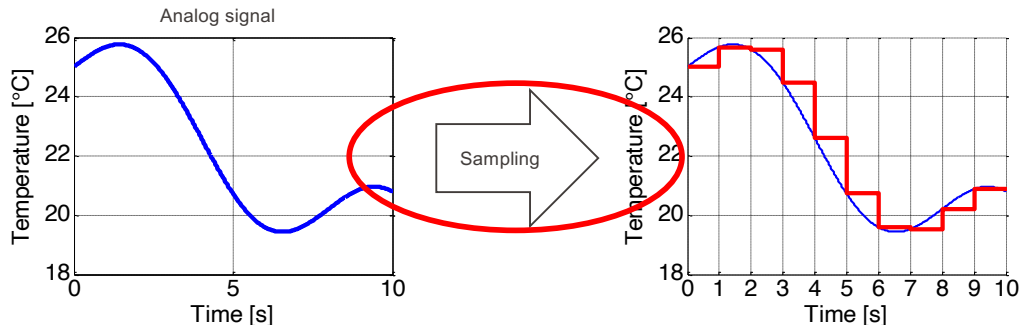


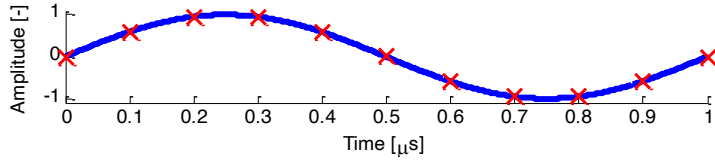
Source: I.T. Vink

- Decide if qubit is  $|0\rangle$  or  $|1\rangle$
- **Need for 1-bit ADC**



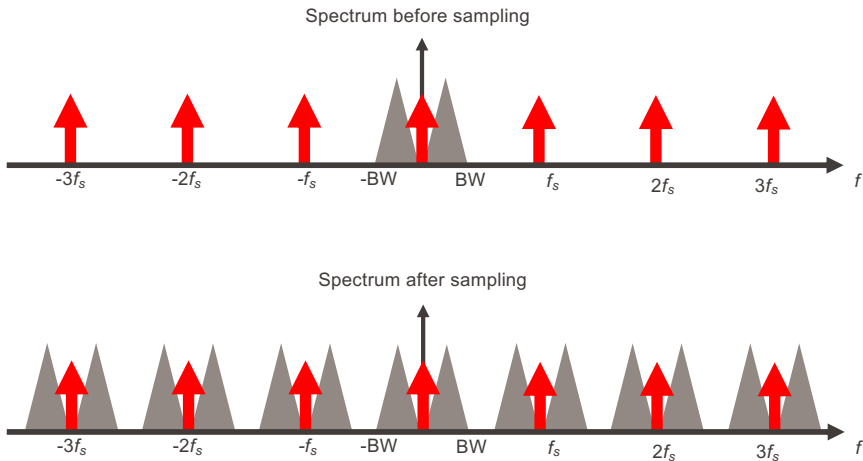
# Sampling and Quantization





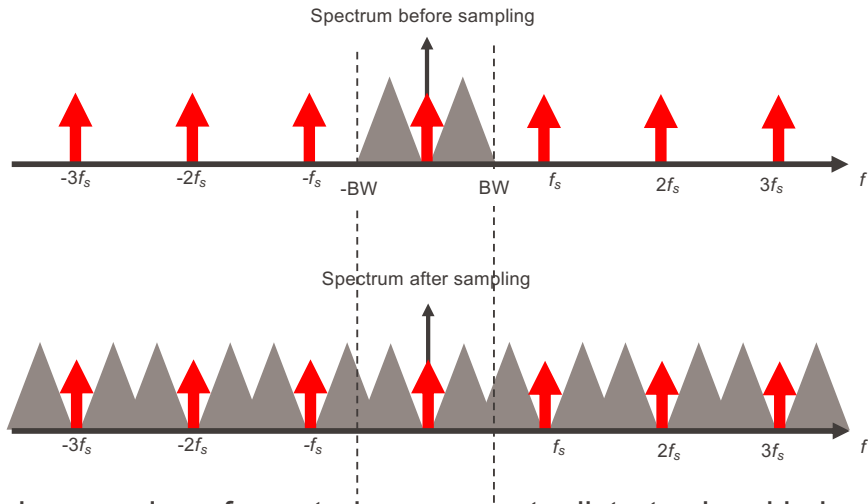
$f_{in} = 1 \text{ MHz}$   
 $f_s = 10 \text{ MHz}$

