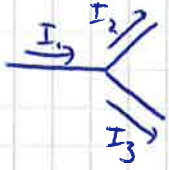


Lecture 13. Magnetostatics. Lorentz force law

Last time: Circuits

* EMF: source of energy to maintain a constant current in a closed circuit.
 $\mathcal{E} \equiv \frac{dW}{dq}$

* Kirchhoff's rules:



$$\sum I_{in} = \sum I_{out}$$

Junction rule

$$I_1 = I_2 + I_3$$

$$\sum_{\text{closed loop}} \Delta V = 0 \quad \text{loop rule}$$

Today: Magnetism

How it started:

* Ancient Greece: Pieces of magnetite → can attract iron
↳ but no effect on Au, Ag, Cu, etc.
↳ can attract or repel ~~other~~ ^{pieces of magnetite} depending on the relative orientation.

* XII century → magnetic compass
↳ small magnetic needle will always come to rest with one end pointing "North" and the other "South"



Like poles repel
Unlike poles attract

Demo 567 and 564 circular magnets & magnetized needles

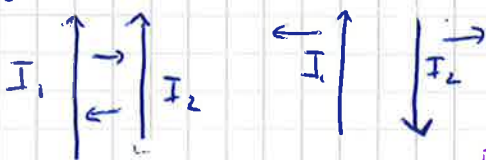
When things got interesting:

* In 1820 Oersted realized that current flowing in a wire made the needle of a compass swing

Rev it demo 564 w/ Helmholtz coil

BIG DEAL: Electricity & magnetism are related

* Soon after came the definite proof w/ Ampère's experiment with parallel wires carrying current.



* If currents are // wires attract

if currents are anti // wires repel

* If we place a stationary charge nearby it doesn't move → wires are overall neutral

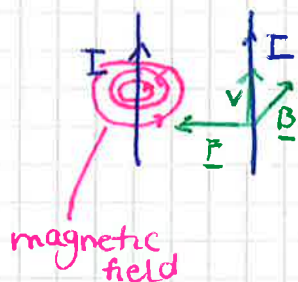
Demo 592 Ampère's experiment.

Whatever $\underline{F}$ accounts for the attraction of $\parallel$ currents & repulsion of antiparallel is 'not' electrostatic.

A **stationary charge** produces only an electric field $\underline{E}$. A **moving charge** generates in addition a magnetic field $\underline{B}$.

Take a compass & you can start finding magnetic fields anywhere. If you take a compass in the vicinity of a current carrying wire you'll see the **magnetic field** "curls" around the source.

And here is where the right hand rule comes back to haunt us!



More refined observations of Ampere's experiment:

$F \sim I_1 I_2$ Force is proportional to the velocity of the charges in motion

Direction of $\underline{F}$ is perpendicular to the velocity

Interpretation $\rightarrow$ Same field is created by the charges in motion.
 $\rightarrow$ magnetic $\underline{E}$ is proportional to the cross product:

$$\underline{F} = q (\underline{v} \times \underline{B}) \quad \text{magnetic force on a charge } q \text{ moving at velocity } \underline{v}$$

In the presence of both electric and magnetic fields, the total force will be:

$$\underline{F} = q [\underline{E} + (\underline{v} \times \underline{B})] \quad \text{Lorentz force law}$$

Thoughts on Lorentz force law:

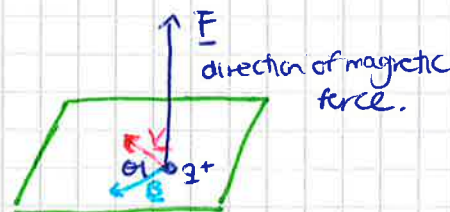
* So for the Lorentz force law is an empirical law, put together from experimental observations.

* It defines the magnetic field $\underline{B}$

* Units of $\underline{B}$:

$$[B] = \frac{[F]}{[qv]} = \frac{N}{m/s \cdot C} = \frac{N}{A \cdot m} = \text{Tesla (T)}$$

where m meters
 N newtons
 s seconds
 C coulomb
 A ampere



* Magnitude of the magnetic force is proportional to v and q .

* Because $\underline{F} \propto \underline{v} \times \underline{B}$, when $\underline{v} \parallel \underline{B}$ the magnetic force vanishes.

* Remembering the geometrical interpretation of the $\times$ product. If $\underline{v}$ makes an angle θ with $\underline{B}$, the direction of $\underline{F}$ is perpendicular to the plane formed by $\underline{v}$ and $\underline{B}$ and its magnitude is proportional to $\sin \theta$.

