AMPL for MILP

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MILP problem



A Mixed-Integer Linear Programming problem is a mathematical optimisation program in which some of the variables are constrained to be integers, while others are allowed to be continuous. The necessary condition for a mathematical problem to be part of the MILP class is that both the objective functions and the constraints have to be linear

subject to
$$\mathbf{c}^T \mathbf{x}$$

 $\mathbf{c}^T \mathbf{x}$
 $\mathbf{c}^T \mathbf{c}^T \mathbf{c}^T$

where

is the vector of structural variables

 $\mathbf{A} \in \mathbb{Q}^{m \times n}$ is the matrix of technological coefficients

 $\mathbf{c} \in \mathbb{O}^n$ is the vector of objective function coefficients

is the vector of constraints right-hand sides (RHS)

is the vector of lower bounds on variables

 $\mathbf{u} \in \mathbb{O}^n$ is the vector of upper bounds on variables

is a nonempty subset of the set $\{1, \ldots, n\}$ of indices

Introduction

AMPL



A Mathematical Programming Language (AMPL)

High-level algebraic modelling language to build and solve complex problems for large-scale mathematical computing

- 1. Natural syntax (concise and easy to read)
- 2. Good scripting language to process data
 - Looping
 - If...then...else... command
- 3. Can handle continuous and integer variables
- 4. Many available solvers

Introduction

- Linear and convex quadratic (e.g. CPLEX, Gurobi,...)
- Nonlinear (e.g. MINOS, SNOPT, CONOPT,...)

https://ampl.com/resources/the-ampl-book/

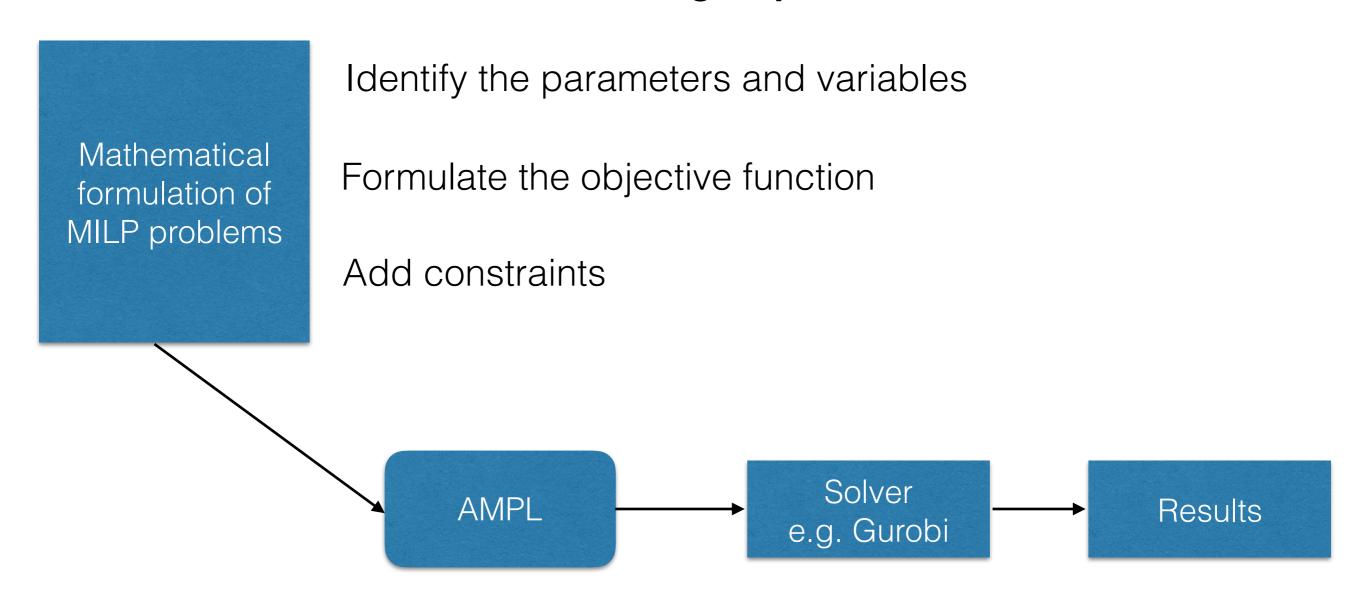


AMPI

AMPL: modelling



Modelling steps





Introduction

Definition

AMPL: types of file



1. .mod

Main file where the entire model is implemented. It contains the definition of the problem variables, constraints and objective function. All the laded data are processed in this file.

2. .datIt contains all the input data to the problem.