# Sampling ( $BW < f_s/2$ )

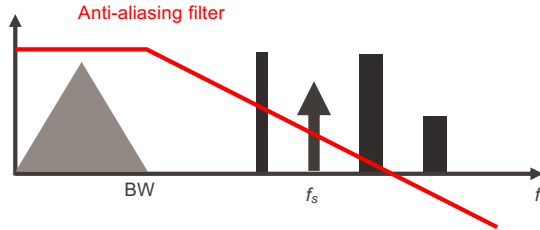


- Replica of the signal around harmonics of sampling frequency ( $f_s$ )

# Sampling ( $BW > f_s/2$ )

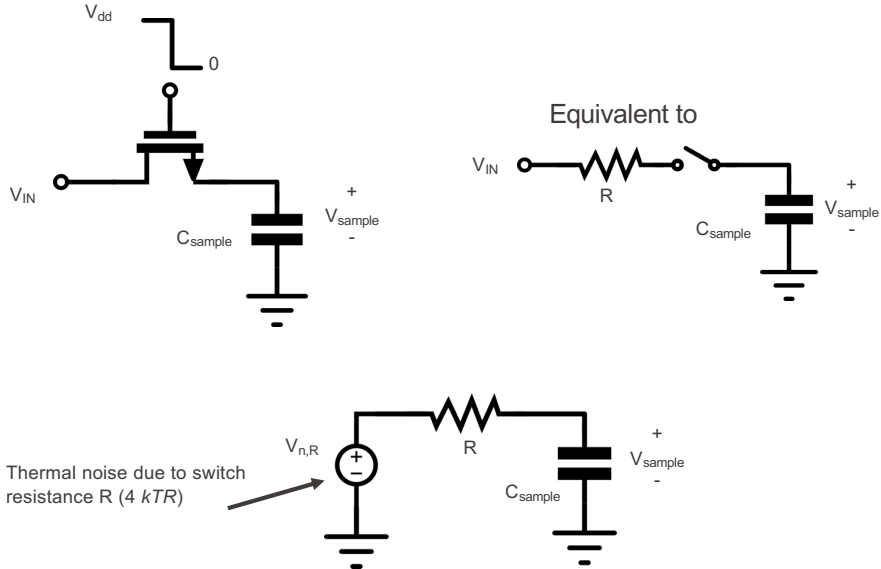


- Aliasing: overlap of spectral components distorts signal in baseband

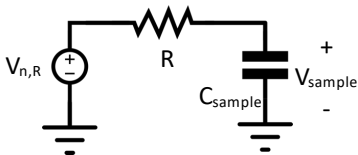


- Nyquist frequency:  $f_s = 2 \cdot BW$
- Anti-aliasing filter attenuates high frequency ( $> f_s/2$ ) components before sampling
- Beware! Also noise (always present) folds back into baseband.

# Sampling Limitations – Noise

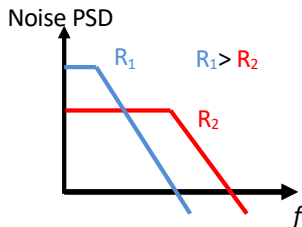


# Sampling Limitations – Noise ( $kT/C$ )



$$\langle V_{sample}^2 \rangle = \int_0^{+\infty} S_{V_{n,R}}(f) |H(f)|^2 df = \frac{kT}{C}$$

- Lower noise  $\Rightarrow$  Larger cap
- Larger cap  $\Rightarrow$  less BW or more power
  - BW  $\sim gm/C$  and  $gm \sim I$



$C_{sample}$	Noise (rms)	SNR ( $V_{IN}=1 V_{pp}$ )	ENOB [see slide 31]
1 pF	64 $\mu$ V	78 dB	12.6 bit
10 pF	20 $\mu$ V	88 dB	14.3 bit
100 pF	6 $\mu$ V	98 dB	16 bit

