

# Computational Cell Biology

Smooth  
endoplasmic  
reticulum

Mitochondrion

Rough  
endoplasmic  
reticulum

Golgi apparatus

Microfilament

Centriole

Nucleus

Ribosomes

Autumn 2025

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Source: <http://www.daviddarling.info>

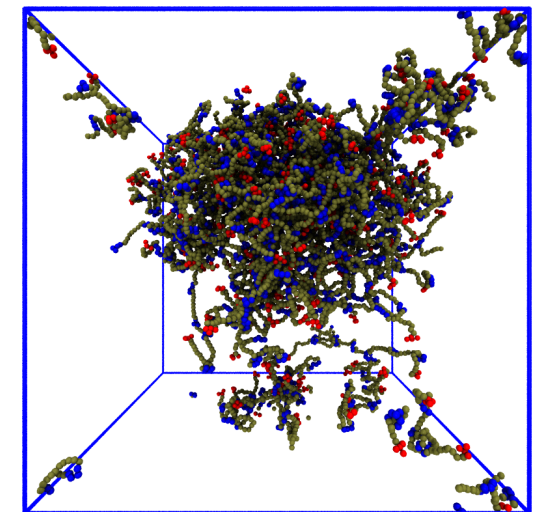
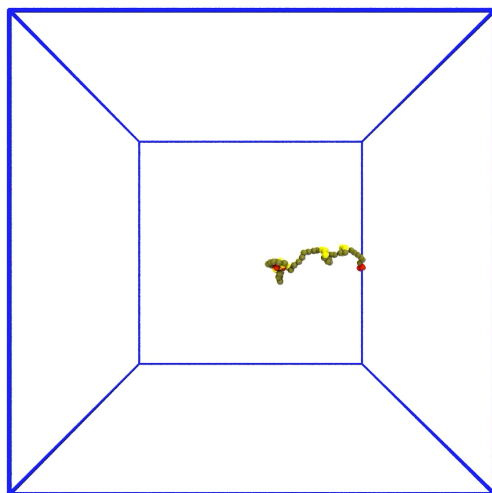
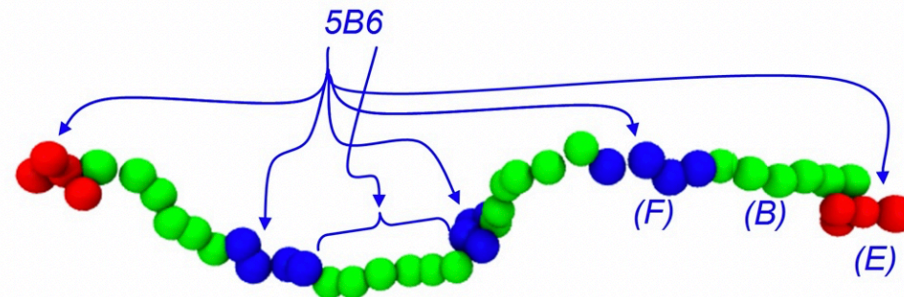
Lysosome

# Question

We looked at the phantom chain last week; now when you think of a flexible polymer you should see  $\langle R_{ee}^2 \rangle = Na^2$ .

But consider a phantom chain that has discrete, sticky domains (red and blue below left) that attract each other, and consider **many** such polymers in water (below right).

Q. Is it possible for the sticky polymer's  $R_{ee}$  to *increase* with increasing affinity, so that it swells compared to its non



Sometimes you have to be sneaky to get your way  
(indirect forces)

Divide and conquer (compartments)

Noise can be useful... it can do work

(Polymers can be quite weird)

How to classify forces relevant in cells? Direct versus Indirect

**Direct:** Gravity, Coulomb, H-bonds, covalent and ionic bonds

- Operate between two atoms “independently” of others  $\Rightarrow$  pairwise additive
- Typically short-ranged (not gravity! or Coulomb force in a vacuum)

**Indirect:** Hydrophobic effect, Depletion, Capillary forces, Membrane-mediated, Fluctuation-induced forces

- Arise between many molecules simultaneously, strongly affected by other objects  $\Rightarrow$  NOT pairwise additive
- Can be long ranged ( $\sim 1/R$ )
- Proportional to temperature (so pressure is *entropic*...  $PV = RT$ )

**Gravitational** force between two point masses:

$$F = G M_1 M_2 / R^2 \quad G = 6.67 \cdot 10^{-11} \text{ N.m}^2/\text{Kg}^2$$

Nearly negligible for cells, but they can sink under gravity

**Coulomb** force between charges in vacuum

$$F = k Q_1 Q_2 / R^2 \quad k = 1 / 4\pi\epsilon_0 = 9 \cdot 10^9 \text{ N.m}^2 / \text{C}^2$$

in a material  $\epsilon_0$  is replaced by  $\epsilon_0 \epsilon$ , where  $\epsilon$  is the relative permittivity of the material, and makes a big difference between water ( $\epsilon \sim 80$ ) and oil ( $\epsilon \sim 1$ ).

Bare force is usually screened out by ions under physiological conditions

**Screened Coulomb force**

$$F = e^{-\kappa R} / R \quad \kappa^{-1} = \text{screening length} \sim 1 \text{ nm in physiol. conditions}$$

$$F_G / F_C \sim G M_1 M_2 / k Q_1 Q_2 \sim 10^{-10} (10^{-27})^2 / 10^{10} (10^{-19})^2 \sim 10^{-36}$$

so gravitational force between bare ions is utterly negligible.

# Chemical and physical bonds

Bond Type	Strength (kJ/Mol)	Strength ( $k_B T$ )	Length (nm)	Description
Covalent	500	200	0.154 (C-C)	Shared outer $e^-$
Ionic	~ 880	~ 355	0.276 (NaCl nn)	$e^-$ donated/summed
Hydrogen	10 - 40	4 - 16	~ 0.176 (O...H)	small H - electroneg. atom
“Van der Waals”	~ 1	~ 0.4	~ $1/R^6$	fluctuating induced dipoles

NB 1 kJ/Mol ~ 0.4  $k_B T$  per particle

J. Israelachvili, *Intermolecular and Surface Forces*, Academic Press, 2nd ed. London 1992.

If Strength ~  $k_B T$ , a force has **no effect** as thermal noise overwhelms it:

- Covalent and ionic bonds cannot be broken just by (room) temperature
- H-bonds may be broken by a large fluctuation
- VDW must occur as many bonds to have any effect

# Limitations of direct forces

Bare electrostatic forces are usually not important in cells because:

- short-ranged/screened
- cell is not a vacuum, water, ions, membranes reduce the forces
- ionic crystals don't form inside cells (but in blood, high concentrations can lead to crystallisation, e.g., uric acid leads to gout)

Exceptions: ion channels, binding pocket where particles are very close, actin/microtubule filaments which are rigidly-connected monomers

For large aggregates or materials  $\gg$  **atomic size**, direct forces appear as **material constants**, e.g., surface tension, stiffness, compressibility, bending modulus, etc., that must be determined by measurements.

These material properties then give rise to **indirect forces** that are mediated by the material or environment.

**Indirect forces** originate in Coulomb's law (electrostatics) but involve **many weak interactions** rather than one strong interaction between two points.

This makes them hard to calculate, and almost impossible to guess their functional form or even their sign, except that they  $\propto \text{Temp}$

Importantly: indirect forces are **free**, i.e., they arise from thermodynamics, not from the specific atomic structure of the interacting molecules. Such *generic* forces are everywhere in a cell. (cp. polymer  $R_{ee}^2 \sim Na^2$  does not depend on monomer type).

## Entropic forces

hydrophobic effect of oily chains in water  
depletion (molecular crowding)  
fluctuation-induced forces

## Membrane-mediated forces

curvature force  
composition mismatch  
thickness mismatch

If we regard a thermodynamic system as composed of molecules, the question arises how its internal energy is distributed among all the molecules?

An important result is the **Principle of Equipartition of Energy:**

“ Each additive, quadratic degree of freedom in the Hamiltonian of a system *in equilibrium* contributes  $1/2 k_B T$  to its internal energy. The energy is shared among all *accessible* degrees of freedom of the system: if the temperature is such that some degrees of freedom cannot be excited they do not contribute to the internal energy.”

(Blackboard calculation)

A consequence of this theorem is:

We have to do work on a macroscopic object to move it - all motion tends to cease as energy is lost to friction, heat, etc.

We have to do work on a microscopic object to STOP it moving - all molecules tend to move continually, bouncing off each other and sharing their energy. In a fluid, this motion can be observed and is called Brownian motion.

# Equipartition theorem

Let  $H(\{x\})$  be the Hamiltonian of a system with dof  $\{x\} = x_1, x_2, x_3, \dots, x_N$

The expected value of an Observable  $A(\{x\})$  is defined by:

$$\langle A \rangle = \int A(\{x\}) e^{-\beta H(\{x\})} dx_1 \dots dx_N / Z$$

$$Z = \int e^{-\beta H(\{x\})} dx_1 \dots dx_N$$

If the following two conditions on  $H$  hold:

- 1)  $H$  is additive in some coordinate  $x_1$ :  $H(\{x\}) = H_1(x_1) + H'(x_2 \dots x_N)$
- 2)  $H_1$  is quadratic in  $x_1$ :  $H_1(x_1) \sim \alpha x_1^2$

Then the mean value of  $\langle H_1 \rangle$  is:

$$\langle H_1 \rangle = 1/2 k_B T$$

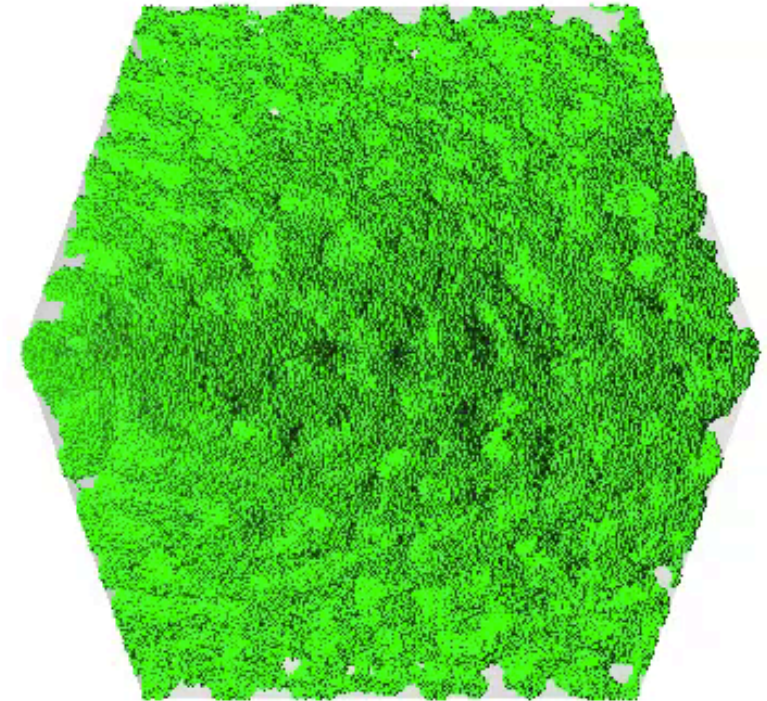
# Hydrophobic effect

Water - an homogenous liquid with no bulk structure beyond  $\sim 1\text{nm}$ , that possesses the unique property of a hydrogen bonded network between the  $\text{H}_2\text{O}$  molecules.

This network has a huge entropy as the molecules continually make and break H-bonds (Eq. Thm again ...)

The hydrophobic effect is the name for the prevention of H-bonding between water by the presence of non-polar molecules that drives them to aggregate in one place.

C. Tanford, *The Hydrophobic Effect*, Wiley, New York 1980



NB. Movies produced from DPD simulations and visualized with Povray and Quicktime. Water in the simulation box is invisible for clarity.

Mix oil and water  $\Rightarrow$  droplets appear by phase separation and create a bounding surface between the phases.

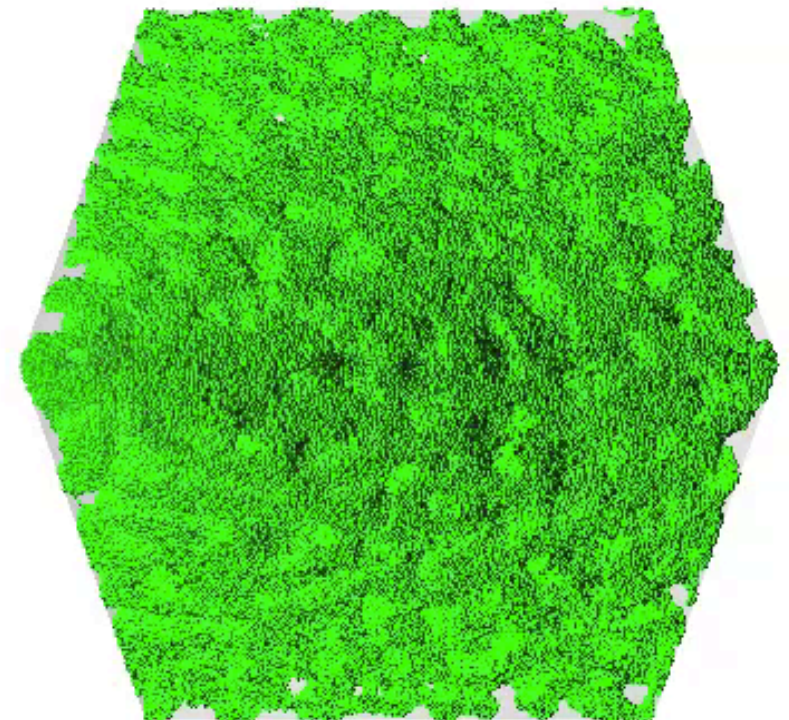
Q. How could you eliminate the planar interface between oil and water?

3 mins.

Why does it form?

What could you do to change the free energy of the interface?

