# EE-429 Fundamentals of VLSI Design

**Spice Simulations** 

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### **Need for Circuit Simulations**

#### Circuit simulators are important to

- Verify that our designs are properly working (verification)
- Extract circuit parameters for high-level models for design and optimization
- Fine tune parameters from an initial hand-crafted (model-based) starting point
- Verify a circuit in different corners and in the presence of uncertainties
- Track down hidden issues in a larger circuit (especially post-layout)

#### They should not serve as a basis for pure trial-and-error

- Analog simulation are too slow for extensive trial and error
- At any stage, you need to have a good idea of "what to expect"
- You should have a good (and well justified) starting point



## The Original of Circuit Simulations

- First circuit simulator was developed in the 1970s at Berkely:
  - Started as a class project: CANCER="Computer Analysis for Non-linear Circuits Excluding Radiation" (under Prof. Ron Rohrer)
  - His successor (Prof. Don Peterson) and his student (Larry Nagel) developed this class project into the first version of Spice
  - 1972 Spice was released as "Public Domain" (free SW), written in FORTRAN
  - 1975 Spice 2: support for hierarchy, better stability and much less basic device models
  - 1989 Spice 3: better UI, advanced MOSFET (BSIM1 models), written in C
  - SPICE: Bimulation Program with Integrated Circuit Emphasis
- Today, there are many versions of Spice, including "famous" commercial simulators
  - LTSpice, PSpice: public domain
  - HSpice: today owned by Synopsys
  - SPECTRE: developed by CADENCE



## Setting up a Simulation

- For an analog (e.g., Spice) circuit information, we need
  - A "Netlist" that describes our circuit
  - A "Testbench" to provide stimuli, supply voltages, and other inputs as well as external components that connect to our DUT (e.g., capacitive loads,...).
  - "Device models" for basic components: part of the simulator
  - "Model parameters": part of the PDK:
  - Initial conditions: The state of our circuit at the start of the simulation
  - Instructions what and how to simulate and simulation parameters (e.g., temperature)
  - Instructions what to record/save and plot

#### INVERTER TRANSIENT ANALYSIS

- MODELS \*
- \*\*\*\*\*
- .model NMOD NMOS (LEVEL=1, VTO=0.7 GAMMA=0 LAMBDA=0 KP=73U)
- .model PMOD PMOS (LEVEL=1, VTO=-0.8 GAMMA=0 LAMBDA=0 KP=21U)
- \*\*\*\*\*\*
- \* CIRCUIT \*
- \*\*\*\*\*\*
- VDD 3 0 DC 5
- VGS 1 0 PULSE(0,5,0,5n,5n,1u,2u)
- M1 2 1 0 0 NMOD L=2U W=10U
- M2 2 1 3 3 PMOD L=2U W=25U
- C1 2 0 0.047n
- .OP
- .TRAN 0.1U 3U
- .PLOT TRAN V(2)
- .PROBE
- .END



## Types of Simulations

#### DC Analysis

- Find the DC Operating Point: circuit solution in steady state (all inputs fixed)
- Solves a non-linear system of equations: usually through linearization and Newton's method
- Iterative process that converges to a solution
- The DC analysis is the starting point for a Transient or AC Analysis

#### Transient Analysis

- Starts from operating point found in DC analysis (time-0)
- Solves a set of non-linear differential equations by discretizing time usually with variable time steps

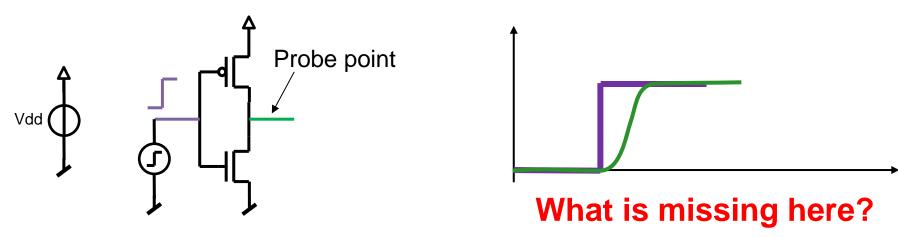
#### AC Analysis

- Used mostly for analog design
- Analyzes frequency domain behavior / response of a circuit