3. .run

Commands file where the model and the data files are loaded. The major run options are defined here (e.g. selection of the solver) together with the *solve* command and the variables that have to be shown after the convergence is reached.

Introduction



Parameter declaration

A parameter is a quantity not subjected to changes during the optimisation. It can be used only after it is declared.

```
param t;
param t := 1;
```

The operator *default* initialises the parameter while allowing its value to be overridden by a data statement or changed by subsequent assignments.

```
param a default 5;
param b := 3;
param c := a+b;
```

A parameter can also be a vector:

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```
param C;
param cost{1..C}; #numeric index from 1 to C
```





It is possible to refer to a specific element of the vector by doing:

```
\ldotscost[x].... #where x is a numeric index
```

If a parameter has to be editable, instead of being introduced by :=, it has to be declared with the command *default* and later changed by using *let*

```
param c default 100;
....
let c := 200;
```

Sets

This is a fundamental component of an AMPL model. Almost all of the parameters, variables and constraints are indexed over sets.

set Technologies default {};





A set can be an unordered collection of character strings.

Set members can also be numbers or even a mixture of numbers and strings. The *by* clause can be used to specify the spacing:

```
set years = 1990..2020 by 5;
```

It is also possible to construct new sets from existing ones (A and B) by using the following operators:

```
A union B # union: in either A or B
```

A inter B # intersection: in both A and B

A diff B # difference: in A but not B

A symdiff B # symmetric difference: in A or B but not both



Introduction



Two other AMPL operators, *in* and *within*, are used to test the membership of sets:

```
"boiler" in Technologies

# true only if "boiler" is a member of the set Technologies

{"boiler", "PV"} within Technologies

# true only if {"boiler", "PV"} is a subset of the set Technologies
```

A parameter can be indexed over multiple sets.

param Qheating{b in Buildings, t in Time} default 0;

It is possible to assign values to the parameters indexed over the two sets Buildings and Time. To do so, one should specify the indexes followed by the corresponding values. To improve **readability** it is convenient to define the parameter as follows:



Introduction



```
param Qheating :=

"BC" 1 value1

"BC" 2 value2

"CE" 1 value3

"CE" 2 value4;
```

An element of the multi-dimensional parameter can be accessed by using the square brackets:

```
... Qheating["BC", 1] ...
```

It is also possible to read values from a .txt file and assign them to a parameter. The file must be unformatted in the sense that it contains nothing except the values to be read. The values in the file are assigned to the entries in the list in the order that they appear.

```
param time_steps := 5;
read {t in 1..time_steps} t_op[t] < values.txt;</pre>
```

From a file values.txt containing only:

100 200 450 135 700



Sets

AMPI



Variables declaration

Variables represent unknown quantities whose values is calculated by the solver. As the parameter they have to be declared before being used.

```
var x;
var mult{Utilities};
```

Zero-one (or **binary**) variables for modelling logical conditions:

```
var use{Utilities} binary;
```

The lower bound has to be specified in order to avoid unfeasible evaluations and facilitate the resolution of the optimisation problem:

```
var mult{Utilities}>=0;
```

Or even the higher bound:

Introduction

var mult{Utilities}>=0, <=10000;</pre>





Objective function

Introduction

It is the function that has to be maximise or minimise. It is declared with the command maximize or minimize followed by the name of the objective and by a mathematical expression of sets, parameters and variables previously defined.

```
minimize Total_cost : Inv_cost + Op_cost;
```

The expression can be even more complicated:

```
minimize Total_cost : sum{tc in Technologies} (cinv1[tc] * use[tc] + cinv2[tc] * mult[tc]) + sum {u in Utilities, t in Time} (cop1[u] * use_t[u,t] + cop2[u] * mult_t[u,t]) * top[t];
```

However, it is highly recommended to avoid a complicated expression of the objective function since it considerably slows down the resolution of the problem!!



Mathematical constraints

The simplest kind of constraint declaration begins with the keywords *subject to*, a name, and a colon. Even the subject to is optional: AMPL assumes that any declaration not beginning with a keyword is a constraint. Following the colon is an algebraic description of the constraint, in terms of previously defined sets, parameters and variables.

subject to name:
$$x \le 4$$
;

Obs: The name of a constraint, like the name of an objective, is not used anywhere else in an algebraic model!!

Most of the constraints in large programming models are defined as indexed collections, by giving an indexing expression after the constraint name.

