

October 16

[Surface integrals
X Divergence
theorem

General Remark on Integrals

The notations S , SS , SSS , $\S$, $\S\S$ are conventions in mathematics / physics but do not carry particular meaning, it just a way to remember what the geometric object looks like

The notation dx , dy , $dsdt$, dl , $d\phi$ is just notation. Historically, they used to signify "infinitesimal" quantities, but that formalism is no longer used. In that sense, the notation is "fossilized"

Agenda

We have seen the divergence theorem over a two-dimensional domain Ω whose boundary is a curve $\partial\Omega$.

We generalize this to 3D volumes V whose boundary is a surface S .

Theory:

Let $V \subseteq \mathbb{R}^3$ be a domain. Let $S = \partial V$ be its boundary.

For any differentiable vector field

$$\vec{F} : \overline{V} \rightarrow \mathbb{R}^3$$

we have

$$\iiint_V \operatorname{div} \vec{F} \, dx_1 dx_2 dx_3 = \oiint_S \vec{F} \cdot \vec{n} \, dG$$



volume integral



closed surface
integral



outward
pointing
unit normal

The physical idea is the same as in 2D

$$\iiint_V \operatorname{div} \vec{F} \, dx_1 dx_2 dx_3 = \oint_S \vec{F} \cdot \vec{n} \, dG$$

what is produced/consumed
inside V

what flows out/in

Practical challenge

- Find a parameterization of the surface $S = \partial V$
- Find the outward pointing unit normal
- Compute the integral

How does this interact with the parameterizations of S

Suppose we have a piecewise regular parameterization
 $\Phi: \Omega \rightarrow S$. Then

$$\iint_S \vec{F} \cdot \vec{n} \, d\sigma = \iint_{\Omega} \vec{F}(\Phi(s,t)) \cdot \vec{n}(\Phi(s,t)) \|\partial_s \Phi(s,t) \times \partial_t \Phi(s,t)\| \, ds \, dt$$

Since $\partial_s \Phi$ and $\partial_t \Phi$ are tangential to S , we must have that $\partial_s \Phi \times \partial_t \Phi$ is normal to S . But we do not know whether that is an inward or outward normal.

If outward, then
$$\vec{n}(\Phi(s,t)) = \frac{\partial_s \Phi \times \partial_t \Phi}{\|\partial_s \Phi \times \partial_t \Phi\|}$$

If inward, then
$$\vec{n}(\Phi(s,t)) = - \frac{\partial_s \Phi \times \partial_t \Phi}{\|\partial_s \Phi \times \partial_t \Phi\|}$$

Hence, if $\partial_s \Phi \times \partial_t \Phi$ points outwards, then

$$\begin{aligned} \iint_S \vec{F} \cdot \vec{n} \, dG &= \iint_{\Omega} \vec{F}(\Phi(s,t)) \cdot \frac{\partial_s \Phi \times \partial_t \Phi}{\|\partial_s \Phi \times \partial_t \Phi\|} \|\partial_s \Phi \times \partial_t \Phi\| \, ds dt \\ &= \iint_{\Omega} \vec{F}(\Phi(s,t)) \cdot (\partial_s \Phi \times \partial_t \Phi) \, ds dt \end{aligned}$$

Instead, if $\partial_s \Phi \times \partial_t \Phi$ points inwards, then

$$\iint_S \vec{F} \cdot \vec{n} \, dG = - \iint_{\Omega} \vec{F}(\Phi(s,t)) \cdot (\partial_s \Phi \times \partial_t \Phi) \, ds dt$$

Examples

1. Sphere

We recall the sphere parameterization

$$\Phi : (0, 2\pi) \times (0, \pi) \rightarrow \mathbb{R}^3,$$

$$(\theta, \varphi)$$

$$\mapsto (\cos \theta \sin \varphi, \sin \theta \sin \varphi, \cos \varphi)$$

We recall

$$\partial_{\theta} \Phi = \begin{pmatrix} -\sin \theta \sin \varphi \\ \cos \theta \sin \varphi \\ 0 \end{pmatrix},$$

$$\partial_{\varphi} \Phi = \begin{pmatrix} \cos \theta \cos \varphi \\ \sin \theta \cos \varphi \\ -\sin \varphi \end{pmatrix}$$

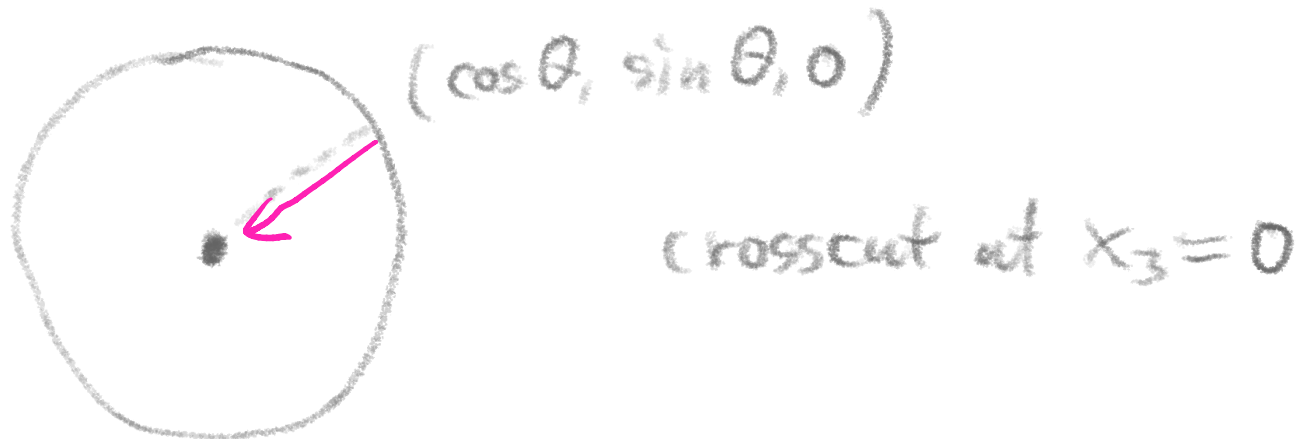
$$\partial_\theta \bar{\Phi} \times \partial_\varphi \bar{\Phi} = - \begin{pmatrix} \cos \theta \sin^2 \varphi \\ \sin \theta \sin^2 \varphi \\ \sin \varphi \cos \varphi \end{pmatrix}$$

Is it outward or inward pointing along S ?

Let's check at $(\theta, \varphi) = (\theta, \pi/2)$

$$(\partial_\theta \bar{\Phi} \times \partial_\varphi \bar{\Phi})(\theta, \pi/2) = - \begin{pmatrix} \cos \theta \\ \sin \theta \\ 0 \end{pmatrix}$$

inward pointing!



If $\partial_\theta \bar{\Phi} \times \partial_\varphi \bar{\Phi}$ points inwards, then
— $\partial_\theta \bar{\Phi} \times \partial_\varphi \bar{\Phi}$ points outwards

$$\underbrace{\iiint_V \operatorname{div} \vec{F} \, dx_1 dx_2 dx_3}_{\checkmark} = - \iint_{\Sigma} \vec{F}(\bar{\Phi}(s,t)) \cdot (\partial_\theta \bar{\Phi} \times \partial_\varphi \bar{\Phi}) \, d\theta d\varphi$$