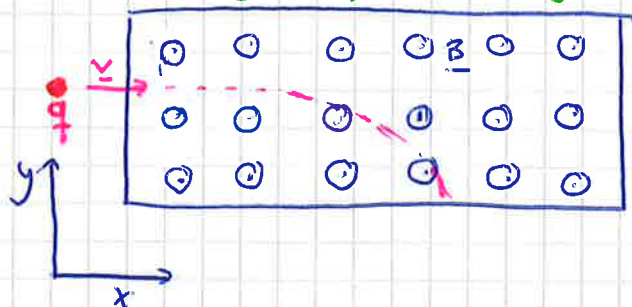
* When we change the sign of q , the direction of $\underline{F}$ also reverses.

EXAMPLE:

Trajectory of a particle in a magnetic field

A particle of charge q and mass m moves with a velocity $\underline{v} \parallel \hat{x}$ axis in a magnetic field $\underline{B} \parallel -\hat{z}$ axis (into the page):

What is the trajectory of q in the magnetic field?



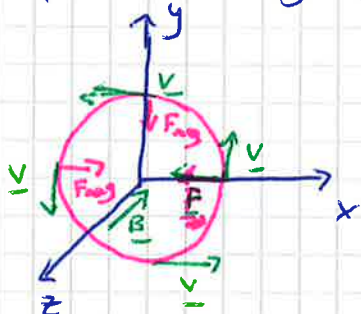
$$\underline{F}_{\text{mag}} = q(\underline{v} \times \underline{B})$$

$\underline{B}$ points out of the page and $\underline{v}$ is $\parallel$ to $\hat{x}$

$$\Rightarrow \underline{B} \perp \underline{v}$$

And we saw that by definition $\underline{F}_{\text{mag}} \perp$ the plane that $\underline{v}$ & $\underline{B}$ are in
 $\therefore \underline{v}$, $\underline{B}$ and $\underline{F}_{\text{mag}}$ are all perpendicular

So then the path of the charged particle will be:



particle moves in a counterclockwise circle!

Magnetic force has a fixed magnitude
 $|\underline{F}_{\text{mag}}| = qvB$

that allows it to sustain circular motion

$$qvB = \frac{mv^2}{R}$$

where R is the radius of the circle its trajectory describes

$$R = \frac{mv}{qB}$$

the time it takes for the particle to complete a ~~full~~ revolution is:

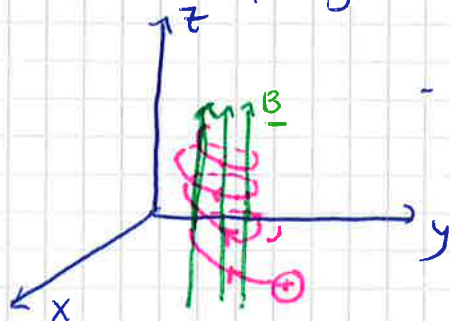
$$T = \frac{2\pi R}{v} = \frac{2\pi mv}{vqB} = \frac{2\pi m}{qB}$$

using the expression of R we just derived

~~And similarly~~ Similarly we can obtain the angular speed of the particle:

$$\omega = 2\pi f = \frac{v}{R} = \frac{qB}{m}$$

If the initial velocity of the charged particle has a component parallel to the magnetic field $\underline{B}$, instead of a circle, the particle's trajectory will be a helical path:



particle velocity has a non-zero component in the direction of $\underline{B}$

Demo 4.15. Deflection of an electron beam by $\underline{B}$

J.J Thompson's experiment

Discovery of the electron and measurements of e/m_e in 1897.

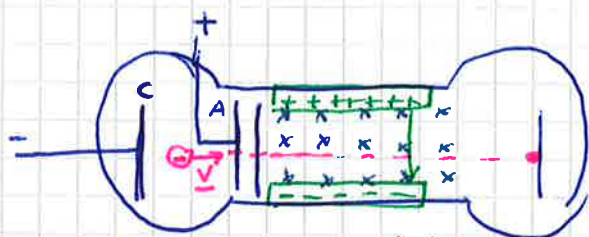
This experiment showed that atoms are not indivisible, rather contain smaller charged particles.

The idea:

→ A beam of "cathode rays" crosses a region with $\underline{E}$ & $\underline{B}$ present.