```
subject to size_cstr1{u in Utilities, t in Time}:
    Fmin[u]*use_t[u,t] <= mult_t[u, t];</pre>
```



Introduction



Iterated operators (sum, prod, min and max)

It is possible to iterate operations over sets. In particular, most large-scale linear programming models contain iterated summations (*sum*):

```
InvCost = sum{tc in Technologies} (cinv1[tc] * use[tc] + cinv2[tc] * mult[tc]);
```

The arithmetic expression is evaluated once for each member of the set *Technologies*, and all the resulting values are added.

Other iterated arithmetic operators are *prod* for multiplication, *min* for minimum, and *max* for maximum. For example one could write:

```
...max{t in Technologies} mult[t]...
```

to obtain the greatest mult among those attributed to each member *t* of the set *Technologies*



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AMPI



Conditional operator if-then-else

It returns one of two different arithmetic values depending on whether the logical expression is true or false. For example:

```
param Qheatingdemand{h in HeatingLevel, t in Time} :=
   if h == 'MediumT' then
      sum{b in MediumTempBuildings} Qheating[b,t]
   else
      sum{b in LowTempBuildings} Qheating[b,t];
```

Qheatingdemand is a bi-dimensional parameter defined for each HeatingLevel h and Time t. If the HeatingLevel h is equal to 'MediumT' then Qheatingdemand is calculated, for each Time t as the sum of all the demands Qheating of the buildings b belonging to the MediumTempBuildings set. The LowTempBuildings set is used otherwise.



Introduction



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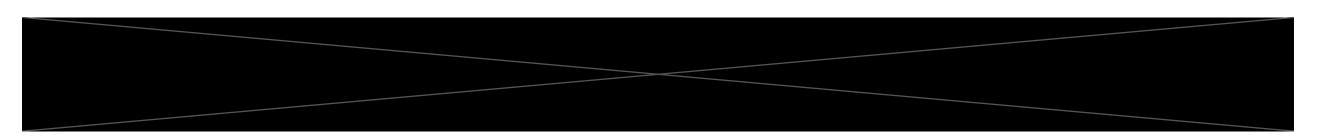
Commands file (.run)

The commands file with extension .run is often used to load both the model and the corresponding data. This is done by including the following lines:

```
model model_name.mod;
data datafile_name.dat;
```

Additional options, such as the used solver, are declared with the command option:

option solver gurobi;



Finally, the commands solve and display are used to compute the model and output to the command window/terminal the desired quantities:

> solve; display Qheating;



Introduction

Commands file **AMPI**

Project structure

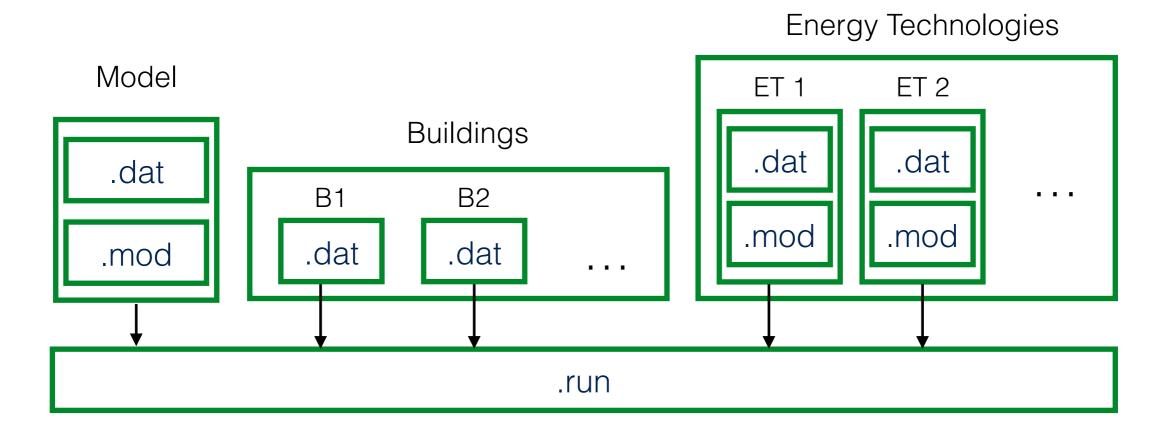


All the .mod and .dat file are finally loaded into the commands file (.run)

- Additional running options can be specified here:
 - 1. Solver

Introduction

- 2. Maximum number of iterations
- The display command is used to output the optimised variables





AMPI

Project files

Commands file

Project structure

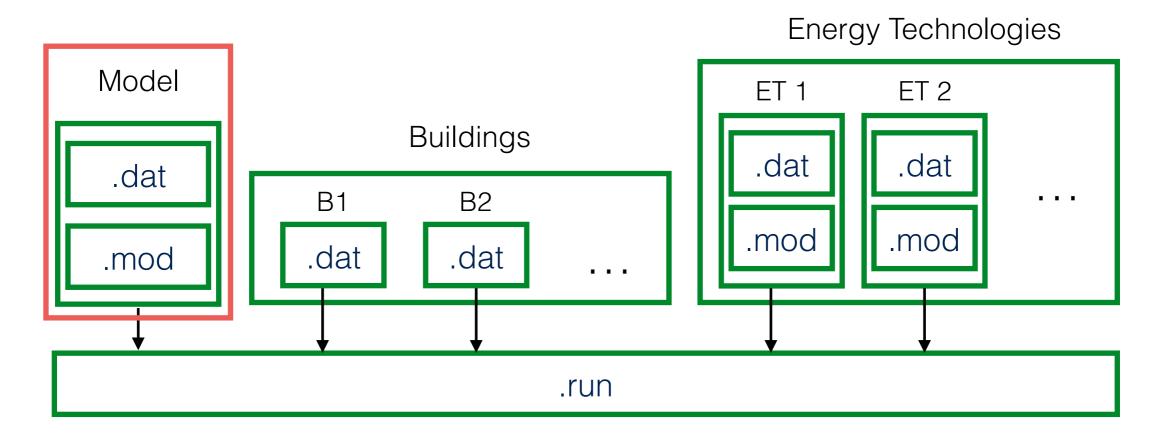


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Project files: .mod and .dat

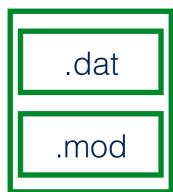


Main model file moes2020.mod

- Sets
- Parameters
- Variables
- Constraints
 - Utility sizing constraints
 - Heating balances (MT and LT)
 - Resource balances
 - Electricity balances
- Objective function

Introduction

Model



Main data file moes2020.dat

- Define the composition of each set
- Define the generic parameters of the model (top, irradiation, Text, c_spec, ...)



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Project structure

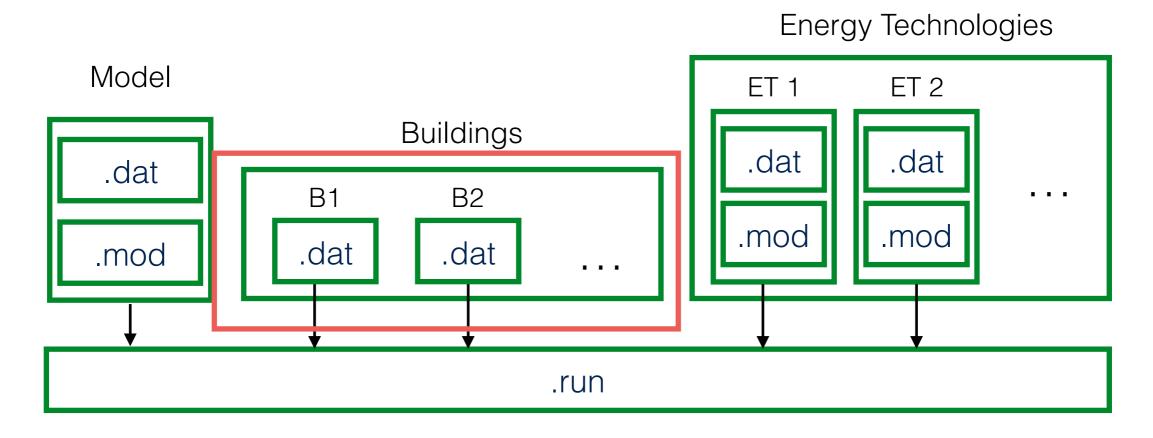