Derivation:

$$H(f) = \frac{1}{1 + j2\pi RCf}$$

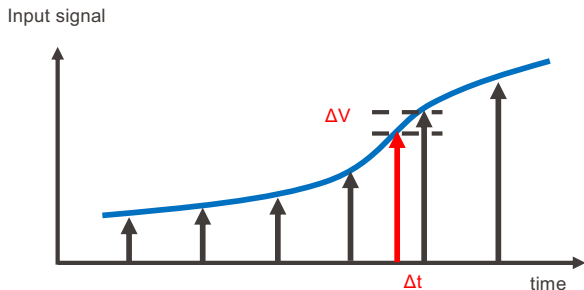
$$S_{V_{n,R}}(f) = 4kTR$$



$$\int_0^{+\infty} S_{V_{n,R}}(f) |H(f)|^2 df = \int_0^{+\infty} \frac{4kTR}{1 + (2\pi RCf)^2} df$$

$$= \int_0^{+\infty} \frac{4kTR}{1 + (2\pi RCf)^2} df = \frac{4kTR}{2\pi RC} \int_0^{+\infty} \frac{1}{1 + x^2} dx$$

$$= \frac{2kT}{\pi C} \lim_{x \rightarrow +\infty} \text{atan } x = \frac{kT}{C}$$



$$\Delta V \cong \Delta t \frac{dV}{dt}$$

- For a sine input:

$$V = A \sin \omega t$$

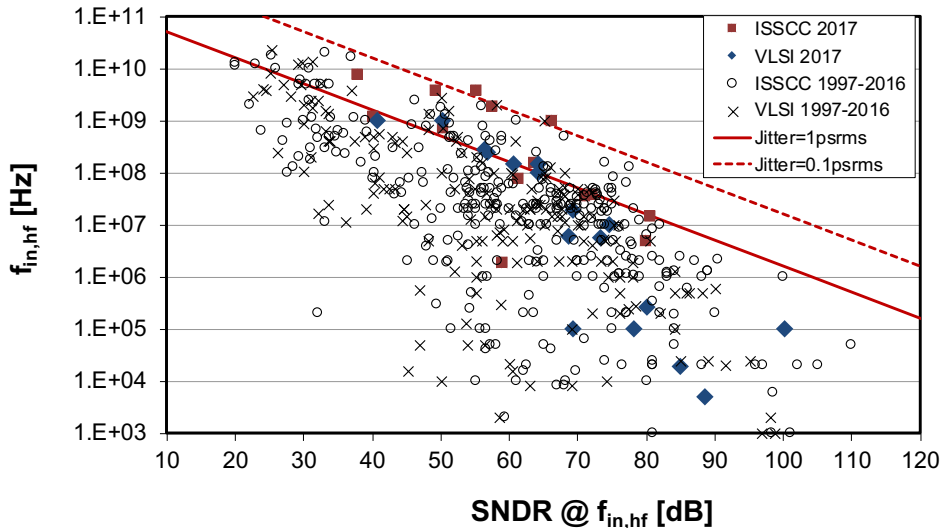
$$\Delta V = \Delta t \omega \cos \omega t$$

- Integrating over a full sine period:

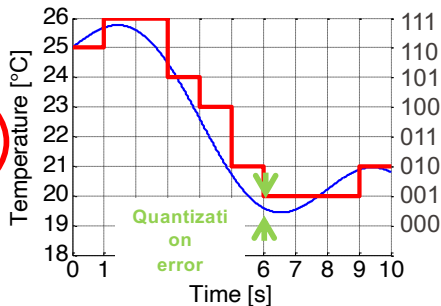
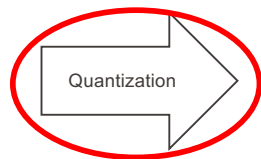
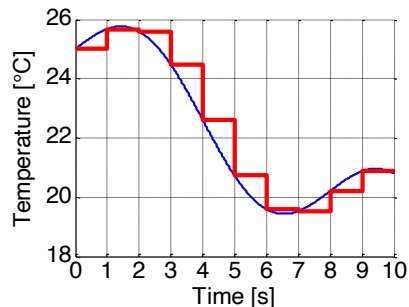
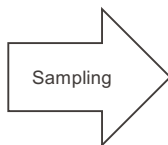
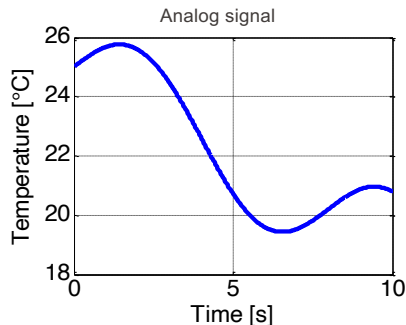
$$\sigma_V^2 = \frac{A^2}{\sqrt{2}} \sigma_t^2 \omega^2 \Rightarrow \text{SNR} = \frac{1}{\sigma_t^2 \omega^2}$$