→ Choosing $v_e \parallel x$ axis, $B \parallel z$ axis, $E \parallel y$ axis $\Rightarrow \underline{F}_{\text{magnetic}} \parallel \underline{F}_{\text{electric}}$

→ E and B can be adjusted such that $F_{\text{mag}} = -F_{\text{electric}}$ so the e will go straight



Thompson's apparatus

x indicates magnetic field

□ charged plates with + or - charge

$\underline{E}$ field points from the top plate to the bottom



* Electrons with charge $q = -e$ and mass m are emitted from the cathode C and then accelerated towards slit A .

* Let the potential difference between A and C be $\Delta V = V_A - V_C$

* Change in potential energy is equal to the work done to accelerate the electrons:

$$\Delta U = W_{\text{ext}} = q \Delta V = -e \Delta V$$

* By conservation of energy, the kinetic energy gained is:

$$\Delta K = -\Delta U = \frac{mv^2}{2} = -e \Delta V$$

↑
sub ΔV

$$\Rightarrow v = \left[\frac{2e\Delta V}{m} \right]^{1/2} \quad (*) \quad \text{is the speed of the electrons}$$

* After this, the $\bar{e}$ will pass through a region with an electric field pointing downwards, so they should be deflected upwards.

However if we also add a magnetic field directed into the page, then the $\bar{e}$ will experience a downward magnetic force $-e \underline{v} \times \underline{B}$.

If the two forces exactly cancel, then the electrons will move in a straight path.

This condition is met when:

$$\underline{F} = q(\underline{E} + \underline{v} \times \underline{B}) = 0$$

$$\Rightarrow q\underline{E} = -q \underline{v} \times \underline{B} \quad \text{in this case } q = -e$$

$$\Rightarrow e\underline{E} = e\underline{v} \times \underline{B} \Rightarrow v = \frac{E}{B} \quad (**)$$

so only particles with speed $v = \frac{E}{B}$ will move in a straight line.

Combining equations (*) and (**) we get:

$$\frac{E}{B} = \left[\frac{2e\Delta V}{m} \right]^{1/2} \Rightarrow \frac{e}{m} = \frac{E^2}{2\Delta V B^2}$$

so if we control experimentally E, B & ΔV then we can measure

$$\frac{e}{m} = 1.7588 \times 10^{11} \text{ C/kg} \quad (4)$$

Important note: Magnetic forces and work

* Moving a charge in an electric field requires work

$$W_{12} = -q \int_1^2 \underline{E} \cdot d\underline{s}$$

* How much work does it take to move a charge in a magnetic field?

$$dW = \underline{F} \cdot d\underline{s} = \underline{F} \cdot \underline{v} dt = q (\underline{v} \times \underline{B}) \cdot \underline{v} dt = 0$$

$$\uparrow$$
$$\underline{F}_{\text{mag}} = q (\underline{v} \times \underline{B})$$

∴ **Magnetic forces DO NOT work**

↑
this follows because
 $(\underline{v} \times \underline{B})$ is $\perp$ to $\underline{v}$ so

$$(\underline{v} \times \underline{B}) \cdot \underline{v} = 0$$

because the dot prod of 2 $\perp$ vectors is zero

No work is needed to move a particle in a magnetic field because $\underline{v}$ & $\underline{F}$ are always $\perp$.

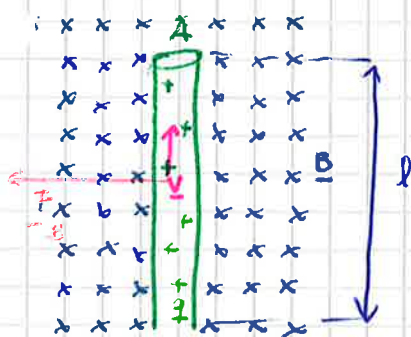
Magnetic forces may alter the direction in which a particle moves but they won't speed it up or slow it down.

Magnetic force on a current carrying wire

We have just seen that a charged particle placed in a magnetic field experiences a force $\underline{F}_{\text{mag}}$.

Since an electric current consists of a collection of charged particles in motion, when placed in a magnetic field $\underline{B}$, a current carrying wire will also experience a magnetic force.

To calculate the force exerted on the wire consider a segment of wire of length l and cross sectional area A . The magnetic field points into the page represented by $\times$'s.