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Project files

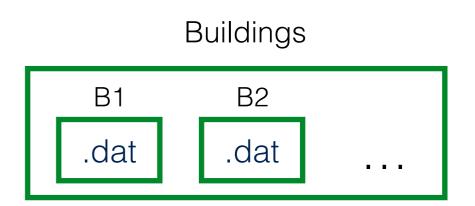
Commands file

Project files: Buildings



Each building is loaded into the model using a .dat file only

- 1. Add the building to the corresponding set (MediumTempBuild or LowTempBuild)
- 2. Define some building-specific parameters:
 - Floor area
 - kth and ksun
 - . . .



A .mod file could be used to model the refurbishment

- Additional binary variable (refurbishment option)
- Equation defining the new heating demand of the building
- Equation for the cost of refurbishment

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Project structure



All the .mod and .dat file are finally loaded into the commands file (.run)

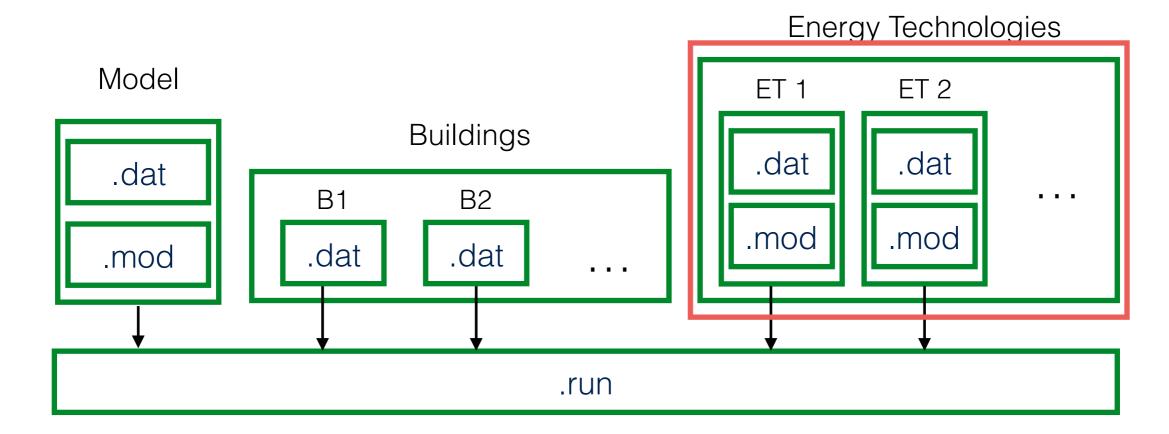
- Additional running options can be specified here:
 - 1. Solver

Introduction

2. Maximum number of iterations

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The display command is used to output the optimised variables





Project files

Project files: Energy Technologies

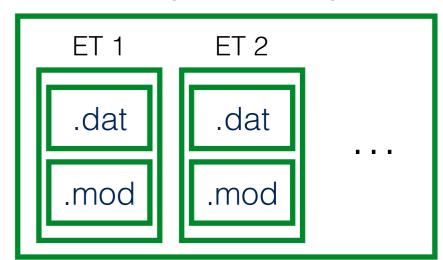


Each energy technology is introduced using the model-data structure

The data file contains:

- Definition of Maximum and minimum scaling factors
- Efficiencies
- Supply temperature
- •

Energy Technologies



The mod file contains the modelling equations:

Supplied heat

Introduction