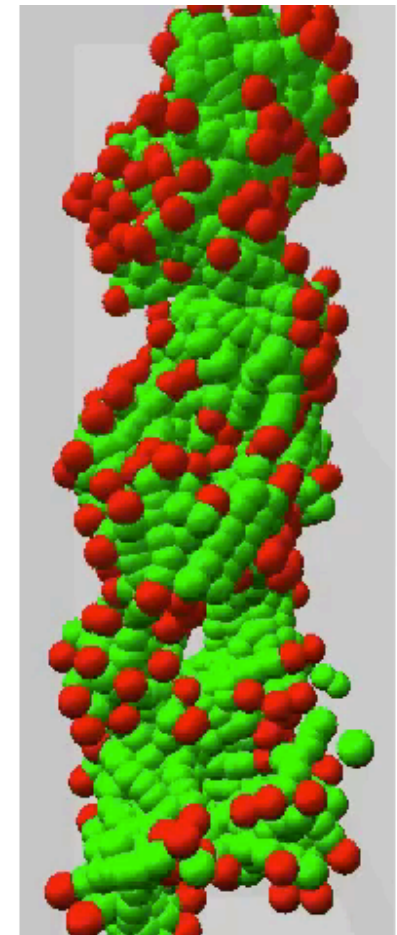
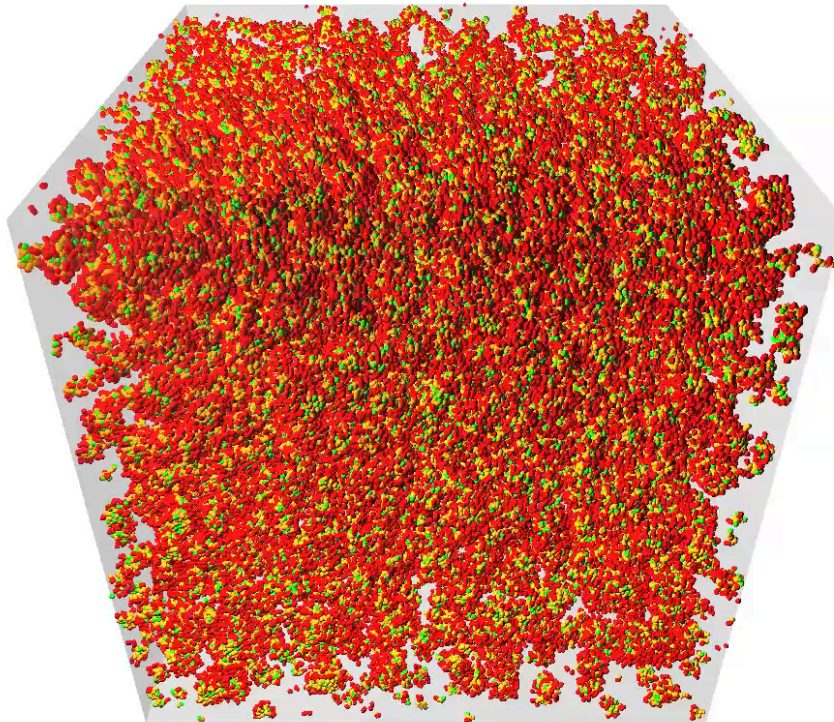
What chemical could you add?



# Amphiphiles form complex aggregates in water

Mix lipids and water  $\Rightarrow$  interfaces and *compartments* appear:

Compartments can support gradients, and gradients can be used to do work, e.g., ion concentrations can differ across the neuronal plasma membrane.



Type of aggregate is encoded in lipid's molecular shape: no external control is needed: we expect that simulations will be useful in predicting lipid phases if we can just capture their amphiphilic nature.

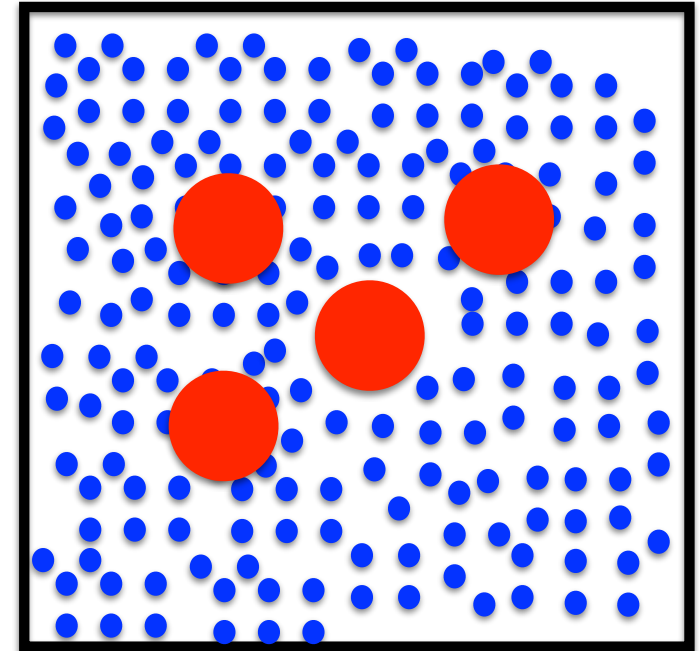
Depletion forces arise when some entities restrict the freedom of others to move (or fluctuate).

Large solute particles (red) exclude the smaller solvent molecules (blue) from around them.

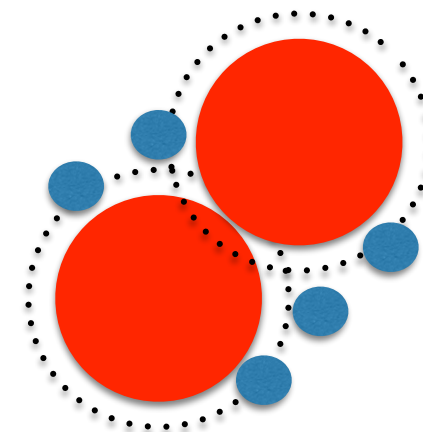
If the red ones cluster, some volume is freed up, and there is more space for the solvent to move around, hence the entropy increases.

Depletion forces don't only arise in bulk solvent, they also arise within membranes (see later).

They are independent of the type of entity (atom, molecule, nanoparticle, membrane) and only require the molecules to be repulsive at short range (steric repulsion) and mobile.



Not to scale

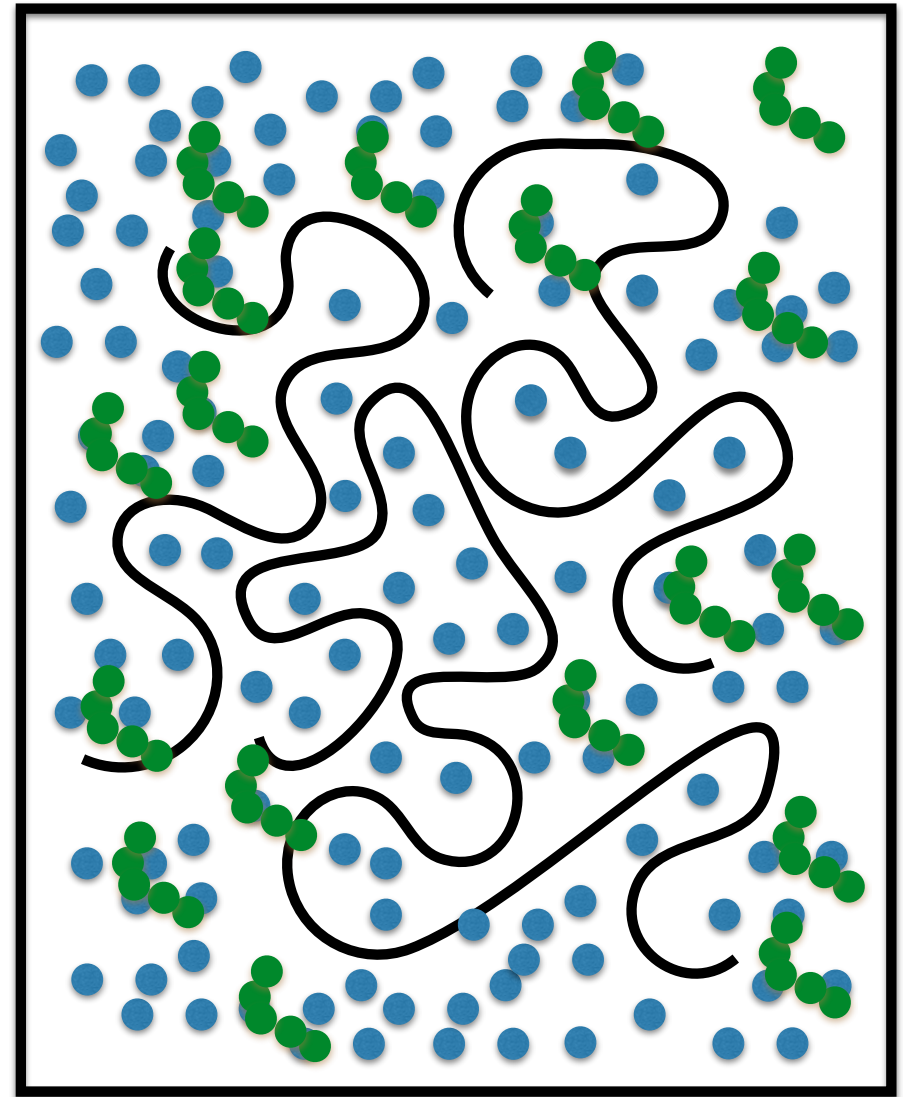


# Molecular crowding

Consider a dilute solution of long polymers in water in the presence of concentrated short polymers.

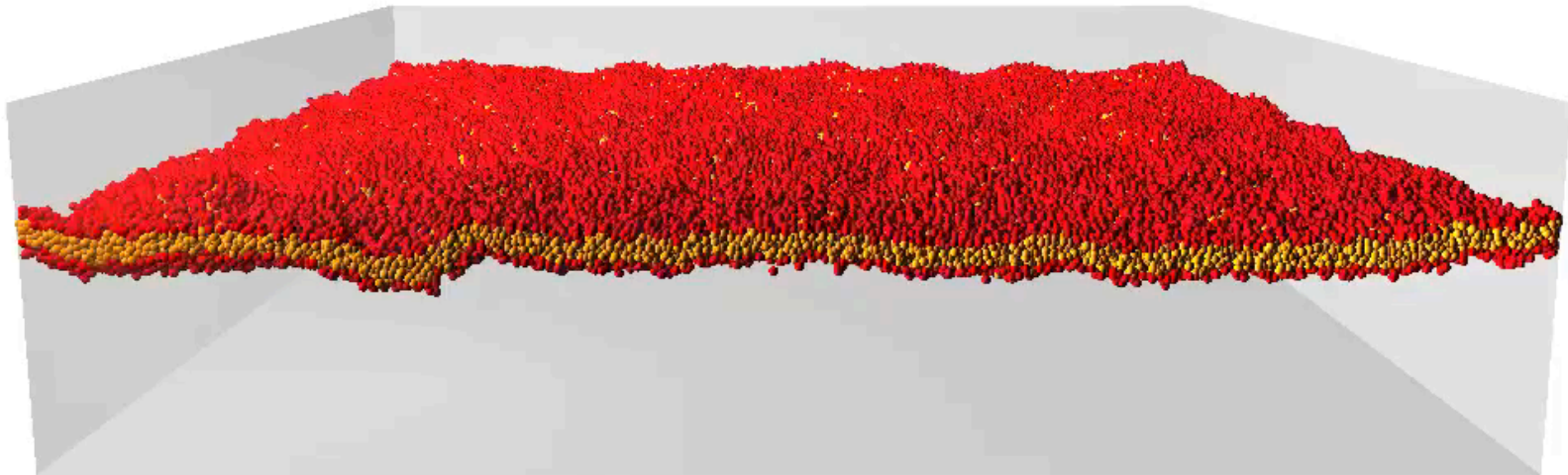
If the two polymer types are sterically repulsive, the long ones restrict the motion and shape fluctuations of the short ones.

This leads to a force on the long ones that squeezes them into a region to maximise the entropy of the short ones.



# Membrane fluctuation force

The thermal fluctuations of a lipid membrane give rise to a repulsive force on an object or material that approaches and suppresses its fluctuations: this would lower its entropy and therefore is opposed.

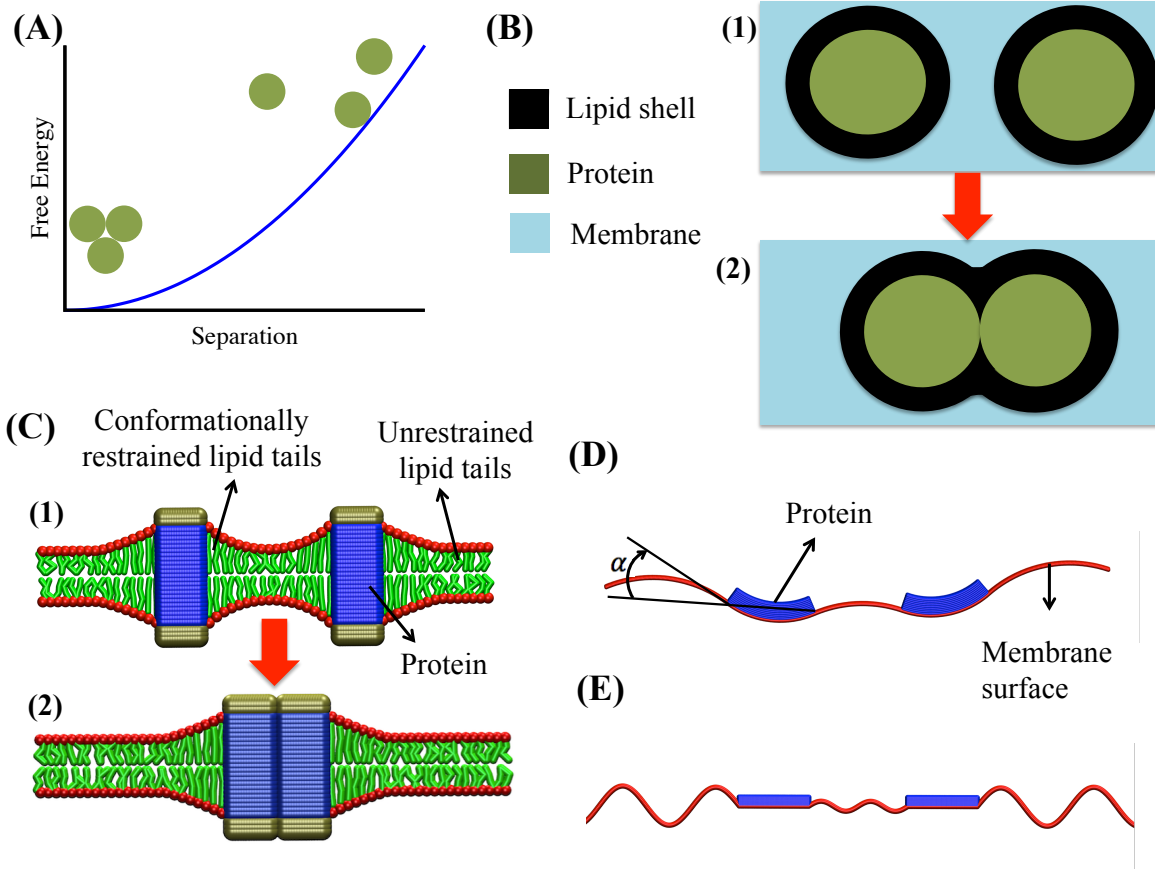


What about forces on small objects in, or adsorbed to, a membrane?