A cross-sectional area of wire

$\underline{B}$ is the magnetic field
that points into the page represented by $\times$

l length of wire

$\underline{v}$ charge move at this av. drift velocity

The total magnetic force on this wire segment is:

$$Q_{\text{tot}} = q (n A l) \quad \text{total amount of charge in the wire segment}$$

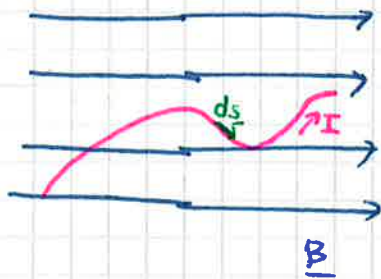
$$\underline{F}_{\text{mag}} = Q_{\text{tot}} (\underline{v} \times \underline{B}) = q n A l (\underline{v} \times \underline{B}) = I (\underline{l} \times \underline{B})$$

$n \equiv \#$ of charges/unit volume

↑
because $I = n q v A$ current definition

with $\underline{l} =$ length vector of magnitude l directed along the direction of the current.

So this is for a small segment of wire, for a wire of arbitrary shape, the magnetic force can be obtained by summing over the forces acting on the small segments that make up the wire:



As usual, we have an infinitesimal wire element: ds

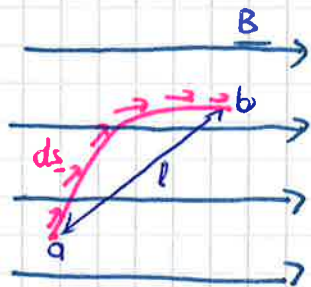
The magnetic $\underline{F}$ acting on this element is:

$$d\underline{F}_{\text{mag}} = I d\underline{s} \times \underline{B}$$

$$\Rightarrow \underline{F}_{\text{mag}} = I \int_a^b d\underline{s} \times \underline{B} \quad \text{where } a \text{ \& } b \text{ are the end points of the wire}$$

we have taken I out of the integral assuming the current has constant magnitude along the wire.

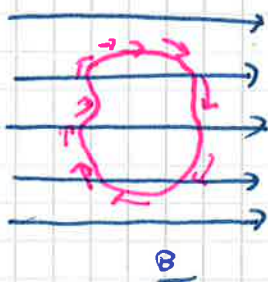
Now if we consider the following wire as an example:



In this case:

$$\underline{F}_{\text{mag}} = I \int_a^b d\underline{s} \times \underline{B} = I \underline{l} \times \underline{B}$$

Now if we consider a closed loop of arbitrary shape:



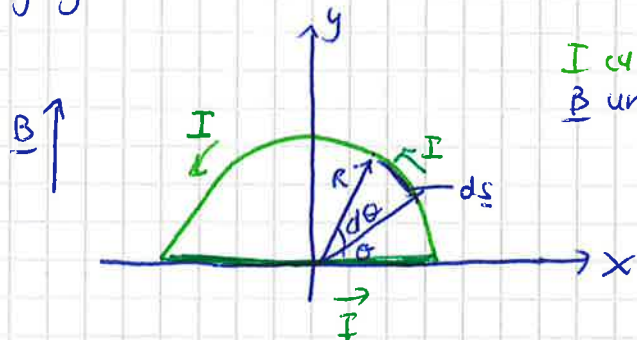
$$\underline{F}_{\text{mag}} = I \oint d\underline{s} \times \underline{B}$$

Since the set of $d\underline{s}$ form a closed polygon and their vector sum is zero $\Rightarrow \oint d\underline{s} = 0$

$$\therefore \text{For any closed loop of current} \quad \underline{F}_{\text{mag}} = 0$$

EXAMPLE: Magnetic force on a semicircular loop

Consider a closed semi-circular loop lying in the x, y plane carrying a current I :



I current flowing counter-clockwise
 $\underline{B}$ uniform magnetic field in y direction

Q. What is the magnetic force acting on the straight segment of the semicircular arc?

↻ this part

Solution:

Let $\underline{B} = B\hat{j}$ the magnetic field (mag B & oriented along y axis)

Let $\underline{F}_1$ & $\underline{F}_2$ be the forces acting on the wire segments a & b respectively

Using the eq. we derived above:

$$\underline{F}_{\text{mag}} = I \int_a^b d\underline{s} \times \underline{B}$$

* For the straight segment we have that:

$$\underline{F}_1 = I(2R)\hat{i} \times B\hat{j} = 2IRB\hat{k}, \text{ where } \hat{k} \text{ is directed out of the page.}$$

length of the straight segment is $2R$, where R is the radius of the circle
 segment is oriented along x axis

* To evaluate $\underline{F}_2$:

