

Problem 1 Suppose that estimator T has expectation equal to $\theta(1 + \gamma)$, so that the bias is $\theta\gamma$. The bias factor γ can be estimated by $C = E^*(T^*)/T - 1$, where E^* denotes expectation over bootstrap sampling and T^* is based on the bootstrap samples.

- (a) Show that in the case of the variance estimate $T = n^{-1} \sum (Y_j - \bar{Y})^2$, C is exactly equal to γ .
- (b) If C were approximated from R resamples by C^* , what would be the simulation variance of C^* ?

Problem 2

Let T be the median of a random sample of size $n = 2m + 1$ with ordered values $y_{(1)} < \dots < y_{(n)}$; the observed value of T is therefore $t = y_{(m+1)}$.

- (a) Show that $T^* > y_{(l)}$ if and only if fewer than $m + 1$ of the Y_j^* are less than or equal to $y_{(l)}$, and deduce that

$$P^*(T^* > y_{(l)}) = \sum_{j=0}^m \binom{n}{j} \left(\frac{l}{n}\right)^j \left(1 - \frac{l}{n}\right)^{n-j}.$$

This specifies the exact resampling distribution of the sample median, and can be used to prove that the bootstrap estimate of $\text{var}(T)$ is consistent as $n \rightarrow \infty$.

- (b) Use the resampling distribution in (a) to show that for $n = 11$,

$$P^*(T^* \leq y_{(3)}) = P^*(T^* \geq y_{(9)}) = 0.051,$$

and deduce that an approximate basic bootstrap 90% confidence interval for the population median is $(2y_{(6)} - y_{(8)}, 2y_{(6)} - y_{(4)})$.

Problem 3 A parameter $\theta = t(G)$ is determined implicitly through the estimating equation

$$\int a(x; \theta) dG(x) = \int a\{x; t(G)\} dG(x) = 0.$$

- (a) Replace G by $G_\varepsilon = (1 - \varepsilon)G + \varepsilon H_y$, where H_y is the Heaviside function putting unit mass at y , and show by differentiation with respect to ε that the influence function for $t(\cdot)$ is

$$L_t(y; G) = \left. \frac{\partial t(G_\varepsilon)}{\partial \varepsilon} \right|_{\varepsilon=0} = \left\{ - \int a_\theta(x; \theta) dG(x) \right\}^{-1} a(y; \theta), \quad \text{where} \quad a_\theta(x; \theta) = \frac{\partial a(x; \theta)}{\partial \theta^T}.$$

- (b) Hence show that with a random sample $y_1, \dots, y_n$ and $\hat{\theta} = t(\hat{G})$ the j th empirical influence value is

$$l_j = L_t(y_j; \hat{G}) = \left\{ -\frac{1}{n} \sum_{k=1}^n a_\theta(y_k; \hat{\theta}) \right\}^{-1} a(y_j; \hat{\theta}).$$

- (c) Check that this gives the result anticipated when $a(x; \theta) = x - \theta$.
- (d) Let $\hat{\theta}$ be the maximum likelihood estimator of the parameter of a regular parametric model $f(y; \theta)$ based on a random sample $y_1, \dots, y_n$. Show that the j th empirical influence value for $\hat{\theta}$ at y_j may be written as $n\hat{\mathcal{J}}^{-1}S_j$, where

$$\hat{\mathcal{J}} = - \sum_{j=1}^n \frac{\partial^2 \log f(y_j; \hat{\theta})}{\partial \theta \partial \theta^T}, \quad S_j = \frac{\partial \log f(y_j; \hat{\theta})}{\partial \theta},$$

and deduce that the nonparametric delta method variance estimate for $\hat{\theta}$ has the sandwich form

$$\hat{\mathcal{J}}^{-1} \left(\sum_{j=1}^n S_j S_j^T \right) \hat{\mathcal{J}}^{-1}.$$

- (e) When $y_1, \dots, y_n$ is a random sample from the exponential distribution with mean θ compare the result in (b) to the usual parametric approximation.