

# Numerical Analysis and Computational Mathematics

Fall Semester 2024 - CSE Section

Prof. Laura Grigori

Assistant: Israa Fakih

Session 2 – September 18, 2024

# Solutions – Nonlinear equations: bisection and Newton methods

#### Solution I (MATLAB)

a) We consider the following implementation of the MATLAB function bisection.m:

```
function [xvect, esterrvect, resvect, nit] = bisection(fun, a, b, tol, nmax)
% BISECTION Find a zero of a nonlinear scalar function inside an interval.
  XVECT=BISECTION (FUN, A, B, TOL, NMAX) finds a zero of the continuous
  function FUN in the interval [A,B] using the bisection method and returns
   a vector XVECT containing the successive approximations of the zero (iterates).
   FUN accepts real scalar input x and returns a real scalar value;
   FUN can also be an inline object.
   TOL is the tolerance on error allowed and NMAX the maximum number of iterations.
   If the search fails an error message is displayed.
   [XVECT, ESTERRVECT, RESVECT, NIT] = BISECTION (FUN, ...) also returns the vector
    ESTERRVECT of error estimators for each iterate, the vector RESVECT of residual
    evaluations for each iterate, and NIT the number of iterations.
   Note: the length of the vectors is equal to ( NIT + 1 ).
if a \ge b
   error(' b must be greater than a (b > a)');
% evaluate f at the endpoints
fa = fun(a);
fb = fun(b);
if sign(fa) * sign(fb) > 0
   error(' The sign of FUN at the extrema of the interval must be different');
if fa == 0 % a is the solution
   xvect = a; fx = 0; esterr = 0; nit = 0;
   resvect = fx; esterrvect = esterr;
```

```
elseif fb == 0 % b is the solution
  xvect = b; fx = 0; esterr = 0; nit = 0;
  resvect = fx; esterrvect = esterr;
  return
end
nit = 0;
xvect = []; resvect = []; esterrvect = [];
% initial approximate solution
x = (a + b) / 2;
% initial error estimator is the half of the length of the interval
esterr = (b - a) / 2;
fx = fun(x);
xvect = x;
resvect = fx;
esterrvect = esterr;
% loop until convergence or maximum number of iterations reached
while esterr ≥ tol && nit < nmax
  if fx == 0 % we found the solution
    return;
   end
   if sign(fx) * sign(fa) < 0 % alpha is in (a,x)
   elseif sign(fx) * sign(fb) < 0 % alpha is in (x,b)
    a = x;
   else
    error('Algorithm not operating correctly');
   % calculate mid-point of updated interval
  x = (a + b) / 2;
   % the error estimator is now half of the previous one
  esterr = esterr / 2;
  fx = fun(x);
  xvect = [xvect, x];
  resvect = [resvect, fx];
   esterrvect = [esterrvect, esterr];
  nit = nit + 1;
end
if esterrvect(end) > tol
  warning(['bisection stopped without converging to the desired tolerance ',...
            'because the maximum number of iterations was reached']);
end
return
```

We solve the nonlinear equation f(x) by considering the following commands, taking  $tol = 10^{-1}$  as tolerance:

```
fun = @(x) sin(2*x) - 1 + x;
a = -1; b = 3; tol = 1e-1; nmax = 100;
[xvect, esterrvect, resvect, nit] = bisection(fun, a, b, tol, nmax);
```

```
x.nit = xvect( nit+1 ) % last iterate (approximated zero)
nit
% x.nit =
%
%     0.3125
%     nit =
%
%     5
```

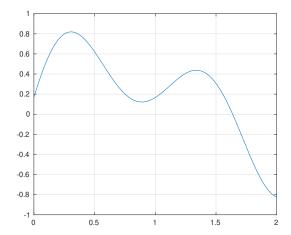
We observe that the bisection method converges in n = 5 iterations to the approximate zero  $x^{(5)} = 0.3125$ .

- b) If we decrease the tolerance to the suggested values ( $tol = [10^{-2}, 10^{-3}, 10^{-4}]$ ), we obtain the approximate solutions [ $x^{(8)} = 0.3516, x^{(11)} = 0.3525, x^{(15)} = 0.3522$ ], respectively (the numbers in bracket represent again the iterations needed by the algorithm to converge).
- c) Note that, above, we have made the algorithm more robust by adding several checks on the input arguments and on some edge cases, and by displaying warning/error messages that can help the user if something goes wrong.

