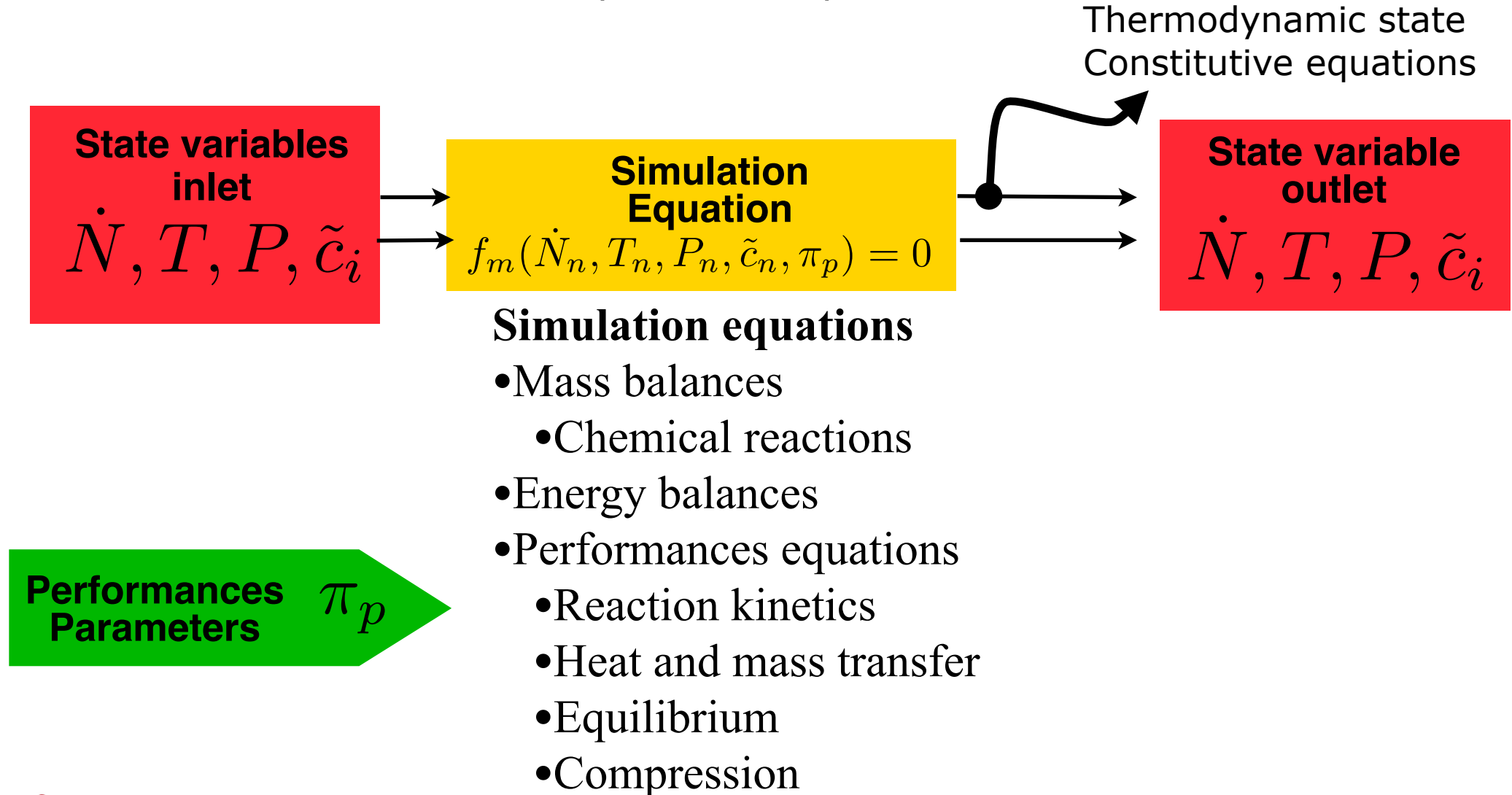
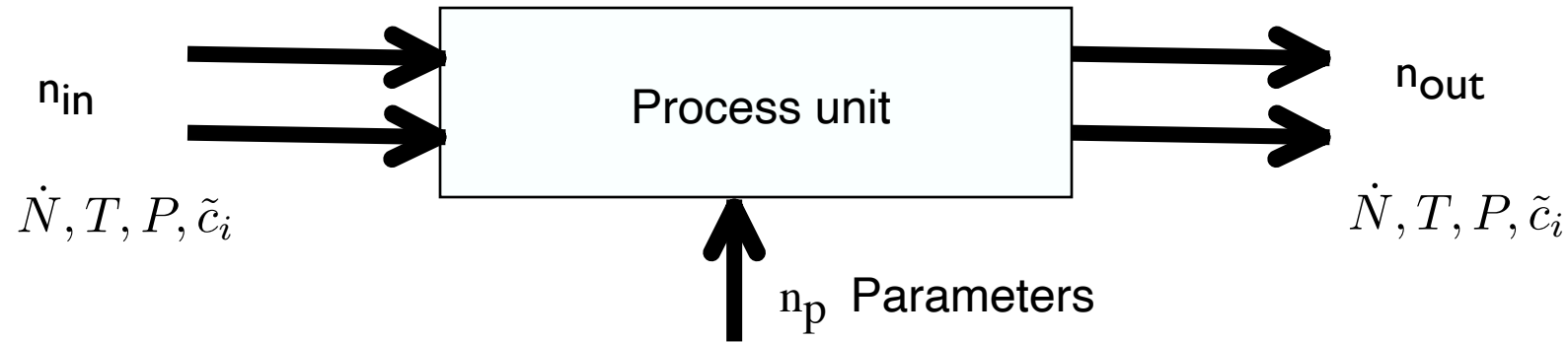


