

Heterophase Interfaces and Thin Films

Lesson 12

MSE 304

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Key Topics in the Previous Class

Described solid-solid interface

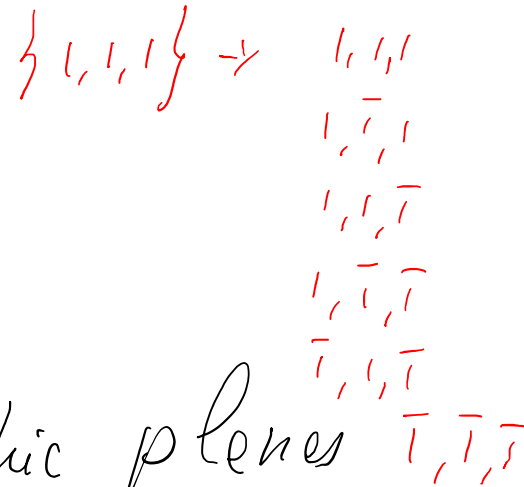
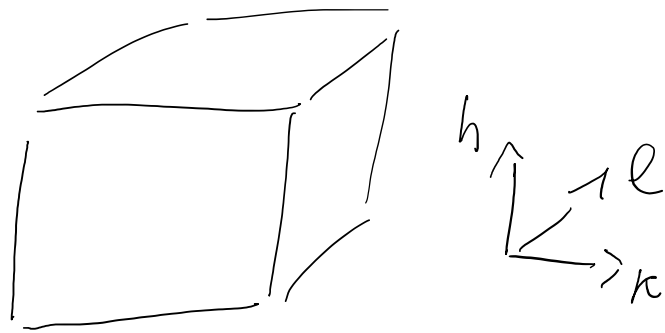
crystallography

energetics

→ solid-solid interface → $\gamma_{ss} \approx n_{bb} \cdot \epsilon_{bb} + \bar{\Gamma}_e$

Slip Planes in a Crystal Structure

how do dislocations move?



