

19 Systems of Conservation Laws, revisited

We return to our discussion of systems of conservation laws. Suppose we have a linear CL
(linear system of conservation laws)

$$\partial_t \underline{U} + \underline{A} \partial_x \underline{U} = 0$$

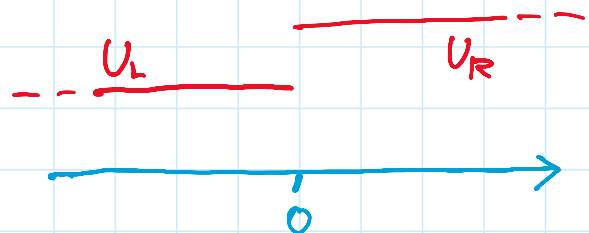
We assume the CL is strictly hyperbolic, so that A is diagonalizable with distinct eigenvalues $\lambda_1 > \lambda_2 > \dots > \lambda_m$

$$\underline{\underline{A}} = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_m \end{pmatrix} \quad \underline{\underline{S}} = \begin{pmatrix} | & | & & | \\ s_1 & s_2 & \dots & s_m \\ | & | & & | \end{pmatrix}$$

$$\underline{\underline{A}} = \underline{\underline{S}} \underline{\underline{\Lambda}} \underline{\underline{S}}^{-1}$$

We consider the Riemann problem of that CL with initial data

$$U_0(x) = \begin{cases} U_L & x < 0 \\ U_R & x > 0 \end{cases}$$



$$U_L = \sum_{i=1}^m \alpha_i s_i,$$

$$U_R = \sum_{i=1}^m \beta_i s_i$$

$$\alpha = (\alpha_1, \alpha_2, \dots, \alpha_m)$$

$$\beta = (\beta_1, \beta_2, \dots, \beta_m)$$

$$U_L = S \alpha$$

$$U_R = S \beta$$

We switch to the "characteristic coordinate system" of the state variable, so that

$$V_{i,0} = \begin{cases} \alpha_i & x < 0 \\ \beta_i & x > 0 \end{cases} \quad V_0 = \begin{pmatrix} V_{1,0} \\ V_{2,0} \\ \vdots \\ V_{m,0} \end{pmatrix}$$

The solution is given by

$$V_i(x,t) = \begin{cases} \alpha_i & \text{if } x < \lambda_i t \\ \beta_i & \text{if } x > \lambda_i t \end{cases} \quad V(x,t) = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{pmatrix}$$

Example

We consider the matrix

$$A = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{pmatrix}$$

$$\lambda_1 = 3, \quad \lambda_2 = 1, \quad \lambda_3 = -1$$

$$S_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

$$S_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

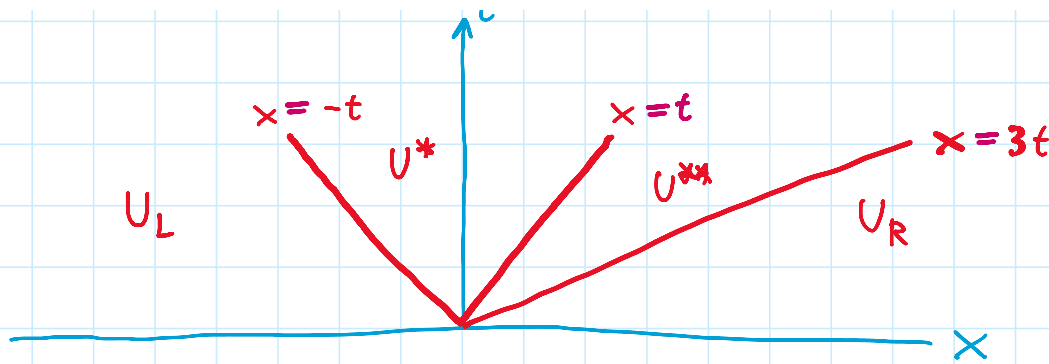
$$S_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

Consider the case

$$U_L = \begin{pmatrix} 2 \\ 1 \\ 0 \end{pmatrix}, \quad U_R = \begin{pmatrix} 0 \\ 0 \\ -2 \end{pmatrix} \quad \Rightarrow \quad \alpha = \begin{pmatrix} \sqrt{2} \\ 1 \\ \sqrt{2} \end{pmatrix}, \quad \beta = \begin{pmatrix} \sqrt{2} \\ 1 \\ -\sqrt{2} \end{pmatrix}$$