Solving Process units models

François Marechal
Shivom Sharma

Unit models represents by a set of equations the thermodynamic phenomena involved in the conversion of the flows in the process unit operation





Equations : n_e

mass balances/network

Energy

Impulsion

models

specification

n_c

1

n_i

n_m

n_s

Variables : n_v

State of the streams

Unit parameters

Internal variables

$n_x = (n_{out} + n_{in}) * (n_c + 2)$

n_p

n_t

$$DOF = n_v - n_e$$

DOF = number of set points to make the unit calculable

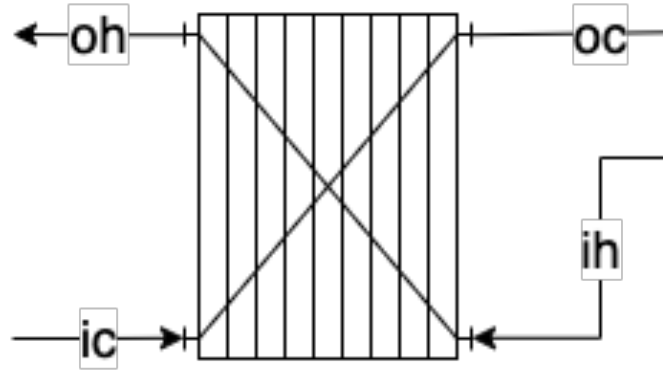
$$\text{Equations } (n_e + n_s) = \text{Variables } (n_v)$$

np parameters

<pre> XXXXXXXX XXXXXX XXXXX XXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXXX XXXXXXXX XXXXXX XXXXXXXXXXX XXX XX XX </pre>	<pre> xx x </pre>	n_e model equations
<pre> x x x x x x </pre>	<pre> x x x </pre>	DOF $n_s = n_v - n_e$ specification equations $\mathbf{x} - \mathbf{x}^s = \mathbf{0}$