(u,v,w) ← crystallographic planes

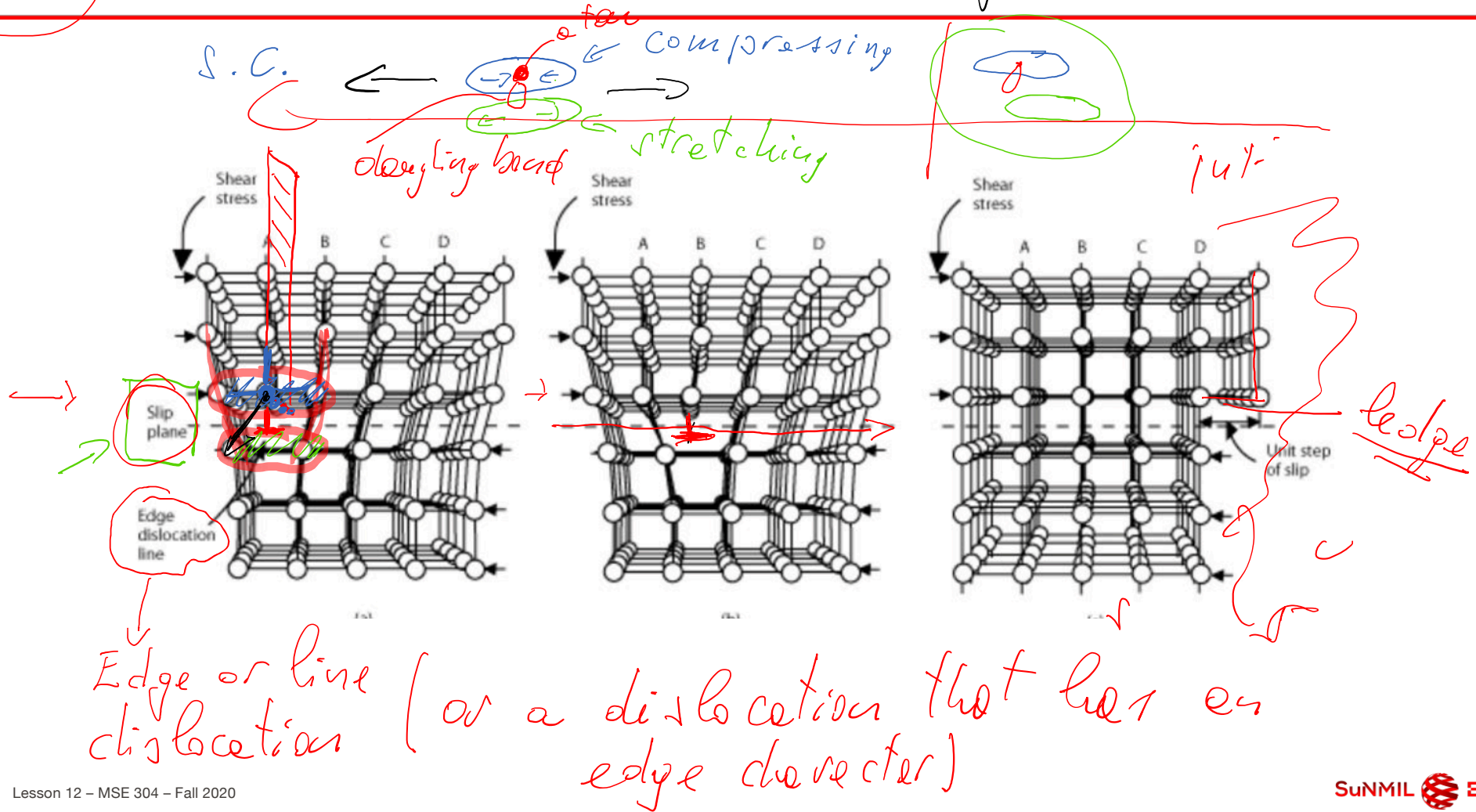
density of a plane depends on u, v, w

slip plane the highest density plane

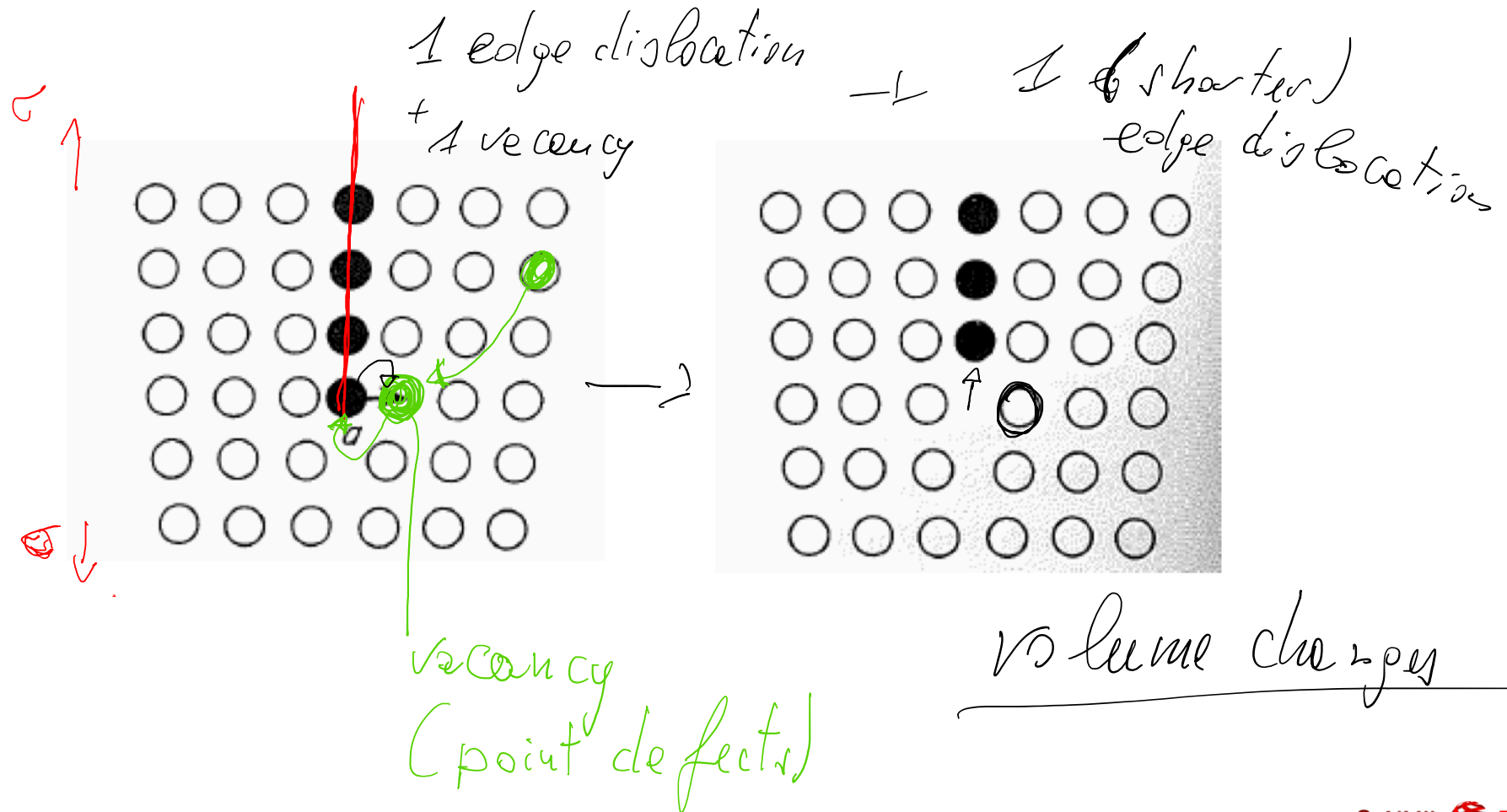
fcc $(1,1,1) \rightarrow \{1,1,1\}$

Glide Motion of Dislocations

no change in volume



Climb Motion for Dislocations



Glide and Climb Motion for Dislocations

$\vec{\ell}$ vector in the plane of the dislocation
 $\vec{t}$ $\rightarrow$ dislocation movement

Glide vs. Climb

Glide/slip: conservative movement within the slip plane

Climb: non-conservative movement away from the slip plane

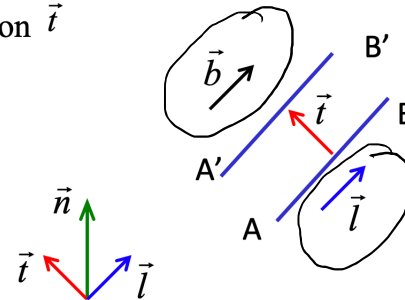
let's consider a dislocation AB that moves to A'B' in the direction $\vec{t}$

$$\vec{n} = \vec{\ell} \times \vec{t} \quad \text{- surface normal}$$

$$\vec{b} \cdot \vec{n} = 0 \quad \text{- conservative motion, glide}$$

$$\left[\begin{array}{l} \vec{b} \cdot \vec{n} > 0 \quad \text{- addition of material} \\ \vec{b} \cdot \vec{n} < 0 \quad \text{- removal of material} \end{array} \right] \quad \text{climb}$$

$$\vec{n} = \vec{\ell} \times \vec{t}$$



Glide and Climb Motion of Dislocations

Glide vs. Climb

Glide/slip: conservative movement within the slip plane

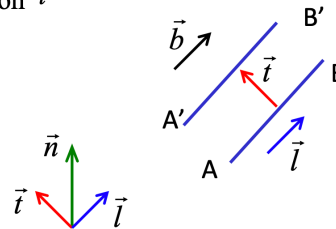
Climb: non-conservative movement away from the slip plane

