

Mechanics of Earthquake

Advanced contact mechanics

Ankit Gupta

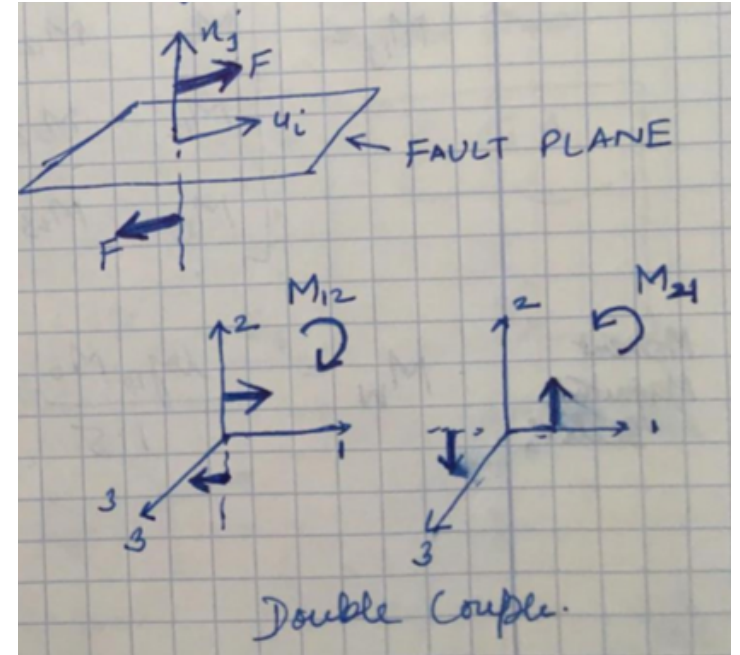
Seismic Moment Tensor

$$M_{ij} = \mu \frac{\Delta u_i n_j + \Delta u_j n_i}{2} A \quad \text{Wrong in book!}$$

Units of M is Nm

μ : shear modulus

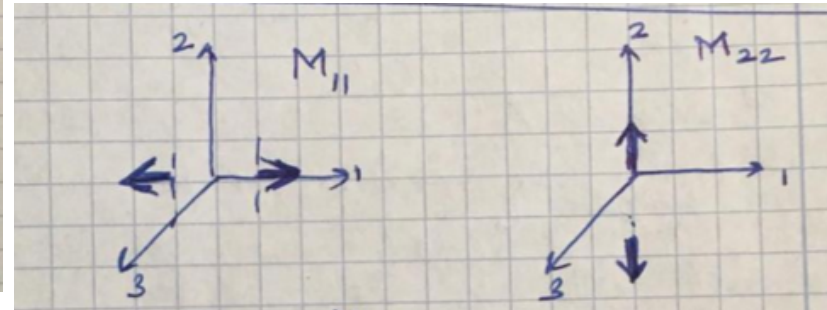
A : rupture area



$$M_{ij} = \begin{bmatrix} M_{11} & M_{12} & M_{13} \\ M_{12} & M_{22} & M_{23} \\ M_{13} & M_{23} & M_{33} \end{bmatrix} \quad \text{SYMMETRIC TENSOR}$$

Moment Magnitude Scale:

$$M_W = \frac{\log_{10} M_0}{1.5} - 6.07 \quad (M_0 \text{ in } N_m)$$



Moment Magnitude Scale is used now, not Richter Scale to measure earthquakes!

STRESS DROP

$$\Delta \sigma_s = C \mu \frac{\Delta \tilde{u}}{\tilde{L}}$$

$\nearrow$ $\nearrow$ $\nwarrow$
 gemmatin constant shear Modulus strain

$$\tilde{L} \sim A^{1/2}$$

$$\Delta \sigma_s = C M_0 A^{-3/2} = C M_0 \tilde{L}^{-3}$$

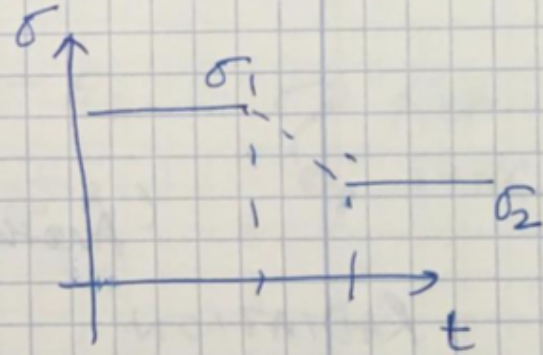
$\checkmark \checkmark \checkmark$
 $\uparrow \uparrow \uparrow$