- Resource consumption (Natural gas, electricity, biogas, ...)
- •



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Project files

Project structure

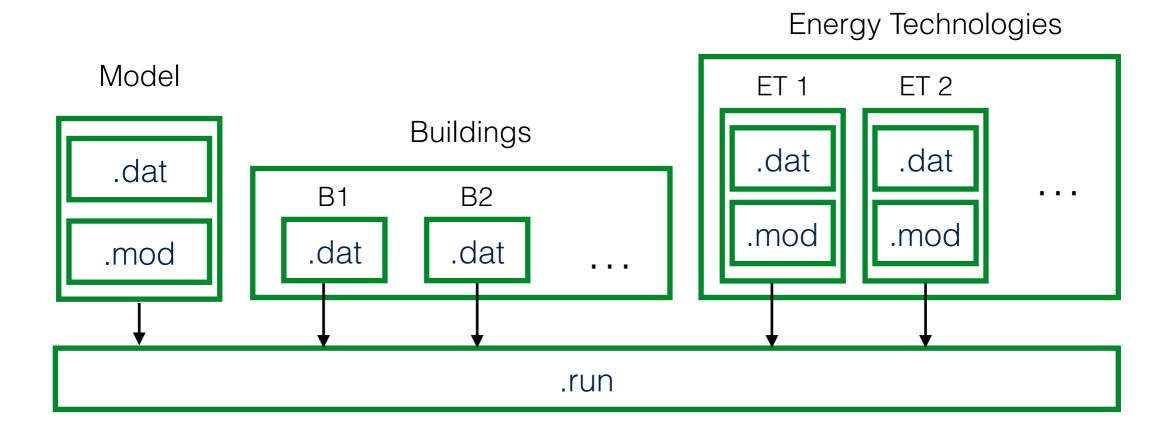


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Introduction

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Project files

Overall picture of the model



Sets are fundamental to model large-scale optimisation problems

They are used to group elements of the same type and repeat operations

In the project, sets are defined for the main elements:

- Time steps
- Buildings
- Technologies
 Origle (to lower seconds)
- Grids (to buy resources)
- Resource layers (Natural gas, electricity, biogas)

Additional sets are used to group elements because of common features

- Low and Medium temperature buildings
- Type of utility (heating, electricity producers and consumers)
- Layer of the utility

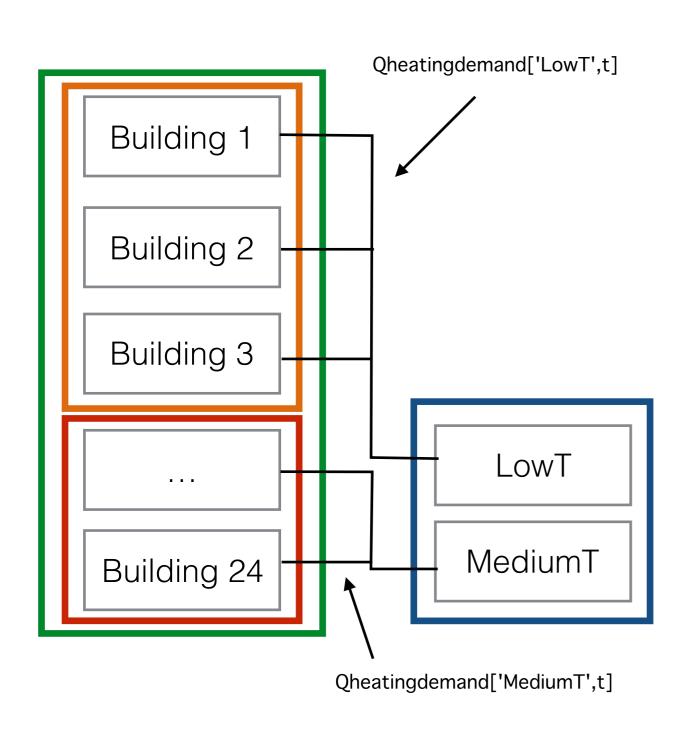
Introduction

Some sets are strictly related to each other since they share same elements!



Demand-side sets





Buildings ——

List of buildings

LowTempBuildings ———

Buildings heated by low T loop

MediumTempBuildings ———

Buildings heated by medium T loop

HeatingLevel ———

- Two options (low/medium)
- Classify buildings
- Each utility can provide heat to both loops mult_heating_t[u,t,'LowT'] mult_heating_t[u,t,'MediumT']



Introduction > AMPL

Utilities set