This is a whole new set of indirect forces.

# Indirect forces: membrane-mediated

Unlike bare forces, membrane-mediated forces arise when two (or more) proteins/nanoparticles adsorb to/embed in a membrane and perturb its state: they perturb their environment and it, in turn, drives them together or apart.



A) All operate by lowering the total free energy of membrane+proteins

B) Capillary force/line tension

C) Depletion force

D) Curvature force

E) Fluctuation-induced force (Lecture II)

Johannes et al. Trends Cell Biol. 2018

## What does a cell do with these forces?

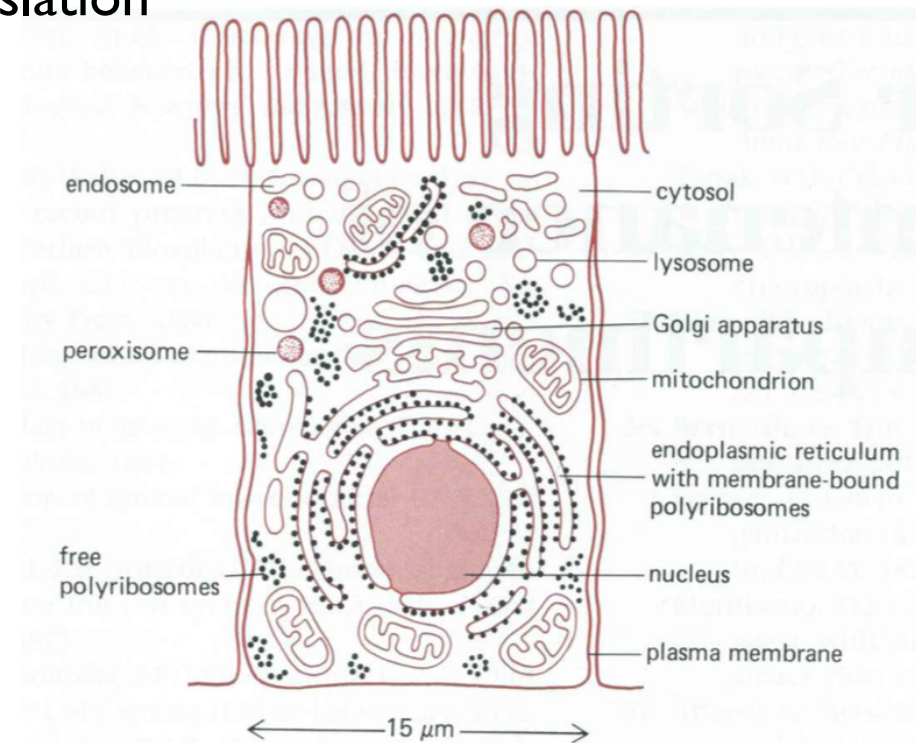
- Bring materials together / push them apart
- Make compartments
- Bacteria use them to lyse cells (Lecture 11)

# Why compartmentalise?

Compartments allow spatial segregation of function: reactions can be kept apart, acidic environment in one place/neutral in another, gradients can form, ATP made, DNA transcribed in nucleus, etc.

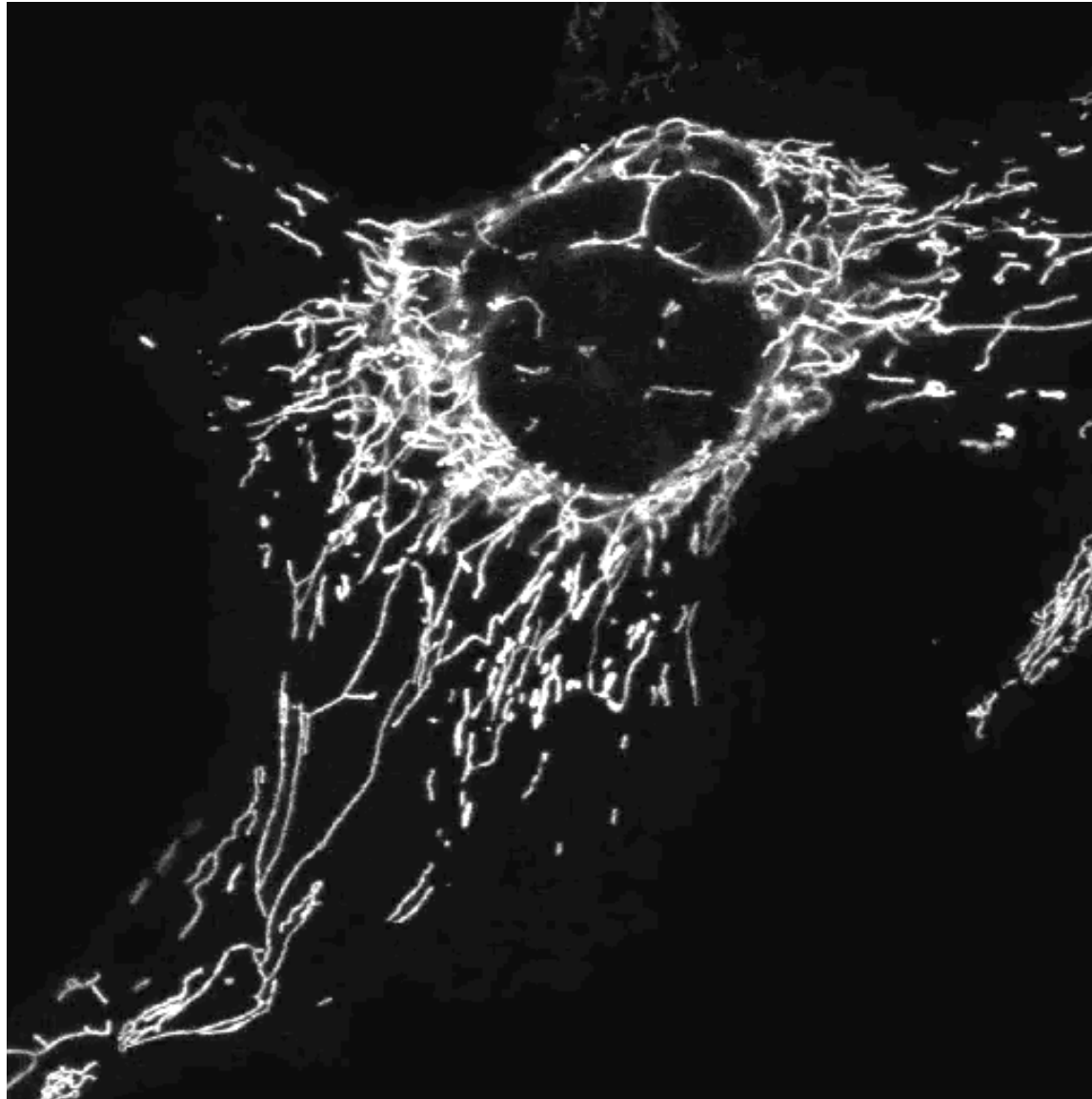
- Nucleus - separates transcription from translation
- Rough ER - ribosomes synthesize proteins
- Smooth ER - lipid synthesis
- Golgi - sorting proteins for destination
- Mitochondria -  $e^-$  transport,  $H^+$  gradient
- Endosome - imports material into cell

Alberts and Bray, Fig. 8.1



and lipid membrane-bound compartments come **for free** because of the hydrophobic effect.

# Membrane-bound organelles are not static



David Chan, Caltech

Fusing and fission of mitochondria

# Self-assembly is a consequence of Equipartition Thm. EPFL

- Self-assembled structures form because they minimise a system's free energy by **phase separating** rather than staying mixed
- The cell uses self-assembly because it's **free**
- It's free because of the Equipartition Theorem

The total energy of a molecular system is continually redistributed among all its atoms and molecules by random thermal motion; this allows the system to eventually discover its state of lowest free energy.

Membrane-bound compartments self-assemble from dispersed lipids because of the hydrophobic effect

- Are there other inter-molecular forces that stabilise aggregates or compartments?
- Are all cellular compartments bounded by lipid membranes?

# Short opinion poll

*All models are wrong but some are useful*

Who has heard this before?

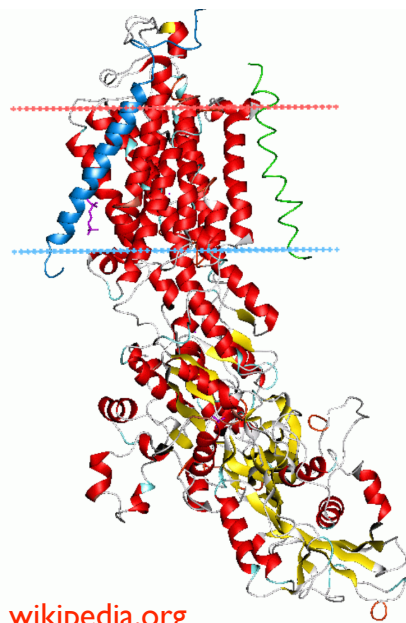
Do you agree with it?

What is the difference between “wrong” and “inaccurate” in the context of science?

# Opposite extremes of protein models

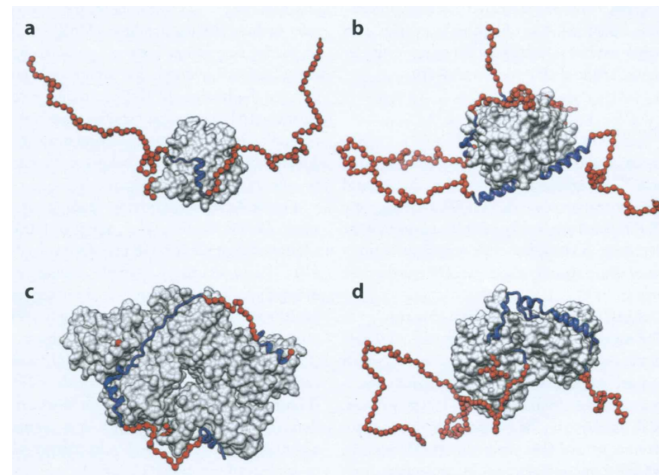
## Folded protein

- Unique folded state
- Lowest energy (**energy dominated**)
- Precise shape
- Precise functions
- Disrupted by single aa mutation
- No model, need the actual protein

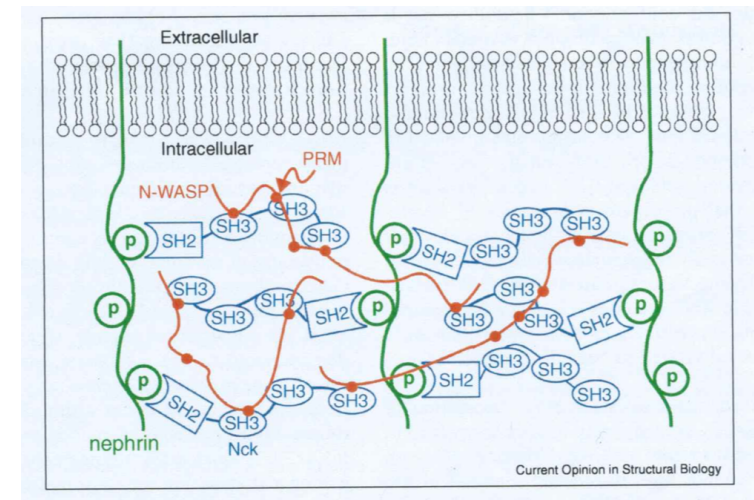


## Intrinsically Disordered protein

- No unique folded state
- Many conformations of similar energy (**entropy dominated**)
- Generic binding via multiple, weak sites
- Sequence not conserved but properties are
- Can fold/unfold on binding
- Model it as a phantom chain?



Oldfield and Dunker  
Ann. Rev. Biochem. I. 83:553 (2014)



Chong and Forman-Kay,  
Curr. Op. Struct. Biol. 41:180 (2016)

# Can we make a mathematical model of IDPs?

## Relevant facts:

- an IDP protein is a long, flexible polymer with multiple, weak binding sites
- aggregate into spherical droplets with a (small) surface tension
- droplets have low density, not densely packed like oil droplets

## Relevant questions:

- How does a polymer's average size in solution scale with its molecular weight?
- At what concentration do proteins in solution “notice” each other?
- What is their shape in solution and in the aggregate (if they form one)?
- What is the shape of the aggregate?
- What are typical energies of the proteins' interactions?
- What is their entropy?
- Which free energy should we consider?

# Start with a simple model of an oil droplet

Why do oil molecules aggregate?