let's consider a dislocation AB that moves to A'B' in the direction $\vec{t}$

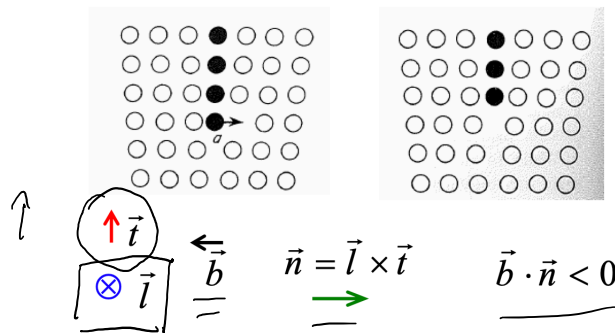
$$\vec{n} = \vec{l} \times \vec{t} \quad \text{- surface normal}$$

$$\vec{b} \cdot \vec{n} = 0 \quad \text{- conservative motion, glide}$$

$$\left. \begin{array}{l} \vec{b} \cdot \vec{n} > 0 \quad \text{- addition of material} \\ \vec{b} \cdot \vec{n} < 0 \quad \text{- removal of material} \end{array} \right\} \text{climb}$$



example:



- positive climb

crystal shrinks in direction parallel to slip plane
results from compressive strain

in general, volume change due to climb is

$$\Delta V = \vec{b} \cdot \vec{l} \times \vec{t} = \vec{b} \times \vec{l} \cdot \vec{t}$$

Glissile and Sessile Interfaces

SESSILE INTERFACE
can move only by a climb of
its interfacial (misfit)
dislocation

Glide

slip
plane =

solid solid
interface

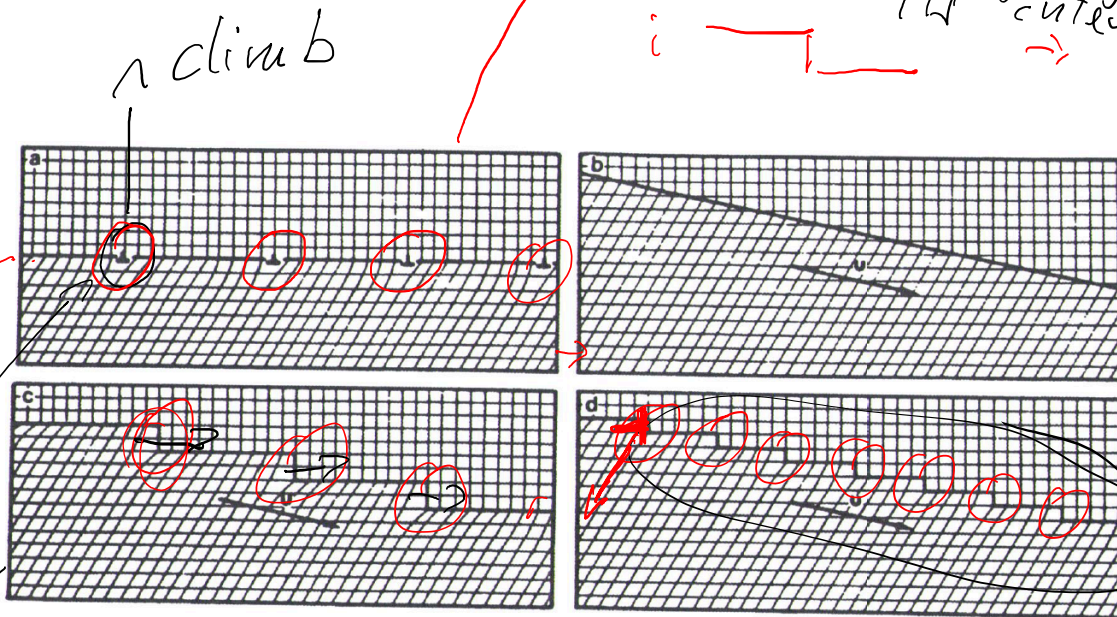


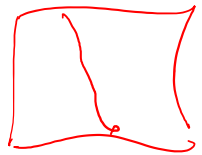
Figure 14.39. Possible interfaces for a transformation described by a shear e_{12} coupled with an expansion e_{11} in the shear plane. (a) The expansion is accommodated by a set of perfect lattice (misfit) dislocations. (b) The interface lies along an invariant line u and no dislocations are necessary. (c) The invariant line is resolved onto every other close-packed plane as in the f.c.c.-h.c.p. transformation where each ledge is an $\alpha/6\langle 112 \rangle$ partial dislocation. (d) The invariant line is resolved onto every close-packed plane as in an f.c.c.-b.c.c. transformation where each ledge contains an $\alpha/12\langle 112 \rangle$ partial dislocation. Reprinted with permission from [153] by Elsevier Science Ltd., Oxford, England.