Technologies -

List of ET



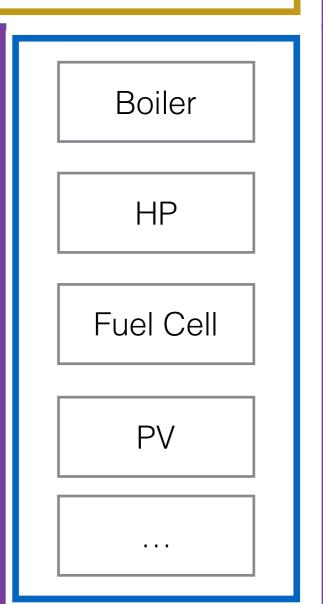
Grids

Grid units to buy resources

Utilities —

Introduction

- List of utilities (technologies + grids)
- Utilities are the object of optimisation
 - Binary variables (use, use_t)
 var use{Utilities} binary;
 var use_t{Utilities, Time} binary;
 - Continuous variabels (mult, mult_t)
 var mult{Utilities}>=0;
 var mult_t{Utilities, Time}>=0;





AMPL

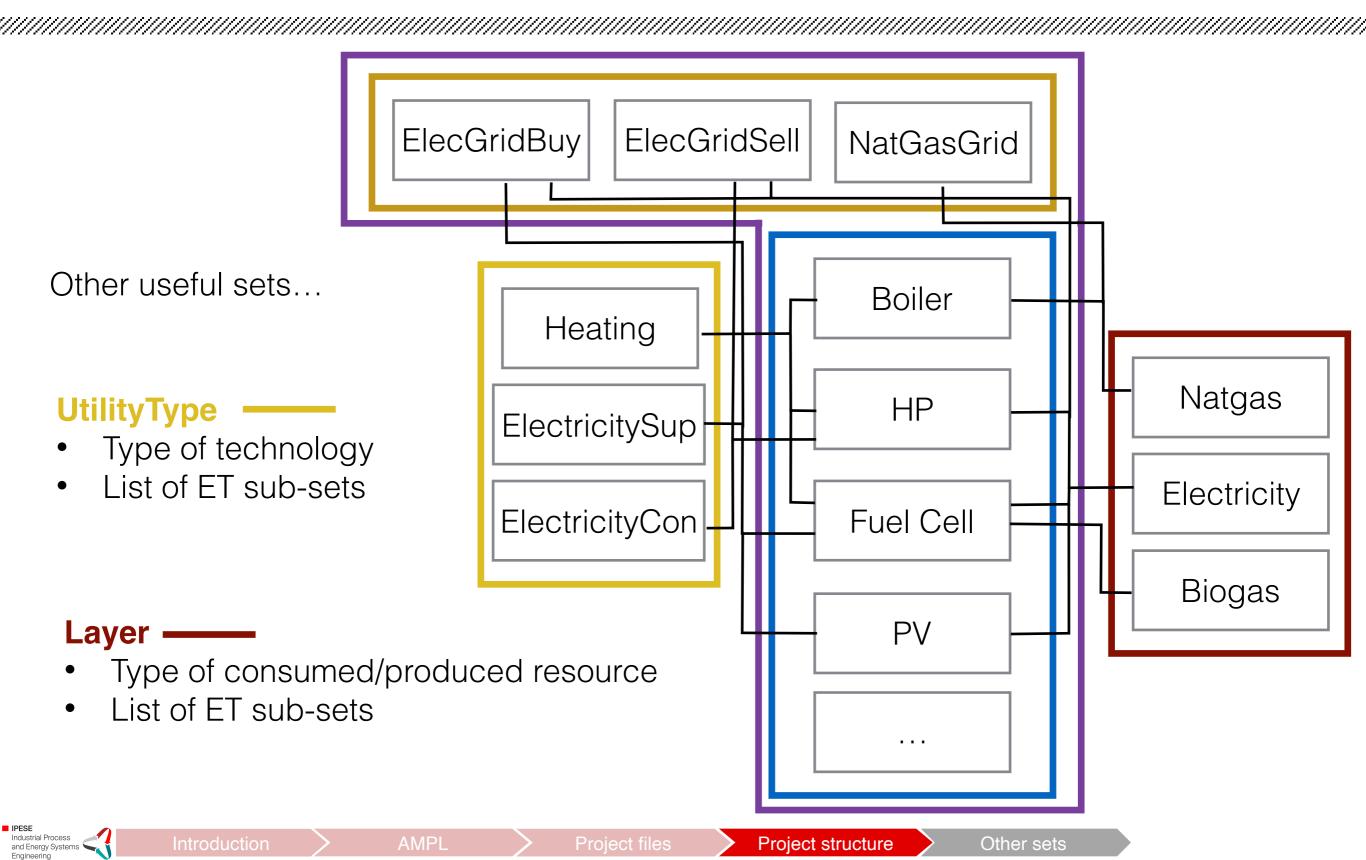
Project files

Project structure

Utilities

Layers and other sets

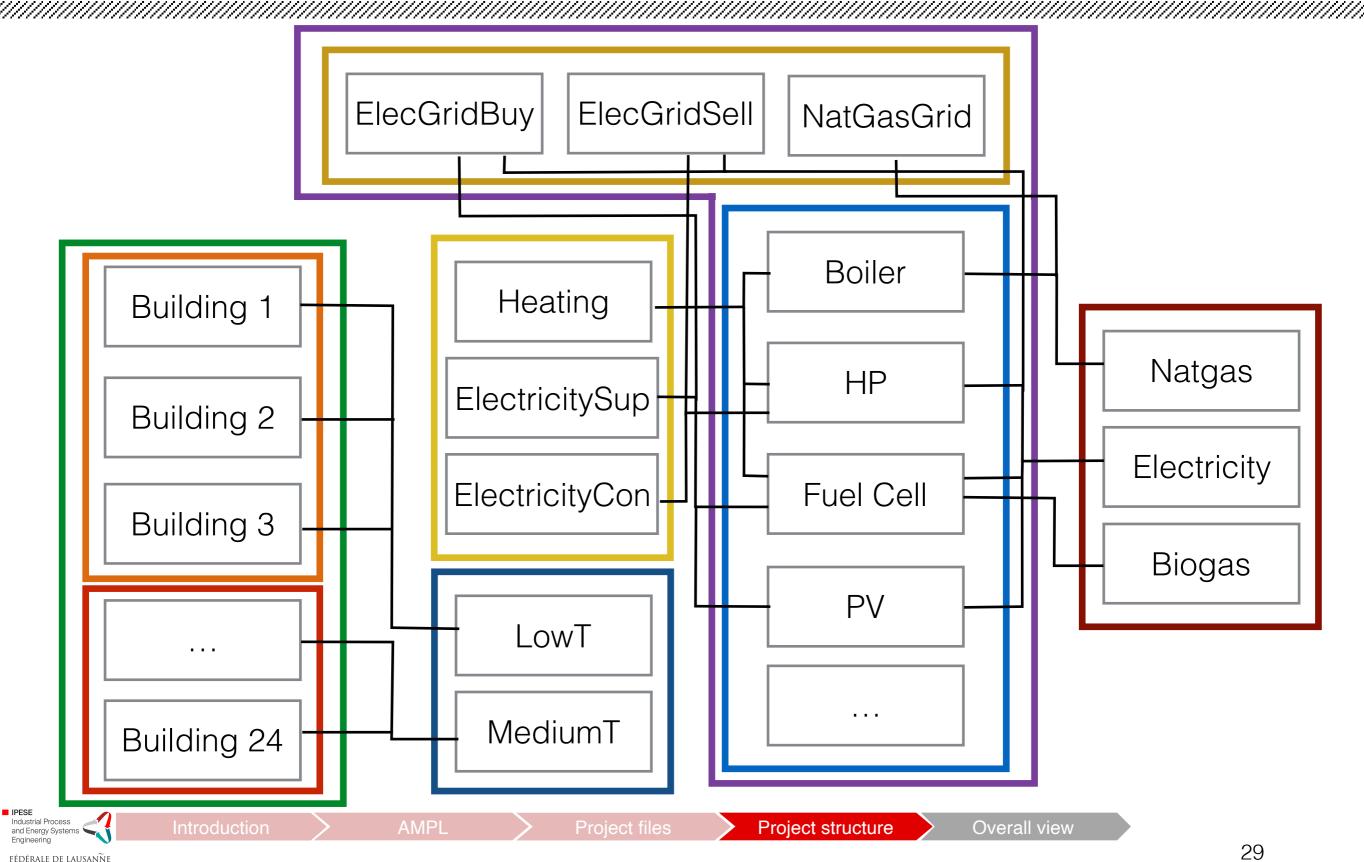




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Overall structure of the sets





Constraints: heating balances



Heating balances:

1. LT_balance{t in Time}

Low temperature demand = sum over the utility set of the heat supplied by each utility of type heating (mult_heating_t[u,t,'LowT'])

2. MT_balance{t in Time}

Medium temperature demand = sum over the utility set of the heat supplied by each utility of type heating (mult_heating_t[u,t,'MediumT'])

Observe that for each utility u and time step t:

mult_t[u,t] = mult_heating_t[u,t,'LowT'] + mult_heating_t[u,t,'MediumT']



Project structure

Constraints: resource balance



Resource balance:

1. Sum of the **FlowInUnit** of the utilities over each layer I = Sum of the **FlowOutUnit** of the utilities over the same layer I (except for electricity layer)

