### **Networks**

#### Introduction and definitions

Michel Bierlaire

Introduction to optimization and operations research



### **Definitions**

#### Motivation

- Networks are everywhere.
- ▶ We introduce a mathematical formalism that mimics the structure of real networks.

## Road networks



# Public transportation networks



# Electricity networks



## Gas networks



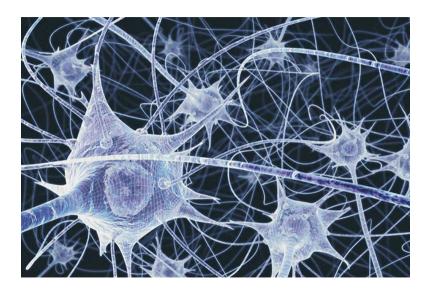
# Water networks



# Computer networks



## Neural networks



# Social networks



### **Networks**

### Concept

System of interconnected people or things.

#### Main features

- Local complexity is low.
- Global complexity is high.

## Mathematical object

Similar property: designed to capture complex structures with simple elements.

### **Networks**

### Concept

System of interconnected people or things.

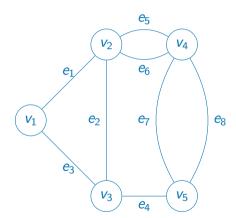
## Vocabulary

- people or thing: vertex, node.
- connection: edge: link (undirected), arc (directed).
- structure: graph (no data), network (with data).

## Undirected graph

#### **Definition**

- ▶ V: set of vertices.
- $\triangleright$   $\mathcal{E}$ : set of edges.
- $ightharpoonup \phi: \mathcal{E} o \mathcal{P}_2(\mathcal{V})$ : incidence function.



# Graph

### Example

$$\mathcal{V} = \{v_1, v_2, v_3, v_4, v_5\},\$$

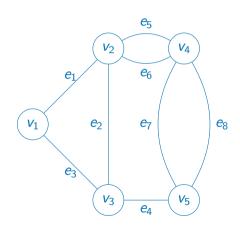
$$\mathcal{E} = \{e_1, e_2, e_3, e_4, e_5, e_6, e_7, e_8\},\$$

$$\phi(e_1) = \{v_1, v_2\}, \ \phi(e_2) = \{v_2, v_3\},\$$

$$\phi(e_3) = \{v_1, v_3\}, \ \phi(e_4) = \{v_3, v_5\},\$$

$$\phi(e_5) = \{v_2, v_4\}, \ \phi(e_6) = \{v_2, v_4\},\$$

$$\phi(e_7) = \{v_4, v_5\}, \ \phi(e_8) = \{v_4, v_5\}.$$

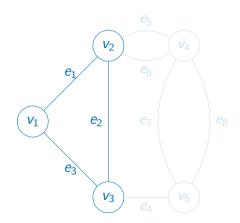


## Subgraph

#### **Definition**

 $(\mathcal{V}', \mathcal{E}', \phi')$  is a subgraph of  $(\mathcal{V}, \mathcal{E}, \phi)$  if

- $\triangleright \mathcal{V}' \subset \mathcal{V}$ .
- $\triangleright \mathcal{E}' \subset \mathcal{E}$ .
- $ightharpoonup \phi'(e) = \phi(e)$ , for each  $e \in \mathcal{E}'$ ,
- ▶ for each  $e \in \mathcal{E}'$ , if  $\phi'(e) = \{i, j\}$ , then i and j both belong to  $\mathcal{V}'$ .



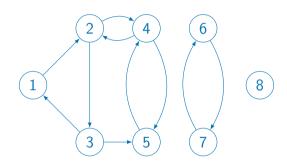
## Directed graph

#### **Definition**

- $\triangleright \mathcal{N}$ : set of nodes.
- ► A: set of arcs.
- $\phi: \mathcal{A} \to \mathcal{N} \times \mathcal{N}$ : incidence function.

### Assumption

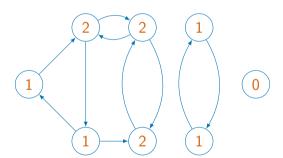
- $ightharpoonup \phi$  is injective.
- For each (i,j), there is at most one a such that  $\phi(a) = (i,j)$ .
- ightharpoonup Arcs are denoted by (i, j).



# Indegree

### Definition

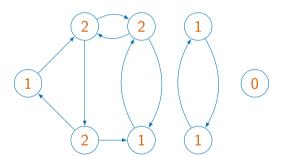
 $d_i^-$ : number of arcs (j, i).



