

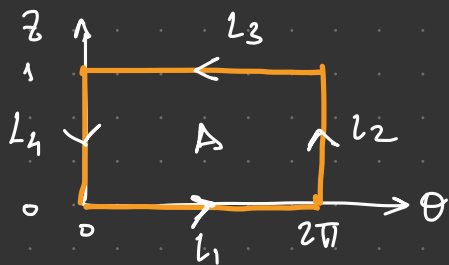
Weem 7 - part 1

Example 1: cylinder $\Sigma = \{ (x, y, z) \in \mathbb{R}^3 : x^2 + y^2 = 1, 0 < z < 1 \}$

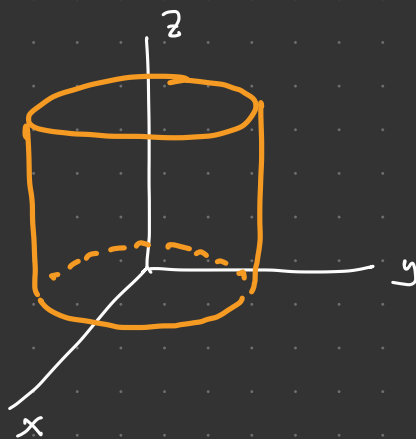
$$A =]0, 2\pi[\times]0, 1[$$

$$\sigma: \bar{A} \rightarrow \mathbb{R}^3$$

$$(\theta, z) \mapsto \sigma(\theta, z) = (\cos\theta, \sin\theta, z)$$



$$\partial A = L_1 \cup L_2 \cup L_3 \cup L_4$$



$$\begin{aligned} \partial \Sigma &= \sigma(\partial A) = \sigma(L_1 \cup L_2 \cup L_3 \cup L_4) \\ &= \sigma(L_1) \cup \sigma(L_2) \cup \sigma(L_3) \cup \sigma(L_4) \end{aligned}$$

$$L_1 = \{ \alpha_1(\theta) = (\theta, 0) \text{ with } \theta: 0 \rightarrow 2\pi \}$$

$$L_2 = \{ \alpha_2(z) = (2\pi, z) \text{ with } z: 0 \rightarrow 1 \}$$

$$L_3 = \{ \alpha_3(\theta) = (\theta, 1) \text{ with } \theta: 2\pi \rightarrow 0 \}$$

$$L_4 = \{ \alpha_4(z) = (0, z) \text{ with } z: 1 \rightarrow 0 \}$$

$$\Gamma_1 = \sigma(L_1(\theta)) = \sigma \circ \alpha_1(\theta)$$

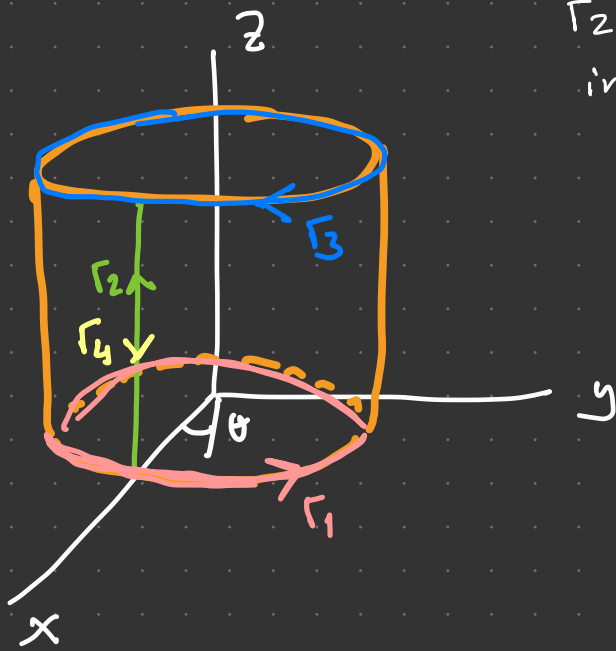
$$\sigma(\theta, z) = (\cos\theta, \sin\theta, z)$$

$$\Gamma_1 = \{ \gamma_1(\theta) = \sigma(\theta, 0) = (\cos\theta, \sin\theta, 0) \text{ with } \theta: 0 \rightarrow 2\pi \}$$

$$\Gamma_2 = \{ \gamma_2(z) = \sigma(2\pi, z) = (1, 0, z) \text{ with } z: 0 \rightarrow 1 \}$$

$$\Gamma_3 = \{ \gamma_3(\theta) = \sigma(\theta, 1) = (\cos\theta, \sin\theta, 1) \text{ with } \theta: 2\pi \rightarrow 0 \}$$

$$\Gamma_4 = \{ \gamma_4(z) = \sigma(0, z) = (1, 0, z) \text{ with } z: 1 \rightarrow 0 \}$$



Γ_2 and Γ_4 are the same, but circulated in opposite sense \rightarrow I remove them both.