GLISSILE

can move
by a glide
motion of its
interfacial dislocation
into the bulk

glide $\rightarrow$ move solid-solid interface

Glissile and Sessile Interfaces

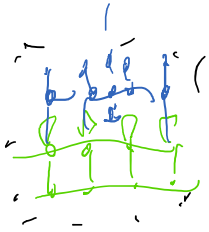


movement of interface a key
mechanical property determinant
for a material
hardening

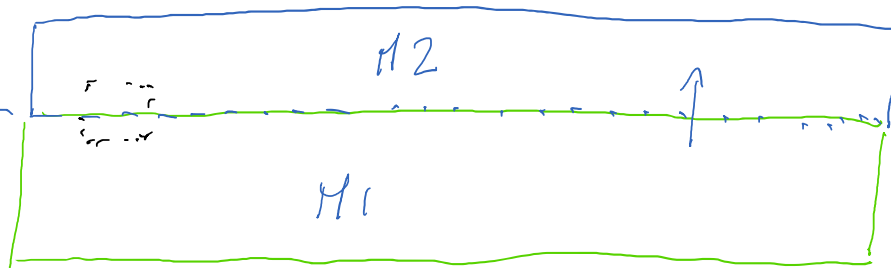
required
the motion of
point defects

Glide motion is always faster than a climb
Glissile interface moves faster than a sessile
interface

Thin Films in Modern Technology



interfacial
electronic
behaviour



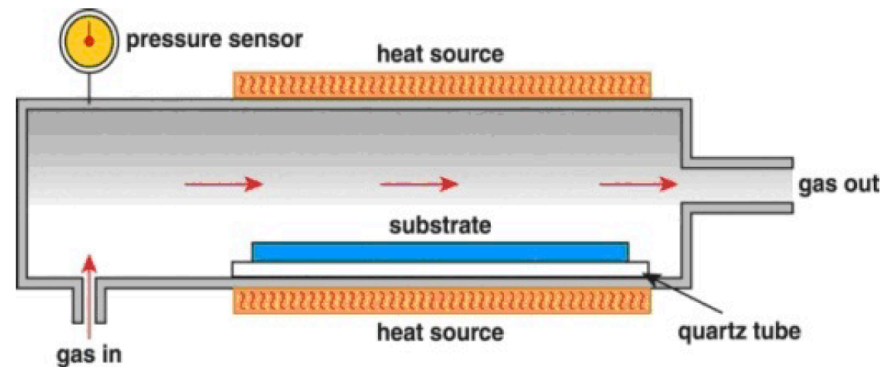
band structure of M_2
band structure of M_1

band structure $\rightarrow$ bonding in a perfect crystal
electronic behaviour of
the material

Thin Films in Modern Technology

- Growth of thin films of materials allows extreme control of the structure of matter at the nano-scale
- On the lab. scale: molecular beam epitaxy (MBE)
 - Extremely “clean” conditions, exquisite control of all parameters
 - Batch operation, extremely slow, ultra-high vacuum
- On the industrial level: chemical vapor deposition (CVD)
 - “Dirtier” operation, but much simpler to operate

in
vacuum

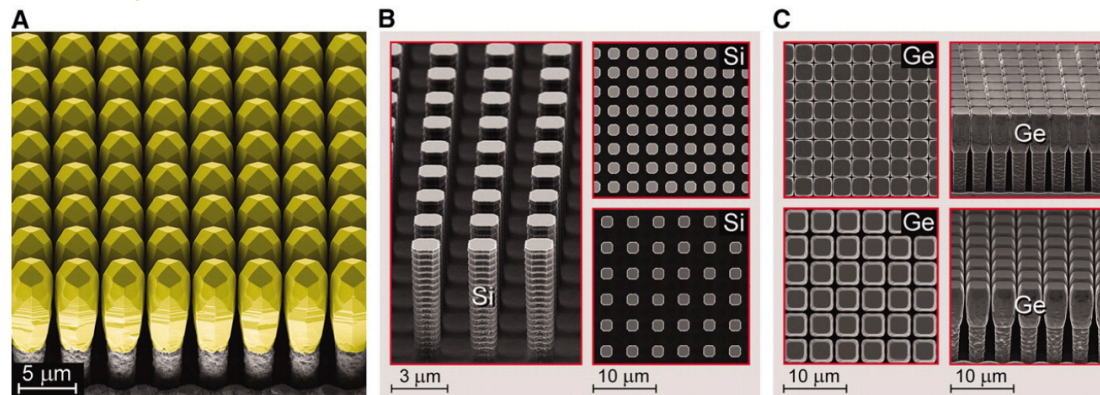


substrate

start a substrate with a known
surface (known crystallography)

Thin Films – Morphology Control

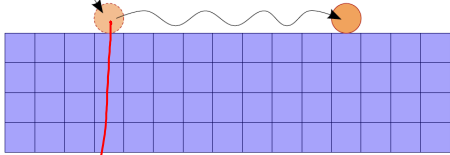
↓ columns, pillars, nanowires



Strain-free Ge nanopillars grown by PECVD. [Falub et al., Science, 2012]

