Multivariable Control (ME-422) - Exercise session 11

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1. Let v and w be jointly Gaussian, independent, with zero average and var[v] = 2, var[w] = 1. Let x and y be defined in the following alternative ways

(a)
$$x = v + w$$
 (b) $x = 2v + 2w$ (c) $x = v + w$ (d) $x = v$
 $y = v - w$ $y = 2v - 2w$ $y = 2v + 2w$ $y = \sqrt{2}w$

Which pairs x, y have the highest/lowest covariance?

2. Consider the following data

$$u_1 = -1$$
 $u_2 = \sqrt{0.5}$ $u_3 = 1$
 $y_1 = 0$ $y_2 = 0$ $y_3 = 1.5$

and the following model

$$y_k = \theta u_k^2 + v_k$$

where

$$\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \sim N \left(\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, V \right) \qquad V = \begin{bmatrix} 1 & \frac{1}{2} & 0 \\ \frac{1}{2} & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Moreover, $\theta \sim N(1,1)$ and is independent of $\begin{bmatrix} v_1 & v_2 & v_3 \end{bmatrix}^T$.

Compute the parameter estimate $\hat{\theta} = E[\theta|y_1, y_2, y_3]$.

Hint: Derive first the probability density of $\begin{bmatrix} \theta & y_1 & y_2 & y_3 \end{bmatrix}$. Use MATLAB for computing the required matrix products.

3. Find the update rule for the covariance matrix $P_k = \mathrm{E}\left[\left(x_k - \mathrm{E}[x_k]\right)\left(x_k - \mathrm{E}[x_k]\right)^T\right]$ of the process

$$x_{k+1} = Ax_k + Bw_k \quad A = \frac{1}{2} \begin{bmatrix} 0 & 1 \\ -1 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$
$$x_0 \sim N\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right)$$

where $w_k \sim WGN(0,1)$. Is P_k convergent as $k \to \infty$? If yes, compute the limit value.

4. Recall the eigenvalue assignment theorem

Theorem. For a given pair $(A, B), A \in \mathbb{R}^{n \times n}, B \in \mathbb{R}^{n \times m}, \exists K \in \mathbb{R}^{m \times n} : (A + BK)$ has prescribed eigenvalues $\iff (A, B)$ is reachable.

Prove the \implies statement.

Hints: In an equivalent way, one can try to prove (A, B) unreachable \implies not all eigenvalues of (A + BK) can be assigned. Use the reachability form of (A, B) for showing the implication.