Jitter

# Sampling Limitation - Jitter



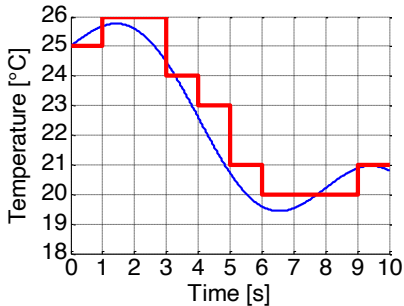
# Sampling and Quantization



Digital signal

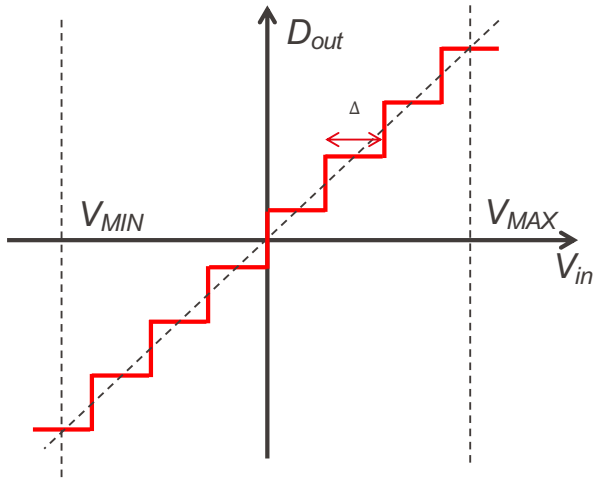
110, 111, 111, 101,  
100, 010, 001, 001,  
001, 010

**3-bit ADC**



$$\Delta = \frac{V_{MAX} - V_{MIN}}{2^N - 1}$$

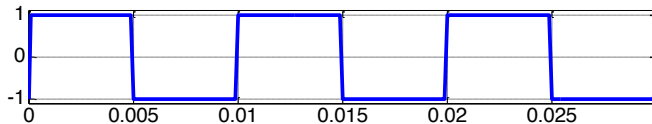
- $\Delta$  = quantization step, LSB (least significant bit)
- $N$  = number of bits of the ADC



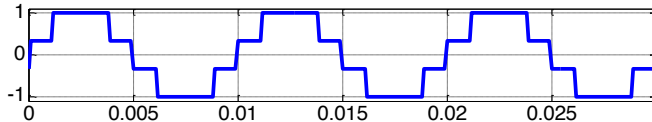
# Quantization – Signal Spectrum

Quantizing a sinusoid at 10 kHz

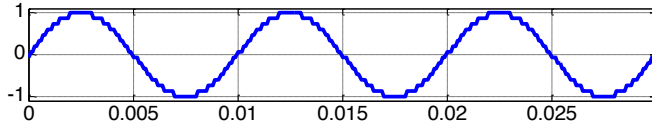
N = 1 bit



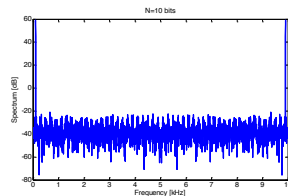
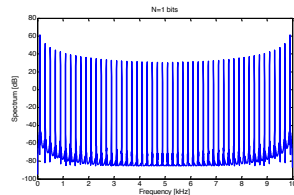
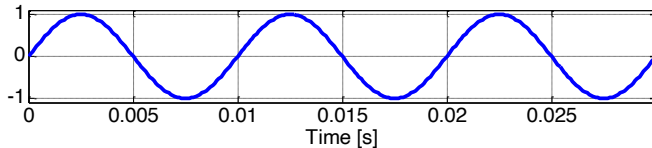
N = 2 bit



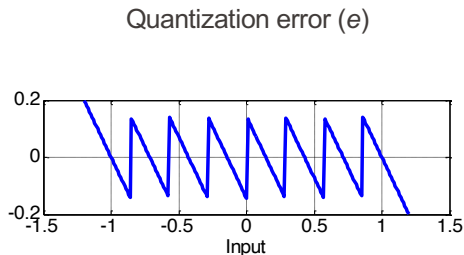
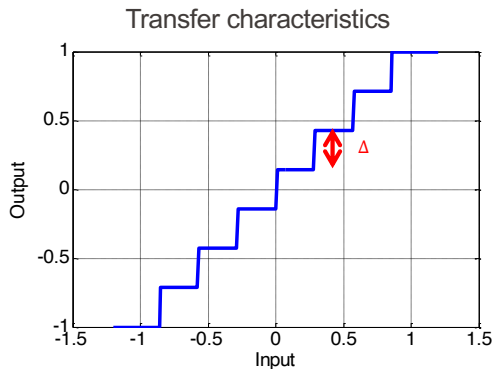
N = 4 bit