# Outdegree

### Definition

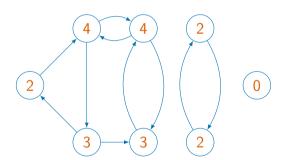
 $d_i^+$ : number of arcs (i, j).



# Degree

## Definition

$$d_i=d_i^-+d_i^+.$$



## Cuts



#### Motivation

- Just as cities are separated into two banks by a river, it may be convenient to separate a directed graph into two sets of nodes.
- ► This is called a cut.

# Directed graph: $(\mathcal{N}, \mathcal{A}, \phi)$

#### Cut

A cut  $\Gamma$  is

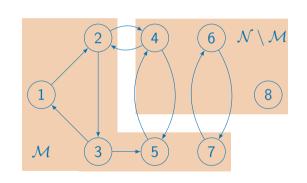
- ► an ordered partition of the nodes
- ▶ into two non empty subsets:

$$\Gamma = (\mathcal{M}, \mathcal{N} \setminus \mathcal{M}),$$

where  $\mathcal{M} \subseteq \mathcal{N}$  and  $\mathcal{M} \neq \emptyset$ .

#### Ordered

$$(\mathcal{M}, \mathcal{N} \setminus \mathcal{M}) \neq (\mathcal{N} \setminus \mathcal{M}, \mathcal{M})$$



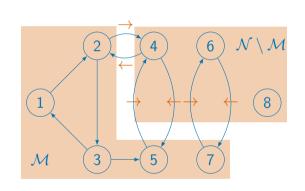
## **Definitions**

#### Forward arcs

$$\Gamma^{\rightarrow} = \{(i,j) \in \mathcal{A} | i \in \mathcal{M}, j \not\in \mathcal{M}\}.$$

#### Backward arcs

$$\Gamma^{\leftarrow} = \{(i,j) \in \mathcal{A} | i \notin \mathcal{M}, j \in \mathcal{M}\}.$$



## **Paths**



#### Motivation

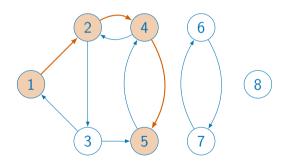
- Networks are designed to connect elements.
- The concept of paths describe how two elements in the network can be connected to each other.

#### Definition

- Sequence of nodes, each pair of consecutive nodes being directed with forward or backward.
- Simple path: no repeated node.
- Forward path: no backward arc.

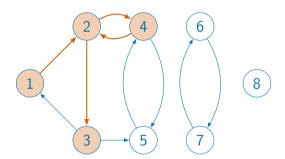
## Simple forward path

$$1 o 2 o 4 o 5 \ P^{ o}=(1,2),(2,4),(4,5), \ P^{\leftarrow}=\emptyset$$



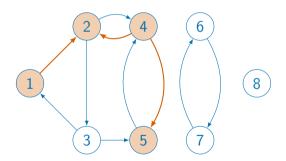
## Forward path

$$1 o 2 o 4 o 2 o 3$$
  $P^{ o} = (1,2), (2,4), (4,2), (2,3), \ P^{\leftarrow} = \emptyset$ 



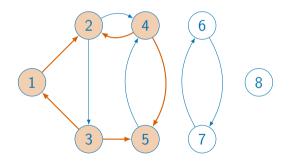
# Simple path

$$1 \to 2 \leftarrow 4 \to 5$$
  
 $P^{\to} = (1,2), (4,5)$   
 $P^{\leftarrow} = (4,2)$ 



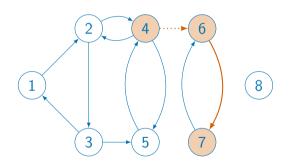
## Simple cycle

$$1 \rightarrow 2 \leftarrow 4 \rightarrow 5 \leftarrow 3 \rightarrow 1$$
  
 $P^{\rightarrow} = (1, 2), (4, 5), (3, 1)$   
 $P^{\leftarrow} = (4, 2), (3, 5)$ 



# Invalid path





## Paths and connected components

#### Motivation

- There are many paths in a network.
- Some are long, some are short.
- ▶ Later on, we will be interested in finding the shortest or the longest path between two nodes.
- ▶ And, sometimes, there is no path connecting two nodes.
- We formalize these concepts now.