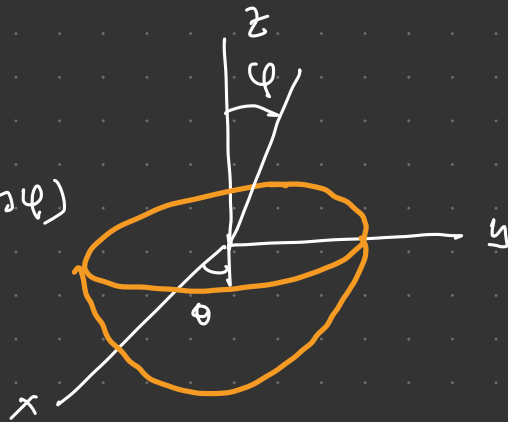
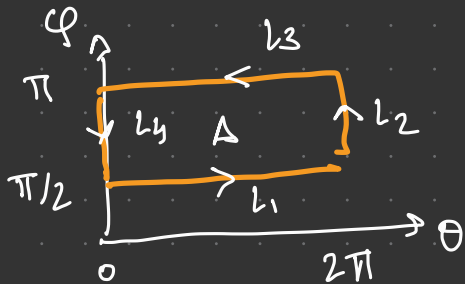
$$\partial\Sigma = \Gamma_1 \cup \Gamma_3$$

Example 2: semi-sphere = $\{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 = 1 \text{ and } z \geq 0\}$

$$A =]0, 2\pi] \times \frac{\pi}{2}, \pi[$$

$$\sigma: \bar{A} \rightarrow \mathbb{R}^3$$

$$(\theta, \varphi) \mapsto \sigma(\theta, \varphi) = (\sin \varphi \cos \theta, \sin \varphi \sin \theta, \cos \varphi)$$



$$\partial \Sigma = \Gamma_1 \cup \Gamma_2 \cup \Gamma_3 \cup \Gamma_4$$

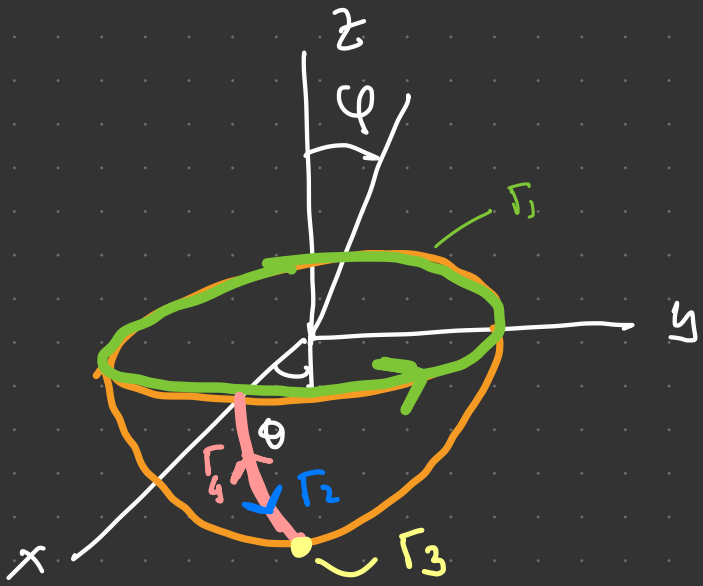
$$\Gamma_1 = \{ \gamma_1(\theta) = \sigma(\theta, \pi/2) = (\cos \theta, \sin \theta, 0) \text{ with } \theta: 0 \rightarrow 2\pi \}$$

$$\times \Gamma_2 = \{ \gamma_2(\varphi) = \sigma(2\pi, \varphi) = (\sin \varphi, 0, \cos \varphi) \text{ with } \varphi: \pi/2 \rightarrow \pi \}$$

