

Exercise Class #4

Numerical Methods for Conservation Laws

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Friday 20th of October, 2023

Exercise Class #4

Today's Topics: Exercise Set #4

- Numerical Methods for CL: The Finite Difference Method.
- Leapfrog Method
- Lax-Friedrichs Method
- Analysis
 - ✓ Consistency
 - ✓ Stability
 - ✓ Convergence

Exercise Set #4 - Exercise 1

Exercise 1: Method of Characteristics

- Define the following concepts:
 - (a) Consistency;
 - (b) Stability; and,
 - (c) Convergence.
- Discuss the importance of these concepts, how they relate to each other, and how in general they can be established.

Exercise Set #3 - Exercise 1: Hints

Exercise 2: Finite Differences Method

- **Consistency.** A method is consistent if its local truncation error τ_k satisfies

$$\tau_k(x, t) = O(k^p) + O(h^q) \quad \text{where} \quad p, q > 0. \quad (1)$$

Essentially, consistency tells us that we are approximating the solution of the correct PDE.

- **Stability.** A method $v^{n+1} = \mathcal{H}_k v^n$ is stable if for each $T > 0$ there exist constants C and k_0 , such that

$$\|\mathcal{H}_k^n\| \leq C \quad 0 \leq nk \leq T, \quad 0 < k < k_0. \quad (2)$$

- **Convergence.** A method is convergent if the error E_k satisfies

$$\lim_{k \rightarrow 0} \max_{0 \leq kn \leq T} \|E_k(\cdot, kn)\| = 0. \quad (3)$$

Exercise Set #3 - Exercise 2

Exercise 2: Leapfrog Method

- The forward time, center space finite difference approximation to the advection equation $u_t + au_x = 0$ leads to a method which is *unstable*.
- So let us try something different.
- **Leapfrog method**. By approximating the time derivative by a centered difference, instead of the forward Euler discretization, we get the

$$v_j^{n+1} = v_j^{n-1} - \frac{ak}{h} (v_{j+1}^n - v_{j-1}^n) . \quad (4)$$

- (i) Draw the stencil of (4).
- (ii) Show that (4) is second order accurate in both space and time.
- (iii) What is an obvious disadvantage of the Leapfrog method compared to the Lax-Friedrichs or Lax-Wendroff methods?

Exercise Set #4 - Exercise 2: Hints

Exercise 2: Leapfrog Method

- (i) You may draw it by yourself.
- (ii) The Leapfrog Scheme is second order accurate in both space and time.

✓ Let u be a smooth solution of $u_t + au_x = 0$.

✓ The local truncation error for the Leapfrog scheme is given by

$$\begin{aligned} k\tau_k(x, t) = & u(x, t+k) - u(x, t-k) \\ & + \frac{ak}{h} (u(x+h, t) - u(x-h, t)) \end{aligned} \quad (5)$$

✓ Next, we expand all the terms on the right hand side of (5) about (x, t) .

✓ For example, we have $u(x, t+k)$ and $u(x, t-k)$ given by

$$u(x, t+k) = u + u_t k + \frac{1}{2} u_{tt} k^2 + O(k^3) \quad (6)$$

and

$$u(x, t-k) = u - u_t k + \frac{1}{2} u_{tt} k^2 + O(k^3), \quad (7)$$

Exercise Set #4 - Exercise 2: Hints

Exercise 2: Leapfrog Method

(ii) (Continuation)

✓ You should obtain

$$\tau_k(x, t) = 2(u_t + au_x) + O(k^2) + O(h^2) . \quad (8)$$

✓ Recall that u satisfies $u_t + au_x = 0$.

(iii) Properties of the Le

✓ What do we need to **store** to compute v^{n+1} in the Leapfrog scheme?

✓ **Initial Values?**

Exercise Set #4 - Exercise 3

Exercise 3: Stability of the Lax-Friedrichs Method

- As a possible numerical method for the linear transport equation $u_t + au_x = 0$, consider the Lax-Friedrichs method

$$v_j^{n+1} = \frac{1}{2}(v_{j+1}^n + v_{j-1}^n) - \frac{ak}{2h}(v_{j+1}^n - v_{j-1}^n) \quad (9)$$