## Longest simple path

#### Lemma 21.5

- Consider a directed graph with *m* nodes.
- ▶ The maximum number of arcs in a simple path is m-1.

#### Proof

- ▶ Suppose that a simple path visiting all the *m* nodes exist.
- ▶ It has exactly m-1 arcs.
- Extend by one more arc: not simple anymore.
- ▶ If there is no such path: the longest has less than m-1 arcs.

## Finite number of simple paths

#### Lemma 21.6

- ▶ Consider a directed graph with m nodes,  $m \ge 2$ .
- Consider an origin node o and a destination node d.
- ▶ There is a finite number of simple paths between o and d.

#### Proof

- ightharpoonup Consider 2 < k < m.
- Each simple path containing k nodes corresponds to a permutation of k-2 nodes.
- For each k, the number of permutations is finite.
- As  $k \leq m$ , the total number is finite.

## Connectivity

### Connected graph

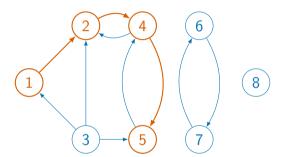
Every pair of nodes is connected with a path.

### Strongly connected graph

Every pair of nodes is connected with a path containing only forward arcs.

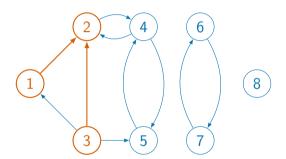
# Connectivity

Nodes 1 and 5 are strongly connected.



# Connectivity

Nodes 1 and 3 are connected.



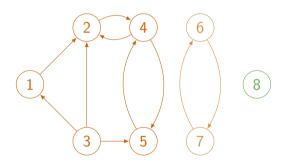
## Equivalence class

#### "is connected with"

- reflexive.
- symmetric,
- transitive.

### Connected component

- ightharpoonup subgraph  $G' = (\mathcal{N}', \mathcal{A}', \phi')$ ,
- $\triangleright$   $\mathcal{N}'$  is an equivalence class on  $\mathcal{N}$  for the relation "is connected with".



## Equivalence class

#### Note

The relation "is strongly connected with" is not symmetric, and does not represent an equivalence class.

### Trees

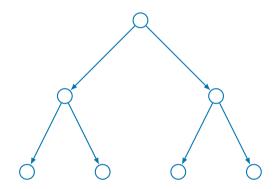


#### Motivation

- ➤ We introduce a family of graphs called "trees".
- ► They are useful in many applications.

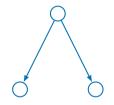
### Tree

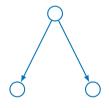
- ► Connected graph,
- without cycle.



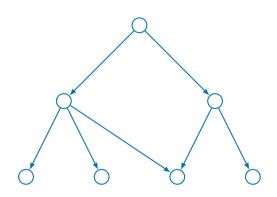
#### Not a tree

Not connected. Sometimes called a forest, as each connected component is a tree.

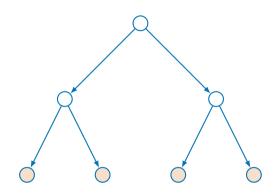




Not a tree Contains a cycle.



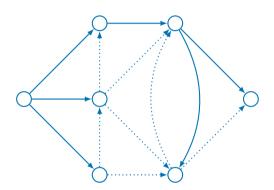
Leaf
Node of degree 1.



# Spanning tree

#### **Definition**

- ▶ Consider the graph  $(V, \mathcal{E}, \phi)$ .
- ▶ The subgraph  $(\mathcal{V}, \mathcal{E}', \phi')$
- $\blacktriangleright$  is a spanning tree of  $(\mathcal{V}, \mathcal{E}, \phi)$ ,
- ▶ if it is a tree.



## Properties of trees

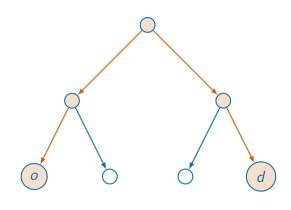
#### Motivation

- ► Trees have some interesting properties
- ▶ We review some of them.
- ▶ We also provide some characterizations of tree, involving these properties.

### Lemma 21.9

# A tree with at least one arc has at least two leafs.

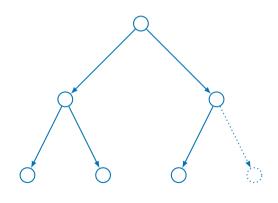
- ▶ Path P with maximum number of arcs.
- First node: o, last node d.
- ▶ As there is no cycle,  $o \neq d$ .
- ▶ Degree of  $o \ge 1$ .
- ▶ If degree of o > 1, another arc can make the path longer. Impossible.
- ▶ Degree of o = 1. It is a leaf.
- $\triangleright$  Same argument for d.