2) independent equations

■ IPESE
Industrial Process
and Energy Systems
Engineering



Nb.	Equation	1. $\dot{m}_{ci}$	2. T_{ci}	3. P_{ci}	4. $\dot{m}_{co}$	5. T_{co}	6. P_{co}	7. $\dot{m}_{hi}$	8. T_{hi}	9. P_{hi}	10. $\dot{m}_{ho}$	11. T_{ho}	12. P_{ho}	13. A	14. $\dot{Q}$	15. U
1(EB)	$\dot{Q} = \dot{m}_{ci} c p_c (T_{co} - T_{ci})$	x	x			x									x	
2(EB)	$\dot{Q} = \dot{m}_{hi} c p_h (T_{hi} - T_{ho})$							x	x			x			x	
3(MB)	$\dot{m}_{hi} = \dot{m}_{ho}$							x			x					
4(MB)	$\dot{m}_{ci} = \dot{m}_{co}$	x				x										
5(P)	$P_{hi} = P_{ho}$								x			x				
6(P)	$P_{ci} = P_{co}$			x			x									
7(M)	$\dot{Q} = U A \frac{(T_{hi} - T_{co}) - (T_{ho} - T_{ci})}{\ln\left(\frac{T_{hi} - T_{co}}{T_{ho} - T_{ci}}\right)}$		x			x			x			x		x	x	x

$$N_x = N_v + N_i + N_p$$

Ns Specifications $X-X_s=0$	Eq1	x			
	Eq2	x			
	Eq3	x			
	Eq4	x			
	Eq5	x			
	Eq6	x			
Nb Balances $B(X_{in})-B(X_{out})=0$	Eq8	x		x	
	Eq9	xx		x	
	Eq7	x		x	
	Eq10	xx		x	
Nm Models $M(X,P)=0$	Eq11	x		xx	
	Eq13	x		xx	
Nc Constitutive equations $C(X)=0$	Eq14	x	x		xx
	Eq12	x		x	x

DOF analysis

Ne=Nx

- Form of the equations
 - **Implicit form**
 - $f(x,y)=0$
 - **Explicit* form**
 - $y=f(x)$
- Types of equations
 - Balance equations
 - Constitutive equations (thermodynamic state) : non linear
 - Model equation
 - Specification equations (constants)
 - $x=x^s$
 - $x-x^s=0$

*Explicit could be also in the form of $y=f(x,y)$, in this case there is the need to solve a non linear equation (iterations) to calculate the value of y .

		XXXXXXXXXXXXXXXXXX
		00000000011111
		12345678901234
Ns X-Xs=0	Eq1	x
	Eq2	x
	Eq3	x
	Eq4	x
	Eq5	x
	Eq6	x
Nb B(Xin)-B(Xout)=0	Eq8	x x
	Eq9	xx x
	Eq7	x x
	Eq10	xx x
Nm M(X,P)=0	Eq11	x xx
	Eq13	x xx
Nc C(X)=0	Eq14	x x xx
	Eq12	x x x