$$\times \Gamma_3 = \{ \gamma_3(\theta) = \sigma(\theta, \pi) = (0, 0, -1) \text{ with } \theta: 2\pi \rightarrow 0 \} \rightarrow \text{a point}$$

$$\times \Gamma_4 = \{ \gamma_4(\varphi) = \sigma(0, \varphi) = (\sin \varphi, 0, \cos \varphi) \text{ with } \varphi: \pi \rightarrow \pi/2 \}$$

$$\partial \Sigma = \Gamma_1$$

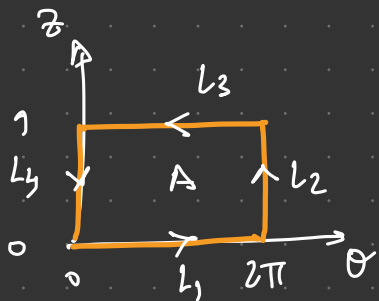


Example 3: cone = $\{ (x, y, z) \in \mathbb{R}^3 : z^2 = x^2 + y^2 \text{ and } 0 < z < 1 \}$

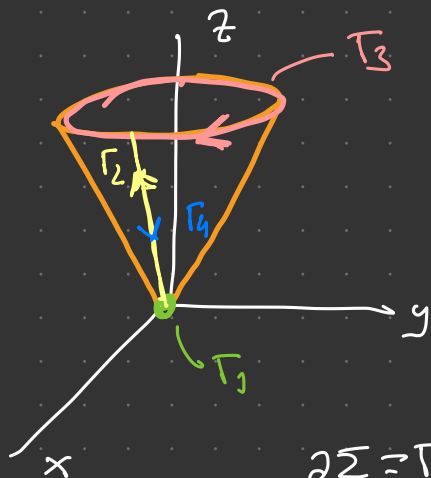
$$A =]0, 2\pi[\times]0, 1[$$

$$\sigma: \bar{A} \rightarrow \mathbb{R}^3$$

$$(\theta, z) \mapsto \sigma(\theta, z) = (z \cos \theta, z \sin \theta, z)$$



$$\partial \Sigma = \Gamma_1 \cup \Gamma_2 \cup \Gamma_3 \cup \Gamma_4$$



$$\partial \Sigma = \Gamma_3$$

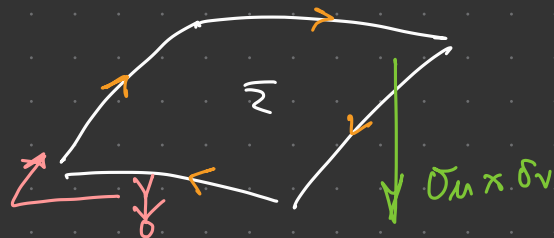
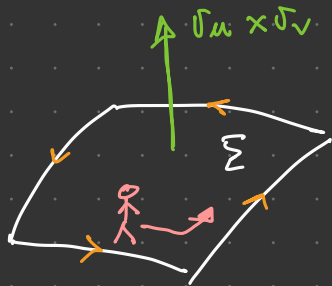
$$\times \Gamma_1 = \{ \gamma_1(\theta) = \sigma(\theta, 0) = (0, 0, 0) \text{ with } \theta: 0 \rightarrow 2\pi \}$$

$$\times \Gamma_2 = \{ \gamma_2(z) = \sigma(2\pi, z) = (z, 0, z) \text{ with } z: 0 \rightarrow 1 \}$$

$$\Gamma_3 = \{ \gamma_3(\theta) = \sigma(\theta, 1) = (\cos \theta, \sin \theta, 1) \text{ with } \theta: 2\pi \rightarrow 0 \}$$

$$\times \Gamma_4 = \{ \gamma_4(z) = \sigma(0, z) = (z, 0, z) \text{ with } z: 1 \rightarrow 0 \}$$

Note: practical rule for obtaining the boundary of a surface induced by a parameterization $\sigma(u, v)$: an observer walks along $\partial\Sigma$, with his/her head pointing in the sense of the normal $\sigma_u \times \sigma_v$, the surface Σ is on his/her left.