### Number of nodes

# A tree with n arcs has m = n + 1 nodes.

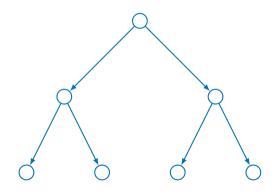
- ightharpoonup Obvious for n=1.
- Assume true for n = p 1 arcs: there are m = p nodes.
- ▶ Proof for a tree with n = p arcs.
- Consider a leaf.
- Remove one node (the leaf) and one arc (the incident arc).
- ▶ We obtain a tree with p-1 arcs.
- ▶ It has *p* nodes.
- ▶ The original tree has p + 1 nodes.



# Single path

## In a tree, there is exactly one path between any two nodes.

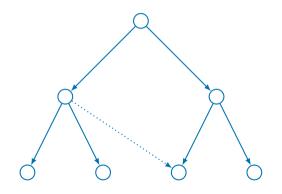
- ► A tree is connected, so there is at least one path.
- ► Suppose there are two different paths.
- ► They form a cycle.
- ► Impossible in a tree.



# Cycle formation

# In a tree, adding any arc forms a cycle.

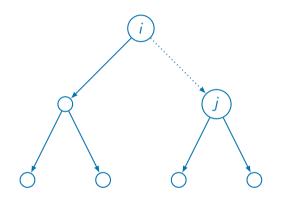
- ightharpoonup Consider adding arc (i, j).
- ► A tree is connected, so there is a path connecting *i* and *j*.
- ► The added arc forms a cycle with the path.



### Disconnection

# In a tree, removing any arc disconnects the graph.

- ightharpoonup Consider arc (i, j).
- ightharpoonup There is a unique path from i to j.
- ► It is the link!
- ▶ Removing it disconnects *i* from *j*.



### Characterization

Consider  $G = (\mathcal{N}, \mathcal{A}, \phi)$  a directed graph with m nodes and n arcs. The following statements are all equivalent.

- ► *G* is a tree;
- ► *G* is connected and without cycles;
- There is a unique simple path connecting any two nodes;
- G has no cycle, and a simple cycle is formed if any arc is added;
- G is connected and the removal of any single arc disconnects the graph;
- ▶ *G* is connected and n = m 1;
- ▶ *G* has no simple cycle and n = m 1.

### Flows

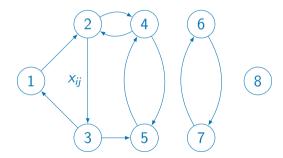


#### Motivation

- Physical networks are often used to transport objects or information: water, electricity, cars, internet packets, etc.
- We provide a generic representation of flows of these objects, and associate them with the graph.
- ▶ In our mathematical formalism, a directed graph is called a network when its nodes and arcs are associated with quantities.
- ► The first of the quantities is the flow

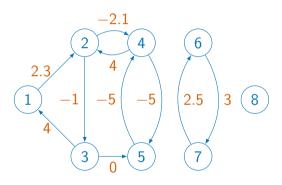
$$x_{ij} \in \mathbb{R}$$

- ► Amount of "things" traversing the arc during a given time period.
- ightharpoonup Associated with each arc (i, j).
- Units are arbitrary and context dependent.
- ► Time period is irrelevant and long enough.
- ► The sign corresponds to the direction.



$$x_{ii} \in \mathbb{R}$$

- ► Amount of "things" traversing the arc during a given time period.
- ightharpoonup Associated with each arc (i, j).
- Units are arbitrary and context dependent.
- ► Time period is irrelevant and long enough.



# Flow through a cut

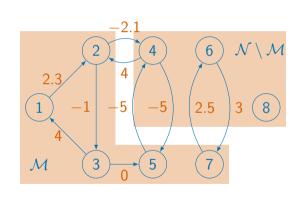
$$X(\Gamma) = \sum_{(i,j)\in\Gamma^{\to}} x_{ij} - \sum_{(i,j)\in\Gamma^{\leftarrow}} x_{ij},$$

$$\sum_{(i,j)\in\Gamma^{\to}} x_{ij} = x_{24} + x_{54} + x_{76} = -2.1 - 5 + 2.5 = -4.6$$

$$\sum_{(i,j)\in\Gamma^{\leftarrow}} x_{ij} = x_{42} + x_{45} + x_{67} = 4 - 5 + 3 = 2.$$

Total flow through the cut:

$$-4.6 - 2 = -6.6$$
.



