

# Numerical Analysis

## GC / SIE

## Linear Systems

Daniel Kressner

Chair for Numerical Algorithms and HPC

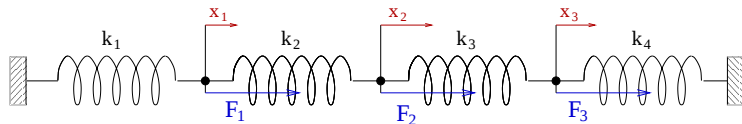
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## A simple example

Let us consider a configuration of springs under some forces. We want to compute the elongation of each spring.



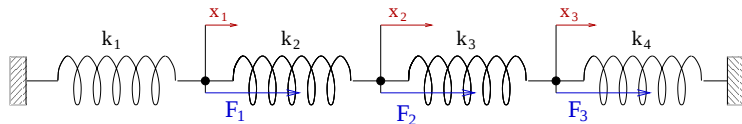
The equilibrium of forces at every node gives

Linear system of 3 equations and 3 unknowns:  $K\mathbf{x} = \mathbf{F}$

After some work, it is possible to obtain a solution by hand.

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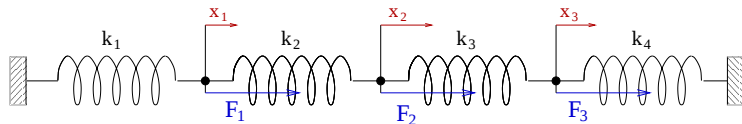
$$\begin{cases} k_1 x_1 + k_2 (x_1 - x_2) = F_1 \\ k_2 (x_2 - x_1) + k_3 (x_2 - x_3) = F_2 \\ k_3 (x_3 - x_2) + k_4 x_3 = F_3 \end{cases}$$

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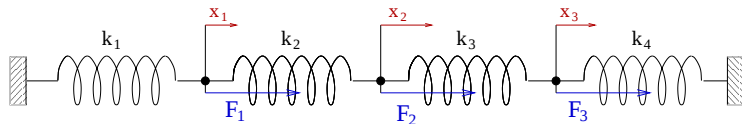
$$\Rightarrow \begin{cases} (k_1 + k_2)x_1 - k_2x_2 & = F_1 \\ -k_2x_1 + (k_2 + k_3)x_2 - k_3x_3 & = F_2 \\ -k_3x_2 + (k_3 + k_4)x_3 & = F_3 \end{cases}$$

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# A more complex application



By imposing the equilibrium of forces at each node, we get a **large linear system of equations** (static case) or a large system of ordinary differential equations system (dynamic case). **Hopeless to solve by hand. Need to use numerical algorithms!**

- ▶ Numerical solution of linear systems.
- ▶ Discretization of differential equations (dynamic case).

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# More complex applications – structural analysis

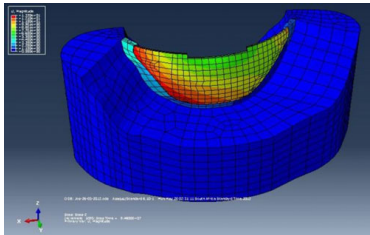


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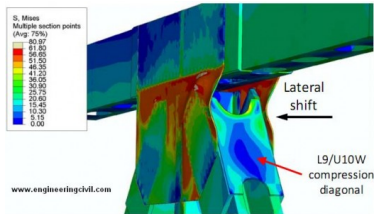


Figure 14. Indicating the lateral shift of the L9/U10W diagonal, with Mises stress contours.

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The structure is divided in many small “cubes” (finite elements). By imposing the equilibrium of forces at each one of them a large linear system is obtained (it may have million of unknowns).

Dealing with such an application relies on the following ingredients:

- ▶ Approximation / Interpolation.
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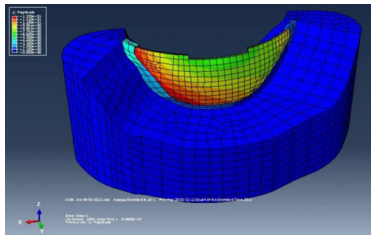


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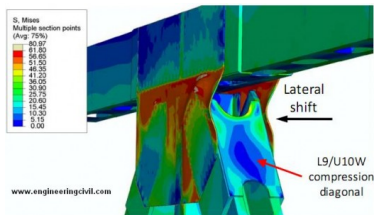


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