N = 8 bit



# Quantization Noise



Variance of the quantization error (assuming uniform distribution):

$$P_q = \int_{-\Delta/2}^{\Delta/2} e^2 P(e) de = \int_{-\Delta/2}^{\Delta/2} e^2 \frac{1}{\Delta} de = \frac{1}{\Delta} \frac{e^3}{3} \Big|_{-\frac{\Delta}{2}}^{+\frac{\Delta}{2}} = \frac{\Delta^2}{12}$$

# Signal-to-Noise Ratio (SNR)

- For a full-scale sinusoid:  $P_S = \frac{(\Delta 2^{N-1})^2}{2}$
- Since  $P_q = \frac{\Delta^2}{12}$ ,  $SNR = \frac{P_S}{P_q} = 1.5 \cdot 2^{2N}$

- In dB:

$$SNR_{dB} = 10 \log_{10} \frac{P_S}{P_q} = 6.02 \cdot N + 1.76$$

$$N = \frac{SNR_{dB} - 1.76}{6.02}$$

# Effective Number of Bits (ENOB)

- Consider
  - Real ADC (noise, quantization noise, distortion) with given  $SNDR$
  - Ideal ADC (only quantization noise) with same  $SNDR$
- The number of bits of the ideal ADC is

$$ENOB = \frac{SNDR_{dB} - 1.76}{6.02}$$

Recall for q-noise:

$$SNR = 1.5 \cdot 2^{2N}$$

$$SNR_{dB} = 6.02 \cdot N + 1.76$$

- Often  $ENOB \neq$  number of (*marketing*) bits

Example:

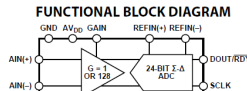


24-Bit, Pin-Programmable,  
Ultralow Power Sigma-Delta ADC

AD7780

## FEATURES

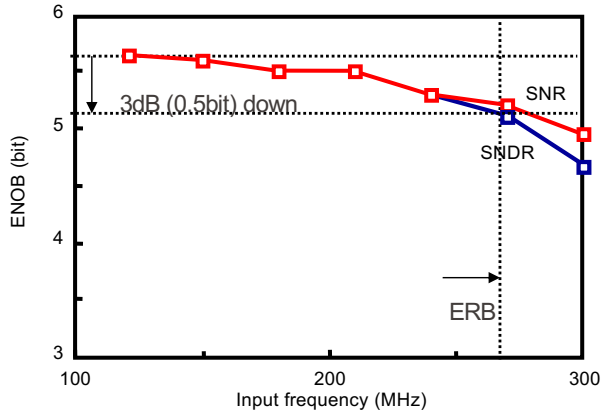
- Pin-programmable filter response
- Update rate: 10 Hz or 16.7 Hz
- Pin-programmable in-amp gain
- Pin-programmable power-down and reset



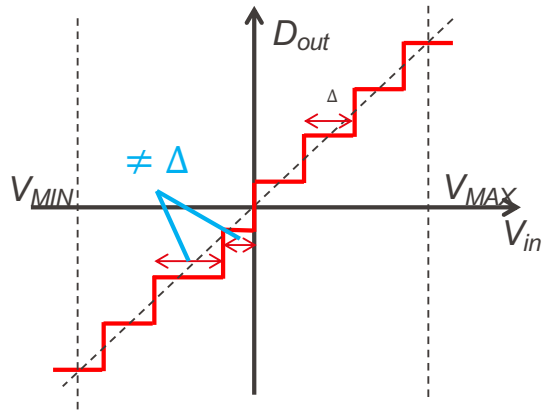
But:

- SNR = 130 dB
  - INL > 6 bits
- ⇒ ENOB < 21 bits

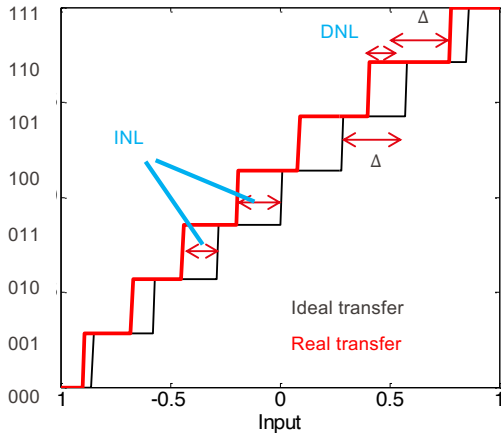
# Effective Resolution Bandwidth (ERB)