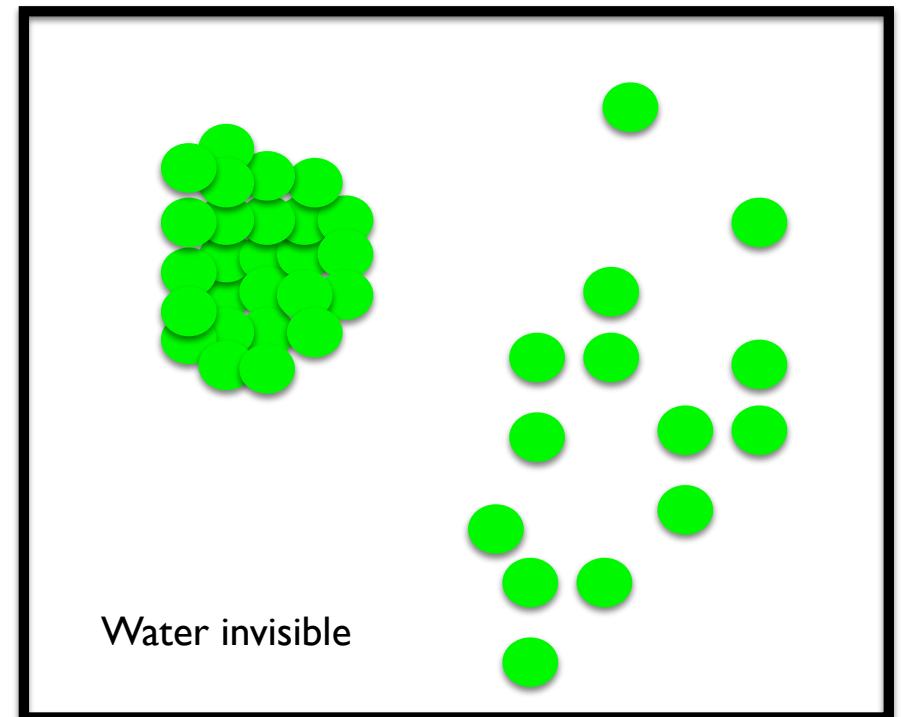
Each oil molecule is repelled from water by a *short-ranged* effective force: the hydrophobic effect.

How can we model this?

When oil molecules aggregate into a sphere, they reduce their energy by a term proportional to the volume ( $\gamma$ ), but still have a repulsive surface energy proportional to the surface area ( $\sigma$ ):

$$U(R) \sim 4\pi\sigma R^2 - 4/3\pi\gamma R^3$$

What preferred size droplets form?

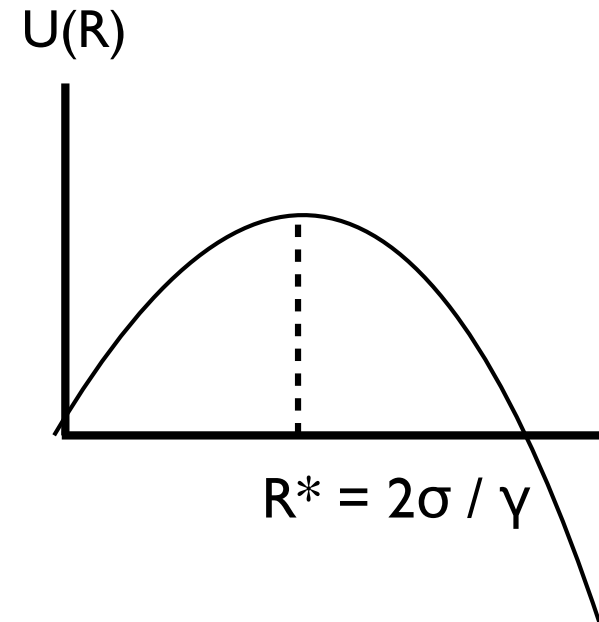


# Oil and water phase separate

$$U(R) \sim 4\pi\sigma R^2 - 4/3\pi\gamma R^3$$

$$dU/dR = 8\pi\sigma R - 4\pi\gamma R^2 = 0$$

So, the energy has a peak at droplet size  $R^*$



If the ratio  $(\sigma/\gamma)$  is high, the barrier is large and at large radius but it is always energetically favourable to increase the droplet size.

There is no equilibrium droplet size: smaller ones will break up while a larger one would grow without bound  $\Rightarrow$  phase separation.

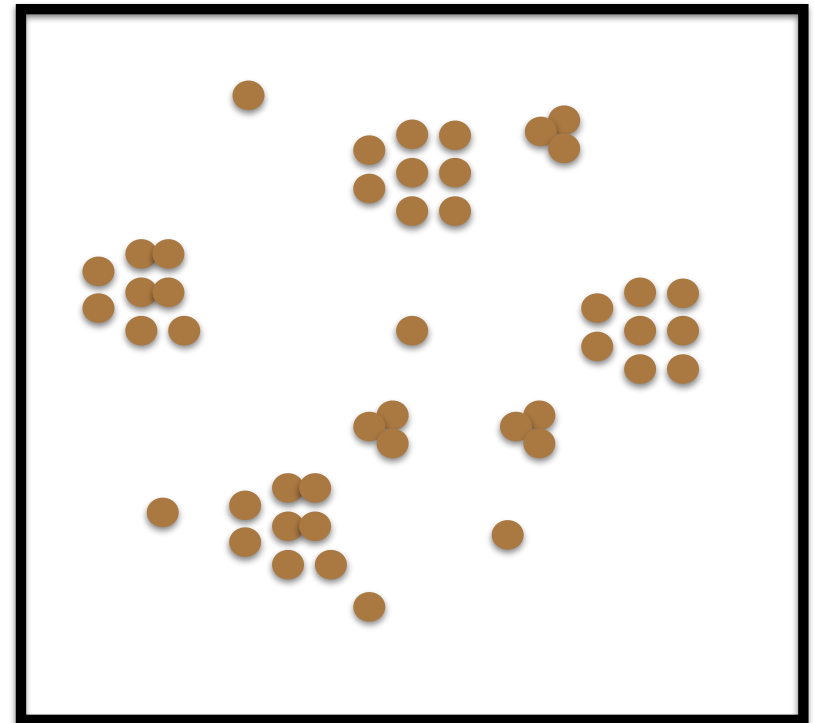
Can we find out how the droplets grow with time?

Consider  $N_0$  oil molecules initially, uniformly dispersed in a closed box of bulk water with volume  $V = L^3$ .

We intuitively expect the oil to form droplets that coalesce and grow in time, but how precisely do the radius and mass change with time?

## Assumptions

- 1) energy cost of the interface drives droplets spherical
- 2) at any time, all droplets have same mean radius
- 3) droplets of radius  $R$  diffuse with a coefficient that is given by the Stokes-Einstein relation:  $D = k_B T / 6 \pi \eta R$   
according to  $\langle X^2 \rangle \sim 6 D t$



# Oil droplet growth

Let  $N(t)$  = mean number of droplets at time  $t$   
 $R(t)$  = mean radius of droplets “

$$\langle \text{vol/droplet} \rangle \sim L^3 / N(t)$$

$$\langle \text{separation} \rangle \sim L / N(t)^{1/3}$$

*Is this reasonable?*

Droplets diffuse around and grow by coalescing when they touch, and we assume that the coalescence time is short compared to the diffusion time.

$$(L / N^{1/3}(t))^2 \sim 6 (k_B T / 6\pi\eta R(t)) \cdot t$$

But the number of oil molecules is constant, so:

$$N(t) \cdot 4\pi R(t)^3 / 3 = \text{constant} \quad \text{or} \quad N(t) \sim 1 / R(t)^3$$

$$\pi\eta R(t) L^2 / k_B T = N(t)^{2/3} \cdot t \sim t / R(t)^2$$

$$R(t) \sim (k_B T / \pi\eta L^2) t^{1/3}$$

$$M(t) \sim R(t)^3 \sim t$$

The radius and mass of an oil droplet grow with time like:

$$R(t) \sim (k_B T / \pi \eta L^2) t^{1/3}$$

$$M(t) \sim R(t)^3 \sim t$$

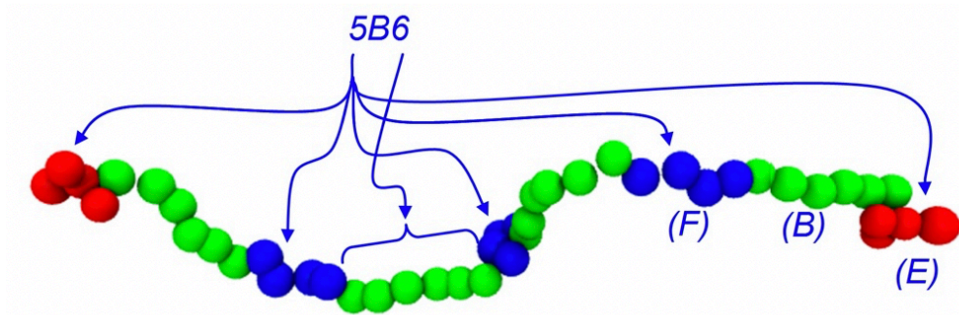
This is **NOT** an equilibrium thermodynamic description

**Q. Why not?**

Is this a good model of IDPs forming membraneless organelles?

No - IDPs are NOT hydrophobic like oil - they are soluble in cytoplasm at physiological conditions.

Aggregation must be driven by something else ... what? (more in lectures 12, 13).



How do we explore the parameter space of this model?

Too many parameters ...

... and it's very slow

We have  $\sim 3 + N^2$  parameters for 1 IDP :

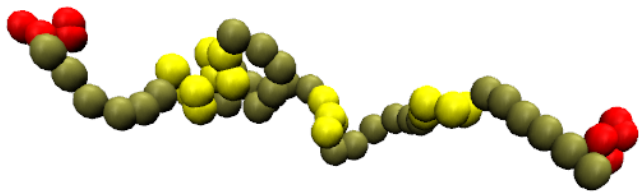
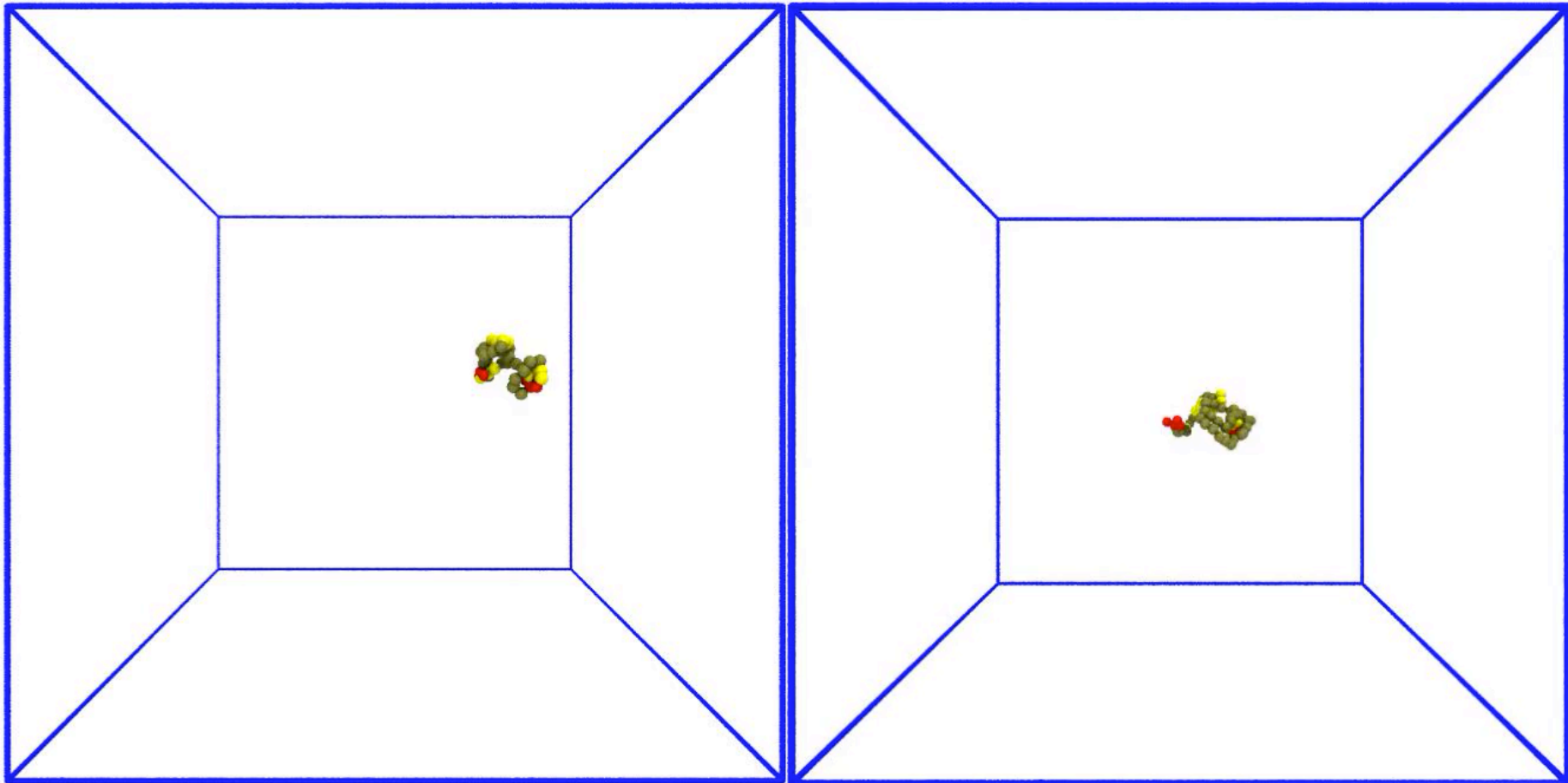
Molecular weight  
Backbone stiffness  
Concentration  
N sticky sites

plus location and cross affinity of N binding sites on IDP

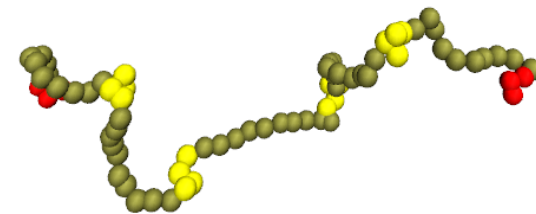
Simplify to: mol. weight = FUS LC, 16.7 kDa, fix stiffness; 6 equally-spaced sticky sites with same affinity.