- Show that this method is stable in the l^∞ norm, provided that k and h satisfy the *CFL condition*

$$\frac{|a|k}{h} \leq 1. \quad (10)$$

Exercise Set #4 - Exercise 3 - Hints

Exercise 3: Stability of the Lax-Friedrichs Method

- To show that the Lax-Friedrichs (LF) scheme is stable provided

$$\frac{|a|k}{h} \leq 1, \quad (11)$$

we show that $\|\mathcal{H}^n\|_\infty$ is bounded for all n , where $\mathcal{H}$ is the operator defined by

$$\mathcal{H}v_j = \frac{1}{2} (v_{j+1} + v_{j-1}) - \frac{ak}{2h} (v_{j+1} - v_{j-1}). \quad (12)$$

- That is, the LF scheme is given by $v^{n+1} = \mathcal{H}v^n$.
- To do so, we suppose v is some grid function, and calculate the norm of $\mathcal{H}v$.
- Prove

$$\|\mathcal{H}^n\|_\infty \leq \|\mathcal{H}\|_\infty^n \leq 1 \quad \forall n \in \mathbb{N}. \quad (13)$$

Exercise Set #4 - Exercise 4

Exercise 4: Unconditionally Stable Method

- We have seen in the previous exercise that the Lax-Friedrichs method is **stable** provided k and h satisfy a CFL condition.
- A method which is stable for any k and h is said to be **unconditionally stable**.
- For $a > 0$, prove that the following backward-time backward-space method

$$v_j^{n+1} = v_j^n - \frac{ak}{h} (v_j^{n+1} - v_{j-1}^{n+1})$$

is unconditionally stable in the l^∞ norm.

- Assume **periodic boundaries**.

Exercise Set #4 - Exercise 4

Exercise 4: Unconditionally Stable Method

- Consider the scheme

$$v_j^{n+1} = v_j^n - \lambda \left(v_j^{n+1} - v_{j-1}^{n+1} \right), \quad \lambda = \frac{ak}{h}. \quad (14)$$

- Re-write the scheme (assuming periodic boundaries) as

$$(1 + \lambda) v_j^{n+1} - \lambda v_{j-1}^{n+1} = v_j^n \quad \implies \quad Av^{n+1} = v^n, \quad (15)$$

- Find A and write the scheme in the form $v^{n+1} = \mathcal{H}v^n$, where $\mathcal{H} = A^{-1}$,
- Prove that A is non-singular by using Gershgorin's theorem.
- Use the following result.

$$\|A^{-1}\|_\infty \leq \frac{1}{\alpha}, \quad \alpha = \min_k \left(|A_{kk}| - \sum_{j \neq k} |A_{kj}| \right). \quad (16)$$

Exercise Set #4 - Exercise 5

Exercise 5: Unconditionally Stable Method

- Consider the scalar advection equation $u_t + au_x = 0$ with $a = 1$.
- Let u be the solution of $u_t + au_x = 0$ in $(-1, 1)$ that satisfies initial condition

$$u(x, 0) = u_0(x), \quad (17)$$

where

$$u_0(x) = \begin{cases} 1 & x < 0 \\ 0 & x > 0 \end{cases}, \quad (18)$$

and boundary conditions

$$u(-1, t) = 1 \quad u(1, t) = 0 \quad (19)$$

- We already know that the exact solution for $0 < t < 1$ is given by $u_0(x - at)$,
- How well do numerical methods approximate such a problem?

Exercise Set #4 - Exercise 5

Exercise 5: Unconditionally Stable Method

- In the following consider the schemes

$$\text{Upwind: } v_j^{n+1} = v_j^n - \frac{ak}{h} (v_j^n - v_{j-1}^n)$$

$$\text{Lax-Friedrichs: } v_j^{n+1} = \frac{1}{2} (v_{j+1}^n + v_{j-1}^n) - \frac{ak}{2h} (v_{j+1}^n - v_{j-1}^n)$$

$$\begin{aligned} \text{Lax-Wendroff: } v_j^{n+1} = & v_j^n - \frac{ak}{2h} (v_{j+1}^n - v_{j-1}^n) \\ & + \frac{(ak)^2}{2h^2} (v_{j+1}^n - 2v_j^n + v_{j-1}^n) \end{aligned}$$

$$\begin{aligned} \text{Beam-Warming: } v_j^{n+1} = & v_j^n - \frac{ak}{2h} (3v_j^n - 4v_{j-1}^n + v_{j-2}^n) \\ & + \frac{(ak)^2}{2h^2} (v_j^n - 2v_{j-1}^n + v_{j-2}^n) . \end{aligned}$$