

## Exercise 1

Many engineering materials at the macro-scale can be considered linear-elastic, but this kind of approximation often breaks down when we look at objects at very small length scales. For example, a molecule of DNA in solution will naturally collapse into a random coil, and require a force to stretch it out. One model for the restoring force  $F$  of a DNA molecule whose endpoints are stretched apart a distance  $x$  is given by:

$$F = \left( \frac{k_B T}{L_p} \right) \left[ \frac{1}{4 \left( 1 - \frac{x}{L_0} \right)^2} - \frac{1}{4} + \frac{x}{L_0} \right] \quad (1)$$

where  $k_B$  is the boltzman constant,  $T$  is the absolute temperature,  $L_p$  is the persistence length of the DNA (a measure of the resistance of the DNA molecule to bending), and  $L_0$  is the contour length (the length along the path of the DNA). The manipulation of DNA is very important in biology. It must be packaged into a compact structure during cell division, and for a gene to be read, the section of interest must be unpackaged into a more stretched-out configuration.

- Calculate the stored energy of a DNA molecule stretched from 0 to a distance  $L$  which is less than  $L_0$ .
- What amount of energy is needed to stretch a DNA molecule with  $L_0 = 2 \mu\text{m}$  from 0 to a length of  $1.9 \mu\text{m}$ ?

Use a persistence length of  $50 \text{ nm}$ , a temperature of  $37^\circ\text{C}$ , and  $k_B = 1.38 \cdot 10^{-23} \text{ J K}^{-1}$ .

## Exercise 2

Normal and shear strains are described by the following displacement field:

$$u(x, y, z) = -z \frac{\partial f(x)}{\partial x}, \quad v(x, y, z) = 0, \quad w(x, y, z) = f(x) \quad (2)$$

where

$$f(x) = \frac{L^3}{6} \left( 3 \left( \frac{x}{L} \right)^2 - \left( \frac{x}{L} \right)^3 \right) \quad (3)$$

and  $L$  is a constant. Calculate all of the normal and shear strains for the defined displacement field and write the 3D strain tensor.

*Note* Function  $f(x)$  multiplied by some factor actually presents the deflection of the cantilever beam induced by the point load. Derived strain  $\varepsilon_x$  is the induced strain in the beam along the cantilever length. But all of this you will learn soon... :)

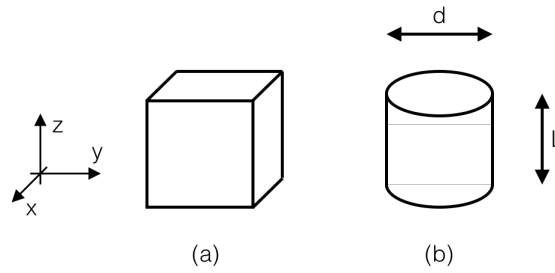


Figure 1: Definition of the geometrical entities.

### Exercise 3

- a) The normalized volume change of a parallelepiped as a function of the strain in all three directions:

$$\frac{\Delta V}{V} = \varepsilon_x + \varepsilon_y + \varepsilon_z$$

Prove this expression by considering a parallelepiped with sides  $x$ ,  $y$  and  $z$  (fig. 1, a). Hint: you will have to cross-out negligible terms.

- b) Similarly to part (a), show that a cylinder (fig. 1, b) that is strained in both the radial and the axial direction will experience a volume change described by:

$$\frac{\Delta V}{V_0} = \varepsilon_L + 2\varepsilon_r$$

- c) When a woman is standing on her two feet, she puts a weight of about  $w = 200\text{N}$  on each of her femurs. By approximating the bone as a cylinder of diameter  $d = 2\text{cm}$  and length  $L = 40\text{cm}$ , find its change in diameter when the woman goes from a sitting to a standing position. Assume that the volume of the bone remains constant.

Young's modulus for the bone:  $E = 16\text{GPa}$

## Exercise 4

A block of rubber (R) is confined in a slot inside a steel block (S). A uniform pressure  $p_0$  to the top of the rubber block induces a deformation.

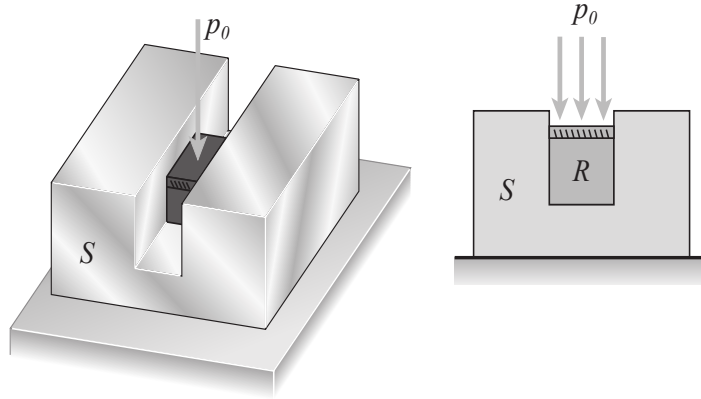


Figure 2: Rubber block in a slotted steel piece.

- Find a formula for the lateral pressure on the block, induced by the downward pressure  $p_0$ , ignoring any friction effects.
- Derive a formula for the dilation  $e$  of the rubber (the volume change ratio  $\Delta V/V$ ).

## Exercise 5

A rubber cube with side length  $a = 1\text{cm}$  is placed on a flat surface (see figure 3). A weight of mass  $m = 20\text{g}$  is added on top. The cube has a known Young's modulus  $E = 0.1\text{GPa}$ , poisson ratio  $\nu = 0.45$ .

You will neglect the variation of area in the calculation of the stress :  $\sigma \approx \frac{F}{A_{\text{no stress}}}$  (as you did up to now in this course).

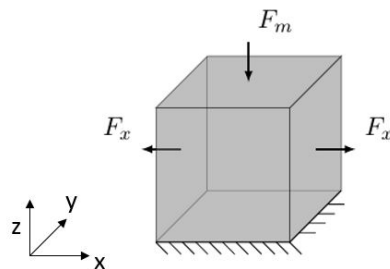


Figure 3: Rubber block on surface.

- What is the change in height of the cube  $\Delta z$ ? What is the change of volume  $\Delta V$ ?

- b) You now want to bring back the cube to its original height. Which force  $F_x$  do you need to apply? What is the change of volume  $\Delta V$ ?
- c) Instead, you want to bring the cube back to its original volume of  $a^3$ . Which force  $F_x$  do you need to apply ?
- d) The force  $F_x$  is no longer applied, only the force  $F_m$  due to the weight remains. Use calculation at the first order (small deformations) to determine the deformation  $\varepsilon_z$  and the stress  $\sigma_z$  without making the approximation that  $\sigma \approx \frac{F}{A_{\text{no stress}}}$ . Instead, use:  $\sigma = \frac{F}{A_{\text{with stress}}}$ . Compare to your results with the approximation (first question). Conclude : is this approximation reasonable?