Still leaves concentration and sticky site affinity ( $a_{EE}$ )

$(48 \text{ nm})^3$   
331,723 particles  
 $10^6$  timesteps  
takes 7 days on 1 core



6 sticky sites, spacing 6 beads

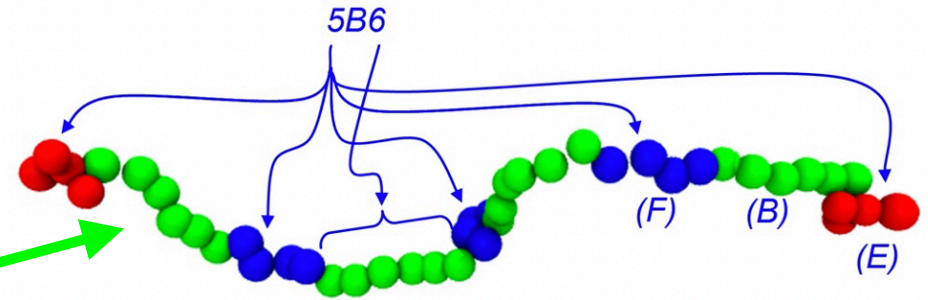


6 sticky sites, spacing 10 beads

Phase separation depends on IDP molecular structure, e.g., moving sticky sites apart weakens it at constant affinity

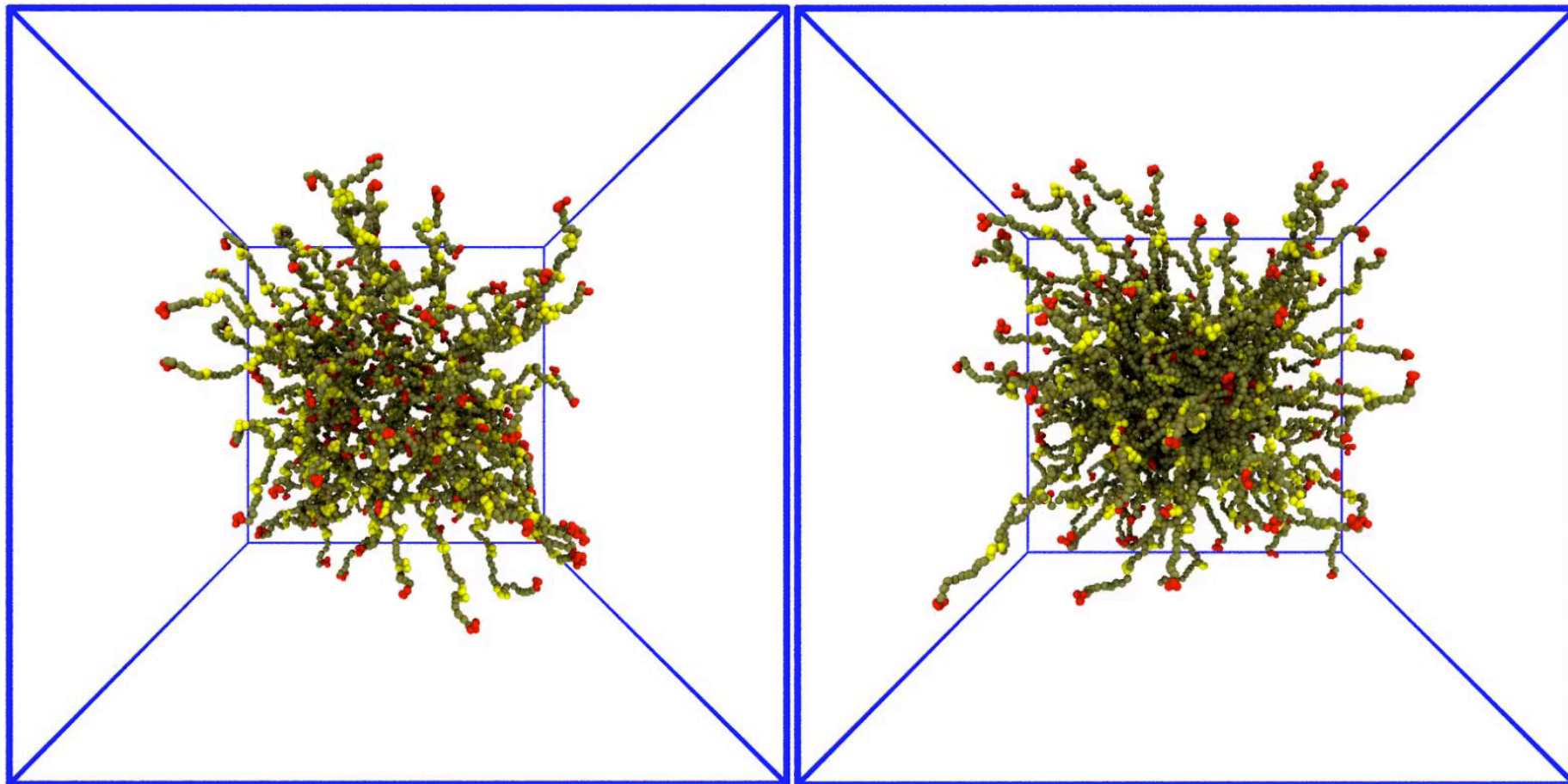
IDP - semi-flexible polymer with multiple sticky sites (e.g., Tyrosine)

Solvent - water, invisible

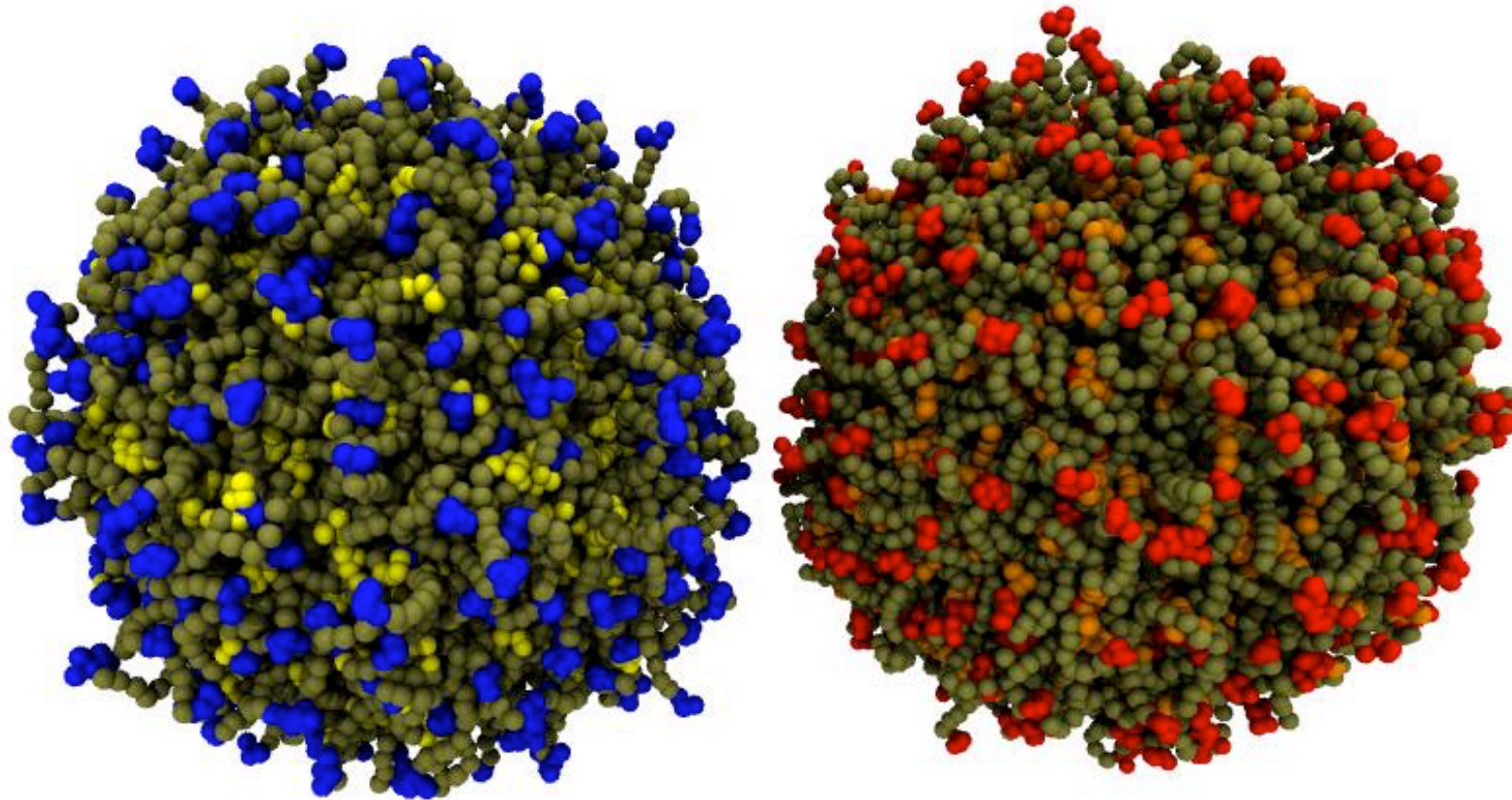
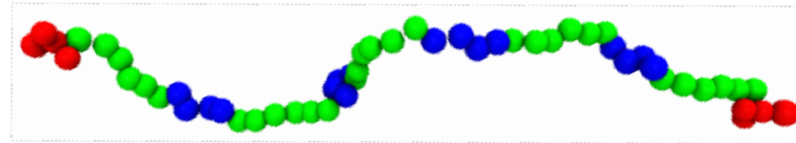


6B6

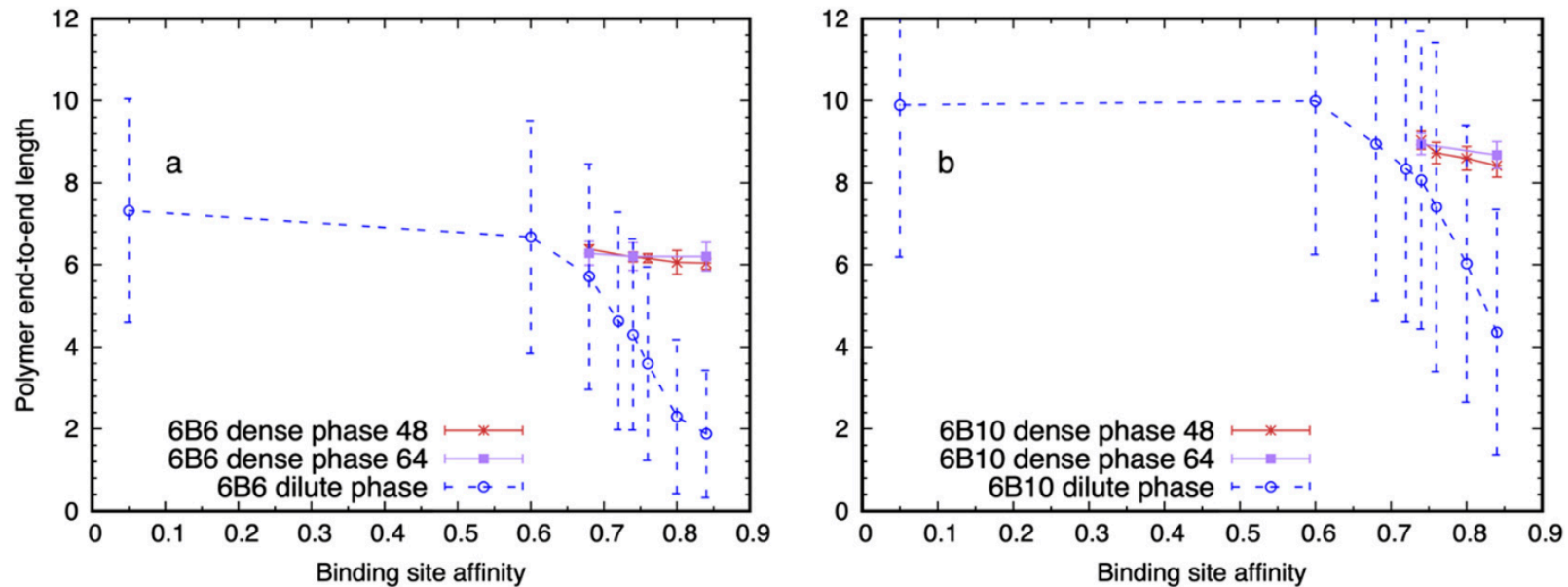
6B10



We can simulate sticky IDPs



# Model IDPs swell in dense phase



**Fig. 4** (a) Variation of the end-to-end length ( $L_{ee}$ ) of a polymer of type 6B6 in the dilute phase (dashed blue curve) and dense phase (red and purple curves for box sizes 48 and 64 respectively) with the binding site affinity in the range  $\varepsilon = 0-0.84$ . (b) Same as (a) for a polymer of type 6B10. Note that the dense phases are only stable for affinities starting at the first data point shown, which occurs when the polymer's mean size in the dilute phase drops below that in the dense phase. Error bars are the standard deviation of the distributions, illustrating the large fluctuations in the dilute phase and much smaller fluctuations in the dense phase. The zero affinity points have been displaced along the abscissa for clarity.

Shillcock et al. *Soft Matter* 18:6674 (2022)

## Sometimes you have to be sneaky to get your way (indirect origin of forces in a cell)

- Indirect forces are more important for cells than direct/bare Coulomb forces
- Indirect forces do **not** depend on **atomic details/chemistry** but arise from the **material** properties of aggregates/membranes/solutes
- Cells use thermal motion to move things, create compartments, create forces
- Noise is a continual source of energy for fluctuations that can exert forces (equipartition theorem)

## Divide and conquer

- Cell is very crowded, bad for biochemistry
- Compartments allow specialisation, protection, separation; they permit gradients like the  $H^+$  in mitochondria that is used for ATP
- Membraneless organelles have no bounding lipid membrane; they form because they minimise the free energy of their constituents, *cp.* lipids forming a membrane due to hydrophobic effect

**Break**

**15 mins.**

Practise test for Test I on 1st October is on moodle for this week; the actual test will be on the following topics, and last 1 hour at the start of the class.