The solution can be depicted as follows

$\uparrow t$



We have

$$\begin{aligned}
 U_L &= \alpha_1 S_1 + \alpha_2 S_2 + \alpha_3 S_3 \\
 U^* &= \alpha_1 S_1 + \alpha_2 S_2 + \beta_3 S_3 \\
 U^{**} &= \alpha_1 S_1 + \beta_2 S_2 + \beta_3 S_3 \\
 U_R &= \beta_1 S_1 + \beta_2 S_2 + \beta_3 S_3
 \end{aligned}$$

As a rule of thumb, we have $m-1$ intermediate states

The solution will generally have m discontinuities and $m-1$ intermediate states

The jump across the p -th discontinuity

$$[u]_p = (\beta_p - \alpha_p) S_p \quad 1 \leq p \leq m$$

$$\begin{aligned}
 [f]_p &= \underline{A} [u]_p = (\beta_p - \alpha_p) \underline{A} S_p \\
 &= (\beta_p - \alpha_p) \lambda_p S_p = \lambda_p [u]_p
 \end{aligned}$$

$$\text{Thus } [f]_p = \lambda_p [u]_p \quad (\text{RH condition})$$

We see

$$\underline{U}_1 - \underline{U}_n = U_1 - U^* + U^* - U^{**} + \dots - U_n$$

$$\begin{aligned}
\underline{U}_L - \underline{U}_R &= \underbrace{\underline{U}_L - \underline{U}^*}_{[U]_m} + \underbrace{\underline{U}^* - \underline{U}^{**}}_{[U]_{m-1}} + \dots - \underline{U}_R \\
&= [U]_1 + [U]_2 + \dots + [U]_m \\
&= \sum_{p=1}^m [U]_p \\
&= \sum_{p=1}^m (\beta_p - \alpha_p) \underline{S}_p = \underline{S} (\beta - \alpha)
\end{aligned}$$

So we can describe the solution to the Riemann problem

1. Find eigenvalues and -vectors
2. Assemble intermediate states by formula above

Example

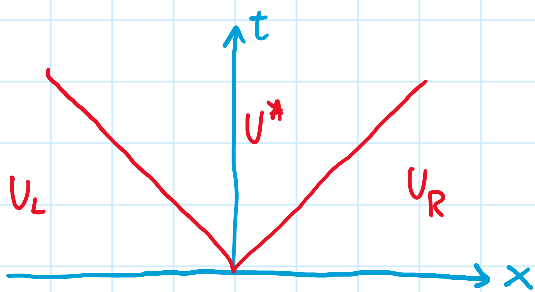
$$\underline{A} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\lambda_1 = 1$$

$$\lambda_2 = -1$$

$$S_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$S_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$



$$A(U^* - U_L) = -(U^* - U_L) \quad (1)$$

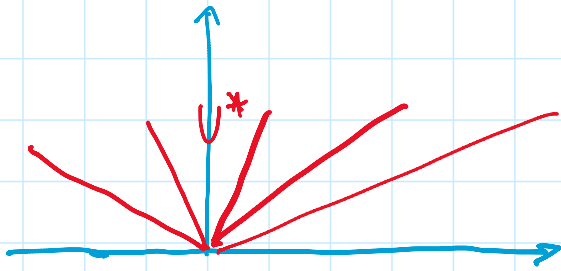
$$A(U_R - U^*) = +(U_R - U^*) \quad (2)$$

$$(1) + (2) \Rightarrow A(U_R - U_L) = U_L + U_R - 2U^*$$

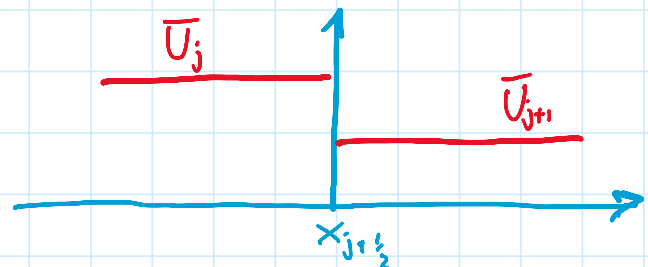
$$\Rightarrow U^* = \frac{1}{2}(U_R + U_L) - \frac{1}{2}A(U_R - U_L)$$