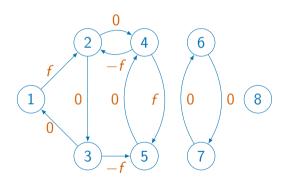
# Simple path flow

 $x \in \mathbb{R}^n$  such that

$$x_{ij} = \left\{ egin{array}{ll} f & ext{if } (i,j) \in P^{
ightarrow} \ -f & ext{if } (i,j) \in P^{\leftarrow} \ 0 & ext{otherwise.} \end{array} 
ight.$$

### Example

$$1 \rightarrow 2 \leftarrow 4 \rightarrow 5 \leftarrow 3$$



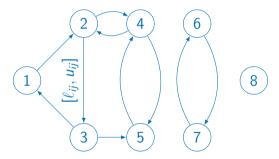
# Capacities

#### Motivation

- ► There is a limit to the quantity of flow that can be transported on each section of a physical network.
- ► For instance, the quantity of water flowing through a pipe depends on the section area.
- ▶ One lane of a highway cannot accommodate more than 2400 veh/h.
- This limit is called the capacity.
- ▶ In our mathematical formalism, we may impose bounds on flows.

$$\ell_{ij} \leq x_{ij} \leq u_{ij}$$
.

- ▶  $\ell_{ij} \in \mathbb{R}$ : minimum quantity of flow.
- ▶  $u_{ij} \in \mathbb{R}$ : maximum quantity of flow.
- ightharpoonup Associated with each arc (i, j).
- ▶ Units are the same as  $x_{ii}$ .
- ► In practice, we often have:
  - $ightharpoonup \ell_{ij} = 0$ , or,
  - $ightharpoonup \ell_{ij} = -u_{ij}$ .



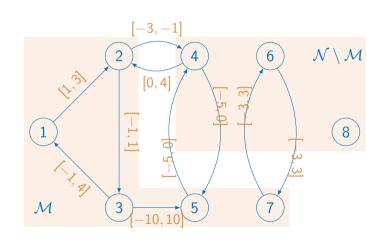
# Capacity of a cut

$$U(\Gamma) = \sum_{(i,j) \in \Gamma^{ o}} u_{ij} - \sum_{(i,j) \in \Gamma^{\leftarrow}} \ell_{ij}.$$

$$\sum_{(i,j)\in\Gamma^{\to}} u_{ij} = u_{24} + u_{54} + u_{76} = -1 + 0 + 3 = 2$$

$$\sum_{\substack{(i,j)\in\Gamma^{\leftarrow}\\\ell_{42}+\ell_{45}+\ell_{67}=0-5-3=-8}} \ell_{ij} =$$

$$U(\Gamma) = 2 - (-8) = 10$$



# Capacity of a cut

Upper bound on the flow

$$X(\Gamma) \leq U(\Gamma)$$
.

Saturated cut

$$X(\Gamma) = U(\Gamma).$$

# Supply and demand

#### Motivation

- Nodes can also be associated with quantities.
- For instance, the supply is a quantity of flow that a node is injecting on a network.
- ▶ In logistics, a warehouse is supplying flow of goods on the network.
- ▶ The demand is a quantity of flow absorbed by a node.
- ▶ In logistics, a customer is collecting the flow from the network.
- We characterizes these notions in our mathematical formalism.

# Divergence

### Flow leaving a node

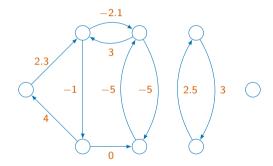
$$\sum_{j|(i,j)\in\mathcal{A}}x_{ij}.$$

$$-2.1-1=-3.1$$

### Flow entering a node

$$\sum_{k|(k,i)\in\mathcal{A}}x_k$$

$$2.3 + 3 = 5.3$$

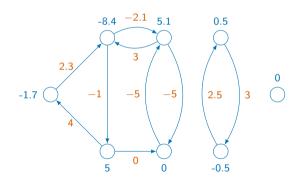


# Divergence

### Divergence

$$\operatorname{\mathsf{div}}(x)_i = \sum_{j \mid (i,j) \in \mathcal{A}} x_{ij} - \sum_{k \mid (k,i) \in \mathcal{A}} x_{ki}.$$

