

SOLUTION 1.

1. See the provided MATLAB/Python routines.
2. We have

$$H^{-1} \approx \begin{bmatrix} 500e^{j0.49968\pi} & 500e^{-j0.5\pi} \\ 500e^{-j0.5\pi} & 500e^{j0.49968\pi} \end{bmatrix}$$

Hence,

$$\Sigma_{\mathbf{v}} = H^{-1}\Sigma_{\mathbf{z}}(H^{-1})^\dagger \approx \sigma^2 \begin{bmatrix} 5 \times 10^5 & -5 \times 10^5 \\ 5 \times 10^5 & 5 \times 10^5 \end{bmatrix}.$$

This means, the variance of  $v_1$  (or  $v_2$ ) is 500 000 times larger than  $\sigma^2$ !

SOLUTION 2.

1. We have shown in class that the LMMSE estimate of  $\mathbf{x}$  is  $\hat{\mathbf{x}} = B\mathbf{y}$ , where

$$B = K_{\mathbf{x}\mathbf{y}}K_{\mathbf{y}}^{-1}.$$

We can easily compute the above covariance matrices:

$$K_{\mathbf{x}\mathbf{y}} = E[\mathbf{x}\mathbf{y}^\dagger] = E[\mathbf{x}(H\mathbf{x} + \mathbf{z})^\dagger] = E[\mathbf{x}\mathbf{x}^\dagger]H^\dagger = H^\dagger,$$

and

$$K_{\mathbf{y}} = E[\mathbf{y}\mathbf{y}^\dagger] = E[(H\mathbf{x} + \mathbf{z})(H\mathbf{x} + \mathbf{z})^\dagger] = HE[\mathbf{x}\mathbf{x}^\dagger]H^\dagger + E[\mathbf{z}\mathbf{z}^\dagger] = HH^\dagger + \sigma^2 I_r.$$

Hence,

$$B = H^\dagger(HH^\dagger + \sigma^2 I_r)^{-1}.$$

Note that, in particular if  $\sigma^2 = 0$ , the LMMSE equalizer reduces to the zero-forcing equalizer of Exercise 1.

2. See the provided MATLAB/Python routines.