- Dimensional analysis in the cell
- Properties of biological polymers, phantom chain result, “sizes” of a polymer, Kuhn length
- Types of indirect forces in the cell, their origin and effect
- Length scales associated with lipids and membranes from the first table
- Statement of the equipartition theorem

Send me title/group for JC paper before next lecture please

## Goal 1: How to organise the output files from many simulations?

- Create a new sub-directory for each exercise (no spaces in path)  
e.g., ~/BIOENG455/ex1, ...
- Use descriptive extensions, e.g., p001 = polymer run 1,  
dmpci.es001 = entropic spring run 001, or dmpci.es10, dmpci.es20, etc.  
where force = 10, 20

## Goal 2: Measure the Force / Extension curve of a single polymer in water

- Description of dmpci.nnn input file
- View the time series of polymer Lee from the dmpchs file
- Measure  $\langle \text{Lee} \rangle$  from the dmpcas file in steady state, and plot it against the force

There are ~ 10 possible homework exercises, and you must hand in one of them in Week 7 (1st November) and Week 12 (6th December). I have put a description on moodle and will go through some of them in the exercise periods.

Once we have finished the entropic spring simulation to illustrate how to use the DPD code, the exercise period can be used to work on the homework problems, Journal club talks, and projects.

You may use the **simulation homework exercises** as a starting point for the semester project, but you should extend them significantly. The project report should cover:

- Explain the question you want to answer with simulations
- Identify sources of error (systematic and statistical)
- Describe the results
- Conclusions, possible future work

Sample reports are on moodle.

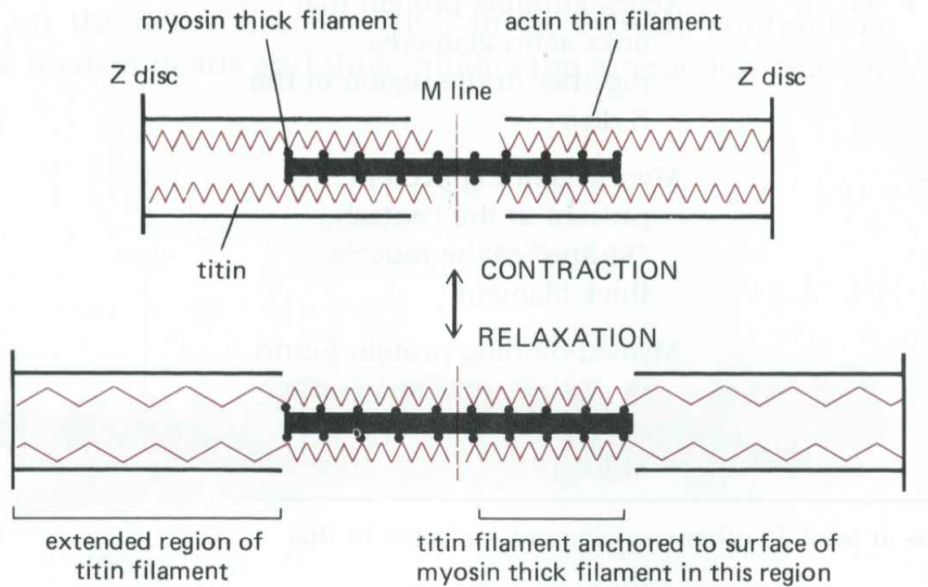
# Homework Ex. I Entropic spring

**Simulation of an entropic spring** - apply a stretching force to both ends of a single, long polymer in a DPD simulation and measure the end-end length as a function of the force (it probably has to be a very small force).

Then invert it to get  $F(L)$  and plot it including error bars of the statistical errors. How do you convert results to physical units?

Now make a fraction of the beads sticky (so that the polymer tends to stick to itself) and see how this changes the  $F(L)$  curve. You will need to vary the number of sticky beads to find an interesting regime (too few and nothing will happen, too many and the polymer will just stick together in a tight ball). Interesting means that the system shows some unusual, non-linear behaviour.

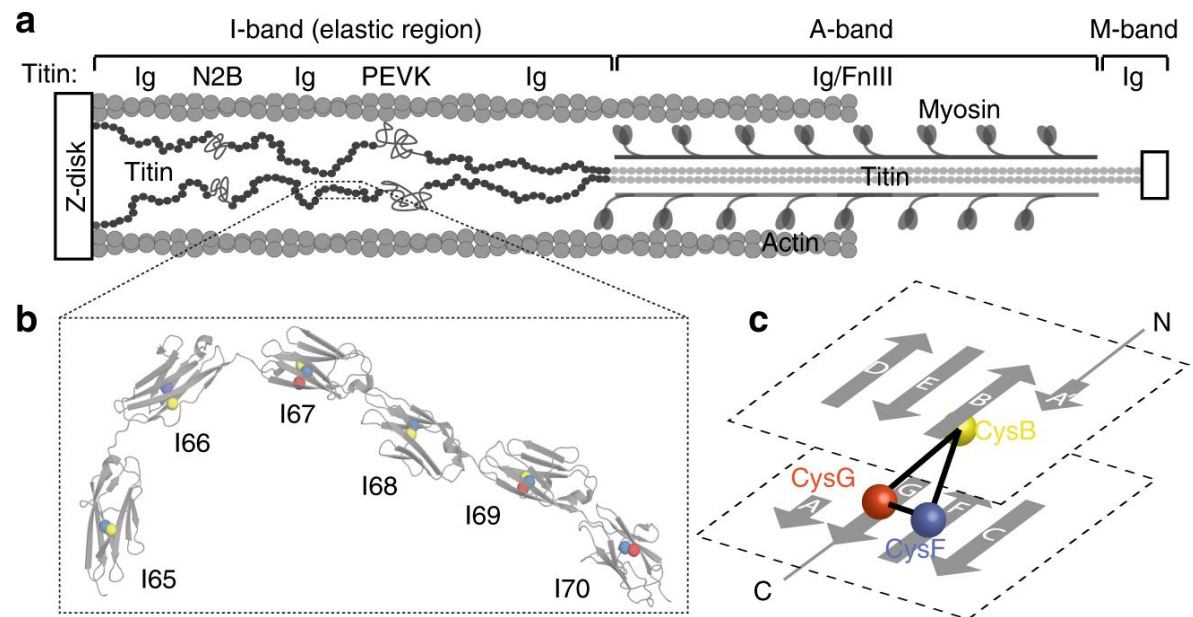
**Needs commands in DPD to solve - see Section 8 of the User Guide.**



Titin has many folded domains that unbind on stretching; each unbound domain contributes many  $k_B T$  to the internal energy

Fig. 11-21 Mol. Biol. Cell, B Alberts et al.

Not every atom matters, but there are many *blobs* that are harmonic  $\sim 1/2 k_B T$ .



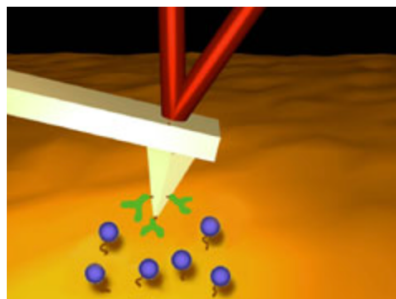
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### spring constants of single molecule and molecular complexe

Direct measurement of the spring constants of single molecule and molecular complexe



Recently we have proposed a new method of direct and continuous measurement of the spring constant of single molecule or molecular complex (see Chtcheglova et al. 2003a). To that end the standard Force Spectroscopy technique with functionalized tips and samples is combined with a small dithering of the tip (fig. 1) The change of the dithering amplitude as a function of the pulling force is measured using a lock-in amplifier in order to extract the spring constant of the complex.

The potentialities of this method have been illustrated for the experiments with single bovine serum albumin (BSA) – its polyclonal antibody (Ab – BSA), fibrinogen – fibrinogen complexes and avidin – biotin. Example of experimental curves obtained for BSA – Ab BSA are presented in Fig. 2: lower curves are standard quasi static AFM pulling off curves, while

### RESEARCH INTERESTS

- AFM-based Single Molecule Force Spectroscopy
- Protein interaction studied with the Atomic Force Microscope
- Cryo-AFM, Atomic Force Microscope at low temperature
- Static and dynamic properties of DNA knots
- Direct measurement of the spring constants of single molecules and molecular complex
- Topoismerase II activity and its interaction with DNA
- Single Molecule Fluorescence Resonance Energy Transfer Scanning Near-field Optical Microscopy (FRET SNOM)

### CONTACTS

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<https://lpmv.epfl.ch/facilities/page-47572-en-html/page-48534-en-html/>

```

Bead W
    0.5
    25
    4.5

Bead B
    0.5
    25 25
    4.5 4.5

Bead BH
    0.5
    25 25 25
    4.5 4.5 4.5

Bead BT
    0.5
    25 25 25 25
    4.5 4.5 4.5 4.5
    
```

Input file: dmpci.f1 on moodle for today

```

Bond BH B 128 0.5
Bond BT B 128 0.5
Bond B B 128 0.5

Polymer Water 0.99995 " (W) "
Polymer Spring 0.00005 " (BH (14 B) BT) "

Box 30 15 15 1 1 1
Density 3
Temp 1
RNGSeed -999
Lambda 0.5
Step 0.01
Time 6000
SamplePeriod 10
AnalysisPeriod 2000
DensityPeriod 6000
DisplayPeriod 100
RestartPeriod 6000
Grid 1 1 1
    
```

A command target is a collection of beads or polymers whose properties can be changed by issuing commands during a simulation (see User Guide, p31ff). They are created by commands that begin `SelectXXXInYYY`, where `XXX` = bead or polymer, and `YYY` is a geometric region, e.g., sphere, cylinder, simbox, etc.

Here, we create two *command target* to hold the beads at the ends of a molecule and apply equal and opposite forces to stretch it.

```
Command SelectBeadTypeInSimBox 1 head BH
Command SelectBeadTypeInSimBox 1 tail BT
```

```
Command Comment 1000 // Apply a constant force to the first and last beads in
the +X and -X directions //
```

```
Command ConstantForceOnTarget          1000 head fh 1 0 0 5.0
Command ConstantForceOnTarget          1000 tail ft 1 0 0 -5.0
```

```
Command Comment 5000 // Delete the applied forces //
```

```
Command RemoveCommandTargetActivity 5000 fh
Command RemoveCommandTargetActivity 5000 ft
```

# Measuring the stress-strain relation for an entropic spring

## To Do:

1. Download the input file `dmpci.fl` from moodle.
2. Notice that a box size of  $30 \times 15 \times 15$  is used to allow the spring to stretch; check that the number fractions create only 1 polymer of type (BH (14 B) BT).
3. Turn force on at  $T = 1000$  steps, and run the simulation for 6000 steps. See next slide for questions to answer.
4. Next, change the backbone to contain a new bead type that is “sticky”. Try (BH B B B S S S S B B B BT), and give S the same interactions as B except for its self interaction that is reduced to make it sticky. Vary the number of S beads until you find a value that makes an observable difference.

You need to copy `dmpci.fl` to a new file, add the new bead type and bond types, and check that only a single polymer is created again.

# Measuring the stress-strain relation for an entropic spring

## Questions to answer

- 1) Look in the dmpchs file and plot the end-to-end length against time when using a force that is large enough to stretch the polymer significantly. Over what time period do you think you should measure the average length under an applied force  $F$ ?
- 2) Plot the stress/strain relation  $F(L)$  for the “molecular spring”
- 3) Does  $F(L)$  have different regimes under different ranges of tension? If so, how many?
- 4) Discuss the origin of the differences in these regimes.
- 5) Explain what you observe when the force is large.
- 6) Before you do the simulation, discuss what you expect the addition of the sticky bead type to do to  $F(L)$ ? After the simulation, was your expectation correct?

dmpcas file contains time-averaged observables

Typically there are 2 columns: mean and standard deviation

dmpcas.fl has <Lee> averaged between 2000 - 4000 steps

```
Time = 4000
Temperature
1.0017449    0.0051323594
```

```
Pressure
23.671181    0.081945563
```

...

```
BB bond length
0.58796179    0.020986014
```

```
Water EE distance
0             0
```

```
Spring EE distance
6.4922776    0.6952996
```

Use the time period while force is applied, which is at the end time of the period



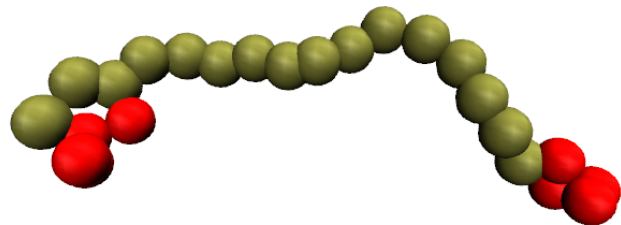
This is the mean and std. dev. of polymer end-to-end length



# Ex. 2 Tethered FRET experiment

FRET measures the separation of two parts of a molecule by attaching two halves of a fluorescent group to the two parts of a molecule and measuring the amount of fluorescence.

Here we measure the distribution of the separation of the two ends of a linear polymer as the attraction between them is varied.



Create a single polymer

```
Polymer Water 0.99998 " (W) "  
Polymer Rod 0.00002 " (E E (16 B) E E) "
```

Measure its radial distribution function averaged over time

```
Command SavePolymerBeadRDF 10000 4 60 15 Rod E
```

How do the endcap binding strength and polymer stiffness affect the RDF?

- 1) Choose a length, e.g., 20 beads, (E-E-(16 B)-E-E) and create one polymer in the box
- 2) Choose a weak BondPair potential for the backbone, e.g.,  $k_3 = 2 k_B T$
- 3) Start with no attraction ( $a_{EE} = 25 = a_{WW}$ ) and gradually increase it by reducing  $a_{EE}$  in steps of 5 down to  $a_{EE} = 5$ .
- 4) Use the SavePolymerBeadRDF command to save the radial distribution function of the endcap beads to a file (see the User Guide for the arguments):

```
Command SavePolymerBeadRDF 5000 3 60 15 Rod E
```

- 5) Plot the RDF of the endcaps for several values of  $a_{EE}$  including  $a_{EE} = 25$  as baseline.
- 6) For a given value of the  $a_{EE}$ , increase the backbone bondpair parameter  $k_3$  to make it stiffer; how does the RDF change now?