As usual we first note that the differential length element $d\underline{s}$ on the semicircle can be written as:

$$d\underline{s} = ds\hat{\theta} = R d\theta (-\sin\theta\hat{i} + \cos\theta\hat{j})$$

↑
definition of arclength

with this the magnetic force is:

$$\underline{F}_2 = I \oint d\underline{s} \times \underline{B} = I \int d\theta (-\sin\theta\hat{i} + \cos\theta\hat{j}) \times B\hat{j} = -IBR \sin\theta d\theta \hat{k} \text{ so } \underline{F}_2 \text{ points into the page.}$$

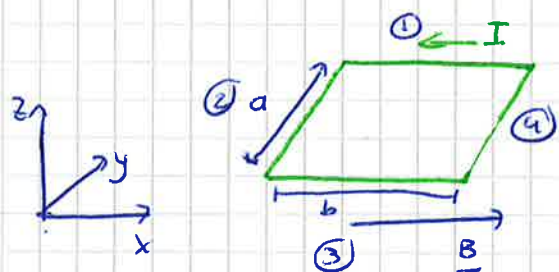
And now we have to integrate over the circular arc:

$$\underline{F}_2 = -IBR\hat{k} \int_0^\pi \sin\theta d\theta = -2IBR\hat{k}$$

And we can see that the net force on the loop is actually zero.
 As it should be for a closed current loop.

Torque on a current loop

what happens when we place a rectangular loop carrying a current I in the xy plane and switch on a uniform $\underline{B} \parallel$ to the plane of the loop?



loop has sides w length a & b

let's consider 4 regions of the loop

What is the magnetic $\underline{F}$ experienced by each region of the loop?

For 1 & 3 $\underline{F}_{\text{mag}} = 0$ (since $\underline{I} \parallel \underline{B}$ therefore $\underline{F}_{\text{mag}} = I(\underline{l} \times \underline{B}) = 0$)

For regions 2 & 4 there is a magnetic force. Using the same eq we see:

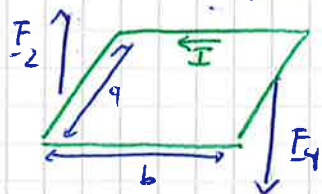
$$\underline{F}_2 = I(-a\hat{j}) \times (B\hat{i}) = Iab\hat{k} \leftarrow \text{points } \text{out} \text{ the page}$$

$$\underline{F}_4 = I(a\hat{j}) \times (B\hat{i}) = -Iab\hat{k} \leftarrow \text{points into the page}$$

As expected the net force on the loop is zero. $\underline{F}_{\text{net}} = \underline{F}_1 + \underline{F}_2 + \underline{F}_3 + \underline{F}_4 = 0$

However, the forces $\underline{F}_2$ and $\underline{F}_4$ will produce a torque, which causes the loop to rotate around the y axis. Let's calculate the torque w/ respect to the center of the loop:

Remembering $\underline{\tau} = \underline{r} \times \underline{F}$



$$\underline{\tau} = \left(-\frac{b}{2}\hat{i}\right) \times \underline{F}_2 + \left(\frac{b}{2}\hat{i}\right) \times \underline{F}_4$$

$$= \left(-\frac{b}{2}\hat{i}\right) \times (IaB\hat{k}) + \left(\frac{b}{2}\hat{i}\right) \times (-IaB\hat{k})$$

substitute expressions we derived for $\underline{F}_2$ & $\underline{F}_4$

$$= \left(\frac{IabB}{2} + \frac{IabB}{2}\right)\hat{j} = IAB\hat{j}$$

where we defined $A = ab$ area of loop

$\therefore \underline{\tau} = IAB\hat{j}$ since it's positive, the rotation is clockwise ~~around the y axis~~ and we see it rotates around the y axis ($\hat{j}$)

We can re-write this in terms of the area vector:

$$\underline{A} = A\hat{n}$$

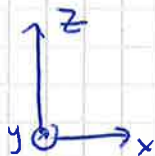
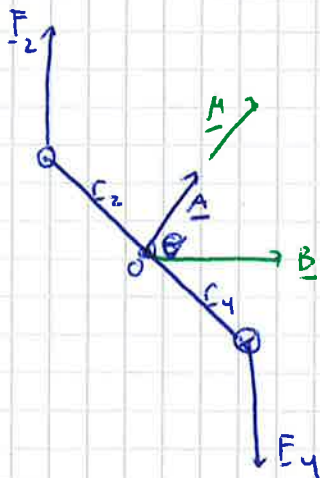
↑ direction normal to the loop ~~and~~ plane