Growth Models for Thin Films

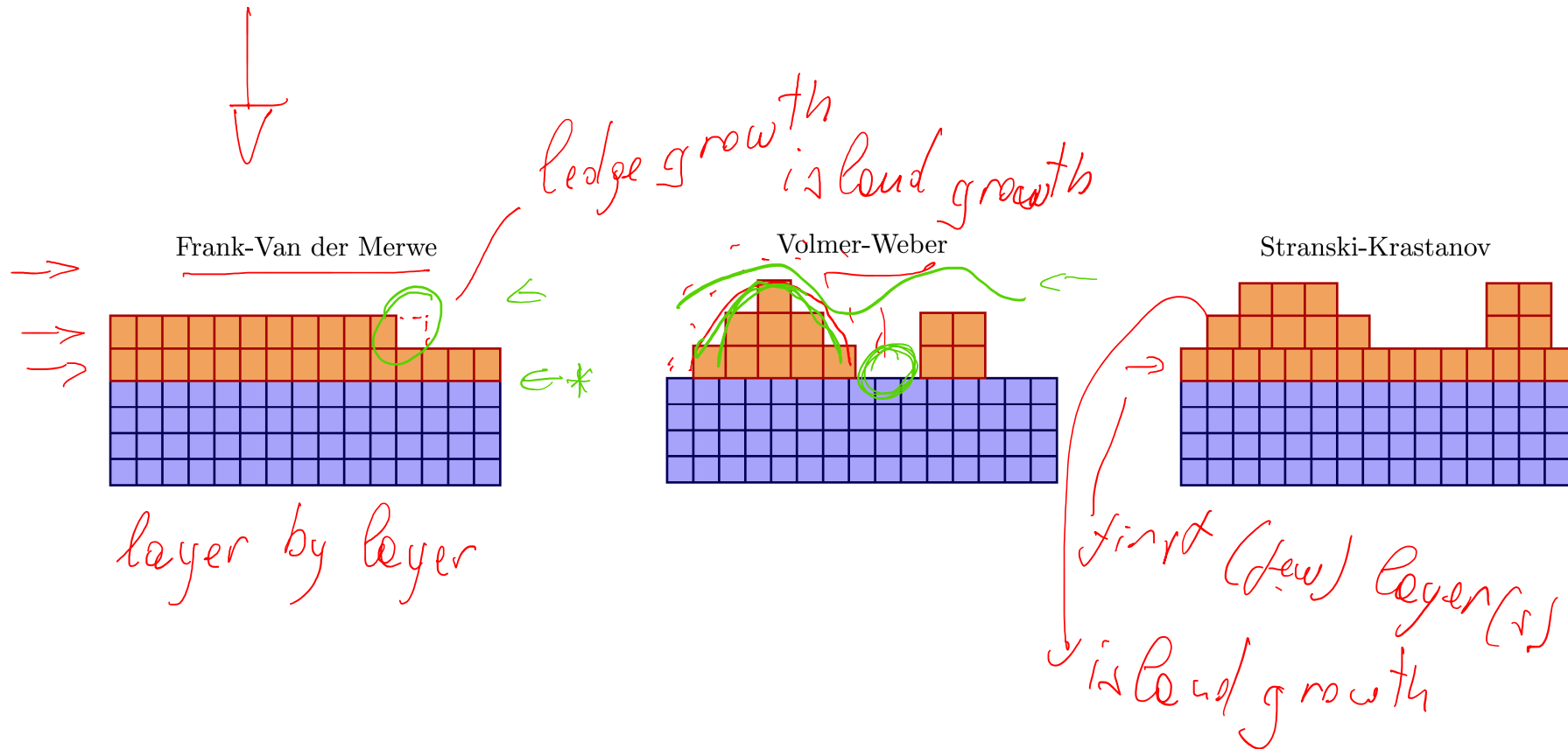
atom MBE
→ molecule that decompose CVD
impinge



→ an adatom can freely move up to its equilibrium position
→ any adatom is kinetically trapped

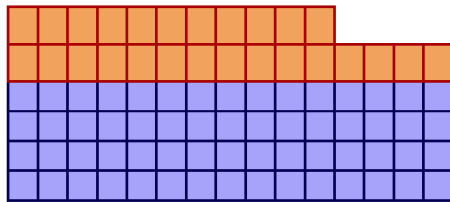
(1)

Growth Models for Thin Films



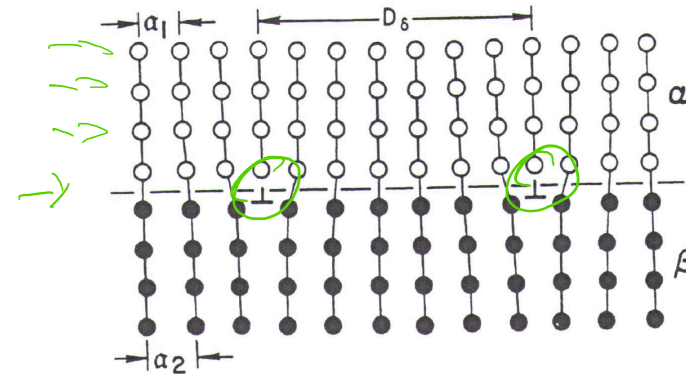
Growth Models for Thin Films

Frank-Van der Merwe



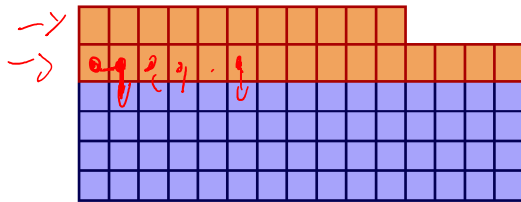
δ is small

↓
no difference in
crystallographic dimension
and symmetry $\rightarrow \delta = 0$



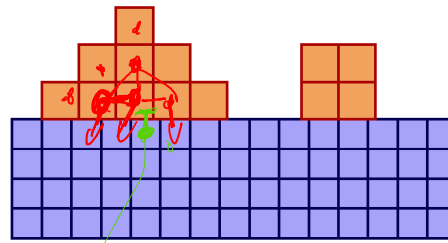
Growth Models for Thin Films: First Explanation

Frank-Van der Merwe



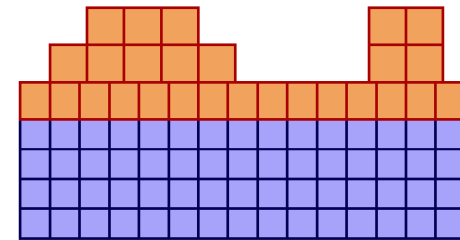
↓
atoms prefer
to bond to substrate
atoms more than
to themselves