we can Measure $\Delta \sigma_s = \sigma_1 - \sigma_2$

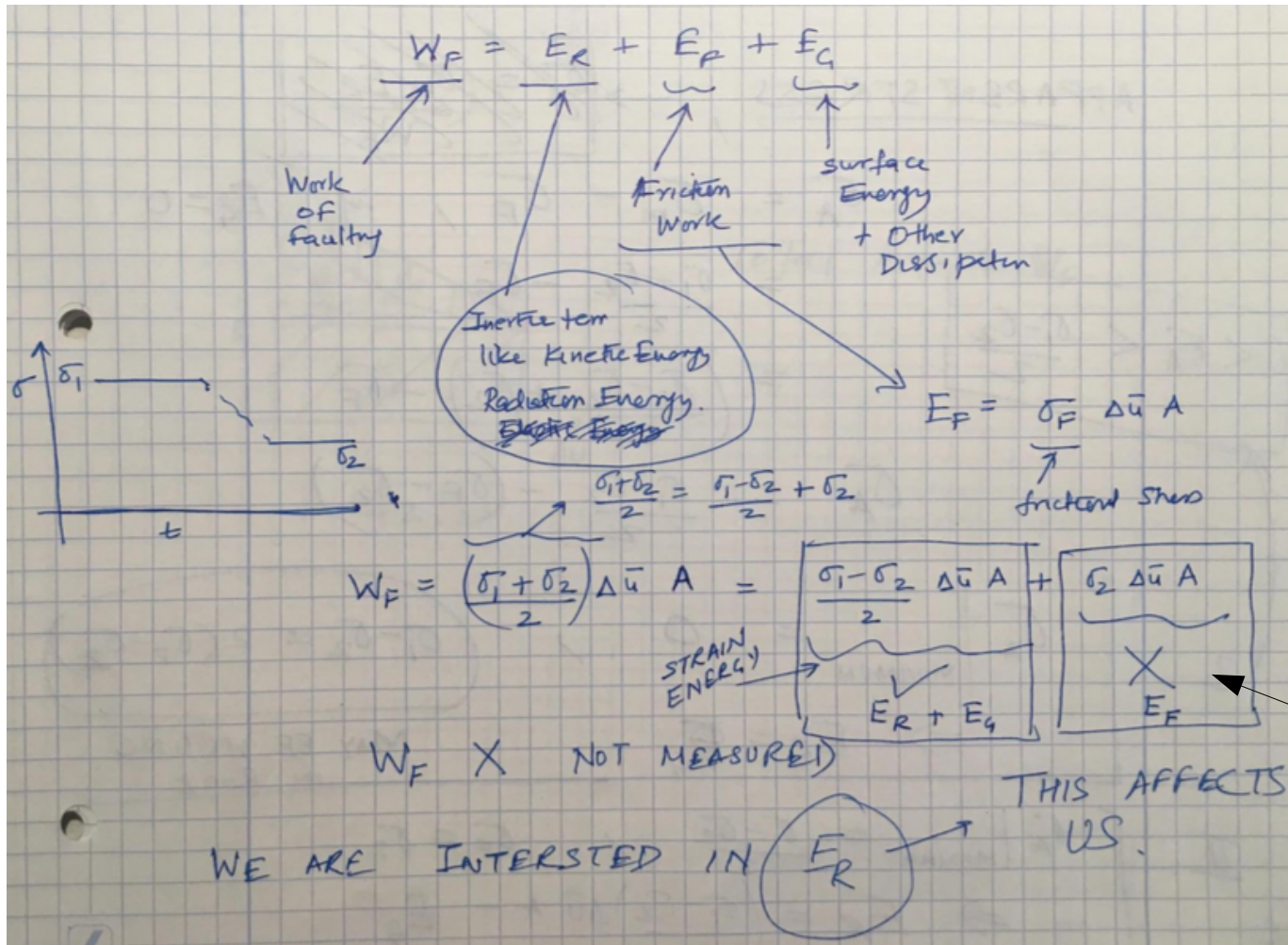
$$M_0 = \mu \Delta u A$$

Can be measured.

Can be measured from SEISMIC DATA.



Dynamic Energy Balance



Dynamic energy release rate, G is defined using E_G

Some definitions ...