## Solution II (Theoretical and MATLAB)

a) We consider the following MATLAB commands to plot the function f(x):

```
fun = @(x) (1-x) .* sin(4*x) + 1/6;
a = 0; b = 2;
xv = linspace(a,b,1001); % xv=[a:(b-a)/1000:b]
plot(xv, fun(xv)); grid on
```



The conditions that need to be satisfied in order to apply the bisection method are the continuity of f(x) in [a,b] and f(a)f(b) < 0 (i.e. f must change its sign over (a,b)). In our example, these conditions are satisfied, since  $f(x) \in C^{\infty}([0,2])$ , f(0) = 1/6 > 0, and  $f(2) = -\sin(8) + 1/6 < 0$ . The conditions imply that there exists at least one zero in the

interval (0,2). By referring to the previous plot, we deduce that the zero  $\alpha \in (0,2)$  is also unique.

b) The error estimator (error bound) at the *n*th iteration of the bisection method is  $\tilde{e}^{(n)} = (b-a)/2^{n+1}$ , so that:

$$e^{(n)} = |x^{(n)} - \alpha| \le \tilde{e}^{(n)} = \frac{b-a}{2^{n+1}}, \quad n = 0, 1, \dots, \infty.$$

Thus, the stopping criterion based on the error estimator implies that n needs to satisfy  $\tilde{e}^{(n)} < \epsilon$ . Taking the logarithm on both sides yields

$$n_{min} > \log_2\left(\frac{b-a}{\epsilon}\right) - 1 = \frac{\log(b-a) - \log(\epsilon)}{\log 2} - 1.$$

We obtain the condition  $n_{min} > 19.9316$ , so  $n_{min} = 20$  iterations will suffice.

c) We consider the following MATLAB commands:

```
tol = 1e-6; nmax = 100;
[xvect,esterrvect,resvect,nit] = bisection(fun,a,b,tol,nmax);
% NOTE: the first entry of the vector xvect contains the initial guess of
% the zero obtained for n=0, i.e. the mid point of the interval [a,b]
resvect( 19 + 1 )
resvect( 20 + 1 )
% ans =
%
% -1.3514e-06
%
% ans =
%
% 1.2434e-06
```

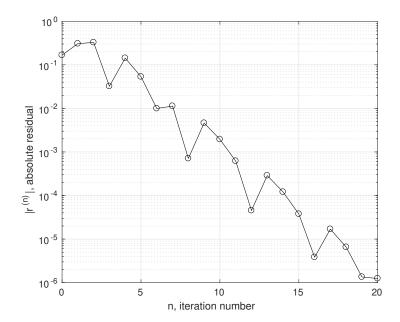
Therefore, we have  $r^{(19)} = -1.3514 \cdot 10^{-6}$  and  $r^{(20)} = 1.2434 \cdot 10^{-6}$ .

d) The residuals of the bisection method are not converging monotonically, and neither are the errors. We verify this property for the function f(x) by plotting the absolute residuals  $|r^{(n)}|$  vs. n with the following MATLAB commands:

```
tol = 1e-6; nmax = 100;
[xvect,esterrvect,resvect,nit] = bisection(fun,a,b,tol,nmax);
% NOTE: the first entry of the vector xvect contains the initial guess of
% the zero obtained for n=0, i.e. the mid point of the interval [a,b]
resvect( 19 + 1 )
resvect( 20 + 1 )
nvect = 0 : nit;
resvect_abs = abs( resvect );
semilogy( nvect, resvect_abs, '-ok' ); grid on
```

e) We consider the following MATLAB commands to obtain the plot representing the sequence  $a_n$  vs. the number of iterations n.

```
alpha = xvect( 20 + 1 ); % approximation of exact zero (alpha)
```



```
nv = [ 0 : 18 ];
nv_ind = nv + 1; % Matlab indexes start from 1
err_n_plus_1 = abs( xvect( nv_ind + 1 ) - alpha );
err_n = abs( xvect( nv_ind ) - alpha );
a_n = err_n_plus_1 ./ err_n;
plot( nv, a_n, '--k*' ); grid on
```

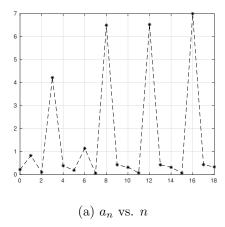
As with the residuals, the convergence of the error  $e^{(n)} = |x^{(n)} - \alpha|$  is not monotonic wrt n in this case, see also point f), Subfigure (a). Therefore, a coefficient  $\mu$  representing the asymptotic convergence factor cannot be deduced from the sequence  $a_n$ , and we cannot infer that the convergence is linear. However, note that this does not mean that the method does not converge.