Volmer-Weber



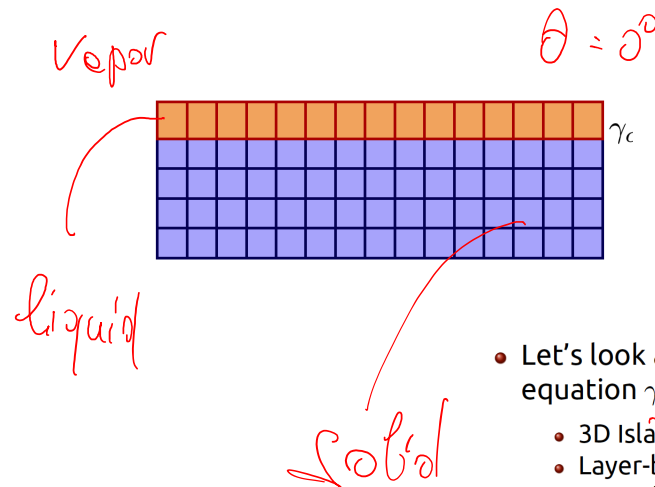
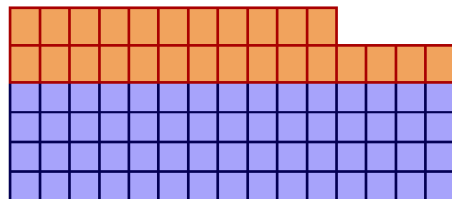
atoms prefer
to bond to themselves
more than to substrate
atoms

Stranski-Krastanov

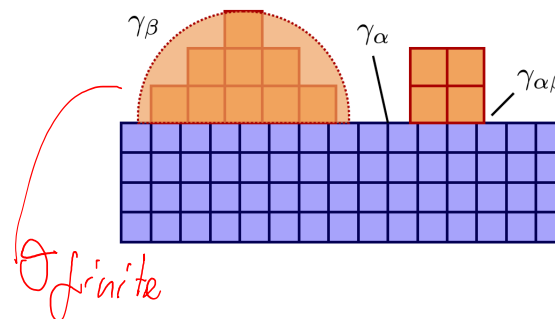
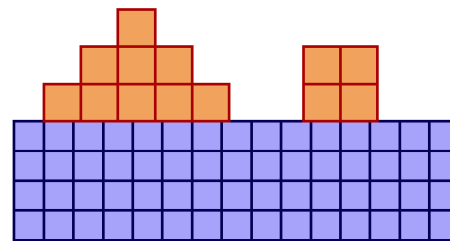


Growth Models for Thin Films: Second Explanation

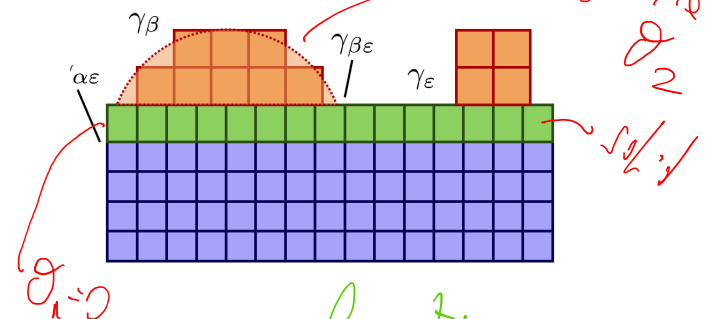
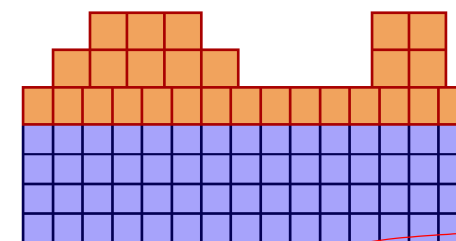
Frank-Van der Merwe



Volmer-Weber



Stranski-Krastanov

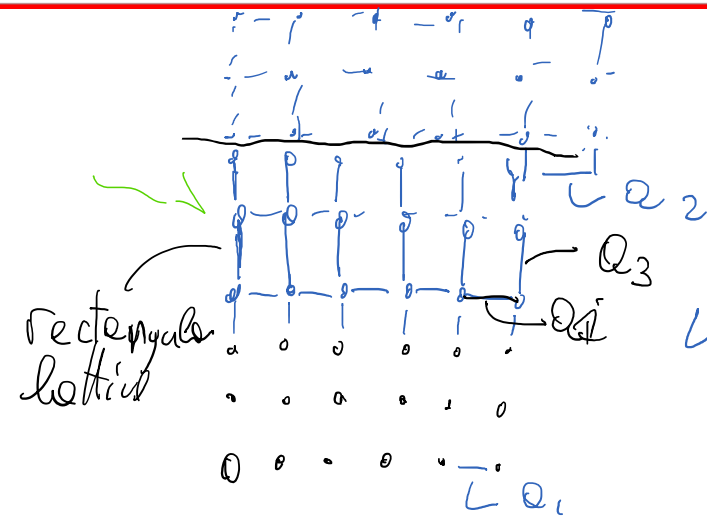


- Let's look at these from a macroscopic point of view: Recall Young's equation $\gamma_\beta \cos \theta = \gamma_\alpha - \gamma_{\alpha\beta}$

- 3D Island (VW) growth corresponds to finite contact angle: $\gamma_{\alpha\beta} + \gamma_\beta > \gamma_\alpha$
- Layer-by-layer (FM) growth corresponds to $\theta = 0$: $\gamma_{\alpha\beta} + \gamma_\beta \leq \gamma_\alpha$
- Stranski-Krastanov growth is harder to explain based on macroscopic surface energies. If we consider the strained film as a different material ϵ , it must be that $\gamma_{\alpha\epsilon} + \gamma_\epsilon \leq \gamma_\alpha$, and $\gamma_{\beta\epsilon} + \gamma_\beta > \gamma_\epsilon$

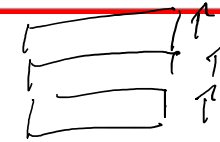
elastic effects disordered!