Seismic Efficiency,

$$\eta = \frac{E_R}{W_F}$$

$$W_F = \frac{\sigma_1 - \sigma_2}{2} \Delta u A + \sigma_2 \Delta u A$$

Not measurable

Radiation Efficiency,

$$\eta_R = \frac{E_R}{E_R + E_G}$$



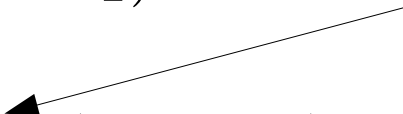
Wrong in book!

Apparent Stress

$$\sigma_A = \frac{\sigma_1 + \sigma_2}{2} - \sigma_F$$

$$\sigma_A = \frac{\sigma_1 - \sigma_2}{2} - (\sigma_F - \sigma_2)$$

Wrong in
book!



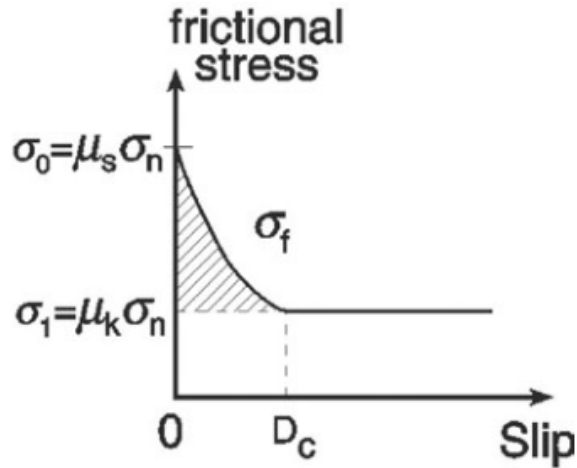
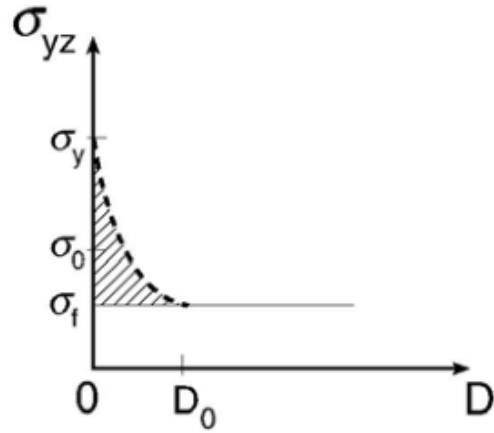
$$\sigma_A = 0, \text{ if } \sigma_1 - \sigma_2 = 2(\sigma_F - \sigma_2) \Rightarrow E_R = -E_G$$

$$\sigma_A = \frac{\sigma_1 - \sigma_2}{2}, \text{ if } \sigma_F = \sigma_2 \Rightarrow E_R = \frac{\sigma_1 - \sigma_2}{2} \Delta u A - E_G$$

$$\eta_R = \frac{E_R}{E_R + E_G} < \frac{\frac{\sigma_1 - \sigma_2}{2} \Delta u A - E_G}{\frac{\sigma_1 - \sigma_2}{2} \Delta u A}$$

Not sure about inequality!