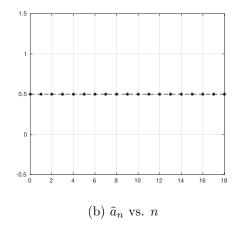
f) Since  $\tilde{e}^{(n)} = (b-a)/2^{n+1}$  and  $\tilde{e}^{(n+1)} = (b-a)/2^{n+2}$ , it follows that  $\tilde{a}_n := \tilde{e}^{(n+1)}/\tilde{e}^{(n)} = \nu = 1/2$  for all  $n \ge 0$ , and the sequence of the error estimators  $\left\{\tilde{e}^{(n)}\right\}_{n=1}^{\infty}$  converges linearly by definition (the order of convergence is 1). We obtain the plot of the sequence  $\tilde{a}_n$  vs. n in Subfigure (b) by using the following commands:

```
esterr_n_plus_1 = ( b - a ) ./ 2.^( nv + 1 );
esterr_n = ( b - a ) ./ 2.^( nv );
a_tilde_n = esterr_n_plus_1 ./ esterr_n;
plot( nv, a_tilde_n, '--k*' ); grid on
```

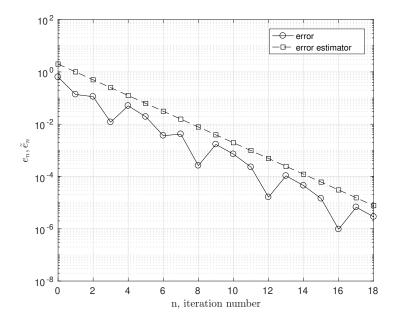
We verify graphically that  $\nu=1/2<1$ . Even if we cannot establish the convergence order of the bisection method according to definition (1) (i.e. for the error  $e^{(n)}=|x^{(n)}-\alpha|$ ), we observe that the error estimators (bounds)  $\{\tilde{e}^{(n)}\}_{n=1}^{\infty}$  represent a dominating sequence of the errors  $\{e^{(n)}\}_{n=1}^{\infty}$ , i.e.:

$$e^{(n)} = |x^{(n)} - \alpha| \le \tilde{e}^{(n)}, \quad n = 0, 1, \dots, \infty.$$





In this case, the behavior of the error resembles that of the estimator, which converges with order 1. We verify this by plotting the errors  $e^{(n)}$  and error estimators  $\tilde{e}^{(n)}$  vs. n with the following commands:

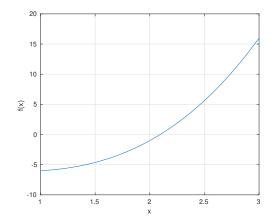


We remark again that the method does not have order 1 because the error is not monotonically decreasing.

## Solution III (Theoretical and MATLAB)

a) Since  $f(x) \in C^0([1,3])$  and f(1)f(3) < 0, there exists at least one zero  $\alpha \in (1,3)$ . By studying the function f(x) in (1,3) we deduce that the zero  $\alpha$  is also unique since f(1) < 0 and the

function is strictly increasing; indeed, the first derivative of f(x) is strictly positive in the interval:  $f'(x) = 3x^2 - 2 > 0$  for all  $x \in [1,3]$ .



b) The Newton method reads:

$$x^{(n+1)} = x^{(n)} - \frac{f(x^{(n)})}{f'(x^{(n)})} = x^{(n)} - \frac{(x^{(n)})^3 - 2x^{(n)} - 5}{3(x^{(n)})^2 - 2} \quad \text{for } n = 0, 1, 2, \dots,$$

until a stopping criterion is satisfied, provided that  $f'(x^{(n)}) \neq 0$  for all  $n = 0, 1, 2, \ldots$ 

c) We use MATLAB to determine the first three approximate zeros. We consider the following commands:

```
fun = @(x) x.^3 - 2*x - 5;
dfun = @(x) 3*x.^2 - 2;
newton.iterate = @(xn) xn - fun(xn) / dfun(xn);
x0 = 1.5;
x1 = newton.iterate(x0)
x2 = newton.iterate(x1)
x3 = newton.iterate(x2)
% x1 =
%
% 2.4737
%
% x2 =
%
% 2.1564
%
% x3 =
%
% 2.0966
```

We deduce that the first three approximate zeros, starting from  $x^{(0)}=1.5$ , are  $x^{(1)}=2.4737$ ,  $x^{(2)}=2.1564$  and  $x^{(3)}=2.0966$ . Note that  $\alpha\simeq 2.0946$ .