-3.1-5.3 = -8.4



# Supply and demand

## Supply node

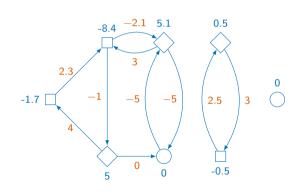
$$\operatorname{div}(x)_i > 0.$$

#### Demand node

 $\operatorname{div}(x)_i < 0.$ 

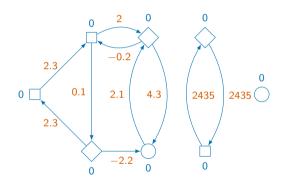
In any case

$$\sum_{i\in\mathcal{M}}\operatorname{div}(x)_i=0$$



### Circulation

 $\operatorname{div}(x)_i = 0, \ \forall i \in \mathcal{N}.$ 



### Costs



#### Motivation

- Moving flow along an arc generate costs.
- In our formalism, we consider proportional costs.
- Modeling costs is not necessarily easy.
- We discuss two common issues.

### Costs

$$c_{ij}, \forall (i,j) \in \mathcal{A}.$$

### Data of the problem

- ightharpoonup Cost of transporting one unit of flow on arc (i, j).
- Unit is arbitrary.
- ▶ Total cost for arc (i, j):

$$C_{ij}X_{ij}$$
.

► Total cost for the network:

$$\sum_{(i,j)\in\mathcal{A}}c_{ij}x_{ij}$$

### Generalized cost



#### Toll road

- travel time (say 30 minutes),
- travel cost (say 10 CHF).

# Value of time 30 CHF/hour or 0.5 CHF/min.

#### Generalized cost

- ► In CHF: 30 min × 0.5 CHF/min + 10 CHF = 25 CHF.
- ► In min: 30 min. + 10 CHF / (0.5 CHF/min) = 50 min.

# Link additivity

Cost of a path

$$C(P) = \sum_{(i,j)\in P^{
ightarrow}} c_{ij}x_{ij} - \sum_{(i,j)\in P^{\leftarrow}} c_{ij}x_{ij}.$$

Cost along a simple path flow

$$C(P) = \sum_{(i,j)\in P^{ o}} fc_{ij} - \sum_{(i,j)\in P^{\leftarrow}} fc_{ij}$$

$$= f(\sum_{(i,i)\in P^{ o}} c_{ij} - \sum_{(i,i)\in P^{\leftarrow}} c_{ij}).$$

# Example



 $\mathsf{GVA} \to \mathsf{ZRH} \to \mathsf{BKK}$  CHF 2412

 $\begin{array}{c} \text{GVA} \rightarrow \text{ZRH} \\ \text{CHF 570} \end{array}$ 

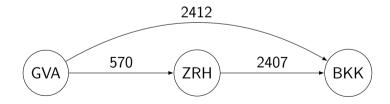
 $ZRH \rightarrow BKK$  CHF 2407

# Modeling

#### First model



#### Second model



## Computer representation

#### Motivation

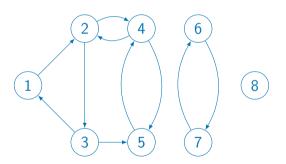
- We, humans, usually use maps or schematics to look at networks.
- We obtain an overview of the overall topology.
- But computers do not have this bird eyes's view.
- ▶ We introduce here two possible representations of networks in a computer.

# Computer representation



# Adjacency matrix

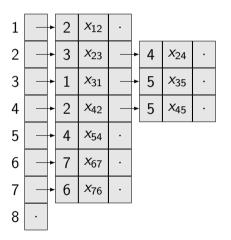
$$A(i,j) = \begin{cases} 1 & \text{if } (i,j) \in \mathcal{A}, \\ 0 & \text{otherwise.} \end{cases}$$

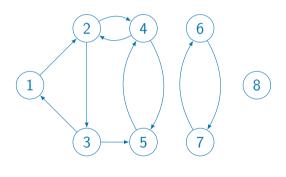


## Adjacency matrix

- Valid representation because the incidence function is injective.
- Arc numbering convention for storing arc quantities.
- Sparse matrix: efficient storage techniques should be used.
- ► For instance, adjacency lists.

# Adjacency lists





# Summary

- Graphs and subgraphs.
- ► Cuts.
- Paths and connected components.
- ► Trees.
- Flows and capacity.
- Supply and demand.
- Costs.
- Computer representations.