Crack model vs Friction model for earthquakes



$$D_0 \approx D_c$$

BRITTLE FRACTURE

- $G = G_c$ (CRACK PROPAGATION CRITERIA)
- STRESS AT CRACK TIP $\rightarrow$ SINGULARITY

STICK-SLIP FRICTION INSTABILITY

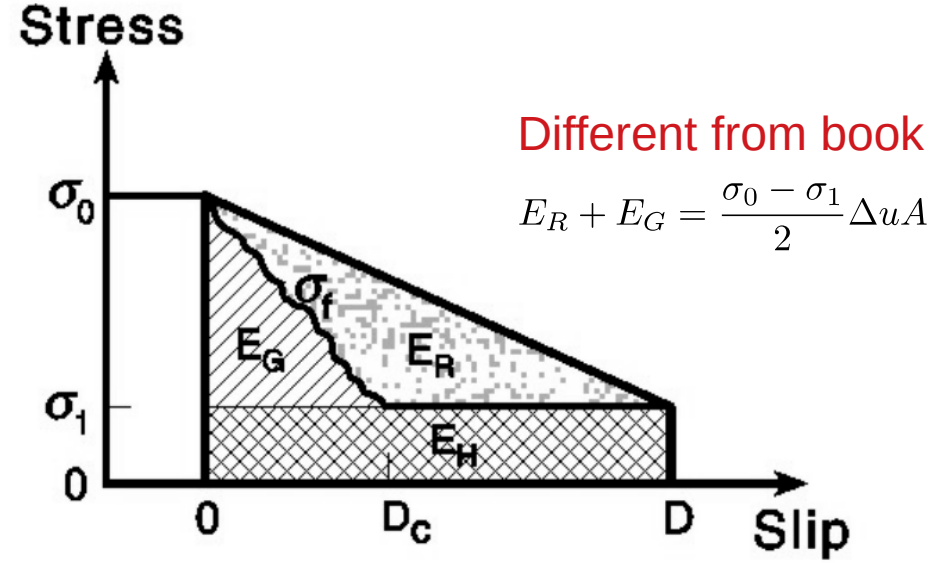
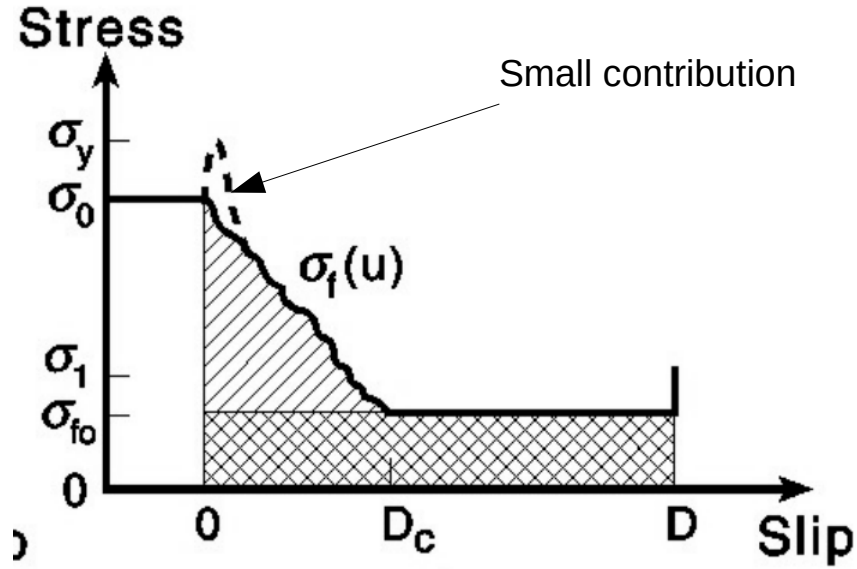
- $\left| \frac{\partial F}{\partial u} \right| > K$

A graph showing the relationship between force F and displacement u for stick-slip friction instability. The vertical axis is labeled F and the horizontal axis is labeled u . The curve shows a peak followed by a sharp drop, indicating instability. A tangent line is drawn at the peak, and the slope is labeled K slope. The area under the curve is shaded with diagonal lines.

$F = \mu N$
FRICTION COEFF.