## Ex. 3 Polymer in a good/bad solvent

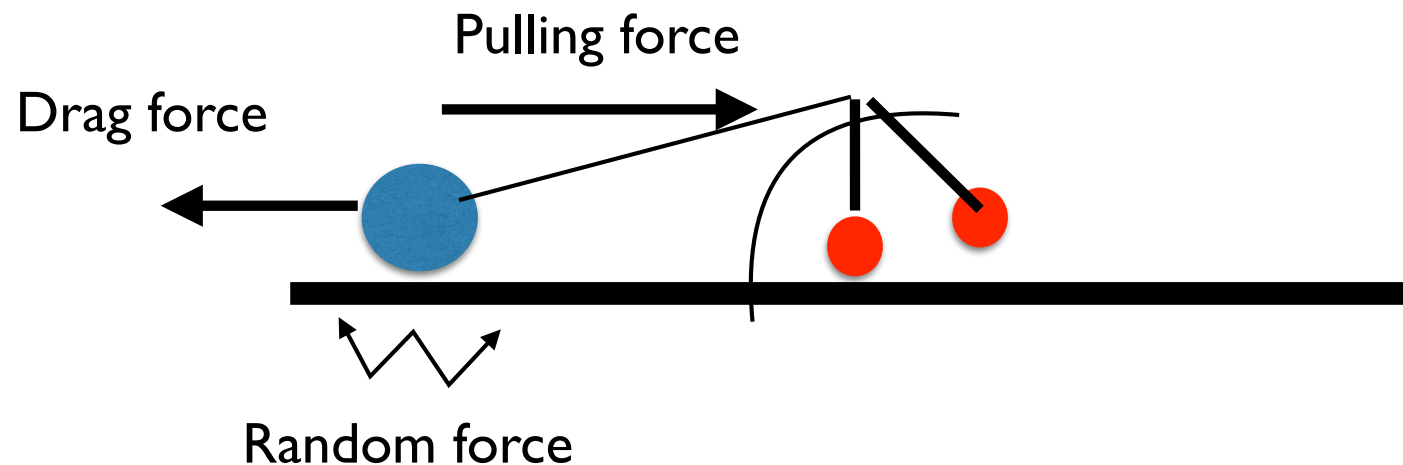
A polymer in a good solvent swells while one in a bad solvent collapses into a dense ball.

- 1) Create a single homopolymer (as in Ex. 2) of length 20, and set  $a_{BW} = 10$ . This represents a **good** solvent as the backbone wants to be solvated.
- 2) Plot its end-to-end length using the time series from the dmpchs file, make sure it is equilibrated (how?) and find the equilibrium value.
- 3) Then repeat the simulation and vary the conservative interaction between the polymer beads and the solvent from attractive ( $a_{BW} = 10$ ), through neutral ( $a_{BW} = 25$ ) to repulsive ( $a_{BW} \gg 25$ ) in steps of 10.
- 4) Plot the  $\sqrt{\langle L^2 \rangle}$  from the dmpcas file against  $a_{BW}$ .

Is there a sharp transition between an extended state and a collapsed state as  $a_{BW}$  is made increasingly repulsive?

## Ex. 4 Langevin equation and nanoparticle

Suppose a molecular motor pulls a vesicle along an actin filament: we can use a Langevin equation to model this or do a DPD simulation.



We model this as a rigid sphere being pulled in a straight line by a constant force while also subject to a (Stokes) drag force and a random force.

# Pulling a nanoparticle in water

Because the vesicle moves slowly - no acceleration - there are two parameters: magnitude of the viscous drag force, and magnitude of the (random) thermal fluctuation force.

Friction coefficient is:  $\gamma = 6\pi\eta a$  (from macroscopic Stokes law for drag on a sphere)

We also need a value for  $\sigma/\gamma$ . Recall from the DPD random force equation:  $\sigma^2 = 2\gamma k_B T$  which leads to:

$$x(t + dt) = x(t) + F_{\text{const.}}dt/\gamma + \sqrt{D} \cdot N(0, 1) \cdot \sqrt{dt}$$

where  $D = 2k_B T/\gamma$ . If we want to relate the results to a physical experiment, we would have to set appropriate values for the solvent viscosity  $\eta$ , nanoparticle size  $a$ , and temperature.

$N(0, 1)$  = Gaussian distributed random number with zero mean 0 and unit variance. But we will use a uniform random number in the interval  $(-1/2, 1/2)$ .

NB make sure it is normalised to unity, i.e., use  $2 \cdot \text{coefficient} \cdot \text{RN}$  in  $(-1/2, 1/2)$ .

# Pulling a nanoparticle in DPD

dpd

```
Title " Pulling a nanoparticle in water "  
Date 27/10/18  
Comment " Create a spherical nanoparticle then apply a constant force to it. "
```

```
State random
```

```
Bead W  
0.5  
25  
4.5
```

```
Polymer Water 1 " (W) "
```

```
Box 48 12 12 1 1 1  
Density 3  
Temp 1  
RNGSeed -21114  
Lambda 0.5  
Step 0.01  
Time 2000  
SamplePeriod 10  
AnalysisPeriod 2000  
DensityPeriod 2000  
DisplayPeriod 20  
RestartPeriod 2000  
Grid 1 1 1
```

```
Command ToggleBeadDisplay 1 W  
Command SetCurrentStateCamera 1 0.5 -4.0 0.5 0.5 0.5 0.5  
Command SetCurrentStateDefaultFormat 1 Paraview
```

```
Command Comment 1 // Create a solid spherical nanoparticle of radius 2.0 //
```

```
Command SelectPolymerTypeHeadInSphere 100 ball1 Water 0.25 0.5 0.5 0.0 2.0  
Command PolymerisePolymersInTarget 100 ball1 12 1.5 1.0 256 0.0  
Command SetTargetDisplayId 100 ball1 1
```

```
Command SelectPolymerTypeHeadInSphere 100 ball2 Water 0.75 0.5 0.5 0.0 2.0  
Command PolymerisePolymersInTarget 100 ball2 12 1.5 1.0 256 0.0  
Command SetTargetDisplayId 100 ball2 2
```

```
Command Comment 100 // Apply a constant force along the +X axis to the NP //
```

```
Command ConstantForceOnTarget 100 ball1 fz 1 0 0 5.0
```

```
Command RemoveCommandTargetActivity 1000 fz
```

# Simple RNG in C

```
#define IA 16807
#define IM 2147483647
#define AM (1.0/IM)
#define IQ 127773
#define IR 2836
#define MASK 123459876

float ran0(long *idum)
"Minimal" random number generator of Park and Miller. Returns a uniform random deviate
between 0.0 and 1.0. Set or reset idum to any integer value (except the unlikely value MASK)
to initialize the sequence; idum must not be altered between calls for successive deviates in
a sequence.
{
    long k;
    float ans;

    *idum ^= MASK;
    k=(*idum)/IQ;
    *idum=IA*( *idum-k*IQ)-IR*k;
    if (*idum < 0) *idum += IM;
    ans=AM*( *idum);
    *idum ^= MASK;
    return ans;
}
```

XORing with MASK allows use of zero and other simple bit patterns for idum.  
Compute idum=(IA\*idum) % IM without overflows by Schrage's method.  
Convert idum to a floating result.  
Unmask before return.

The period of `ran0` is  $2^{31} - 2 \approx 2.1 \times 10^9$ . A peculiarity of generators of the form (7.1.2) is that the value 0 must never be allowed as the initial seed — it perpetuates itself — and it never occurs for any nonzero initial seed. Experience has shown that users always manage to call random number generators with the seed `idum=0`. That is why `ran0` performs its exclusive-or with an arbitrary constant both on entry and exit. If you are the first user in history to be proof against human error, you can remove the two lines with the  $\wedge$  operation.

Numerical Recipes in C: The Art of Scientific Computing  
W. H. Press et al. Cambridge University Press, 2nd ed. 1992

# Better RNG in C

```
#define MBIG 1000000000
#define MSEED 161803398
#define MZ 0
#define FAC (1.0/MBIG)
According to Knuth, any large MBIG, and any smaller (but still large) MSEED can be substituted
for the above values.

float ran3(long *idum)
Returns a uniform random deviate between 0.0 and 1.0. Set idum to any negative value to
initialize or reinitialize the sequence.
{
    static int inext,inextp;
    static long ma[56];
    static int iff=0;
    long mj,mk;
    int i,ii,k;

    if (*idum < 0 || iff == 0) {
        iff=1;
        mj=MSEED-(*idum < 0 ? -*idum : *idum);
        mj %= MBIG;
        ma[55]=mj;
        mk=1;
        for (i=1;i<=54;i++) {
            ii=(21*i) % 55;
            ma[ii]=mk;
            mk=mj-mk;
            if (mk < MZ) mk += MBIG;
            mj=ma[ii];
        }
        for (k=1;k<=4;k++)
            for (i=1;i<=55;i++) {
                ma[i] -= ma[1+(i+30) % 55];
                if (ma[i] < MZ) ma[i] += MBIG;
            }
        inext=0;
        inextp=31;
        *idum=1;
    }
    Here is where we start, except on initialization.
    if (++inext == 56) inext=1;
    if (++inextp == 56) inextp=1;
    mj=ma[inext]-ma[inextp];
    if (mj < MZ) mj += MBIG;
    ma[inext]=mj;
    return mj*FAC;
}
```

The value 56 (range ma[1..55]) is special and should not be modified; see Knuth.

Initialization.

Initialize ma[55] using the seed idum and the large number MSEED.

Now initialize the rest of the table, in a slightly random order, with numbers that are not especially random.

We randomize them by "warming up the generator."

Prepare indices for our first generated number. The constant 31 is special; see Knuth.

Increment inext and inextp, wrapping around 56 to 1.

Generate a new random number subtractively. Be sure that it is in range.

Store it, and output the derived uniform deviate.

Numerical Recipes in C: The Art of Scientific Computing  
W. H. Press et al. Cambridge University Press, 2nd ed. 1992

# Ex. 5 Molecular force spectroscopy I

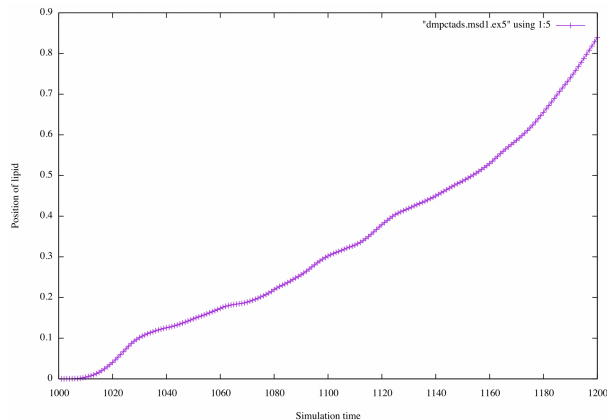
Select a single lipid:

```
Polymer Water 0.978967 " (W) "  
Polymer Lipid 0.021013 " (H H (* (T T T T)) H T T T T) "  
Polymer Lipid1 0.00002 " (H1 H (* (T T T T)) H T T T T) "
```

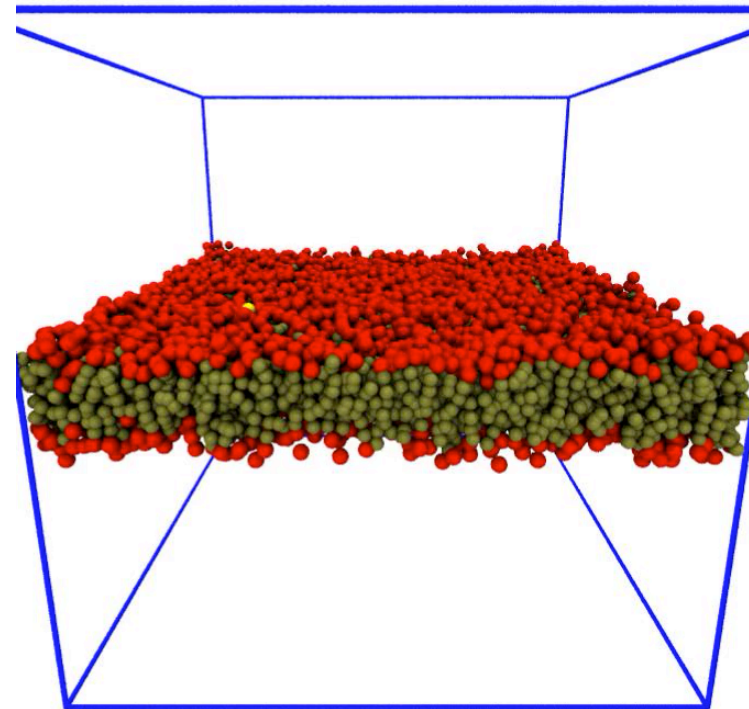
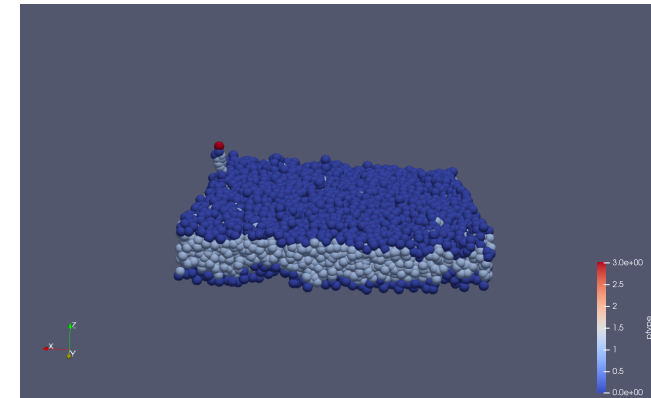
apply a pulling force normal to membrane:

```
Command Comment 1 // Following commands apply a force upwards to the single lipid with the H1 bead //  
Command SelectBeadTypeInSimBox 1 head H1  
Command ConstantForceOnTarget 100 head fh 0 0 1 20.0  
Command RemoveCommandTargetActivity 1000 fh
```

