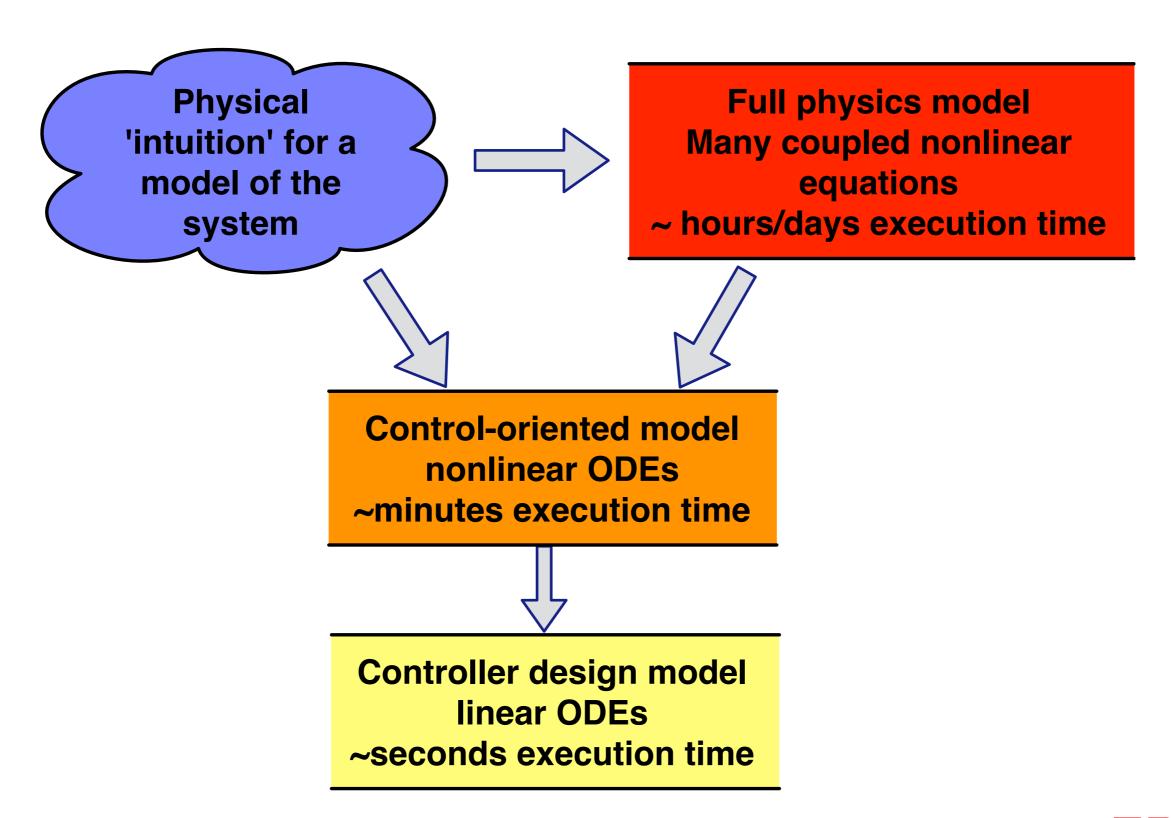
## General concepts in control-oriented modeling

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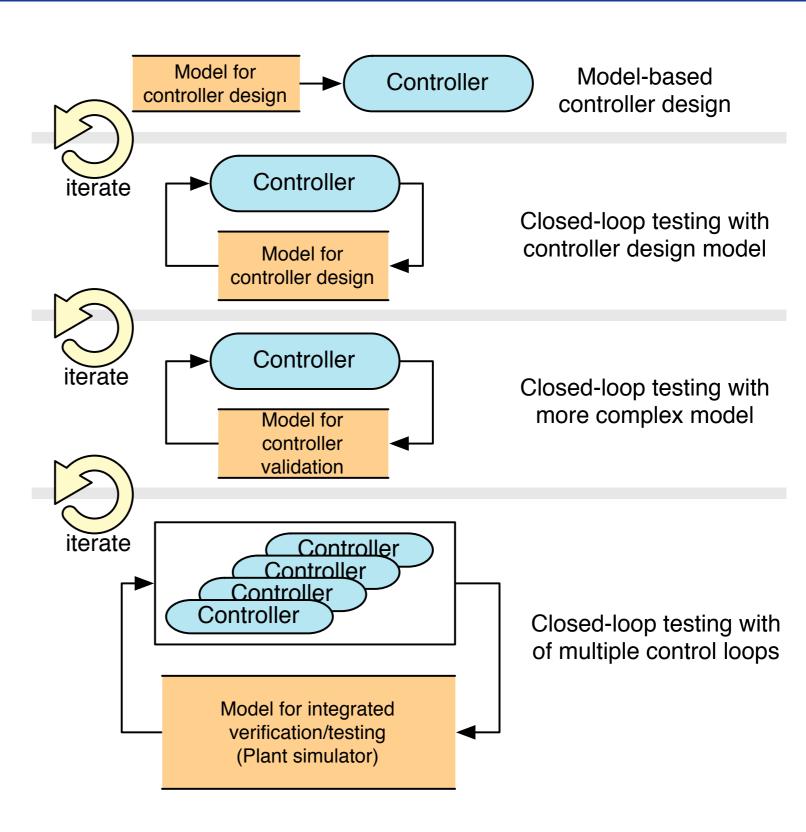
## The importance of control-oriented models





## The importance of control-oriented models

- To design and test controllers, we always use a model of the system.
  - Models of varying complexity are used at various stages of design/testing
  - Choice of correct model for task is an <u>integral</u> part of the control engineer's task





# The control engineer's toolbox: some examples

#### **PID** control

there are three knobs to turn try until it works

#### **Predictive control**

looking into the future decide what is best

#### **Learning Controller**

what went wrong last time you tried?

do better next time

#### **Adaptive control**

constantly changes to match the system controlled

#### **Robust controller**

perturbed system? no problem it works anyway



## Requirements for control-oriented models

Role of model	Typical requirements	Typical model structure
Controller design	Tractable form for which controller synthesis tools exist.	Linear time invariant ODEs Linear parameter varying LTI + simple nonlinearity
Controller testing	Fast, so it does not slow down the controller design iterations	Linear/Nonlinear ODEs
Controller validation	Includes key effects which could not be included in the controller design model	Nonlinear ODE or PDE
Integrated verification/testing	Maximum possible realism	Complex simulator including events + hardware/software interfaces of final plant



## **Deriving models**

- First-principle, physical modeling
  - Derive models from laws of physics governing controlled system.
- Mixed empirical + first-principle models
  - Derive models from physics, but use empirical formulas 'difficult' parts of the model
- System identification
  - Black-box: derive entire model from data
  - Grey-box: derive unknown model parameters from data
- A large part of this course was about modeling:
  - Derive models of the plasma in a form suitable for controller design
  - Awareness of hierarchy in model complexity for various control problems



### Conclusions

- Operation of tokamaks calls for multiple complex, interconnected control loops
- Deriving good controllers is a multidisciplinary problem
  - Physical modeling: plasma physics & electromagnetism
  - Controller design/testing: Control engineering
  - Implementation: hardware/software knowledge
- Cutting edge of science and engineering
  - Much to do for physicists, control engineers, software engineers, numerical mathematics, machine learning ...