- SNDR changes with input frequency
- ERB is the bandwidth at which SNDR drops by 3 dB (0.5 bits)
- Note: we are observing variations of the input frequency, not of the sample frequency



- Mismatch causes errors in the input/output transfer

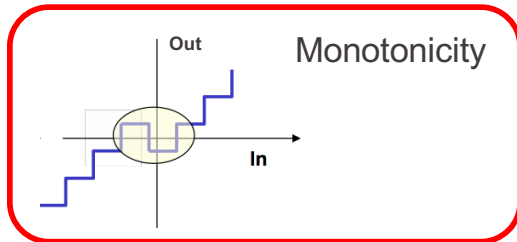


Differential non-linearity (DNL)

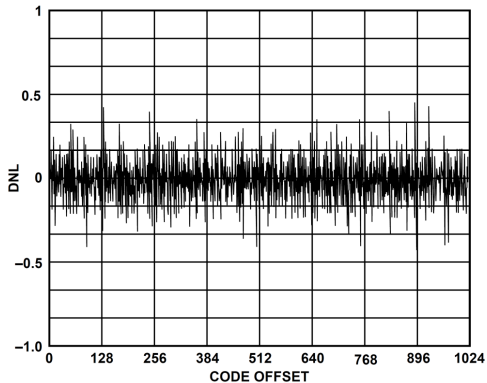
$$DNL[i] = INL[i] - INL[i - 1]$$

Integral non-linearity (INL)