```
where...
```

```
FlowInUnit[I, u, t] = mult_t[u,t] * Flowin[I,u];
FlowOutUnit[l, u, t] = mult_t[u,t] * Flowout[l,u];
```

Observe that for each utility u and layer I:

Flowin[I,u] and Flowout[I,u] are calculated using the reference size



Project structure

Constraints: electricity balance



Electricity is considered to be a resource as well...

Electricity balance constraint:

 Total electricity demand + Sum of the FlowInUnit of the utilities over the sub-set ElectricityCons = Sum of the FlowOutUnit of the utilities over the sub-set ElectricityProd

Observe that:

UtilitiesOfType['ElectricityCons'] and UtilitiesOfType['ElectricityProd'] are two sets indexed over the elements of the set UtilityType



Objective function



The objective function is the **Total cost** (annual) defined as the same between:

1. Operating cost

OpCost = sum {u in Utilities, t in Time} (cop1[u] * use_t[u,t] + cop2[u] * mult_t[u,t]) * top[t];

2. Annualised investment cost

InvCost = sum{tc in Technologies} (cinv1[tc] * use[tc] + cinv2[tc] * mult[tc]);

Where:

cop1[u] is the fixed operating cost of the utility u [CHF/h] cinv1[tc] is the fixed investment cost of the technology to [CHF/y] cop2[u] is the variable operating cost of the utility u [CHF/h] cinv2[tc] is the variable investment cost of the technology to [CHF/y]



Thanks for your attention and ENJOY!