measure position of lipid and work done on it

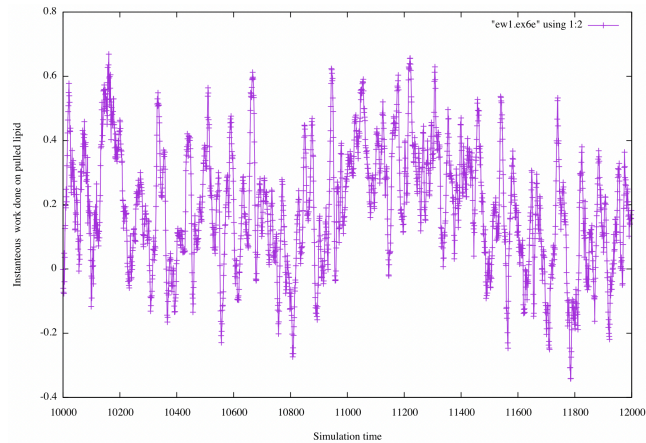


Lipid position in z direction

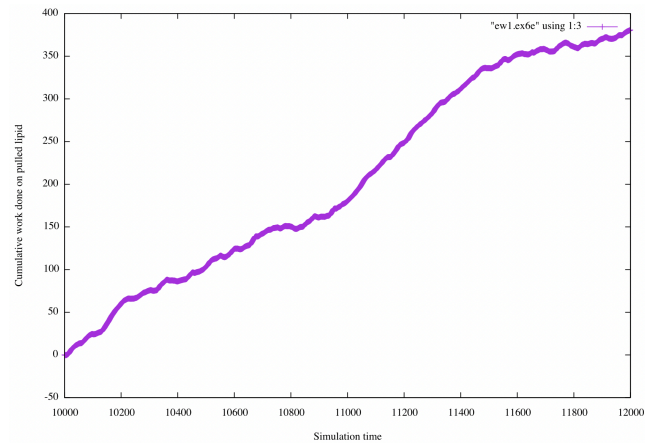


# Ex. 6 Molecular force spectroscopy 2

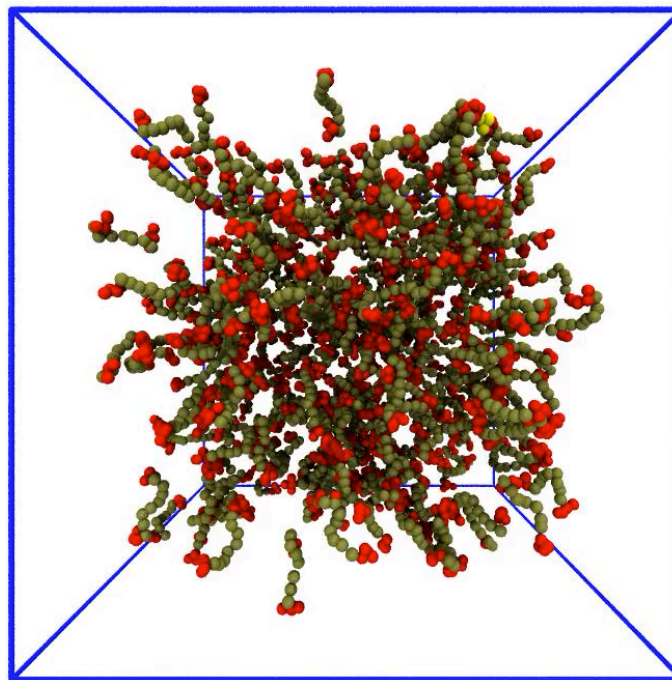
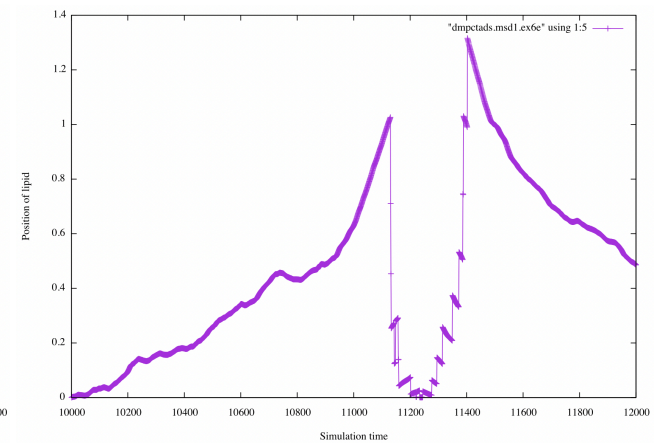
Apply a force to a single IDP in a droplet and extract it and measure the work done against the force



Work done



Position



see `dmpci.ex6e`

# Ex. 7 Thermodynamic model of IDP droplet

Recall from Lecture 3, a model of the self-assembly of polymers with sticky binding sites:

$U$  = surface energy of spherical aggregate = surface tension  $\times$  area

$P(R)$  = prob. of polymer with  $R_{ee}$  having a size of  $R \sim \exp(- (R - R_{ee})^2 / 2R_{ee}^2)$

Add the binding energy of  $M$  binding sites per polymer ( $-\varepsilon$ ) and let  $M$  vary with droplet size;  $M$  has an upper limit of  $M_{max}$  per polymer.

The Helmholtz free energy is now:

$$F = U - TS = 4\pi \sigma R^2 - N M(R) \varepsilon / 2 - N k_B T \log P(R)$$

How does  $M$  depend on the aggregate's radius? Do stretched polymers expose more binding sites or do they find it harder to bind due to increased shape fluctuations?

Assume a functional form for  $M$ , minimise the free energy, and find how the radius varies with the parameters  $\sigma$ ,  $\varepsilon$ ,  $M_{max}$ , and  $T$ .

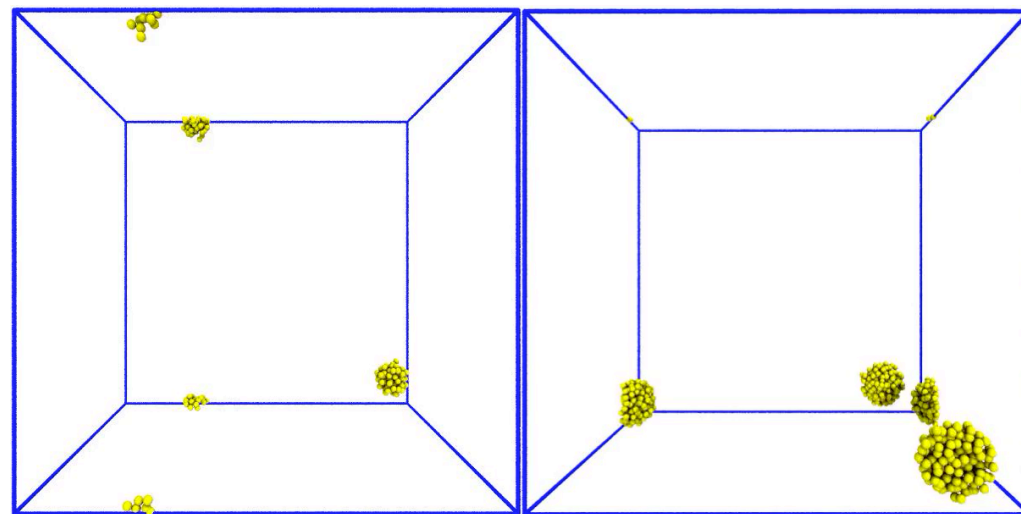
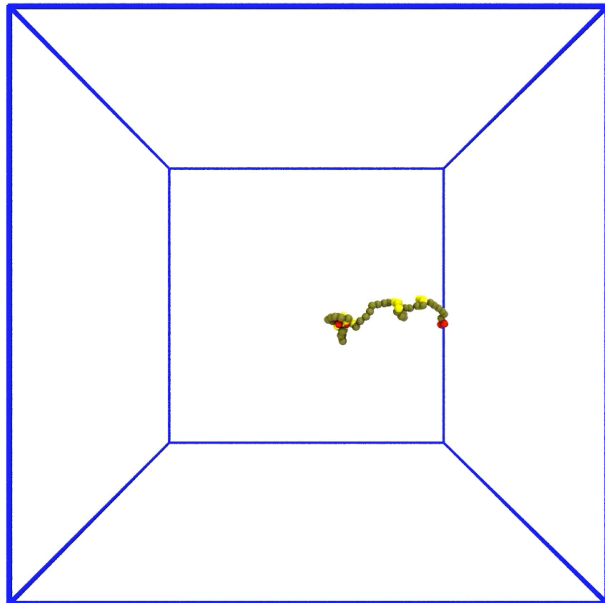
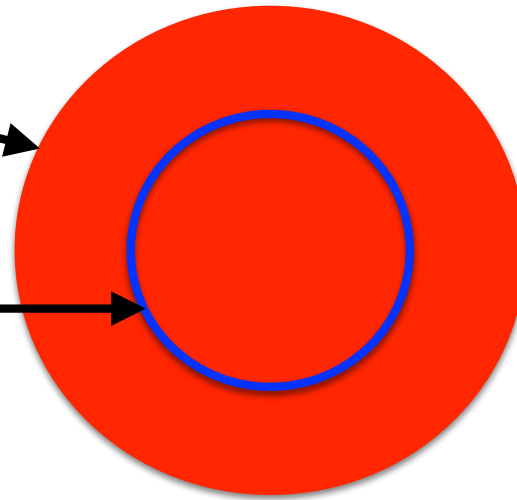
Check the dimensions make sense.

# Ex. 8 Compare the diffusion of a hard sphere and a **EPFL** fluctuating polymer

$R_h$  = actual sphere radius

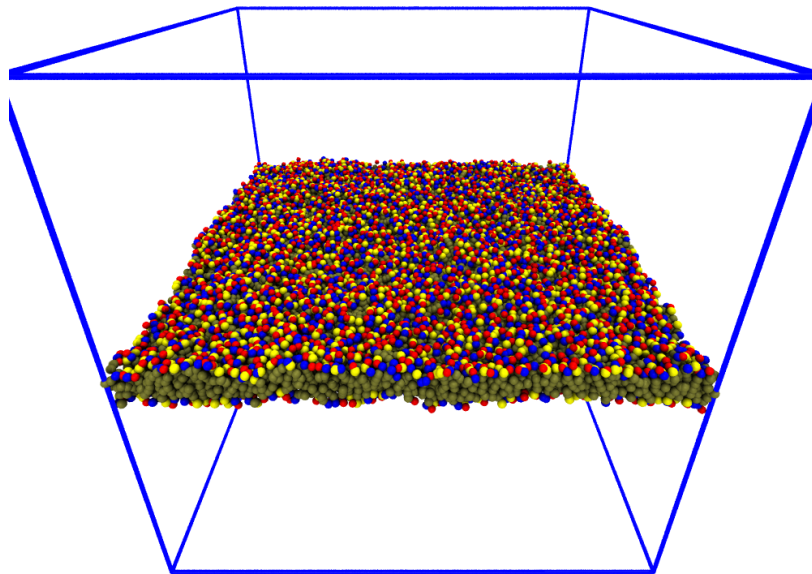
$R_g$  ~ distribution of mass in space

$$M R_g^2 = \int r(m)^2 dm$$

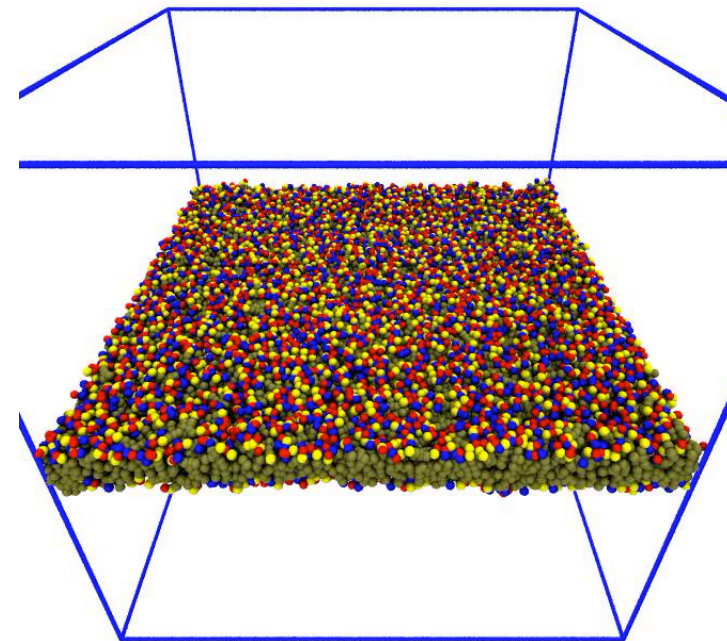


# Ex. 9 Effect of charged headgroups on lipid bilayer stability

Simulate a stable membrane with a lipid whose headgroup can be charged, then set a screened Coulomb repulsion between the headgroups on a fraction of the lipids (from 1 down to ?) and observe the effect on the membrane.



No charge



Charged

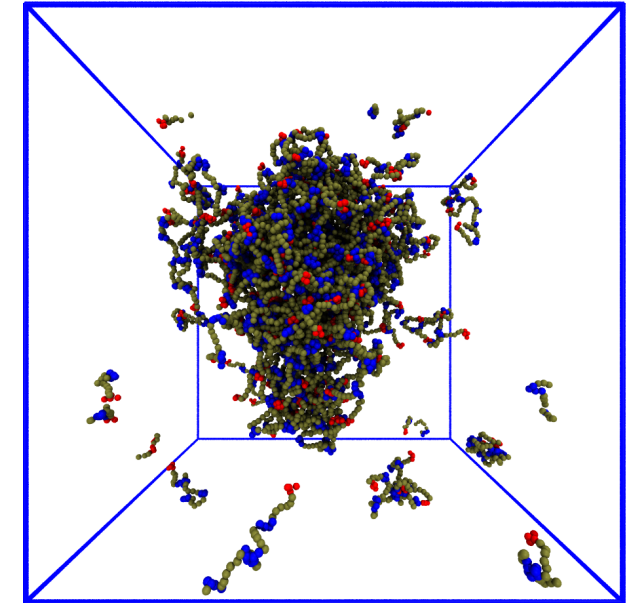
```
3 Polymer Water 0.98787 " (W) "  
4 Polymer Lipid 0.01213 " (P04 (* (COH T T T T)) NHO T T T) "  
5  
6 Command ChargeBeadByType 10000 1 2.8 2.0  
7
```

# Ex. 10 What are the dense and dilute phase concentrations of a phase separated droplet of a model IDP?

## Simple way

assume dense phase is a sphere, measure  $R_g$ ,  
and use density = mass / volume

dilute phase density = # polymers not in  
dense phase / (box volume - sphere volume)



## Accurate way

Monte Carlo method for estimating dense phase volume

dilute phase density = # polymers not in dense phase / (box volume - dense volume)