In this case we have $\hat{n} = +\hat{k}$ so we can re-write the torque as:

$$\underline{\tau} = I \underline{A} \times \underline{B}$$

Notice this is maximum when $\underline{B}$ is $\parallel$ to the plane of the loop (or $\perp$ to $\underline{A}$)

Now let's consider ^{the} general case where the loop (or the area vector $\underline{A}$) makes an angle θ with respect to $\underline{B}$:



From this figure we can see:

$$\underline{r}_2 = \frac{b}{2}(-\sin\theta\hat{i} + \cos\theta\hat{k}) = -\underline{r}_4 \text{ and the net torque becomes:}$$

$$\begin{aligned} \underline{\tau} &= \underline{r}_2 \times \underline{F}_2 + \underline{r}_4 \times \underline{F}_4 = 2\underline{r}_2 \times \underline{F}_2 = 2\frac{b}{2}(-\sin\theta\hat{i} + \cos\theta\hat{k}) \times (IaB\hat{k}) \\ &= IabB\sin\theta\hat{j} = I \underline{A} \times \underline{B} \end{aligned}$$

And if we have a loop with N "turns":

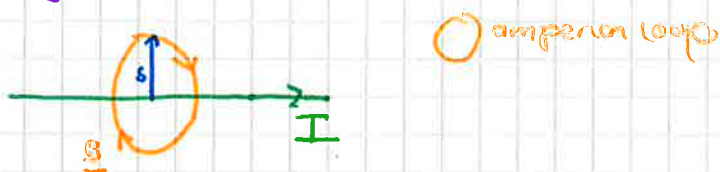
$$\underline{\tau} = NIAB\sin\theta$$

The quantity NIA is called the magnetic dipole moment $\underline{\mu}$:

$$\underline{\mu} = NIA$$

← note direction of $\underline{\mu}$ is the same as $\underline{A}$, determined by the right hand rule.

EXAMPLE: Calculate the magnetic field a distance s from a long straight wire carrying a steady current I .



We know that the direction of $\underline{B}$ is circumferential, circling around the wire as indicated by the right hand rule.

By symmetry the magnitude of $\underline{B}$ is constant around the loop so:

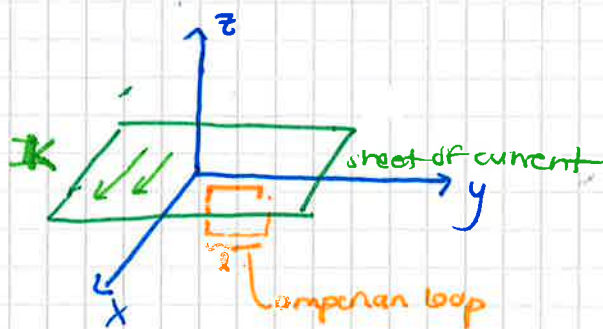
$$\oint \underline{B} \cdot d\underline{l} = B \oint dl = B(2\pi s) = \mu_0 I_{enc}$$

$$\Rightarrow B = \frac{\mu_0 I}{2\pi s}$$

this is key to take it out of the integral just like for Gauss's law.

EXAMPLE: Calculate the magnetic field of an infinite uniform surface current

$\underline{K} = K \hat{x}$ flowing over the x, y plane.



K is flowing in the x direction

First of all we want to determine the direction of $\underline{B}$? We know that it can't have an x component, since the source is $\parallel$ to x .

$$\underline{B}(\underline{r}) = \frac{\mu_0}{4\pi} \int \frac{\underline{K}(\underline{r}') \times \underline{\hat{r}}}{r^2} d\Omega$$

then the ^{component} x term in the ^{cross} $\times$ prod is zero

The field is $\perp$ to K , so in this case it is $\perp$ to x .

Can the field have a z component? No, because of symmetry.

Any vertical contribution ~~at~~ from a filament at $+y$ will be cancelled by a filament at $-y$.

Now let's draw a loop as shown in the figure ~~and~~ parallel to the x, z plane. Applying Ampère's law:

$$\oint \underline{B} \cdot d\underline{l} = B(2l) = \mu_0 I_{enc} = \mu_0 K l$$

$\uparrow$
by definition of K



$$\Rightarrow B = \frac{\mu_0 K}{2} \text{ and more precisely}$$

$$B = \begin{cases} \mu_0/2 K \hat{y} & z > 0 \\ -\mu_0/2 K \hat{y} & z < 0 \end{cases}$$