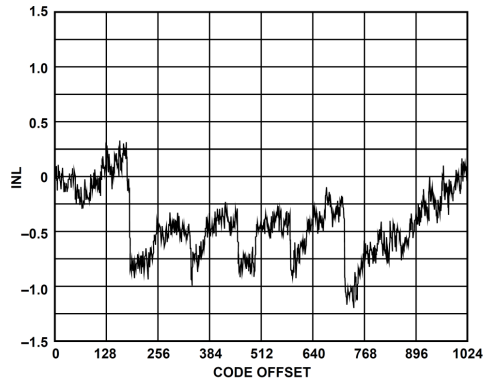
$$INL[i] = \sum_{j=1}^i DNL[j]$$



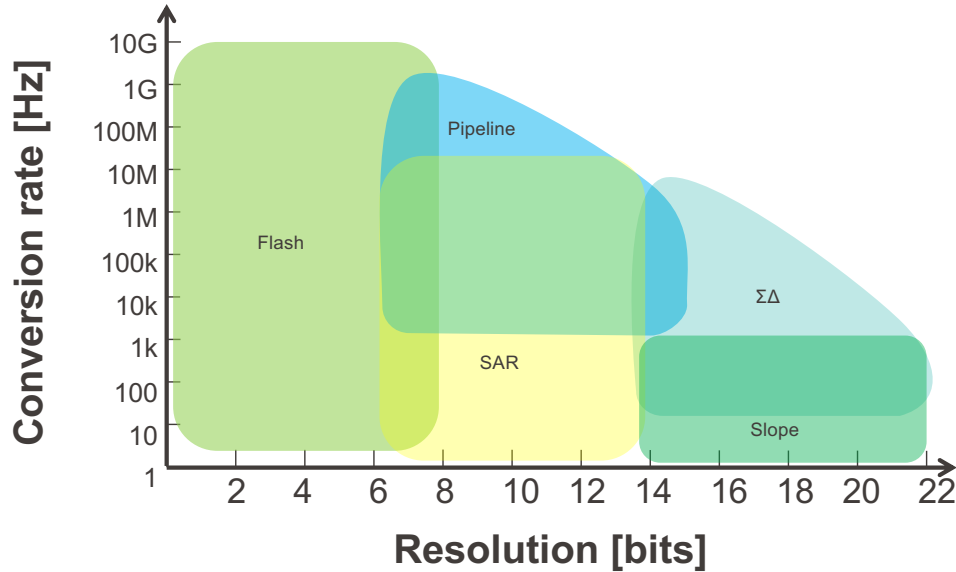
## DNL



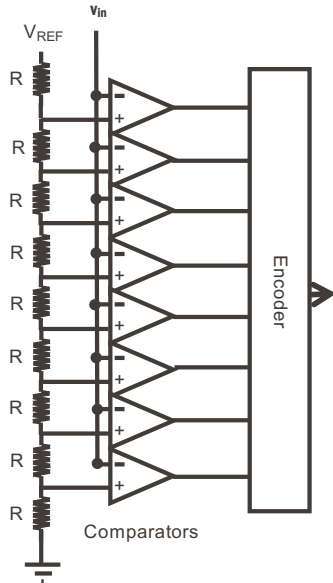
## INL



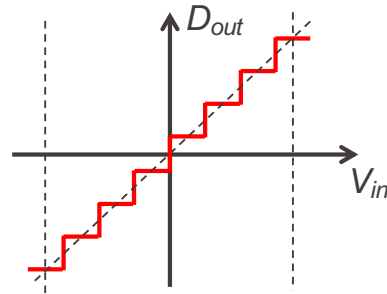
[Datasheet: AD9201]



Source: Pelgrom 2006



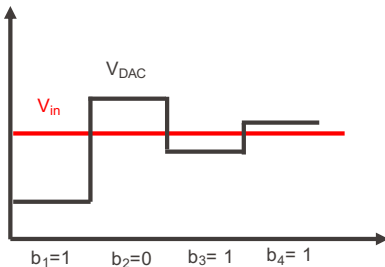
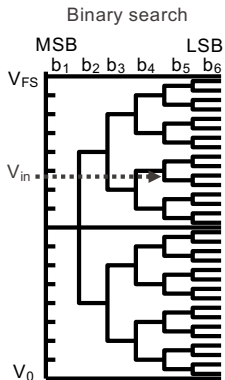
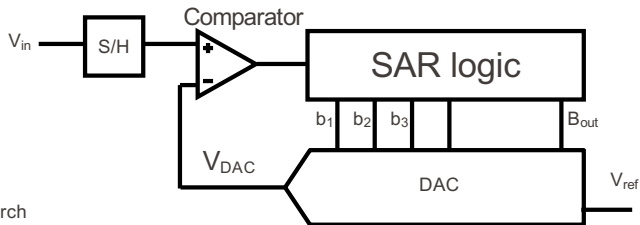
Digital  
out



Features:

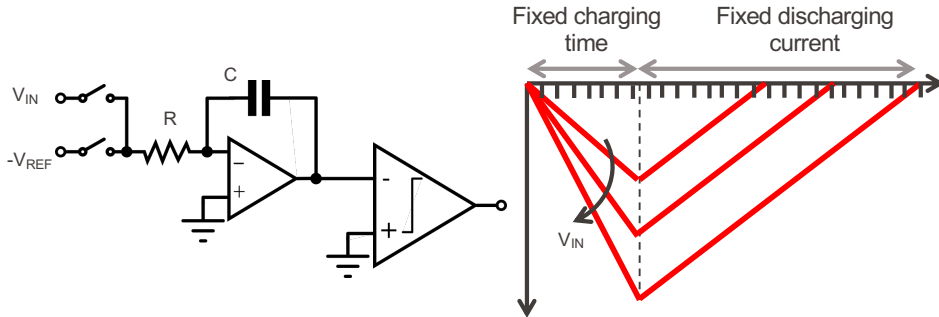
- Low resolution (<8 bits)
- High power
- Ultra-high speed
- Large input capacitance

# Successive-approximation ADC (SAR)



## Features:

- Moderate resolution
- Low power
- Relatively low speed
- Easy calibration
- Needs multi-clock



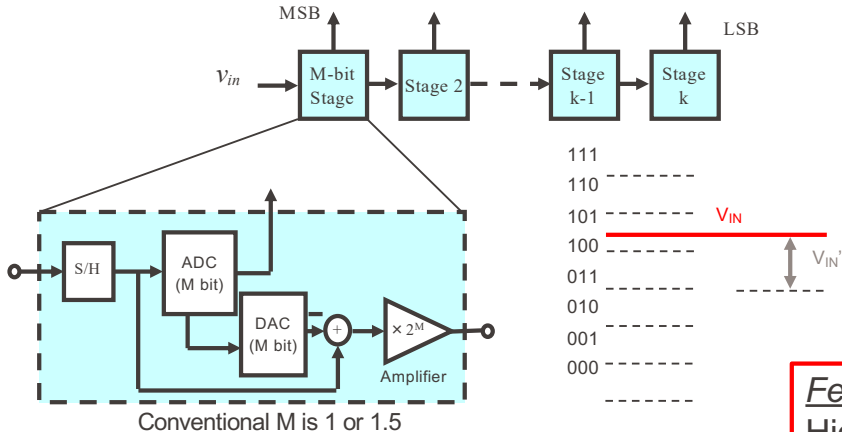
Features:

High resolution (<20b)

Low speed

Small DNL

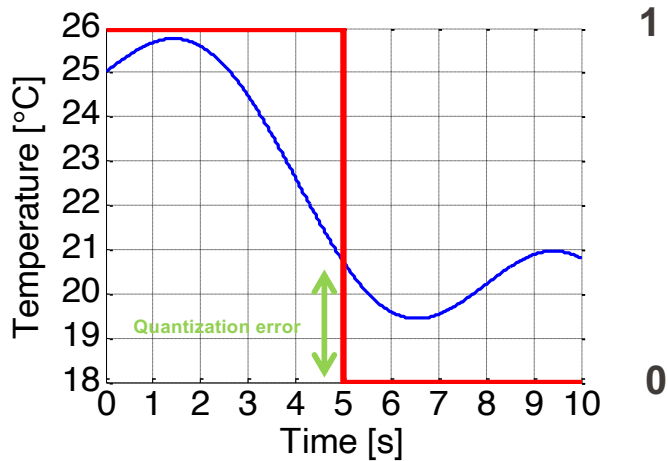
Small area/power



- Cascaded stages contribute less noise
- Scaling of the stage

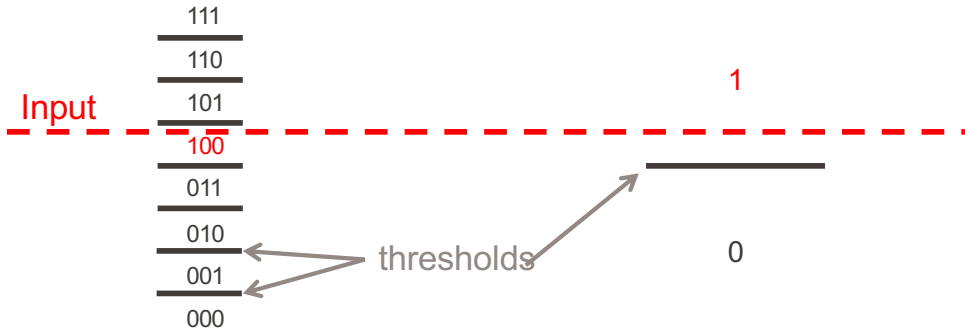
### Features:

High resolution  
Low power  
Moderate speed

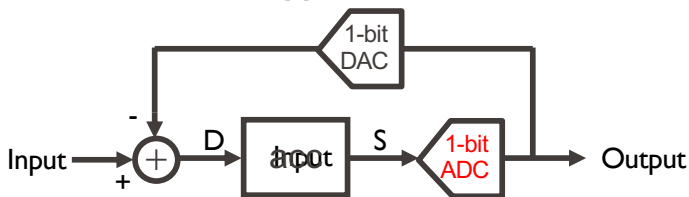
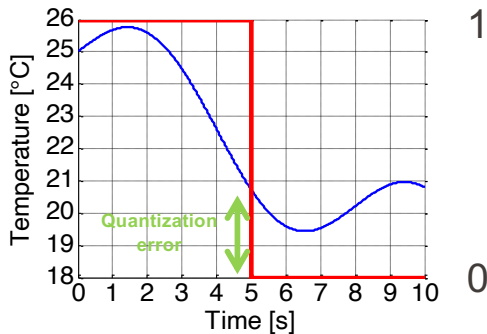


# Why 1-bit ADC?

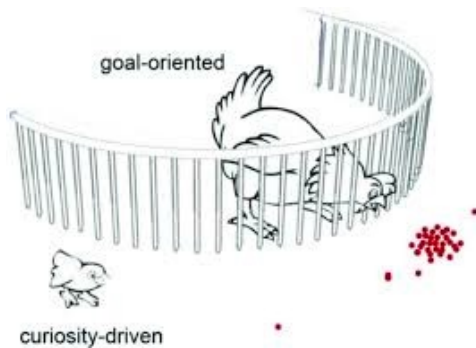
- Multi-bit ADCs
  - Many thresholds
  - Many comparisons
  - Prone to errors
  - Complex circuit
- 1-bit ADCs
  - One threshold
  - One comparison
  - Robust
  - Simple circuit



# Basic Idea of a Sigma-Delta ADC



# Thank you



T. Haensch