Considerons
$$T: \mathbb{R}^{3} \to \mathbb{R}^{2}$$
 $\vec{z} \mapsto A\vec{x}$ avec
$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$
• Ker $(\tau) = \begin{cases} 1 & \vec{z} \in \mathbb{R}^{3} \mid T(\vec{x}) = \vec{0} \end{cases}$

$$A\vec{z} = \vec{0} \iff \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix} = \begin{bmatrix} 0 \\ 0 \end{pmatrix}$$

$$A\vec{z} = \vec{0} \iff \begin{bmatrix} x_{1} = 0 \\ x_{2} = 0 \\ x_{3} \text{ libre} \end{bmatrix}$$

$$= \text{Span } f \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} f$$
• Im $(T) = f T(\vec{x}) \mid \vec{z} \in \mathbb{R}^{3} f \subseteq \mathbb{R}^{2}$

$$\text{Soit } \vec{x} = \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix} \text{. Alas } T(\vec{z}) = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix}$$

$$= \begin{pmatrix} x_{1} \\ x_{2} \\ x_{3} \end{pmatrix}$$

$$T \text{ est autjective }, \text{ donc}$$

$$\exists m (T) = \mathbb{R}^{2}$$