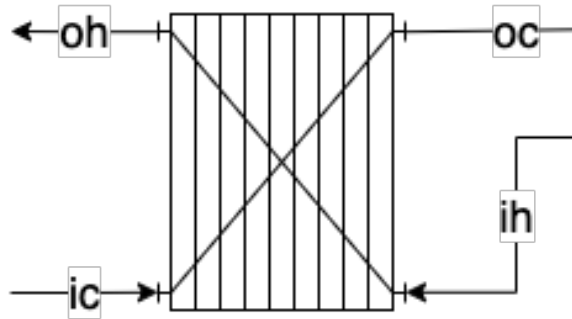
Find X such that

$$F(X)=0$$

For a given X, F(X) is evaluated

NxN

set of N non linear equations



Find X such that

$$F(X)=0$$

15x15

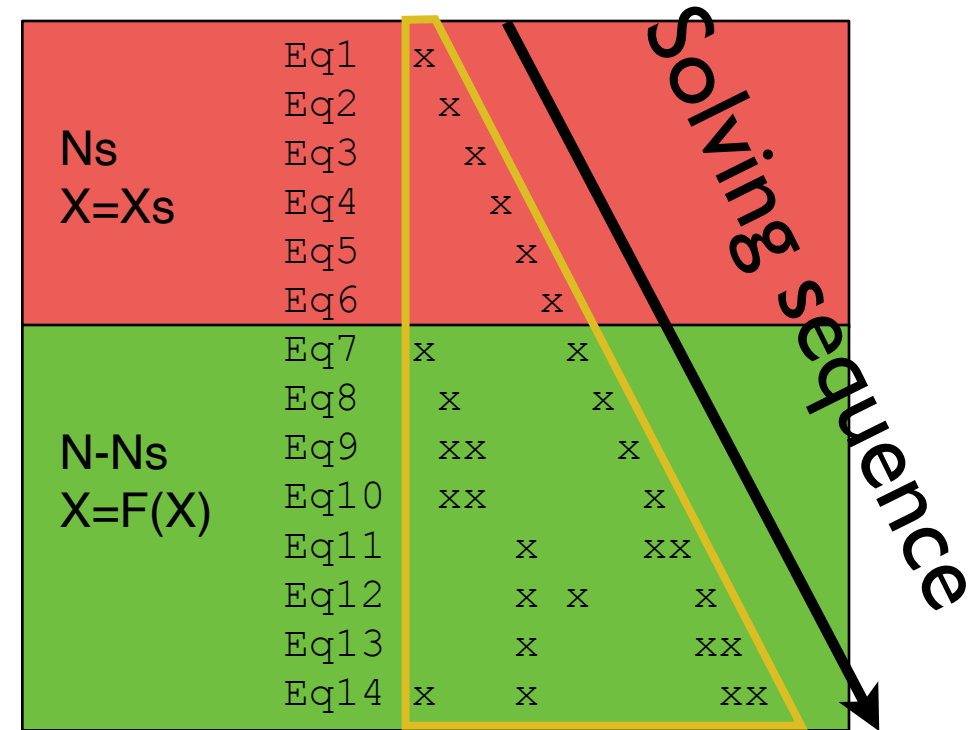
set of 15 non linear equations

Nb.	Equation	1. $\dot{m}_{ci}$	2. T_{ci}	3. P_{ci}	4. $\dot{m}_{co}$	5. T_{co}	6. P_{co}	7. $\dot{m}_{hi}$	8. T_{hi}	9. P_{hi}	10. $\dot{m}_{ho}$	11. T_{ho}	12. P_{ho}	13. A	14. $\dot{Q}$	15. U
1(EB)	$\dot{Q} = \dot{m}_{ci} c p_c (T_{co} - T_{ci})$	x	x			x									x	
2(EB)	$\dot{Q} = \dot{m}_{hi} c p_h (T_{hi} - T_{ho})$							x	x			x			x	
3(MB)	$\dot{m}_{hi} = \dot{m}_{ho}$							x			x					
4(MB)	$\dot{m}_{ci} = \dot{m}_{co}$	x				x										
5(P)	$P_{hi} = P_{ho}$								x			x				
6(P)	$P_{ci} = P_{co}$			x			x									
7(M)	$\dot{Q} = U A \frac{(T_{hi} - T_{co}) - (T_{ho} - T_{ci})}{\ln\left(\frac{T_{hi} - T_{co}}{T_{ho} - T_{ci}}\right)}$		x			x			x			x		x	x	x
8(S)	$\dot{m}_{ci} = \dot{m}_{ci}^s$	x														
9(S)	$T_{ci} = T_{ci}^s$		x													
10(S)	$P_{ci} = P_{ci}^s$			x												
11(S)	$T_{hi} = T_{hi}^s$								x							
12(S)	$P_{hi} = P_{hi}^s$									x						
13(S)	$\dot{m}_{hi} = \dot{m}_{hi}^s$							x								
14(S)	$A = A^s$													x		
15(S)	$U = U^s$															x