- STRESS FINITE
- NO ENERGY DISSIPATION

Slip Weakening



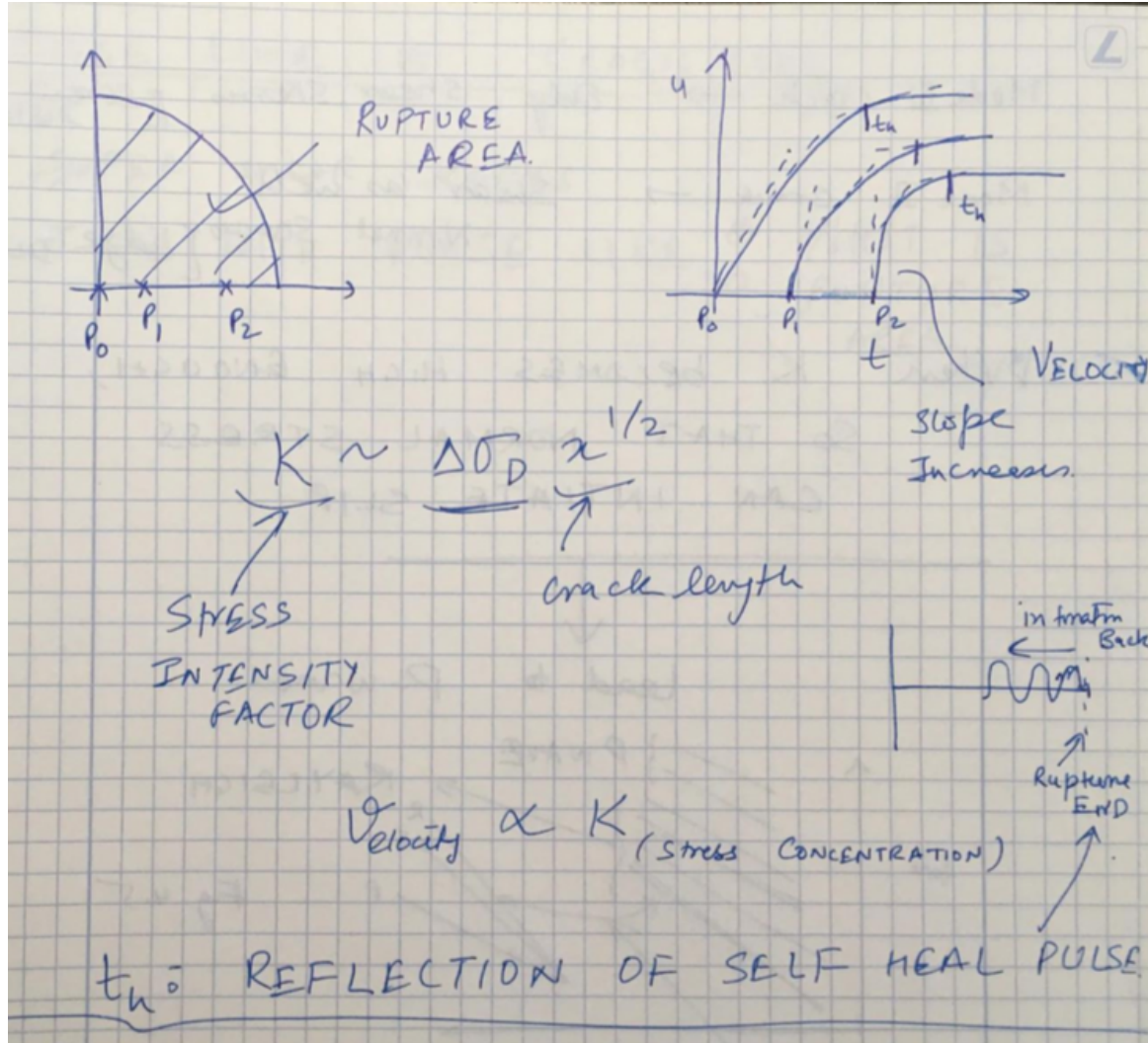
$$W_F = E_R + E_G + E_H$$

$$\eta_R = \frac{E_R}{E_R + E_G}$$

$$\eta_R \approx 1, \quad E_G \approx 0$$

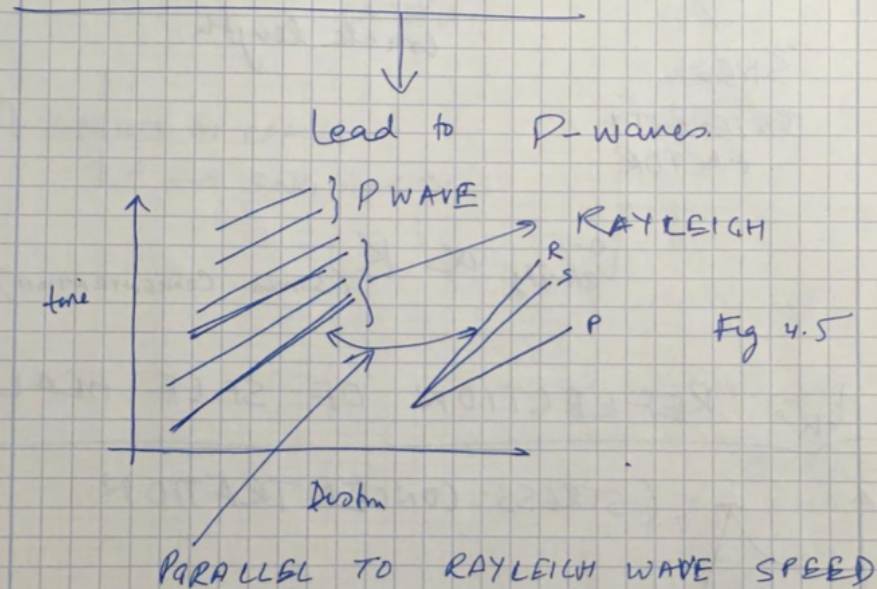
$$\eta_R \ll 1, \quad D_c \text{ comparable to } D$$

Rupture Propagation



Mode II Rupture Propagation

When K becomes high enough,
so that normal stress
can initiate slip



Initially R-wave
AFTER SOME TIME P-WAVE