Week 7 - part 2

3.4.3 Stokes' theorem

- Theorem: let $\Sigma \subset \mathbb{R}^3$ be a (piecewise) orientable regular surface. let $F: \Sigma \rightarrow \mathbb{R}^3$ be a vector field s.t. $F \in C^1(\bar{\Sigma}, \mathbb{R}^3)$ then:

$$\iint_{\Sigma} \text{curl } F \cdot d\mathbf{s} = \int_{\partial \Sigma} F \cdot d\mathbf{b}$$

- Remarks:

1- This is a generalization of Green's theorem for \mathbb{R}^3 .

2- Once the parameterization $\sigma: \bar{A} \rightarrow \Sigma$ is chosen
 $(u,v) \rightarrow \sigma(u,v)$

we take $\sigma_u \times \sigma_v$ as the normal vector in the surface integral.

I.e.
$$\iint_{\Sigma} \text{curl } F \cdot d\mathbf{s} = \iint_A \text{curl } F(\sigma(u,v)) \cdot \sigma_u \times \sigma_v \, du \, dv$$

3 - The sense of circulation of $\partial\Sigma$ in the integral $\int_{\partial\Sigma} \mathbf{F} \cdot d\mathbf{b}$ is induced by σ . I.e, it is obtained by circulating ∂A in positive sense (counter-clockwise).

week 7 - part 3

3.4.4 Stokes' theorem examples

• Example 1: Verify the Stokes' theorem for

$$\Sigma = \{ (x, y, z) \in \mathbb{R}^3 : z^2 = x^2 + y^2 \text{ and } 0 < z < 1 \}$$

and $F: \Sigma \rightarrow \mathbb{R}^3$

$$(x, y, z) \mapsto F(x, y, z) = (z, x, y)$$

$$A =]0, 2\pi[\times]0, 1[$$

$$\sigma: \bar{A} \rightarrow \mathbb{R}^3$$

$$(\theta, z) \mapsto \sigma(\theta, z) = (z \cos \theta, z \sin \theta, z)$$



$$\begin{aligned}
 \circ \iint_{\Sigma} \operatorname{curl} F \cdot d\mathbf{s} & \quad \operatorname{curl} F = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \quad \sigma_{\theta} \times \sigma_z = \begin{pmatrix} z \cos \theta \\ z \sin \theta \\ -z \end{pmatrix} \\
 & \quad \text{"} \\
 \iint_A (1, 1, 1) \cdot (z \cos \theta, z \sin \theta, -z) \, dz \, d\theta & = \int_0^{2\pi} \int_0^1 z (\cos \theta + \sin \theta - 1) \, dz \, d\theta \\
 & = \frac{1}{2} \int_0^{2\pi} \underbrace{(\cos \theta + \sin \theta - 1)}_{=0} \, d\theta = -\frac{1}{2} \int_0^{2\pi} d\theta = -\pi
 \end{aligned}$$

$$\begin{aligned}
 \circ \int_{\partial \Sigma} F \cdot d\mathbf{h} & \quad , \quad \Gamma = \partial \Sigma, \quad \gamma: [2\pi, 0] \rightarrow \mathbb{R}^3 \\
 & \quad \theta \mapsto \gamma(\theta) = (\cos \theta, \sin \theta, 1) \\
 \int_{2\pi}^0 F(\gamma(\theta)) \cdot \gamma'(\theta) \, d\theta & = \int_{2\pi}^0 (1, \cos \theta, \sin \theta) \cdot (-\sin \theta, \cos \theta, 0) \, d\theta \\
 & = \int_{2\pi}^0 (-\sin \theta + \cos^2 \theta) \, d\theta = \int_{2\pi}^0 \cos^2 \theta \, d\theta = -\pi \quad \left(\int_0^{2\pi} \cos^2 \theta \, d\theta = \pi \right)
 \end{aligned}$$