Let us revisit the flux in the finite volume method

$$\partial_t U + \underline{A} \partial_x U = 0$$



What is $F = f(U^*)$



$$\bar{U}_j = \sum \alpha_i$$

$$\bar{U}_{j+1} = \sum \beta_i$$

We find that

$$\lambda_1, \dots, \lambda_q > 0$$

$$\lambda_{q+1}, \dots, \lambda_m < 0$$

$$U(x, t) = \sum_{i=1}^q \alpha_i \underline{S}_i + \sum_{i=q+1}^m \beta_i \underline{S}_i$$

$$= \bar{U}_j + \sum_{i=q+1}^m \underbrace{(\beta_i - \alpha_i)}_{\gamma_i} \underline{S}_i$$

$$= \bar{U}_{j+1} - \sum_{i=1}^q (\beta_i - \alpha_i) \underline{S}_i$$

Now we see

$$U(x_{j+1/2}, t) = \bar{U}_j + \sum_{i: \lambda_i < 0} \gamma_i \underline{S}_i$$

$$= \bar{U}_{j+1} - \sum_{i: \lambda_i > 0} \gamma_i \underline{S}_i$$

$$= \bar{U}_{j+1} - \sum_{i: \lambda_i > 0} x_i \underline{S}_i$$

The flux becomes

$$F_{j+\frac{1}{2}} = \underline{A} U^* = \underline{A} \bar{U}_j + \sum_{i: \lambda_i < 0} x_i \lambda_i \underline{S}_i$$

$$\underline{A} \bar{U}_{j+1} - \sum_{i: \lambda_i > 0} x_i \lambda_i \underline{S}_i$$

Yet another approach

$$\underline{A}^\pm = \underline{S} \underline{\Lambda}^\pm \underline{S}^{-1} \quad \text{where}$$

$$\Lambda_{ii}^+ = \max(0, \lambda_i) \quad \Lambda_{ii}^- = \min(0, \lambda_i)$$

$$\text{So we have } \Lambda = \Lambda^+ + \Lambda^-$$

$$\underline{\Lambda}^+ = \begin{pmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \lambda_q & \\ & & & 0 & \ddots & 0 \end{pmatrix} \quad \underline{\Lambda}^- = \begin{pmatrix} 0 & & & \\ & \ddots & & \\ & & 0 & \lambda_{q+1} & \ddots & \\ & & & \ddots & \ddots & \lambda_m \end{pmatrix}$$

$$\text{Since } \bar{U}_{j+1} - \bar{U}_j = \sum_{i=1}^m x_i \underline{S}_i$$

$$\text{we have } \underline{A} (\bar{U}_{j+1} - \bar{U}_j) = \sum_{i=1}^m x_i \lambda_i \underline{S}_i$$

We summarize

$$F_{j+\frac{1}{2}} = \underline{A} \bar{U}_j + \underline{A}^- (\bar{U}_{j+1} - \bar{U}_j) \quad (3)$$

$$F_{j+\frac{1}{2}} = \underline{\underline{A}} \bar{U}_j + A^- (\bar{U}_{j+1} - \bar{U}_j) \quad (3)$$

$$= \underline{\underline{A}} \bar{U}_{j+1} - A^+ (\bar{U}_{j+1} - \bar{U}_j) \quad (4)$$

Average (3) and (4) :

$$F_{j+\frac{1}{2}} = \frac{1}{2} \underline{\underline{A}} (\bar{U}_j + \bar{U}_{j+1}) + \frac{1}{2} (A^- - A^+) (\bar{U}_{j+1} - \bar{U}_j)$$

$$= \frac{1}{2} \underline{\underline{A}} (\bar{U}_j + \bar{U}_{j+1}) - \frac{1}{2} |A| (\bar{U}_{j+1} - \bar{U}_j)$$

$$\text{where } |A| = \underline{\underline{S}} |\Lambda| \underline{\underline{S}}^{-1}$$

$$|\Lambda| = \begin{pmatrix} |\lambda_1| & & & \\ & |\lambda_2| & & \\ & & \ddots & \\ & & & |\lambda_m| \end{pmatrix}$$

We observe that

$$f(U) = \underline{\underline{A}} \cdot U \quad \|\underline{\underline{A}}\|_2 \leq |\lambda_1|$$

We can define

$$F_{j+\frac{1}{2}} := \frac{f(\bar{U}_j) + f(\bar{U}_{j+1})}{2} - \frac{1}{2} |\lambda_1| (\bar{U}_{j+1} - \bar{U}_j)$$

$\Rightarrow$ Lax - Friedrich