Strained and Unstrained Growth



$$\frac{a_3}{a_1} = 1$$

Poisson ratio



$$E_{el} = e^2 C_5 L_f$$

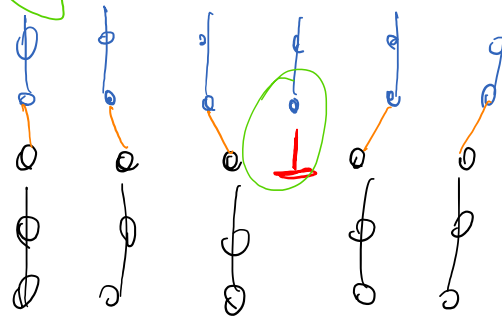
$$C_5 = 2\mu_f \left[\frac{1 + \nu_f}{1 - \nu_f} \right]$$

thickened of film

energy per atom

ν_f

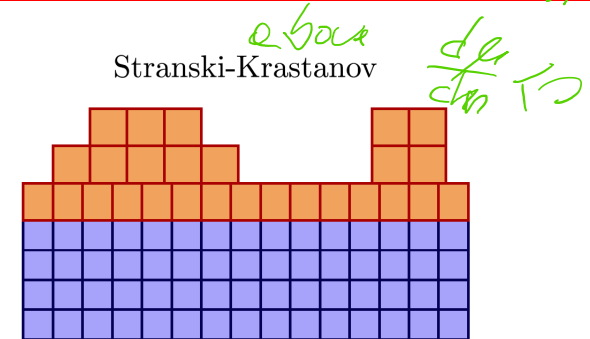
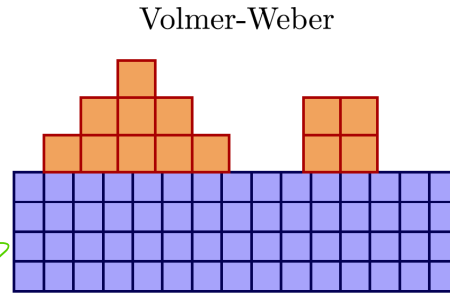
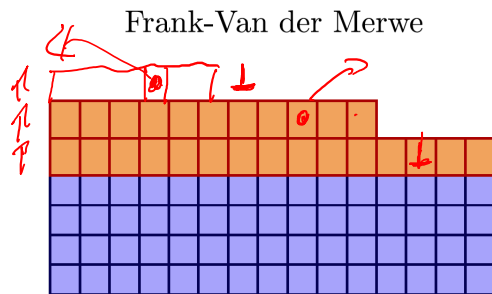
unstrained growth



$$\epsilon < 5\%$$

Growth Models for Thin Films: Third Explanation

it* below $\frac{d\mu}{dn} > 0$



desorption energy of atoms (1st layer) $\epsilon_d(n)$

Moreover $\epsilon_e(n)$

$$\mu(n) = \mu_\infty + [\varphi_a - \varphi'_a(n) + \epsilon_d(n) + \epsilon_e(n)]$$

φ_a $\rightarrow$ desorption energy of the atoms on following layers

$\varphi'_a(n)$ $\rightarrow$ of the film without interface

$\frac{d\mu}{dn} > 0$

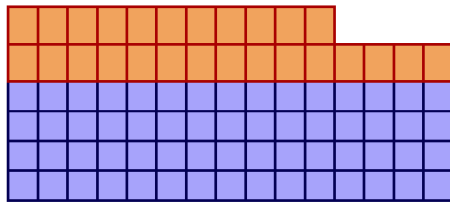
$\frac{d\mu}{dn} < 0$

depend on n the film # of layers

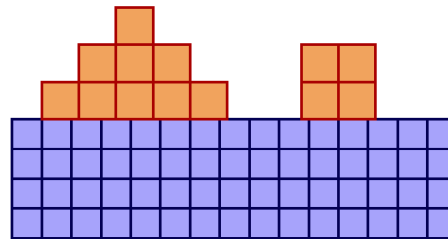
per atom $\left\{ \begin{array}{l} * \epsilon_d(n) \text{ energy of the dislocations} \\ \Delta \epsilon_e(n) \text{ elastic energy} \end{array} \right.$

Growth Models for Thin Films: Third Explanation

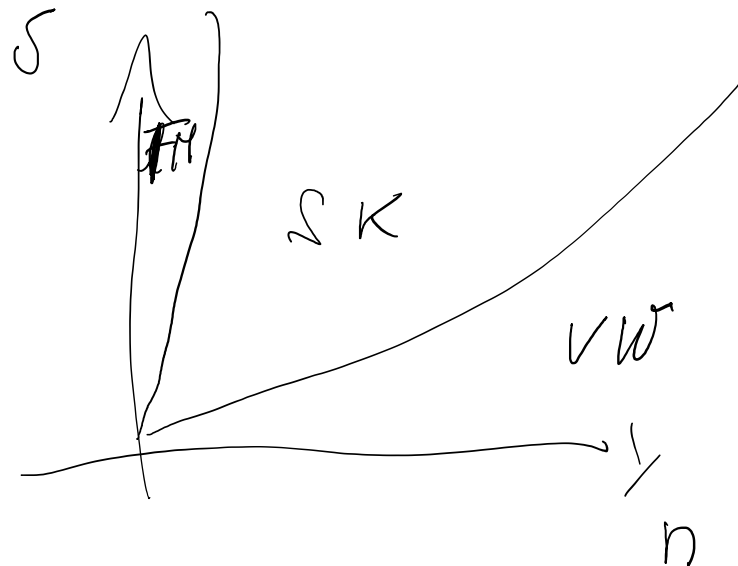
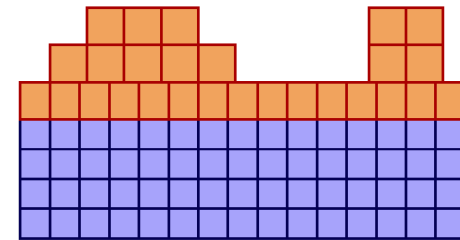
Frank-Van der Merwe