1. Process mathematical equations to have an explicit form $X_i = f(X_{k \neq i})$
2. Rearrange the matrix to have a diagonal matrix

if
$$diag_i = f(diag_k, k = 1, \dots, i - 1)$$

3. Define the order of resolution
Solve the sequence

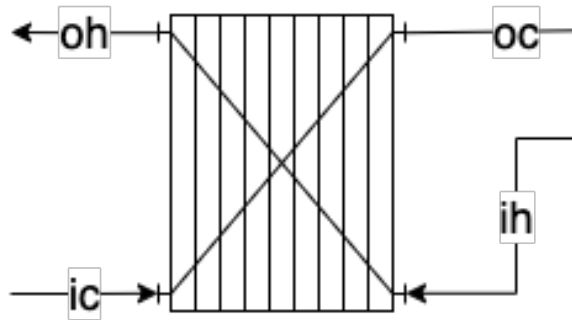


- $$\text{if not } \quad diag_i = f(diag_k, k = 1, \dots, i - 1)$$

- 6.3 if Yes continue with the sequence

Ns X=Xs	Eq1	x					
	Eq2		x				
	Eq3			x			
	Eq4				x		
	Eq5					x	
	Eq6						x
N-Ns X=F(X)	Eq7	x			x		
	Eq8		x			x x	
	Eq9		xx				x
	Eq10		xx				x
	Eq11			x		xx	
	Eq12			x	x		x
	Eq13			x			xx
	Eq14	x		x			xx

6.2 can also be solved by iterating to solve $Xd^k - Xd^{k-1} = 0$



Explicit form

$$diag_i = f(diag_k, k = 1, \dots, i - 1)$$

Nb.	Equation	1. $\dot{m}_{ci}$	2. T_{ci}	3. P_{ci}	9. P_{hi}	8. T_{hi}	7. $\dot{m}_{hi}$	13. A	15. U	10. $\dot{m}_{ho}$	4. $\dot{m}_{co}$	6. P_{co}	12. P_{ho}	5. T_{co}	11. T_{ho}	14. $\dot{Q}$
8(S)	$\dot{m}_{ci} = \dot{m}_{ci}^s$	x														
9(S)	$T_{ci} = T_{ci}^s$		x													
10(S)	$P_{ci} = P_{ci}^s$			x												
11(S)	$T_{hi} = T_{hi}^s$				x											
12(S)	$P_{hi} = P_{hi}^s$					x										
13(S)	$\dot{m}_{hi} = \dot{m}_{hi}^s$						x									
14(S)	$A = A^s$							x								
15(S)	$U = U^s$								x							
3(MB)	$\dot{m}_{hi} = \dot{m}_{ho}$						x			x						
4(MB)	$\dot{m}_{ci} = \dot{m}_{co}$	x									x					
5(P)	$P_{hi} = P_{ho}$				x							x				
6(P)	$P_{ci} = P_{co}$			x									x			
1(EB)	$\dot{Q} = \dot{m}_{ci} c p_c (T_{co} - T_{ci})$	x	x											x		x
2(EB)	$\dot{Q} = \dot{m}_{hi} c p_h (T_{hi} - T_{ho})$					x	x								x	x
7(M)	$\dot{Q} = U A \frac{(T_{hi} - T_{co}) - (T_{ho} - T_{ci})}{\ln(\frac{T_{hi} - T_{co}}{T_{ho} - T_{ci}})}$		x			x		x	x				x	x		x

Sequential resolution

$$x_i = f(x_{j < i})$$

$$\text{Solve } x_i - f(x_{j \leq i}) = 0$$

- A flowsheet is a set of interconnected units
- System State Variables : what we need to know to characterize the system
 - State variables for each flow
 - Unit parameters
- Model (simulation) equations
 - Constitutive equations define the thermodynamic state of the flows
 - Unit models model the thermo-chemical transformations in units
 - Balance equations : mass + energy + impulsion
 - Thermo-chemical and mechanical transformations/transfer
- Specifications
 - Variables that needs to be fixed to fix the degrees of freedom
- Define the resolution strategy
 - simultaneous or sequential

	Simultaneous	Sequential
Problem statement	Incidence matrix implicit	DOF analysis required
Robustness	unique solving scheme	specific solving procedure bounds; if-then-else
calculation modes	specifications	solving scheme
Derivatives	Required	numerical noise at flowsheet level if iterative scheme