Homework:

$$\sigma(z, \theta) = (z \cos \theta, z \sin \theta, z)$$

$$\text{normal: } \sigma_z \times \sigma_\theta = -\sigma_\theta \times \sigma_z =$$

$$\begin{pmatrix} -z \cos \theta \\ -z \sin \theta \\ +z \end{pmatrix}$$

$\partial \Sigma$ has the opposite orientation

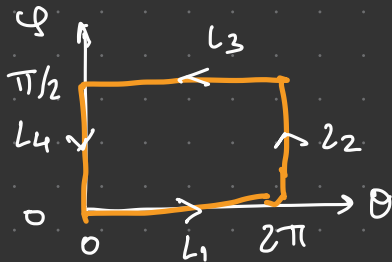
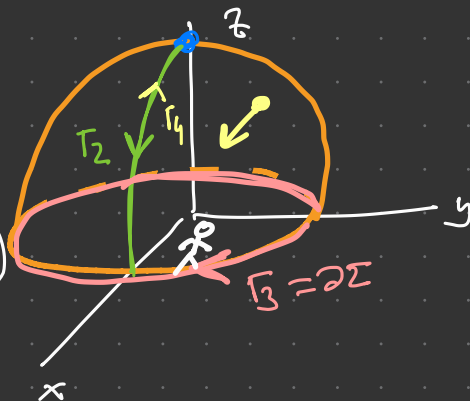
Example 2: $\Sigma = \{ (x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 = 1 \text{ and } z > 0 \}$

$$F(x, y, z) = (z, x, y^2)$$

$$A =]0, 2\pi[\times]0, \pi/2[$$

$$\sigma: \bar{A} \rightarrow \mathbb{R}^3$$

$$(\theta, \varphi) \mapsto \sigma(\theta, \varphi) = (\sin \varphi \cos \theta, \sin \varphi \sin \theta, \cos \varphi)$$



$\partial \Sigma ?$

$$\times \Gamma_1 = \{ \gamma_1(\theta) = \sigma(\theta, 0) = (0, 0, 1) \text{ with } \theta: 0 \rightarrow 2\pi \}$$

$$\times \Gamma_2 = \{ \gamma_2(\varphi) = \sigma(2\pi, \varphi) = (\sin\varphi, 0, \cos\varphi) \text{ with } \varphi: 0 \rightarrow \pi/2 \}$$

$$\Gamma_3 = \{ \gamma_3(\theta) = \sigma(\theta, \pi/2) = (\cos\theta, \sin\theta, 0) \text{ with } \theta: 2\pi \rightarrow 0 \}$$

$$\times \Gamma_4 = \{ \gamma_4(\varphi) = \sigma(0, \varphi) = (\sin\varphi, 0, \cos\varphi) \text{ with } \varphi: \pi/2 \rightarrow 0 \}$$

$$\circ \int_{\partial\Sigma} F \cdot d\mathbf{l} = \int_{2\pi}^0 F(\gamma_3(\theta)) \cdot \gamma_3'(\theta) d\theta = \int_{2\pi}^0 (0, \cos\theta, \sin^2\theta) \cdot (-\sin\theta, \cos\theta, 0) d\theta$$

$$= \int_{2\pi}^0 \cos^2\theta d\theta = -\pi.$$

$$\circ \iint_{\Sigma} \text{curl} F \cdot d\mathbf{S} = \iiint_A [(\text{curl} F) \cdot \sigma(\theta, \varphi)] \cdot (\sigma_\theta \times \sigma_\varphi) d\theta d\varphi.$$

$$\text{curl } F = (2y, 1, 1), \quad \text{curl } F \circ \sigma(\theta, \varphi) = (2 \sin \varphi \sin \theta, 1, 1)$$

$$\sigma_\theta \times \sigma_\varphi = -\sin \varphi \begin{pmatrix} \sin \varphi \cos \theta \\ \sin \varphi \sin \theta \\ \cos \varphi \end{pmatrix} = -\sin \varphi \sigma(\theta, \varphi)$$

$$\iint_{\Sigma} \text{curl } F \cdot ds = - \int_0^{\pi/2} \int_0^{2\pi} (2 \sin \varphi \sin \theta, 1, 1) \cdot \sigma(\theta, \varphi) \sin \varphi \, d\theta \, d\varphi$$

$\int_0^{2\pi} \sin \theta \cos \theta \, d\theta = 0$

$$= - \int_0^{\pi/2} \int_0^{2\pi} (2 \sin^3 \varphi \sin \theta \cos \theta + \sin^2 \varphi \sin \theta + \sin \varphi \cos \varphi) \, d\theta \, d\varphi$$

$$= -2\pi \int_0^{\pi/2} \sin \varphi \cos \varphi \, d\varphi = -2\pi \left. \frac{1}{2} \sin^2 \varphi \right|_0^{\pi/2} = -\pi$$