

October 17

Divergence theorem

As a specific example, consider the vector field

$$\vec{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3, \quad (x_1, x_2, x_3) \mapsto (x_1, x_2, x_3),$$

the source vector field. Using our parameterization of the sphere,

$$\begin{aligned} \oint_S \vec{F} \cdot \vec{n} \, dG &= \int_0^{2\pi} \int_0^\pi \underbrace{\cos^2 \theta}_{\text{outward pointing}} \sin^3 \varphi + \underbrace{\sin^2 \theta}_{\text{unit normal}} \sin^3 \varphi + \sin \varphi \cos^2 \varphi \, d\varphi \, d\theta \\ &= \int_0^{2\pi} \int_0^\pi \sin^3 \varphi + \sin \varphi \cos^2 \varphi \, d\varphi \, d\theta \\ &= 2\pi \int_0^\pi \sin^3 \varphi + \sin \varphi \cos^2 \varphi \, d\varphi \\ &= 2\pi \int_0^\pi \sin \varphi \left(\underbrace{\sin^2 \varphi + \cos^2 \varphi}_{=1} \right) d\varphi \\ &= 2\pi \underbrace{\int_0^\pi \sin \varphi \, d\varphi}_{=2} = 4\pi \end{aligned}$$

Let's get back to the divergence theorem

$$\begin{aligned} \oint_S \vec{F} \cdot \vec{n} \, dG &= \iiint_V \operatorname{div} \vec{F} \, dx_1 dx_2 dx_3 = \iiint_V 3 \, dx_1 dx_2 dx_3 \\ &= 3 \cdot \left(\text{volume of 3D unit ball} \right) \end{aligned}$$

This shows that the volume of the 3D unit ball equals

$$\frac{1}{3} \oint_S \vec{F} \cdot \vec{n} \, dG = \frac{4}{3} \pi$$

2. Example : Cylinder

The cylinder is the volume

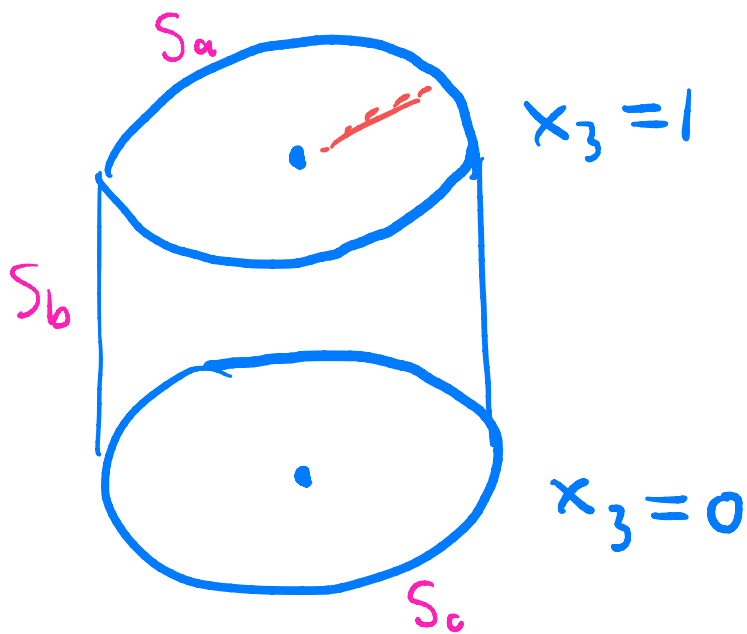
$$V = \{ \vec{x} \in \mathbb{R}^3 \mid 0 < x_3 < 1, \quad x_1^2 + x_2^2 < 1 \}$$

whose surface has three pieces.

$$S_a = \{ (x_1, x_2, 1) \in \mathbb{R}^3 \mid x_1^2 + x_2^2 < 1 \}$$

$$S_b = \{ (x_1, x_2, x_3) \in \mathbb{R}^3 \mid x_1^2 + x_2^2 = 1, \quad 0 < x_3 < 1 \}$$

$$S_c = \{ (x_1, x_2, 0) \in \mathbb{R}^3 \mid x_1^2 + x_2^2 < 1 \}$$



For the divergence theorem:

$$\iiint_V \operatorname{div} \vec{F} \, dx_1 dx_2 dx_3 = \oint_S \vec{F} \cdot \vec{n} \, d\sigma$$

$$= \iint_{S_a} \vec{F} \cdot \vec{n}_a \, d\sigma + \iint_{S_b} \vec{F} \cdot \vec{n}_b \, d\sigma + \iint_{S_c} \vec{F} \cdot \vec{n}_c \, d\sigma \quad ,$$

we need to find the outward pointing unit normal and the parameterization that we use for the integral

We choose the following parameterizations

$$\Phi_a : \underbrace{\{s^2 + t^2 < 1\}}_{\Omega_a} \rightarrow S_a, \quad (s, t) \mapsto (s, t, 1)$$

$$\Phi_b : \underbrace{(0, 2\pi) \times (0, 1)}_{\Omega_b} \rightarrow S_b, \quad (\theta, z) \mapsto (\cos \theta, \sin \theta, z)$$

$$\Phi_c : \underbrace{\{s^2 + t^2 < 1\}}_{\Omega_c} \rightarrow S_c, \quad (s, t) \mapsto (s, t, 0)$$

We compute the normals given by these parameterizations

$$\partial_s \Phi_a \times \partial_t \Phi_a = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

pointing outward along top plate

$$\partial_s \Phi_c \times \partial_t \Phi_c = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

pointing inward along bottom plate

$$\partial_\theta \Phi_b \times \partial_z \Phi_b = \begin{pmatrix} -\sin \theta \\ \cos \theta \\ 0 \end{pmatrix} \times \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \cos \theta \\ \sin \theta \\ 0 \end{pmatrix}$$

pointing outward
along shell

For illustration, we pick the following vector field

$$\vec{F}: \mathbb{R}^3 \rightarrow \mathbb{R}^3, \quad (x_1, x_2, x_3) \mapsto (x_2, x_1, x_3 e^{x_3})$$

We compute the boundary integrals

Top cap:
$$\iint_{S_a} \vec{F} \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} dG = \iint_{\Omega_a} 1 e^1 ds dt = \pi e$$

Bottom cap:
$$\iint_{S_c} \vec{F} \cdot \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} dG = \iint_{\Omega_c} 0 e^0 ds dt = 0$$

Cylinder shell:
$$\begin{aligned} \iint_{S_b} \vec{F} \cdot \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix} dG &= \iint_{S_b} \begin{pmatrix} x_2 \\ x_1 \\ x_3 e^{x_3} \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix} dG \\ &= \int_0^1 \int_0^{2\pi} 2 \cos \theta \sin \theta \cdot 1 \, d\theta \, dz \end{aligned}$$

$$= \int_0^1 \int_0^{2\pi} \partial_\theta (\sin^2 \theta) d\theta dz$$

$$= \int_0^1 \sin^2 \theta \Big|_{\theta=0}^{\theta=2\pi} dz = 0$$

In summary

$$\iiint_V \operatorname{div} \vec{F} dx_1 dx_2 dx_3 = \oint_S \vec{F} \cdot \vec{n} dG$$

$$= \underbrace{\iint_{S_a} \vec{F} \cdot \vec{n}_a}_{\pi e} + \underbrace{\iint_{S_b} \vec{F} \cdot \vec{n}_b}_0 + \underbrace{\iint_{S_c} \vec{F} \cdot \vec{n}_c}_0 = \pi e$$