 A proper testbench (adapted to what we want to see) is critical to have meaningful results

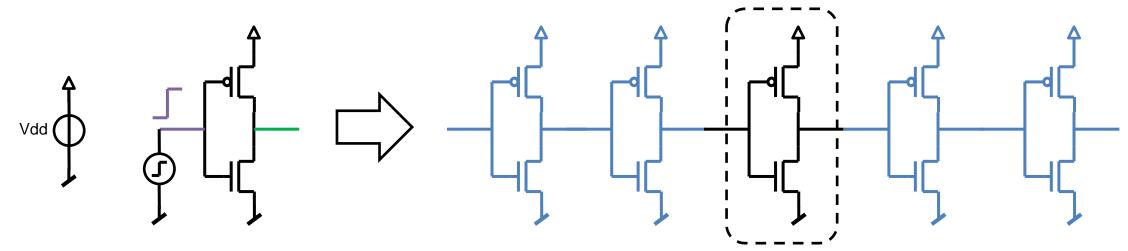
#### Example: delay (transient) simulation of an inverter





- A proper testbench (adapted to what we want to see) is critical to have meaningful results
- Must properly reflect not only the circuit, but also the boundary conditions
  - Realistic input signals
  - Realistic electrical characteristics of the inputs and outputs

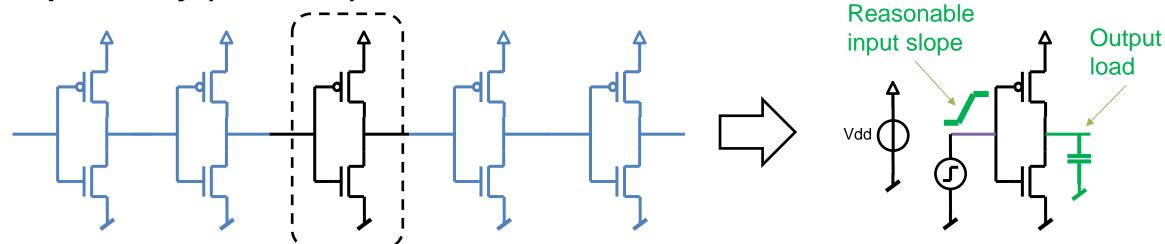
#### **Example: delay (transient) simulation of an inverter**





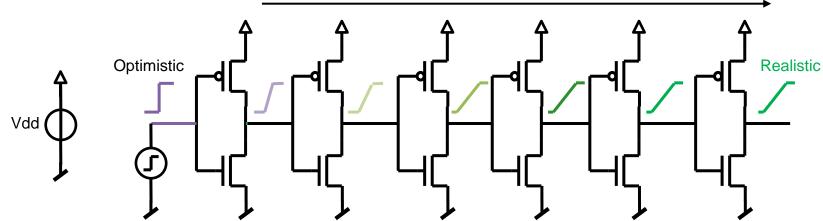
- A proper testbench (adapted to what we want to see) is critical to have meaningful results
- Must properly reflect not only the circuit, but also the boundary conditions
  - Realistic input signals
  - Realistic electrical characteristics of the inputs and outputs
- Efficiently represent boundary conditions with a proper model

#### Example: delay (transient) simulation of an inverter





- Using simulation to find proper values for transition time and output load:
  - Build a testbench that allows to calculate the desired model parameters from known quantities
- Input transition time: Impact of ideal slop reduces with each stage



- Using simulation to find proper values for transition time and output load:
  - Build a testbench that allows to calculate the desired model parameters from known quantities
- Load capacitance:
  - Extract from RC model

