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# Numerical Analysis and Computational Mathematics

Fall Semester 2025 – CSE Section

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## Linear systems: iterative methods

**Note:** in this series you will need the MATLAB functions implemented in Series 9.

### Exercise I (MATLAB)

Consider the general linear system  $A\mathbf{x} = \mathbf{b}$  with  $A \in \mathbb{R}^{n \times n}$  and  $\mathbf{x}, \mathbf{b} \in \mathbb{R}^n$ .

- a) Write a MATLAB function `preconditioned_gradient.m` that implements the preconditioned gradient method for the solution of the linear system. The stopping criterion should be based on the norm of the residual:  $r^{(k)} = \|\mathbf{r}^{(k)}\| = \|\mathbf{b} - A\mathbf{x}^{(k)}\| < tol$ . Use the function `preconditioned_gradient_template.m` as template:

```
function [ x, k, res ] = preconditioned_gradient( A, b, P, x0, tol, kmax )
% PRECONDITIONED_GRADIENT solve the linear system A x = b by means
% of the Preconditioned Gradient method; the preconditioning matrix must be
% non singular. Stopping criterion based on the residual.
% [ x, k, res ] = preconditioned_gradient( A, b, P, x0, tol, kmax )
% Inputs: A      = matrix (square matrix)
%         b      = vector (right hand side of the linear system)
%         P      = preconditioning matrix (non singular, same size of A)
%         x0     = initial solution (column vector)
%         tol    = tolerance for the stopping criterion based on residual
%         kmax   = maximum number of iterations
% Outputs: x     = solution vector (column vector)
%         k      = number of iterations at convergence
%         res    = value of the norm of the residual at convergence
%
return
```

(*Hint:* use the MATLAB command `\` to solve, at each step of the iterative method, the linear system involving the preconditioning matrix  $P$ ).



### Exercise III (Theoretical)

Consider the linear system  $A\mathbf{x} = \mathbf{b}$ , where  $A \in \mathbb{R}^{n \times n}$  and  $\mathbf{x}, \mathbf{b} \in \mathbb{R}^n$ . For its numerical solution, we use an iterative method, where  $\mathbf{x}$  is obtained as the limit of the sequence  $\{\mathbf{x}^{(k)}\}_{k=0}^{\infty}$ . The iterative method is in the form:

$$\mathbf{x}^{(k+1)} = B\mathbf{x}^{(k)} + \mathbf{g}, \quad k = 0, 1, \dots,$$

for a given initial solution  $\mathbf{x}^{(0)}$ , iteration matrix  $B \in \mathbb{R}^{n \times n}$ , and vector  $\mathbf{g} \in \mathbb{R}^n$ . We assume that there exists an invertible preconditioner  $P \in \mathbb{R}^{n \times n}$  such that  $B = I - P^{-1}A$  and  $\mathbf{g} = P^{-1}\mathbf{b}$ .

Specifically, we set  $n = 2$  and  $A = \begin{bmatrix} 3 & -1 \\ -1 & 2 \end{bmatrix}$ .

- a) Set  $P = P_1 = \beta D$ , where  $D \in \mathbb{R}^{n \times n}$  is the diagonal matrix extracted from  $A$  and  $\beta > 0$  is a parameter. Which iterative method do we obtain for  $\beta = 1$ ? Calculate the values of  $\beta$  for which this iterative method converges for all  $\mathbf{x}^{(0)}$ .
- b) Calculate the value of  $\beta$  for which the iterative method from point a) exhibits the fastest convergence rate (for any choice of  $\mathbf{x}^{(0)}$ ).
- c) Repeat point a) by setting  $P = P_2 = \beta(D - E)$ , where  $E$  is the lower triangular matrix such that  $(E)_{ij} = -(A)_{ij}$  for  $i = 2, \dots, n$ ,  $j = 1, \dots, i - 1$ .
- d) Repeat point b) by considering the preconditioning matrix  $P_2$  from point c).
- e) Which of the two preconditioning matrices  $P_1$  or  $P_2$  and which value of  $\beta$  would you choose to ensure the fastest convergence of the iterative method, starting from a generic initial solution  $\mathbf{x}^{(0)}$ ?