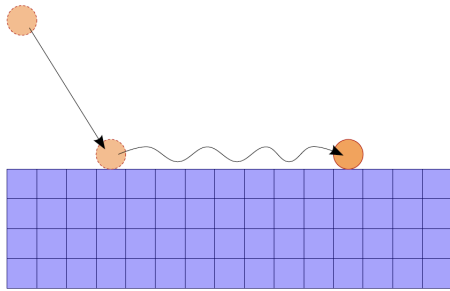
Volmer-Weber



Stranski-Krastanov



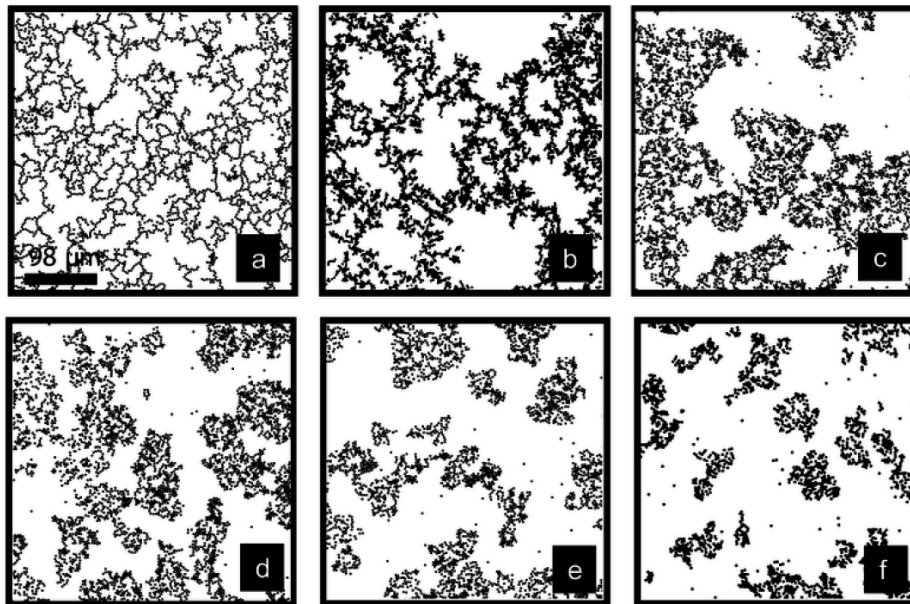
Growth Models for Thin Films



2 atoms
are stuck

Diffusion Limited Aggregation

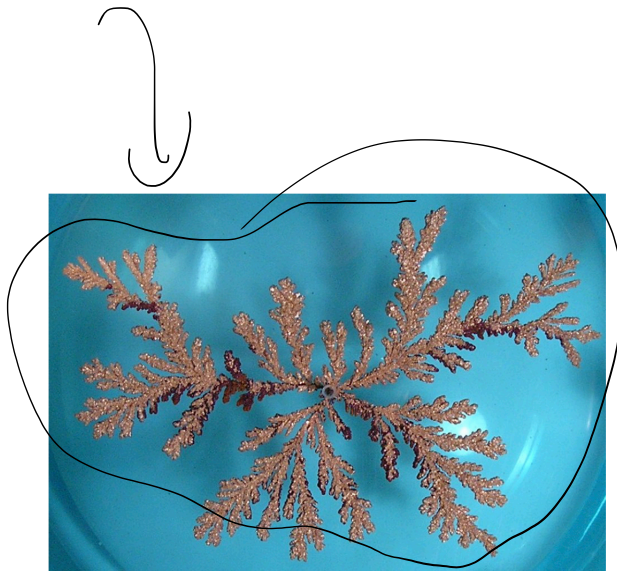
DLA



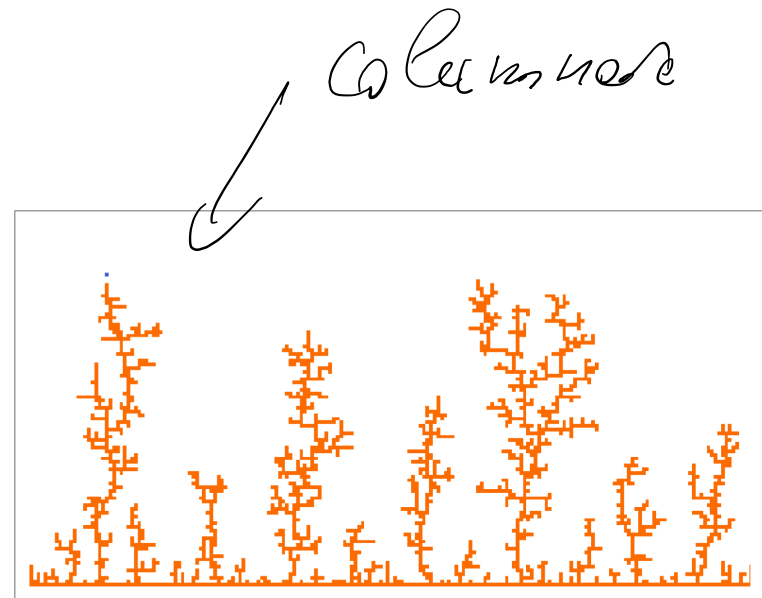
Flow-induced aggregation of colloids. [Massachaele et al., Soft Matter, 2011]

Diffusion Limited Aggregation

- Growth regimes discussed this far assume local equilibration between atom attachments
- The opposite case is a “stick where you hit” grow mode - strongly out of equilibrium structure
- Diffusion-limited aggregation



*snow flakes
dendrimer*



Conclusions

interface movement depends
on the nature of the interfacial
mechanical dislocations
properties

→ can control thin film

growth
electronic properties